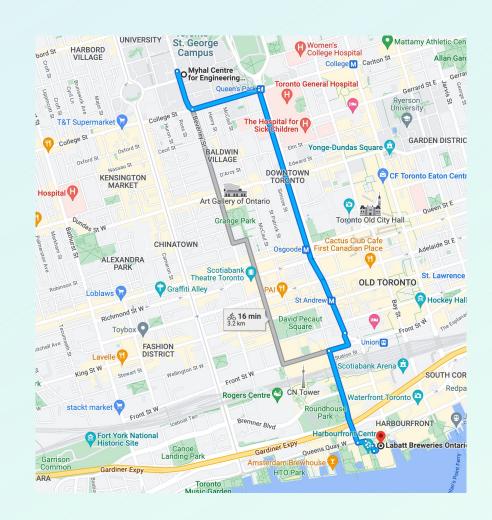
Optimization, constraints and Linear Programming

Day 3

Labatt Impact Lab Bootcamp

What is Optimization?

- Major field within Data Analytics,
 Operations Research and
 Management Science
- Basic idea: find the values of the decision variables that maximize (or minimize) the objective value, while staying within the constraints
- How do I find the <u>shortest</u> route to bike to Labatt, <u>without</u> breaking traffic laws?



What is Optimization?

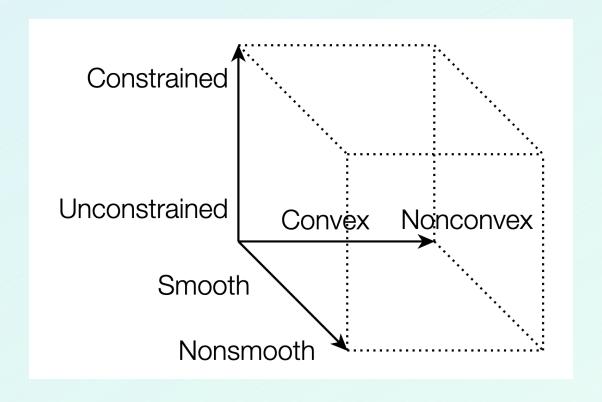
- In machine learning, we usually want to <u>minimize</u> the result of a loss function
- A huge number of ML problems can be solved using optimization
 - e.g. regression, classification, maximum likelihood
- If we can use optimization, we get access to powerful tools which can find our answer





Classes of optimization problem

- Many different types of problem can be framed as an optimization problem
- Three main distinctions help to define them
- Constrained vs Unconstrained
- Convex vs Nonconvex
- Smooth vs Nonsmooth (less important)



Constrained vs Unconstrained

- Constraints are conditions on what answers are acceptable
- When finding the shortest driving route, you are really finding the shortest legal driving route
- When scheduling employees, have to factor in their availability

$$\underset{x}{\text{minimize}} f(x)$$

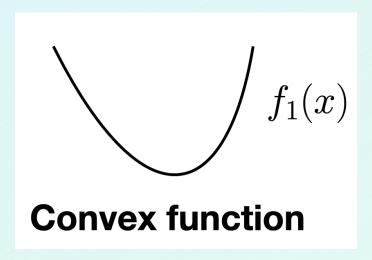
VS

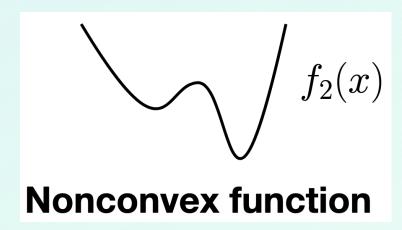
minimize
$$f(x)$$

subject to $g_i(x) \leq 0, \quad i = 1, \dots, m$
 $h_i(x) = 0, \quad i = 1, \dots, p$

Convex vs Nonconvex

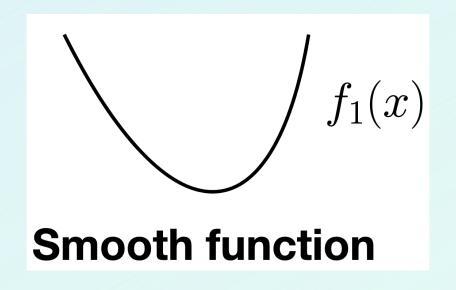
- A function is convex if there is exactly one "bottom" point – the global minimum
- This makes the problem much easier to solve because as long as the error is decreasing, you are getting closer to the best answer
- If the function is nonconvex, you can be "tricked" by a local minimum

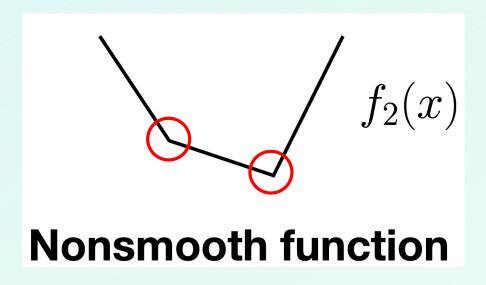




Smooth vs Nonsmooth

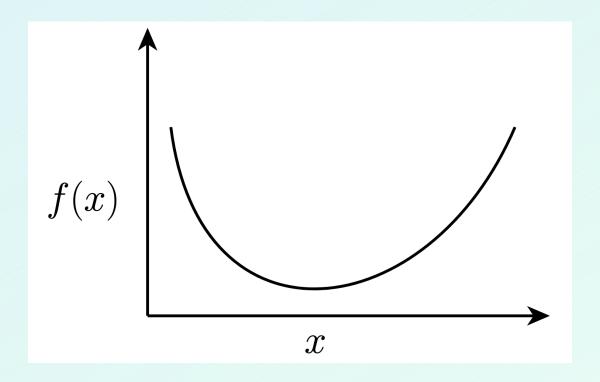
- Many modelling methods depend on calculating the derivative of the error – this tells us how to change our answer to get closer to the minimum
- If the function is nonsmooth, there are points (red) where it is not possible to differentiate



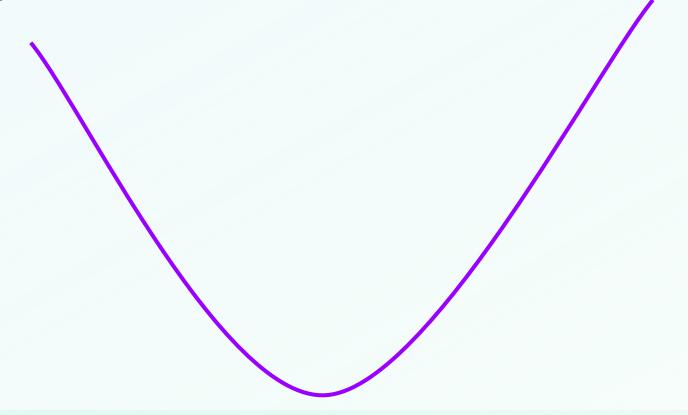


Solving an optimization problem

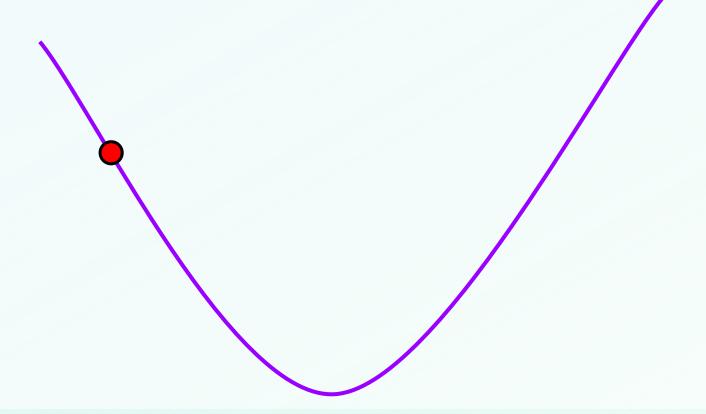
- Let's start with the simplest case: unconstrained, convex, smooth function
- We just need to find the point where the curve is flat (i.e. derivative is zero) - this is the minimum
- If the function is <u>very</u> simple, we can just calculate this value directly
- Otherwise, we can use gradient descent



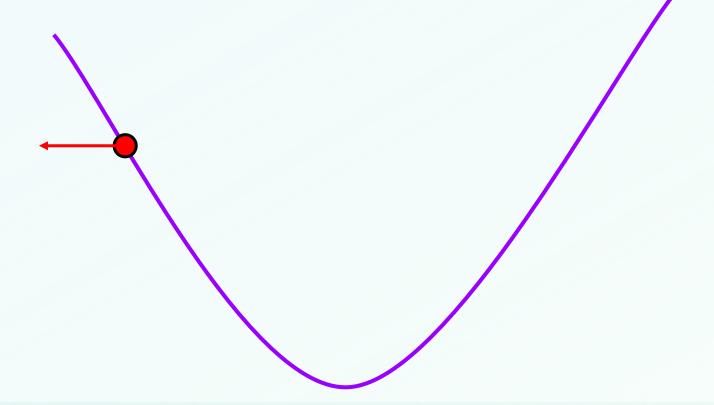
For some loss function $L(\mathbf{w})$, gradient $\nabla L(\mathbf{w})$ points towards in direction of steepest ascent.



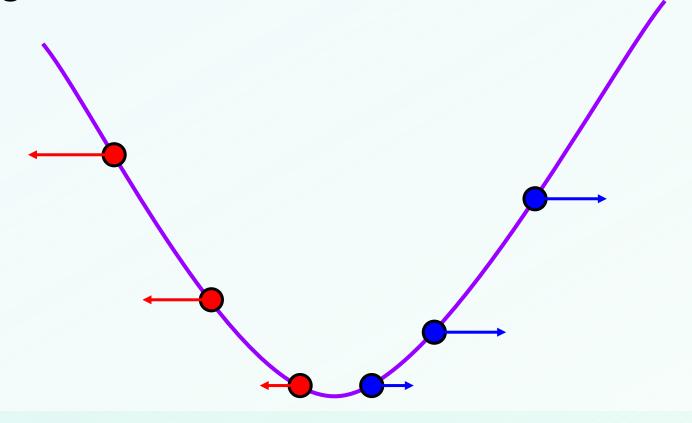
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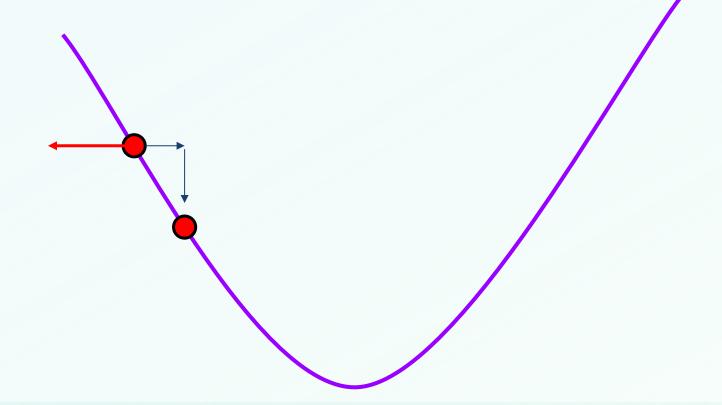


For some loss function $L(\mathbf{w})$, gradient $\nabla L(\mathbf{w})$ points towards in direction of steepest ascent.

In Id, either points left or right

Algorithm:

Take derivative
Move slightly in other
direction
Repeat

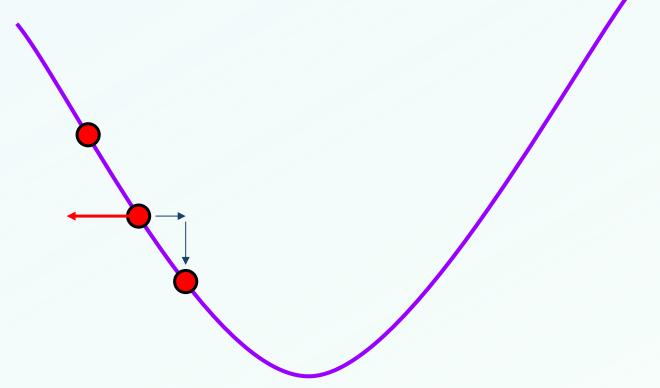


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Algorithm:

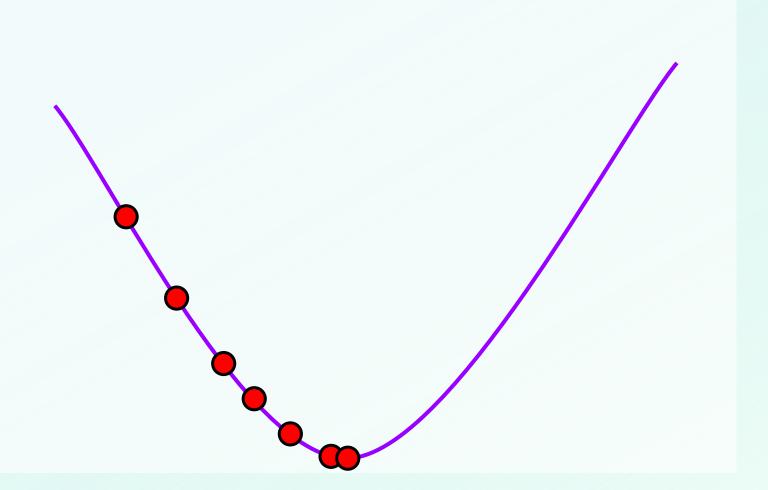
Take derivative

Move slightly in other

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Repeat

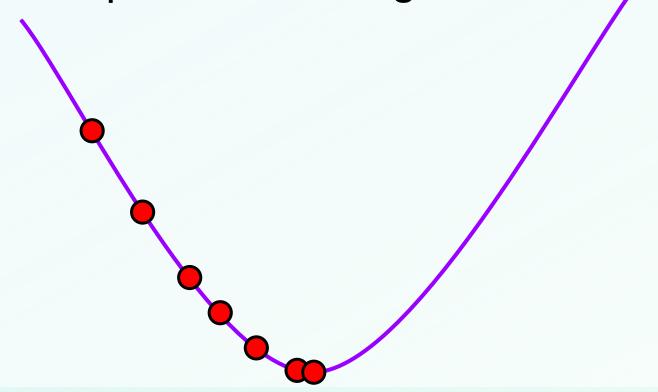
End up at local optima



Formally:

$$\mathbf{w}_{t+1} = \mathbf{w}_{t} - \eta \nabla L(\mathbf{w})$$

Where η is step size, how far to step relative to the gradient



Optimization in action: Linear Programming

- As we've discussed, often optimizing a function can be extremely difficult
- Linear functions, even with constraints, are efficiently solvable (or can be approximated)
- If we can <u>reformulate</u> a problem to be described in a certain way, then it can be solved much more easily
- Note: the "programme" in linear programming is not the same as a computer program! It refers to <u>planning</u>.

What makes a linear programme

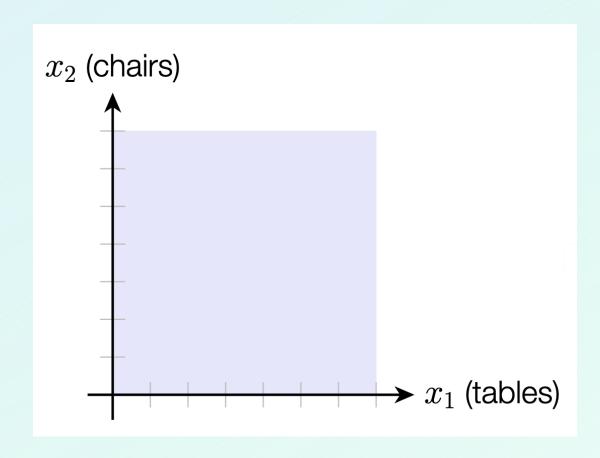
- Optimization problem consisting of
 - maximizing (or minimizing) a <u>linear</u> objective function
 - of n decision variables
 - subject to a set of constraints expressed by <u>linear</u> equations or inequalities.
- In linear programme: objective function + constraints are <u>all linear</u> Typically (not always): variables are non-negative

A large factory makes tables and chairs. Each table returns a profit of \$200 and each chair a profit of \$100.

Each table takes I unit of metal and 3 units of wood and each chair takes 2 units of metal and I unit of wood.

The factory has 6 units of metal and 9 units of wood.

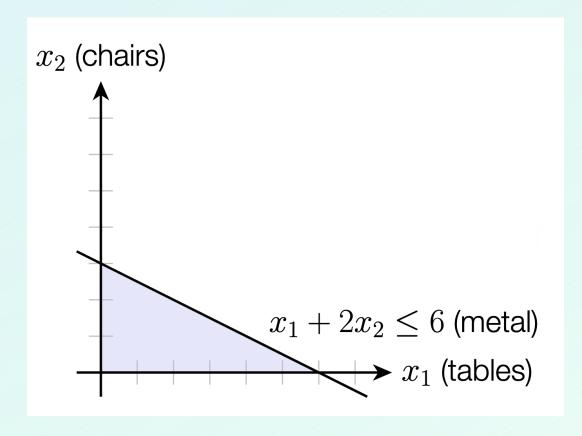
How many tables and chairs should the factory make to maximize profit?



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$$1x_1 + 2x_2 \le 6$$

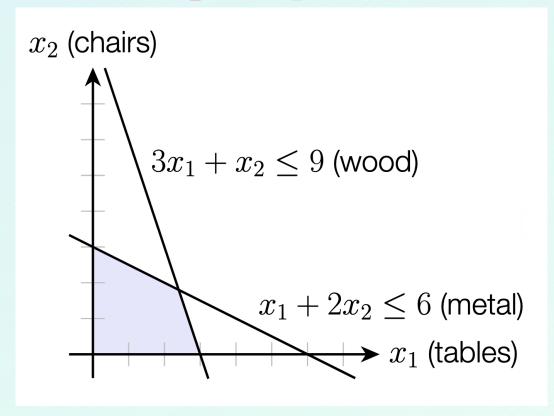


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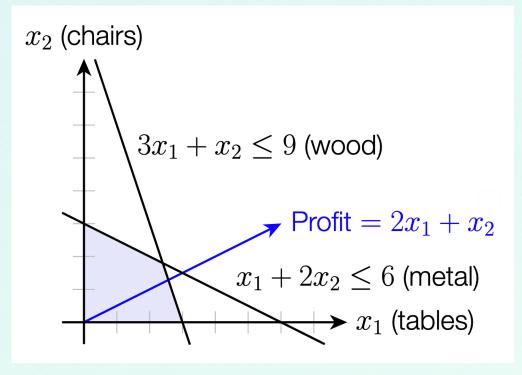
$$3x_1 + 1x_2 \le 9$$



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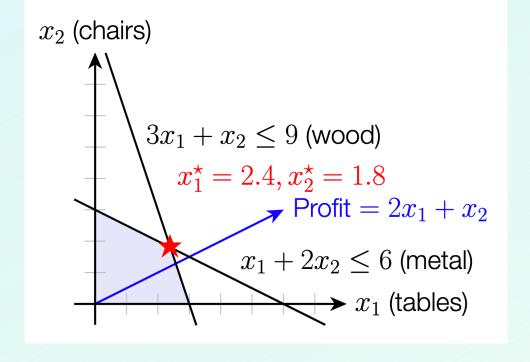
$$\begin{aligned}
 1x_1 + 2x_2 &\leq 6 \\
 3x_1 + 1x_2 &\leq 9 \\
 Profit &= 2x_1 + 1x_2
 \end{aligned}$$



maximize
$$2x_1 + x_2$$

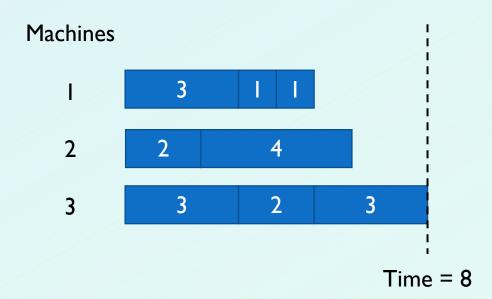
subject to $x_1 + 2x_2 \le 6$
 $3x_1 + x_2 \le 9$
 $x_1, x_2 \ge 0$

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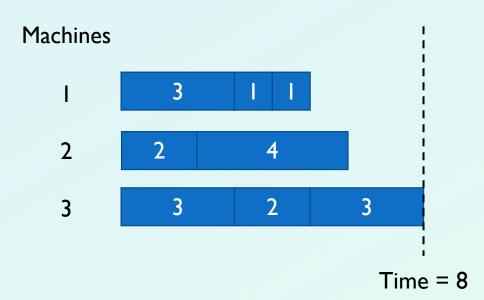


Lab Part I

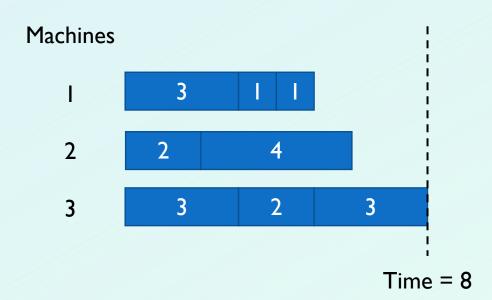
- 3 machines must complete 8 tasks, each of which takes a varying amount of time.
- How do we assign the tasks so that the total time spent is as short as possible?



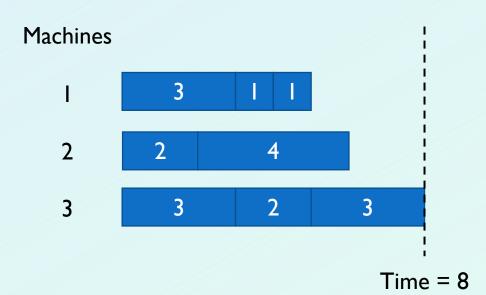
- 3 machines: $j_1 \dots j_3$
- 8 tasks: $i_1 ... i_8$
- Each task i lasts t_i units of time



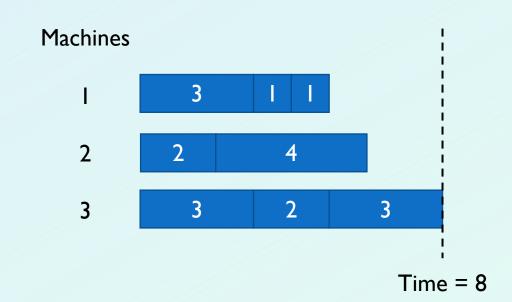
- 3 machines: $j_1 \dots j_3$
- 8 tasks: $i_1 ... i_8$
- Each task i lasts t_i units of time
- The total amount of time needed by any one machine must be less than or equal to the total time needed
- Every task must be assigned exactly one time



- 3 machines: $j_1 ... j_3$
- 8 tasks: $i_1 ... i_8$
- Each task i lasts t_i units of time
- The total amount of time needed must be less than or equal to the amount of time needed by one machine
- Every task must be assigned exactly one time
- $x_i^j = 1$ if task i is assigned to machine j

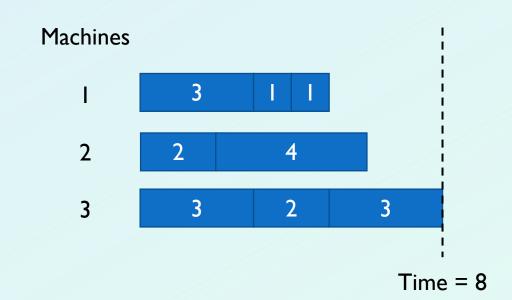


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$$\sum_{i} (t_i * x_i^j) \le t_{total}$$
 (For each machine j)

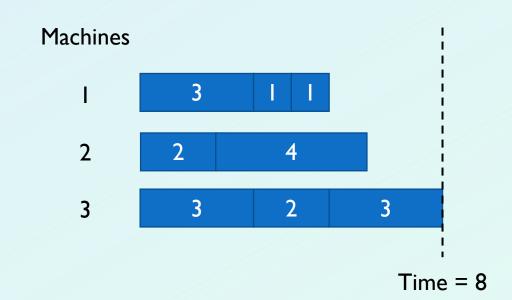
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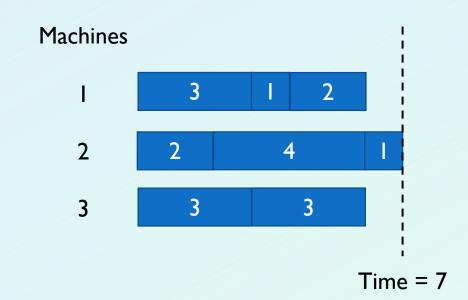


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Minimize $t_{total}!$

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 (For each machine j)

$$\sum_{j} x_{i}^{j} = 1$$
 (For each task i)

Minimize $t_{total}!$

- Capable of handling even more complex requirements
- e.g. preferred jobs to certain machines, or jobs that must be completed before others can begin

