

# ALEXANDRE CLIN DEFFARGES

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## Education

**Master's degree in Robotic / AI, ETHZ** *Zurich, Switzerland - 2023-2025*

**Global year exchange, Tokyo Institute of Technology** *Tokyo, Japan - 2022 - 2023*

**Bachelor's degree in microtechnology, EPFL** *Lausanne, Switzerland - 2020 - 2022*  
Grade : 5,23/6

## Work Experience

**Internship at SPOTS, Anti-Poaching Technology Development** | Computer Vision, ROS2

**Dinokeng game reserve, South Africa, 09/2024 - 12/2024, On site**

At Dinokeng Game Reserve, I developed models for poacher detection via drone and an autonomous patrol car. I created models to detect humans and animals in video, raising alerts for unwanted presence, and worked on recognizing poacher footpaths.

**Internship at Infosys, NLP and RAG Modeling** | Deep Learning, RAG

**Bengalore, India, 06/2024 - 08/2024, On site**

I developed a model to classify and transform multimodal data (emails, PDFs, images, graphs) into structured data for a Retrieval-Augmented Generation (RAG) model, enhancing data processing and retrieval.

**AI Specialist - Automating Student Essay Evaluation through LLMs - IBE** | LLMs, Python

**Zurich, Switzerland, 04/2024 - now, Remote**

Alongside my other work, in my 40% part-time position at IBE, I dedicated my efforts to leveraging AI and LLMs to automate the grading of students' language essays. This aimed to optimize the evaluation process and improving its efficiency.

**Internship at the Space Domain - Swiss Army** | Signal processing, Machine learning, Github

**Lausanne, Switzerland, 05/2023 - 08/2023, On site**

During my internship at Solenix, I consulted on Swiss Army Space Domain projects, calculating satellite deltaV and fuel consumption using historical data, and applying signal processing and machine learning with Python and Java (<https://space-campus.ch/>).

**Internship of manufacturing - ETML** | Manufacturing

**École technique École des métiers, Lausanne, 07/2022 - 08/2022, On site**

During this internship, I learned drilling, milling, turning, brazing, and sawing by making various parts with different machines.

## Projects and Research

**AI for Education: Transforming Learning Experiences - TalentKick Incubator**

**Zurich, Switzerland, 01/01/2024 - now**

As part of the TalentKick incubator (<https://www.talentkick.ch/>), I built a team to develop an AI-powered education project that won the CHF 5,000 incubator prize. Our solution leverages AI to help students prepare for exams and enhances educational experiences.

**Spatial reasoning from LLM for global navigation - ETHZ** | LLMs, python

**Zurich, Switzerland, 15/02/2024 - 15/06/2024, On site**

For my semester project, I tested the spatial reasoning capabilities of LLMs, such as GPT-4, to enhance robot navigation in very diverse environments. The aim was to evaluate the strengths and weaknesses of LLMs, followed by testing with the ANYmal robot.

**Robotic Hand project - ETHZ** | Robotic, Computer vision, CAD, RL

**Zurich, Switzerland, 09/2023 - 01/2024, On site**

For a project at ETHZ, I led a team of five to design and build an articulated robotic hand from scratch with a CHF 250 budget. I applied skills in computer vision, design, fabrication, reinforcement learning, control, and testing to achieve object manipulation.

**Learning Recovery Maneuvers for Robotic Parkour - ETHZ** | Reinforcement Learning

**Zurich, Switzerland, 15/02/2024 - 15/06/2024, On site**

As a semester project, I had to train a policy, using Reinforcement Learning in order to teach the robot ANYmal (<https://www.anybotics.com/robotics/anymal/>) to know how to fall and reduce its damage.