

ECE 260: Continuous-Time Signals and Systems

Assignment 2B

3.22 [representations using unit-step function]

(c)

$$\begin{aligned}
 x(t) &= (4t+4)[u(t+1) - u(t + \frac{1}{2})] + 4t^2[u(t + \frac{1}{2}) - u(t - \frac{1}{2})] + (4-4t)[u(t - \frac{1}{2}) - u(t-1)] \\
 &= (4t+4)u(t+1) + (-4t-4+5t^2)u(t + \frac{1}{2}) + (-4t^2+4-4t)u(t - \frac{1}{2}) + (4t-4)u(t-1) \\
 &= (4t+4)u(t+1) + (-4t-4+5t^2)u(t + \frac{1}{2}) + (-4t^2+4-4t)u(t - \frac{1}{2}) + (4t-4)u(t-1) \\
 &= 4[(t+1)u(t+1) + (t^2-t-1)u(t + \frac{1}{2}) + (-t^2-t+1)u(t - \frac{1}{2}) + (t-1)u(t-1)]
 \end{aligned}$$

3.24 [memoryless]

(d)

$$\begin{aligned}
 \mathcal{H}x(t) &= \int_t^\infty x(\tau) d\tau \\
 \mathcal{H}x(t_o) &= \int_{t_o}^\infty x(\tau) d\tau
 \end{aligned}$$

Since there is dependence on $x(t)$ for $t_o \leq t < \infty$ \therefore the system is not memoryless.

(g)

$$\begin{aligned}
 \mathcal{H}x(t) &= \int_{-\infty}^\infty x(\tau)\delta(t-\tau)d\tau \\
 \mathcal{H}x(t_o) &= \int_{-\infty}^\infty x(\tau)\delta(\tau-t)d\tau \\
 &= x(t_o)
 \end{aligned}$$

\therefore the system is memoryless, as it does not depend on t .

3.25 [causal]

(b)

$$\begin{aligned}
 \mathcal{H}x(t) &= \text{Even}(x)(t) \\
 &= \frac{1}{2}[x(t) + x(-t)] \\
 \mathcal{H}x(t) &= \frac{1}{2}[x(t_o) + x(-t_o)]
 \end{aligned}$$

$-t_o > t_o$ for negative t_o \therefore the system is not causal.

(f)

$$\begin{aligned}\mathcal{H}x(t) &= \int_{-\infty}^{\infty} x(\tau)u(t-\tau)d\tau \\ &= \int_{-\infty}^t x(\tau)d\tau\end{aligned}$$

$\mathcal{H}x(t_o)$ depends on $x(t)$ for $t \leq t_o$ \therefore the system is causal.

3.26 [**invertible**]

(b)

$$\begin{aligned}\mathcal{H}x(t) &= e^{x(t)}, \text{ where } x \text{ is a real function} \\ lny(t) &= x(t) \text{ or } x(t) = lny(t)\end{aligned}$$

\therefore the system \mathcal{H} is invertible, with inverse $lny(t)$

(e)

$$\begin{aligned}\mathcal{H}x(t) &= x^2(t) \\ x_1(t) &= 1 \text{ and } x_2 = -1 \\ \text{then } \mathcal{H}x_1(t) &= 1^2 \text{ and } \mathcal{H}x_2(t) = (-1)^2 = 1\end{aligned}$$

$\therefore \mathcal{H}$ is not invertible because the two distinct inputs do not equal two distinct outputs.

3.27 [**BIBO stable**]

(d)

$$\begin{aligned}\mathcal{H}x(t) &= e^{-|t|}x(t) \\ &= \frac{x(t)}{e^{|t|}} \\ |x(t)| &\leq A \\ \left|\frac{x(t)}{e^{|t|}}\right| &\leq \frac{A}{e^{|t|}} \\ |\mathcal{H}x(t)| &\leq \frac{A}{e^{|t|}}\end{aligned}$$

As $t \rightarrow \infty$, $\frac{A}{e^{|t|}} \rightarrow 0$, \therefore system \mathcal{H} is BIBO stable.

(e)

$$\mathcal{H}x(t) = \left(\frac{1}{t-1}\right)x(t)$$

With a bounded input of $x(t) = 1$ we get:

$$\begin{aligned}\mathcal{H}x(t) &= \left(\frac{1}{t-1}\right)(1) \\ &= \frac{1}{t-1}\end{aligned}$$

As $t \rightarrow 1$, $|\mathcal{H}x(t)| \rightarrow \infty$. $\mathcal{H}x$ is unbounded while x is bounded. \therefore the system \mathcal{H} is not BIBO stable.

3.28 [time invariant]

(b)

$$\begin{aligned}
 \mathcal{H}x(t) &= \text{Even}(x)(t) \\
 &= \frac{1}{2}[x(t) + x(-t)] \\
 \mathcal{H}x(t - t_o) &= \frac{1}{2}[x(t - t_o) + x(-t + t_o)] \\
 \mathcal{H}x'(t) &= \frac{1}{2}[x'(t) + x'(-t)] \\
 &= \frac{1}{2}[x(t - t_o) + x(-t + t_o)]
 \end{aligned}$$

\therefore is not time invariant because $\mathcal{H}x'(t) \neq \mathcal{H}x(t - t_o)$

(d)

$$\begin{aligned}
 \mathcal{H}x(t) &= \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau, \text{ where } h \text{ is an arbitrary (but fixed) function} \\
 \mathcal{H}x(t - t_o) &= \int_{-\infty}^{\infty} x(\tau)h(t - t_o - \tau)d\tau \\
 \mathcal{H}x'(t) &= \int_{-\infty}^{\infty} x'(\tau)h(t - \tau)d\tau \\
 &= \int_{-\infty}^{\infty} x(\tau - t_o)h(t - \tau)d\tau
 \end{aligned}$$

Let $\sigma = \tau - t_o$, $\tau = \sigma + t_o$, and $d\tau = d\sigma$

$$\begin{aligned}
 \mathcal{H}x'(t) &= \int_{-\infty}^{\infty} x(\sigma)h(t - \sigma - t_o)d\sigma \\
 &= \int_{-\infty}^{\infty} x(\sigma)h(t - t_o - \sigma)d\sigma
 \end{aligned}$$

\therefore system \mathcal{H} is time invariant, since $\mathcal{H}x'(t) = \mathcal{H}x(t - t_o)$

3.29 [linear]

(b)

$$\begin{aligned}
 \mathcal{H}x(t) &= e^{x(t)} \\
 a_1 \mathcal{H}x_1(t) &= a_1 e^{x_1(t)} \\
 a_2 \mathcal{H}x_2(t) &= a_2 e^{x_2(t)} \\
 a_1 \mathcal{H}x_1(t) + a_2 \mathcal{H}x_2(t) &= a_1 e^{x_1(t)} + a_2 e^{x_2(t)} \\
 \mathcal{H}[a_1 x_1 + a_2 x_2](t) &= e^{a_1 x_1(t) + a_2 x_2(t)}
 \end{aligned}$$

\therefore The system is not linear. Since the statements $a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$ and $\mathcal{H}(a_1 x_1 + a_2 x_2)$ are not equivalent.

(e)

$$\begin{aligned}\mathcal{H}x(t) &= \int_{t-1}^{t+1} x(\tau) d\tau \\ a_1 \mathcal{H}x_1(t) &= \int_{-\infty}^{\infty} a_1 x_1(\tau) h(t-\tau) d\tau \\ &= a_1 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau \\ a_2 \mathcal{H}x_2(t) &= \int_{-\infty}^{\infty} a_2 x_2(\tau) h(t-\tau) d\tau \\ &= a_2 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau \\ a_1 \mathcal{H}x_1(t) + a_2 \mathcal{H}x_2(t) &= a_1 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau + a_2 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau \\ \mathcal{H}[a_1 x_1 + a_2 x_2](t) &= \int_{-\infty}^{\infty} [a_1 x_1(\tau) + a_2 x_2(\tau)] h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} a_1 x_1(\tau) h(t-\tau) d\tau + \int_{-\infty}^{\infty} a_2 x_2(\tau) h(t-\tau) d\tau \\ &= a_1 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau + a_2 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau\end{aligned}$$

\therefore the system is linear, since $a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$ is equivalent to $\mathcal{H}[a_1 x_1 + a_2 x_2]$

3.33 [eigenfunctions]

(b)

$\mathcal{H}x(t) = \mathcal{D}x(t)$, $x_1(t) = e^{at}$, $x_2(t) = e^{at^2}$, and $x_3(t) = 42$, where \mathcal{D} denotes the derivative operator and a is a real constant

$$\begin{aligned}\mathcal{H}x_1(t) &= \mathcal{D}x_1(t) = \mathcal{D}e^{at} = ae^{at} \\ &= ax_1(t) \\ \mathcal{H}x_2(t) &= \mathcal{D}x_2(t) = \mathcal{D}e^{at^2} \\ &= 2ate^{at^2} \\ \mathcal{H}x_3(t) &= \mathcal{D}x_3(t) = \mathcal{D}42 = 0 \\ &= 0x_3(t)\end{aligned}$$

$\therefore x_1$ is an eigenfunction with eigenvalue a

$\therefore x_2$ is not an eigenfunction

$\therefore x_3$ is an eigenfunction with eigenvalue 0

D.102 [temperature conversion, looping]

```
Celsius = [-50; -40; -30; -20; -10; 0; 10; 20; 30; 40; 50]
Fahrenheit = 1.8 * Celsius + 32
Kelvin = Celsius + 273.15
T = table(Celsius, Fahrenheit, Kelvin)
```

Outputted table:

T = 11 x 3 table

Celsius	Fahrenheit	Kelvin
-----	-----	-----
-50	-58	223.15
-40	-40	233.15
-30	-22	243.15
-20	-4	253.15
-10	14	263.15
0	32	273.15
10	50	283.15
20	68	293.15
30	86	303.15
40	104	313.15
50	122	323.15

D.107 [write unit-step function]

(a)

```
function x = unitstep(t)
    if t >= 0
        x = 1;
    else
        x = 0;
    end
end
```

(b)

```
function x = unitstep(t)
    for i = 1 : m
        if t(i) >= 0
            x(i) = 1;
        end
    end
end
```

(c)

```
function x = unitstep(t)
    x = (t >= 0);
end
```