User Manual for YC2440&UTU2440 Linux

V5.1

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1 General

This guide applies to all product series of YC2410 and YC2440.

This guide's description is based on open SUSE Linux 10.2 host development PC. If you are using other distributions like RedHat 9.0, Fedora Core, or Ubuntu Desktop etc, it also works although there is slightly difference. Please refer to the user manual of your particular Linux distribution when necessary.

There are some assumptions in this guide:

- The IP address of host PC is 192.168.2.3.
- The IP address of target is 192.168.2.10.
- The gateway of router is 192.168.2.1.

2 Hardware Connection

Please connect your devices as one of the figures below:

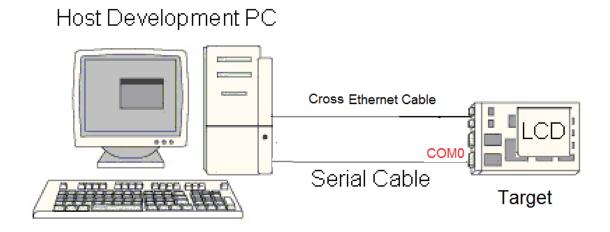


Figure 1 Use crossed Ethernet cable.

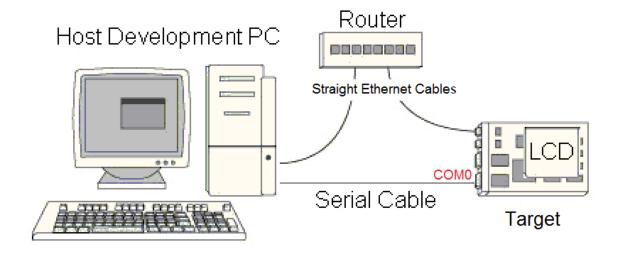


Figure 2 Use straight Ethernet cables.

3 Setup Linux Development Platform

The following programs are available for all Linux platforms. You may have to install them if they haven't been installed. Please refer to the installation procedure of your particular Linux distribution to install them. You should have root privileges.

To prevent from some problems caused by firewall, please first disable the firewall of your host Linux PC.

3.1 Setup minicom

The first time Minicom is run, you will have to initialize the settings. To do this perform the following steps:

#minicom -s

The Minicom Setup screen will now appear:



Go down to Serial port setup and hit Enter.

The Serial port setup window should now appear:

```
A - Serial Device : /dev/ttyS0
B - Lockfile Location :
C - Callin Program :
D - Callout Program :
E - Bps/Par/Bits : 115200 8N1
F - Hardware Flow Control : No
G - Software Flow Control : No
Change which setting?

Screen and keyboard
Save setup as dfl
Save setup as .
Exit
Exit from Minicom
```

In this menu type the letter of the option you want to choose (e.g. 'A' would be Serial Device) and then edit the configuration for that option as above.

115200 baud is the default serial transfer rate for U-Boot and the linux kernel. Hit Esc to return to the main menu.

Next Go down to Modem and Dialing and hit Enter, the modem features must be disabled:



The modem and dialing setup screen should now appear:

```
—[Moden and dialing parameter setup]
   Init string .....
 - Reset string ......
   Dialing prefix #1
 - Dialing suffix #1.
   Dialing prefix #2.
   Dialing
   Dialing prefix #3....
 - Dialing
           suffix #3.
   Connect string ......
   No connect strings .. NO CARRIER
                                               BUSY
                         NO DIALTONE
                                               VOICE
K - Hang-up string ......
 - Dial cancel string ...
 - Dial time ......
                                 Q - Auto bps detect .....
                                 R - Modem has DCD line .. Yes
 - Delay before redial . 2
                                 S - Status line shows ... DIE speed
 - Number of tries ..... 10
P - DTR drop time (0=no). 1
                                 T - Multi-line untag ...
Change which setting?
                           (Return or Esc to exit)
```

In this menu hit the letter of the option you want to choose (e.g. 'A' would be Init string) and then edit the configuration for that option as above.

Hit Esc to return to the main menu

Now that the configuration has been set, it should be saved as the default configuration so that every time Minicom starts these settings will be restored.

3.2 Setup TFTP server

The TFTP server is used by U-Boot to load image file (bootloader image, kernel image or file system image) from host PC to the target system.

```
Check you have TFTP package installed:
#/usr/sbin/in.tftpd -V
Create /etc/xinetd.d/tftp and put this entry:
service tftp
{
protocol
            = udp
socket type = dgram
wait
           = yes
           = root
user
           = /usr/sbin/in.tftpd
server
server args = -s / tftpboot
disable
           = no
Create /tftpboot directory
#mkdir /tftpboot
#chmod -R 777 /tftpboot
#chown -R nobody /tftpboot
Start tftpd through xinetd
#/etc/init.d/xinetd restart
```

3.3 Setup NFS server

NFS is a useful tool to make the development easy. You can mount a file system on the host PC and develop your applications on the host PC before deploying them to the target. You can also transfer any files between the target and the NFS mounted directories.

Before you can configure NFS, you need to verify that the NFS server is running.

To verify that the NFS server is running, complete the following tasks:

Verify that the nfs daemon is running. Use the command:

```
#ps -aef | grep nfs

Messages similar to the following are displayed: root 11622 1 0 Apr17 ? 00:00:00 [nfsd] root 11623 1 0 Apr17 ? 00:00:00 [nfsd]
```

Verify that portmap is available.

#ps -aef | grep portmap

Message similar to the following are displayed: bin 398 1 0 Apr10 ? 00:01:01 /sbin/portmap

Verify that the rpc.mountd mount daemon is available.

#ps -aef | grep mountd

Message similar to the following are displayed: root 11614 1 0 Apr17 ? 00:00:00 /usr/sbin/rpc.mountd

To setup NFS server

Add the following line in /etc/exports:

your_dir *(rw,no_root_squash,no_all_squash)
(ENTER THE PRECEDING STRING AS A SINGLE LINE.)

The above directory (your_dir) could be any directories you want to export, and you can add as many lines as you want so that you can export many directories.

Restart the NFS daemon.

#/usr/sbin/rcnfsserver restart

Sync the NFS daemon.

#/usr/sbin/exportfs -ra

NFS is now set up.

3.4 Install Cross-compiling Toolchain

The toolchain packages are in arm-linux-gcc-3.4.1.tar.bz2. You can use this toolchain to compile kernel and applications, however you need arm-linux-gcc-3.3.2.tar.bz2 to compile the provided qtopia version.

3.4.1 Extract the toolchain package in to /usr/local/arm

#mkdir -p /usr/local/arm

#tar -xjvf arm-linux-gcc-3.4.1.tar.bz2 -C /

3.4.2 Set path

Add a line in /etc/profile like below:

..

PATH=/usr/local/arm/3.4.1/bin:\$PATH << Add this line export PATH

- -

Save, and logoff and logon

If your Linux is not Suse Linux, the PATH setup may be different.

3.4.3 Verify the toolchain has been installed

#arm-linux-gcc -version

Message similar to the following are displayed: arm-linux-gcc (GCC) 3.4.1

4 Experience Linux

The following software applications are stored in the 64Mbytes NAND flash memory. You don't need to do programming at this time. You can always restore them using the pre-built images of bootloader, kernel, and file system in the supplied CD.

During booting, you might see some messages on the Minicom console as below:

Block XXXX is marked bad

Block XXXX is bad

That is all right. It is very common that NAND flash has bad blocks. Your Linux file system is smart enough to detect and mark those blocks. Those bad blocks will not be used when running.

4.1 Mount a USB drive

Insert a USB drive into USB host, you will see some messages on your minicom terminal.

#mount /dev/sda1 /mnt

#ls/mnt

#umount /mnt

4.2 Mount a SD/MMC card

Insert a SD card into SD slot, you will see some messages on your minicom terminal.

#mount /dev/mmcblk0p1 /mnt

#ls/mnt

#umount /mnt

4.3 Play a mp3 music using madplay

madplay is a command line mp3 player.

To see how to use it:

#madplay -h

To play a mp3 music #madplay music.mp3

4.4 Check your target's IP address

#ifconfig -a

4.5 Check the network.

#ping 192.168.2.1

4.6 Using telnet to logon the target

#telnet 192.168.2.10

4.7 Set, save and read the real-time clock

To set the current system clock: #date -s 112717122006 Mon Nov 27 17:12:00 UTC 2006

To save current system time into the hardware clock, afterwards the real-time clock will be maintained by the battery on the board:

#hwclock -w

To read the system time from the hardware clock after the system boots up: #hwclock –s

4.8 Test buttons

#buttons

Press each button, you will see some messages on the minicom terminal.

4.9 Test LEDs

#led [0-3] [1|0]

4.10 Test blacklight

This is supported only on some LCDs.

#lcdbacklight on

#lcdbacklight off

4.11 Using USB camera

Many USB cameras are supported. Plug in your USB camera into USB host connecter, you will probably see some messages on your minicom terminal like below:

#usb 1-1: new full speed USB device using s3c2410-ohci and address 2 drivers/usb/media/gspca/gspca core.c: USB SPCA5XX camera found.(ZC3XX)

4.11.1 To display video on LCD

#servfox -g -L

servfox version: 1.1.2 date: 07:10:2005 (C) mxhaard@magic.fr

frame buffer: 320x240, 16bpp, 0x25800byte

Ctrl + C to STOP!



4.11.2 To display on the web browser of host PC

#servfox -d /dev/video0 -g 640 480 -w 7070

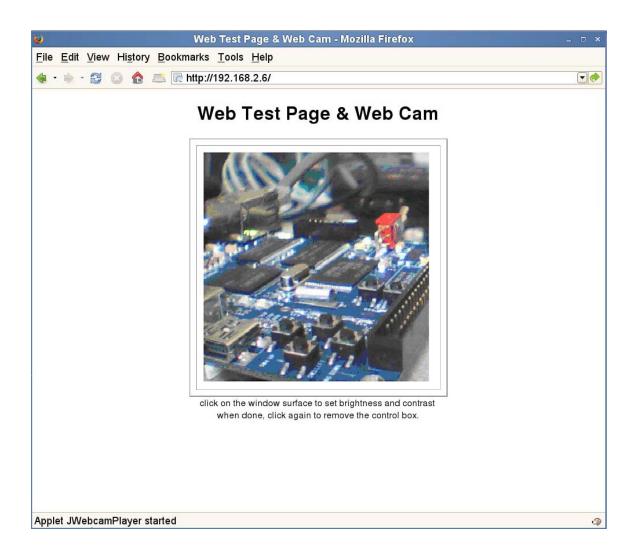
servfox version: 1.1.2 date: 07:10:2005 (C) mxhaard@magic.fr

VIDIOCSWIN failed : Invalid argument

Waiting for connection. CTrl c to stop !!!!

Open the web browser of your host PC.

Type 192.168.2.10 on the address field and press Enter, and install SUN JRE if prompted.



4.12 Surf the internet

Connect your systems as Figure 2.

#udhcpc &

udhcpc (v1.3.2) started
Sending discover...
Sending select for 192.168.2.10...
Lease of 192.168.2.10 obtained, lease time 7172
deleting routers
route: SIOC[ADD|DEL]RT: No such process
adding dns 202.106.46.151
adding dns 202.106.195.68

[1] + Done udhcpc

For some routers, this command may not work. If it does not work, edit /etc/init.d/rcS as below to set static ip address and gateway address:

. . .

#config network by manual work /sbin/ifconfig eth0 192.168.2.10 /sbin/route add default gw 192.168.2.1 #config network by udhcpc #/sbin/udhcpc &

. . .

Now you can surf the internet using Qtopia. If your Qtopia doesn't display your language, you can click the **Setting Tab**, and then change the default language.

5 Update bootloader, kernel or file system images

You may accidentally damage the bootloader image, kernel image or file system image when you do your development, or you may update those images with your own customized images. We have 3 developed commands of u-boot to make it easier – install-bootloader, install-kernel and install-filesystem. We also provide you with 3 ready-to-use images in case you need to restore your flash memory:

Bootloader image – u-boot.bin Kernel image – uImage File system image – filesystem.yaffs

Before you start to update, make sure the following have been done:

- TFTP server has been setup correctly on host PC as **3.2**.
- Host PC's IP address is the same as u-boot's TFTP server address. To set host PC's IP address, use "ifconfig" command. To set u-boot's TFTP server address, use "setenv serverip" command of u-boot.
- Copy bootloader image (u-boot.bin), kernel image (uImage), or file system image (filesystem.yaffs) to /tftpboot of host PC. If your images are not the same as the above, please rename them. In the provided CD, "***800x480" is for 7 inch LCD, "***480x272" is for 4.3 inch LCD.

5.1 Update bootloader

Power-on the target and some startup messages show up on the minicom terminal, press space key to enter u-boot command entry line.

#run install-bootloader

After it is finished, power-off the target.

5.2 Update kernel

Power-on the target and some startup messages show up on the minicom terminal, press space key to enter u-boot command entry line.

#run install-kernel

After it is finished, power-off the target.

5.3 Update file system

Power-on the target and some startup messages show up on the minicom terminal, press space key to enter u-boot command entry line.

#run install-filesystem

After it is finished, power-off the target.

5.4 How to make your own file system image

#cp mkyaffsimage to /usr/bin (mkyaffsimage is a Linux utility provided in CD) #chmod 755 /usr/bin/mkyaffsimage

Assume rootfs is the directory of your root file system on host PC #mkyaffsimage rootfs filesystem.yaffs

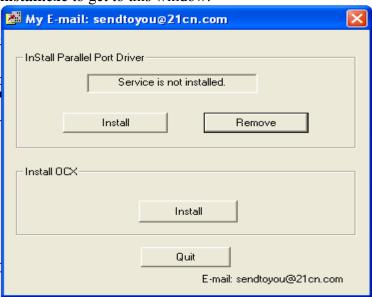
5.5 What to do if u-boot is corrupt or does not exist

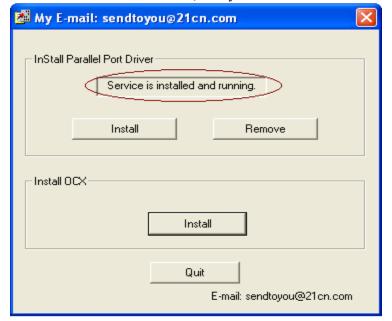
If your u-boot is somehow corrupt or your nand flash is blank, you can use the provided Windows utility to load u-boot into the nand flash.

The following steps are done on Windows PC.

5.5.1 Install GIVEIO driver

Find \Windows Utilities\GIVEIO driver directory on the provided CD, double click install.exe to get to this window.





Click those 2 **Install** buttons, and you will see the driver installed.

Click **Quit** button to close the window. Now GIVEIO driver is installed.

5.5.2 Make hardware connection

PC parallel port <-> Provided Parrallel Cable <-> Wiggler Board <-> 20 Lines JTAG Cable <-> JTAG connector of 2410(or 2440) board.

Power-on the board. It does not matter if the board is now running WinCE/Linux or not.

5.5.3 Load bootloader image into nand flash

Copy \Windows Utilities\sjf2440.exe on the provided CD to C:\.

Copy u-boot image, for example, u-boot.bin, to C:\.

Open Command Prompt by click Start->Programs->Accessories->Command Prompt, and then go to C:\ by typing: cd \

C:\>sjf2440.exe /f:u-boot.bin

Here comes the following window. You need to type "0" 3 times to complete the loading process. Normally it will take a few minutes.

```
C:\WINDOWS\system32\cmd.exe
      SEC JTAG FLASH(SJF) v 0.1
      ($3C2440X & $MDK2440 B/D)
                                      Н
Usage: SJF /f:<filename> /d=<delay>
 $3C2440X(ID=0x0032409d) is detected.
[SJF Main Menul
 0:K9S1208 prog
                    1:28F128J3A prog
                                       2:AM29LU800 Prog
                                                           3: Memory
 4:Exit
elect the function to test:0
[K9S1208 NAND Flash JTAG Programmer]
K9S1208 is detected. ID=0xec76
0:K9S1208 Program
                        1:K9S1208 Pr BlkPage
Select the function to test :0
[SMC(K9S1208U0M) NAND Flash Writing Program]
Source size:0h~238efh
Available target block number: 0~4095
Input target block number:0
target start block number
                              =0
                   <0x4000×n> =0x24000
target size
STATUS : Ερρορρορρορρορρορρορρορρορρορρορρορρ
Ερρορορορορορορορορορορορορορορορορο
Ερρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρ
Εրրրթրթրթրթրթրթրթրթրթրթրթրթրթ
Εրրթթթթթթթթթթթթթթթթթթթթթթթթթթթ
Ερρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρ
Ερρορρορορρορρορρορρορρορρορρορρορρ
Ερρρορορορορορορορορορορορορορορορορο
Ερρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρρ
0:K9S1208 Program 1:K9S1208 Pr BlkPage
                                                2:Exit
Select the function to test :_
```

After it is complete, power-off the board, unplug the JTAG cable, power-on it, and you will see the new bootloader is running. Now you can continue to upload the kernel and file system images as **5.2** and **5.3**.

5.6 A TFTP server on Windows XP – tftpd.exe

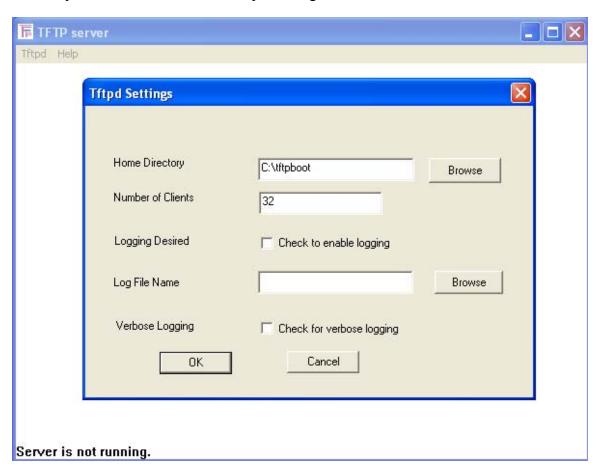
There is a TFTP server utility that can be running on Windows XP – tftpd.exe. It can also be used to update the kernel and file system. The steps are as below.

Make a directory folder, C:\tftpboot.

Copy "uImage" and "filesystem.yaffs" into C:\tftpboot.

Double-click "tftpd.exe" to start the application.

Click "Tftpd" -> "Configure'. Click "Browse" and select "C:\tftpboot" to be "Home Directory". Click "OK" to finish "Tftpd Settings".



Click "Tftpd" -> "Start" to start the TFTP server.

6 Develop your own application

This section tells you how to cross-compile the application – buttons on the host PC, transfer the application executable file to the target, and then run it.

6.1 Cross-compile application

On the host PC, create a directory – buttons that contains your application "buttons" source code – buttons.c.

#arm-linux-gcc -o buttons buttons.c

6.2 Copy your application to target by NFS

Assume that /your_dir is a directory exported by NFS. Please refer 3.3 for NFS server set-up.

On the host PC: #cp buttons /your dir

On the target minicom terminal: #mount –t nfs -o nolock 192.168.2.3:/your_dir /mnt #cp /mnt/buttons . #umount /mnt

Now the application, buttons, is in your current directory of the target.

6.3 Copy your application to target by TFTP

Assume that /tftpboot is a directory exported by TFTP. Please refer 3.2 for TFTP server set-up.

On the host PC: #cp buttons /tftpboot

On the target minicom terminal: #tftp –g -r buttons 192.168.2.3

Now the application, buttons, is in your current directory of the target.

6.4 Run application

On the target minicom terminal:

#./buttons

7 Mount a root file system on host PC

It is very useful during development stage if we are able to let booting kernel mount a root file system on host PC. We do not have to copy the intermit applications to nand flash for testing every time after they are cross-compiled on host PC. The cross-compiled applications only need to be copied to an exported directory, and the target kernel can mount it as if it is its own root directory.

The steps are detailed as below.

7.1 Create NFS mountable root file system on host PC

Create a directory on host PC, for example, /opt/rootfs.

Export the above directory as described in **3.3 Setup NFS server**.

Unzip nfs-filesystem.tar.gz to /opt/rootfs:

#tar -zxvf nfs-filesystem.tar.gz -C /opt/rootfs.

Edit /opt/rootfs/etc/init.d/rcS as below to set static ip address and gateway address:

. . .

#config network by manual work /sbin/ifconfig eth0 192.168.2.10 /sbin/route add default gw 192.168.2.1 #config network by udhcpc #/sbin/udhcpc &

• • •

Logoff and logon host PC

7.2 Edit u-boot environment variable – bootargs

Power on the target, and enter u-boot command line.

#setenv bootargs 'console=ttySAC0 root=/dev/nfs nfsroot=192.168.2.3:/opt/rootfs ip=192.168.2.10'

#saveenv

Reboot the target, and you will see some messages as:

. . .

Kernel command line: console=ttySAC0 root=/dev/nfs nfsroot=192.168.2.3:/opt/roo0

```
irq: clearing pending ext status 00000300
irq: clearing subpending status 00000002
...
IP-Config: Guessing netmask 255.255.255.0
IP-Config: Complete:
    device=eth0, addr=192.168.2.10, mask=255.255.255.0, gw=255.255.255.255, host=192.168.2.10, domain=, nis-domain=(none), bootserver=255.255.255.255, rootserver=192.168.2.3, rootpath=
Looking up port of RPC 100003/2 on 192.168.2.3
Looking up port of RPC 100005/1 on 192.168.2.3
VFS: Mounted root (nfs filesystem).
Freeing init memory: 176K
...
```

Now /opt/rootfs directory on host PC is your target's root file system.

8 Build kernel

The following steps are done at host PC.

"mkimage" is a utility to convert "zImage" to "uImage". "uImage" is a kernel image we need to write to NAND flash so that u-boot can load it and boot it.

#cp mkimage to /usr/bin
#chmod 755 /usr/bin/mkinage

```
Unzip the kernel source tree to a directory such as /opt: #tar -xjvf utu-linux2.6.***.tar.bz2 -C /opt #cd /opt/utu-linux2.6.***
```

To build your own kernel, you need to do kernel configuration. The kernel configuration file is ".config", a hidden file. To see this file, type console command "ls –a" instead of "ls".

To configure the kernel correctly, you need to have substantial knowledge of Linux and the architecture of your board, however, we provide some templates of configuration file ".config" as shown below. Please use one of them as your starting point.

```
arch
                     config_640x480_mouse include
                                                          net
block
                     confiq_640x480_ts
                                          init
                                                          README
config_240x320_mouse config_800x480_mouse ipc
                                          ipc REPORTING-
Kbuild samples
kernel scripts
lib security
                                                          REPORTING-BUGS
config_240x320_ts config_800x480_ts
config_320x240_mouse COPYING
config_320x240_ts CREDITS
                                           Пib
                                                          security
                                          MAINTAINERS
config_480x272_mouse crypto
                                                          sound
config_480x272_ts Documentation
                                           Makefile
                                                          usr
config_480x290_mouse drivers
                                           mmo
config_480x290_ts
                                           Module.symvers
```

If your LCD is 4.3 inch (480x272) and touch screen, config_480x272_ts is your template of ".config". Replace the hidden configuration file (.config) by config_480x272_ts: #cp config_480x272_ts .config

To compile kernel: #make uImage

If compiling succeeds, you will find "uImage" in directory /opt/ utu-linux2.6.***/arch/arm/boot.

The following are some detailed configuration selections.

8.1 Configure the kernel

#make menuconfig

```
.config - Linux Kernel v2.6.24.4 Configuration
                        Linux Kernel Configuration
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       General setup --->
       [*] Enable loadable module support --->
       [*] Enable the block layer --->
           System Type --->
Bus support --->
           Kernel Features --->
           Boot options --->
           Floating point emulation --->
           Userspace binary formats --->
           Power management options --->
                     <5elect>
                                 < Exit >
                                             < Help >
```

8.2 Configure CPU

At main menu, select **System Type**.

```
.config - Linux Kernel v2.6.24.4 Configuration
                                System Type
   Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       [ ] 53C2410 PM Suspend Memory CRC
       (0) 53C UART to use for low-level messages
           53C2400 Machines --->
           53C2410 Machines --->
           53C2412 Machines --->
       53C2440 Machines --->
           53C2442 Machines --->
           53C2443 Machines --->
           *** Processor Type ***
       [*] Support ARM920T processor
                     ⟨Select⟩
                                 < Exit >
                                             < Help >
```

```
S3C2440 Machines

Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉,
Highlighted letters are hotkeys. Pressing 〈Y〉 includes, 〈N〉 excludes,
〈M〉 modularizes features. Press 〈Esc〉〈Esc〉 to exit, 〈?〉 for Help, 〈/〉
for Search. Legend: [*] built-in [] excluded 〈M〉 module 〈〉

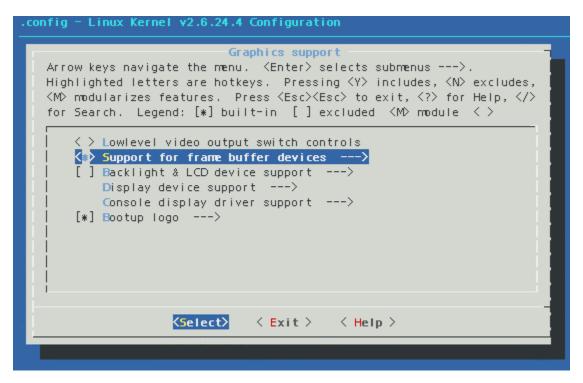
[] Simtec Electronics ANUBIS
[] Simtec IM2440D20 (OSIRIS) module
[] HP iPAQ rx3715
[] SMDK2440
[] UTU2440
[] [] NexVision NEXCODER 2440 Light Board

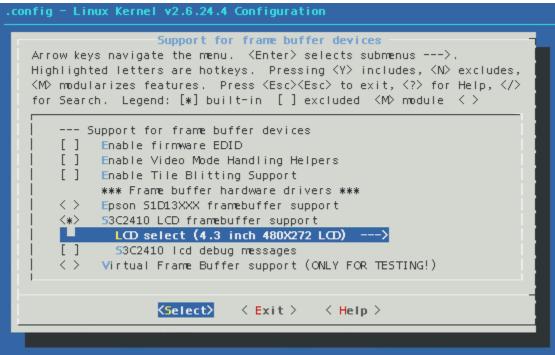
| Select〉 〈 Exit〉 〈 Help〉
```

8.3 Configure LCD

At main menu, select Device Drivers.

```
Device Drivers
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    -(-)-
    [*] Watchdog Timer Support --->
       Sonics Silicon Backplane --->
       L3 serial bus support --->
       Multifunction device drivers --->
       Multimedia devices --->
      Graphics support --->
       5ound --->
    [*] HID Devices --->
    [*] USB support --->
    <*> MMC/SD card support --->
                  <5elect>
                             < Exit >
                                         < Help >
```





8.4 Configure touch screen

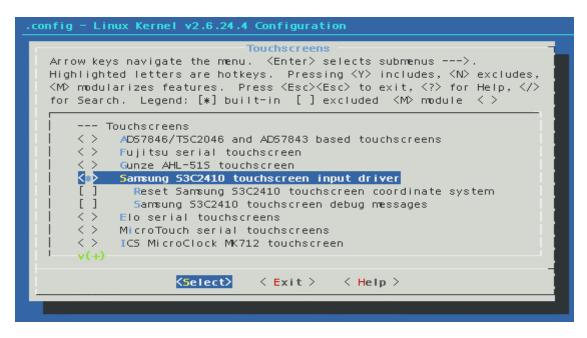
At main menu, select **Device Drivers** -> **Input device support**.

```
Input device support
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
⟨M⟩ modularizes features. Press ⟨Esc⟩⟨Esc⟩ to exit, ⟨?⟩ for Help, ⟨/⟩
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    ^(-)-
   (1024) Horizontal screen resolution
   (768)

    Vertical screen resolution

         Joystick interface
    <○> Touchscreen interface
    (1024) Horizontal screen resolution
    (768) Vertical screen resolution
    <*> Event interface
    <*> Event debugging
         *** Input Device Drivers ***
    [*]
         Keyboards --->
                  <5elect>
                             < Exit >
                                         < Help >
```

```
Input device support
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    -(-)-
   <*> Event interface
   <*> Event debugging
         *** Input Device Drivers ***
    [*]
        Keyboards --->
         Mice --->
    Γ 1
    [ ]
         Joysticks/Gamepads --->
          Tablets --->
        Touchscreens --->
    []
         Miscellaneous devices --->
       Hardware I/O ports --->
                 <5elect>
                             < Exit >
                                         < Help >
```

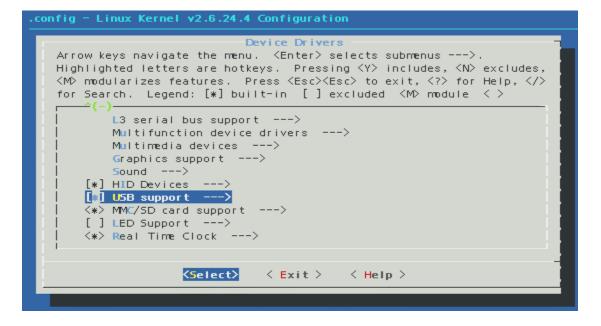


"Reset Samsung S3C2410 touchscreen coordinate system" can set the coordinate up and down. If your touch screen is responded, but the calibration never succeeds, select it.

8.5 Configure USB mouse

Right now, USB mouse can't work with touch screen at the same time, and the USB mouse hotplug does not work, that means USB mouse needs to be connected before the system boots up.

At main menu, select **Device Drivers** -> **USB support**.



```
USB support
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    --- USB support
    Support for Host-side USB
           USB verbose debug messages
           *** Miscellaneous USB options ***
    [*]
        USB device filesystem
    [ ]

    USB device class-devices (DEPRECATED)

          *** USB Host Controller Drivers ***
    ISP116X HCD support
    <*> OHCI HCD support
    \langle \ \rangle
         5L811HS HCD support
                  <5elect>
                             < Exit > < Help >
```

At main menu, select **Device Drivers** -> **HID Devices**.

```
.config - Linux Kernel v2.6.24.4 Configuration
                             Device Drivers
   Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       [*] Watchdog Timer Support --->
          Sonics Silicon Backplane --->
           L3 serial bus support --->
           Multifunction device drivers --->
           Multimedia devices --->
           Graphics support --->
           5ound --->
       [a] HID Devices --->
       [*] USB support --->
       <*> MMC/SD card support --->
                     <5elect>
                                < Exit >
                                            < Help >
```

```
HID Devices
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    --- HID Devices
    <*>
         Generic HID support
    [*]
           HID debugging support
    [*]
           /dev/hidraw raw HID device support
         *** USB Input Devices ***
        USB Human Interface Device (full HID) support
         USB HID Boot Protocol drivers --->
                  <5elect≻
                             < Exit >
                                         < Help >
```

8.6 Configure USB drive support

At main menu, select **Device Drivers** -> **SCSI device support.**

```
Device Drivers
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    ^(-)·
    [ ] Misc devices --->
   < > ATA/ATAPI/MFM/RLL support
   5CSI device support --->
   < > Serial ATA (prod) and Parallel ATA (experimental) drivers --
    [ ] Multiple devices driver support (RAID and LVM) --->
    [*] Network device support --->
    < > ISDN support --->
        Input device support --->
       Character devices --->
   <*> I2C support --->
                  <5elect>
                             < Exit >
                                         < Help >
```

```
SCSI device support
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    < > RAID Transport Class
    <∗> SCSI device support
    []] legacy /proc/scsi/ support
       *** SCSI support type (disk, tape, CD-ROM) ***
   <∗> SCSI disk support
   < > 5CSI tape support
   SCSI OnStream SC-x0 tape support
   SCSI CDROM support
   <*> SCSI generic support
   SCSI media changer support
                 <5elect>
                             < Exit > < Help >
```

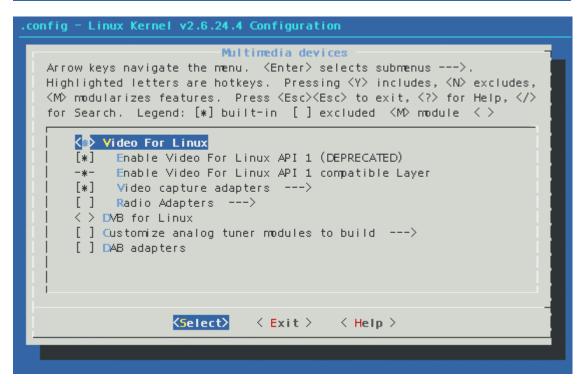
At main menu, select **Device Drivers** -> **USB support**.

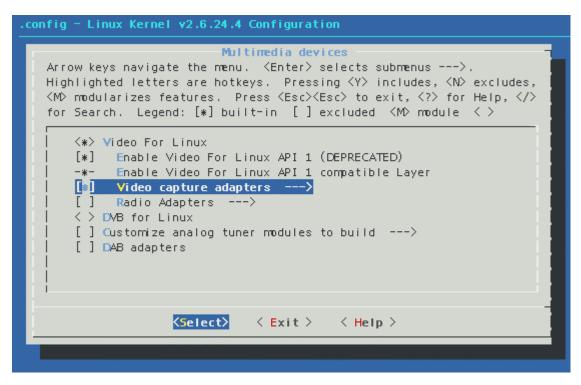
```
USB support
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
⟨M⟩ modularizes features. Press ⟨Esc⟩⟨Esc⟩ to exit, ⟨?⟩ for Help, ⟨/⟩
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    -(-)-
    \langle \ \rangle
         USB Modem (CDC ACM) support
    <>
         USB Printer support
          *** NOTE: USB_STORAGE enables SCSI, and 'SCSI disk support'
          *** may also be needed; see USB_STORAGE Help for more infor
        USB Mass Storage support
    [*]
           USB Mass Storage verbose debug
    [ ]
           Freecom USB/ATAPI Bridge support
    [ ]
           ISD-200 USB/ATA Bridge support
    [ ]
            Microtech/ZiO! CompactFlash/SmartMedia support
    [ ]
            Support for Rio Karma music player
                  <5e1ect≻
                              < Exit >
                                          < Help >
```

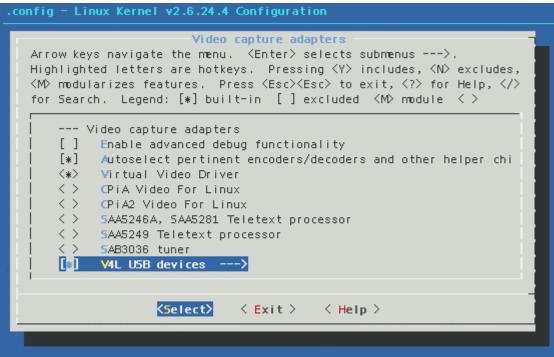
8.7 Configure USB camera

At main menu, select Device Drivers-> Multimedia devices.

```
.config - Linux Kernel v2.6.24.4 Configuration
                             Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       ^(-)-
           Sonics Silicon Backplane --->
          L3 serial bus support --->
          Multifunction device drivers --->
       Multimedia devices --->
           Graphics support --->
           Sound --->
       [*] HID Devices --->
       [*] USB support --->
       <*> MMC/SD card support --->
       [ ] LED Support --->
                     <5elect>
                                < Exit >
                                            < Help >
```







```
V4L USB devices
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
         OmniVision Camera Chip support
    USB SPCA5XX Sunplus/Vimicro/Sonix jpeg Cameras
        USB W896[87]CF JPEG Dual Mode Camera support
         USB OV511 Camera support
   < >
         USB SE401 Camera support
         USB SN9C1xx PC Camera Controller support
    < >

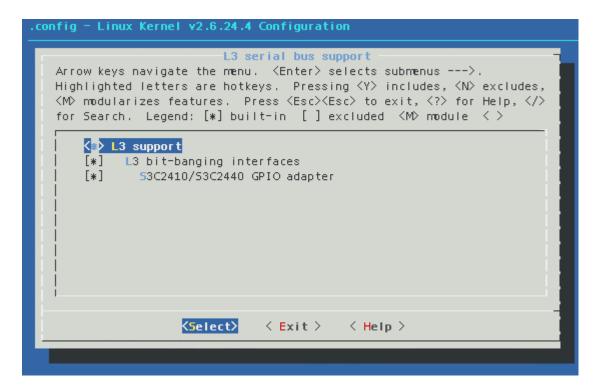
    USB STV680 (Pencam) Camera support

        USB ZC0301[P] Image Processor and Control Chip support
   USB Philips Cameras
    < >
        USB ZR364XX Camera support
                  <5elect>
                             < Exit >
                                        < Help >
```

8.8 Configure sound

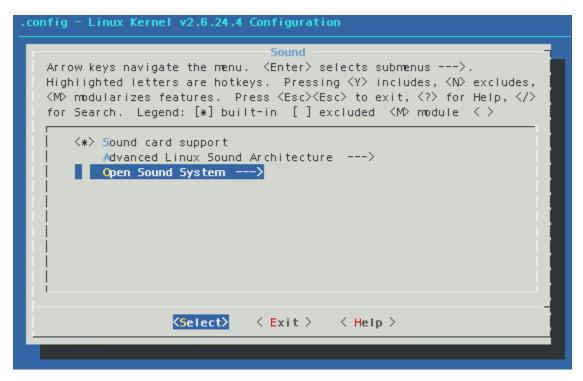
At main menu, select **Device Drivers->** L3 serial bus support.

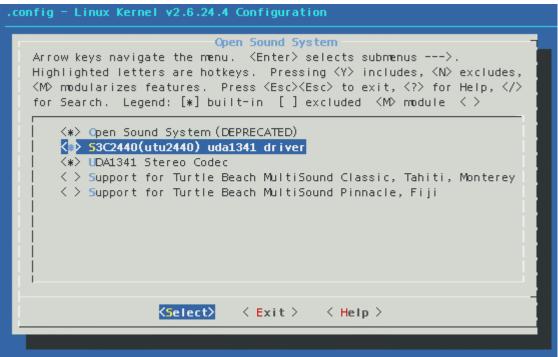
```
.config - Linux Kernel v2.6.24.4 Configuration
                              Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       ^(-)·
           Character devices --->
       <*> I2C support --->
          SPI support --->
       < > Dallas's 1-wire support --->
       Power supply class support --->
       < > Hardware Monitoring support --->
       [*] Watchdog Timer Support --->
           Sonics Silicon Backplane --->
       L3 serial bus support --->
           Multifunction device drivers --->
                     <5elect>
                                < Exit >
                                            < Help >
```



At main menu, select **Device Drivers-> Sound.**

```
.config - Linux Kernel v2.6.24.4 Configuration
                             Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       < > Hardware Monitoring support --->
       [*] Watchdog Timer Support --->
          Sonics Silicon Backplane --->
          L3 serial bus support --->
           Multifunction device drivers --->
           Multimedia devices --->
           Graphics support --->
       Sound --->
       [*] HID Devices --->
       [*] USB support --->
                     <Select>
                                〈 Exit 〉
                                            < Help >
```

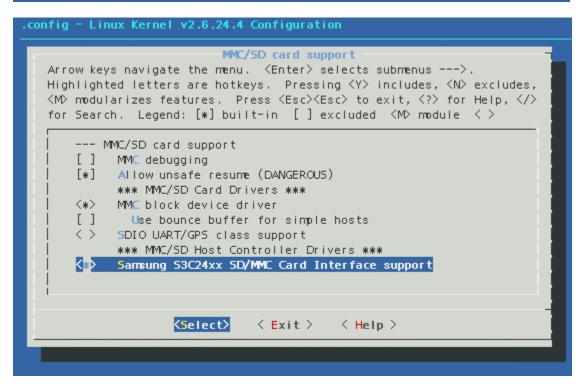




8.9 Configure SD/MMC

At main menu, select **Device Drivers-> MMC/SD Card support.**

```
Device Drivers
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    -(−)-
       L3 serial bus support --->
       Multifunction device drivers --->
       Multimedia devices --->
       Graphics support --->
       Sound --->
    [*] HID Devices --->
    [*] <u>USB</u> support --->
    ★ MMC/SD card support --->
    [ ] LED Support --->
    <*> Real Time Clock --->
                  <5elect≻
                              < Exit >
                                          < Help >
```



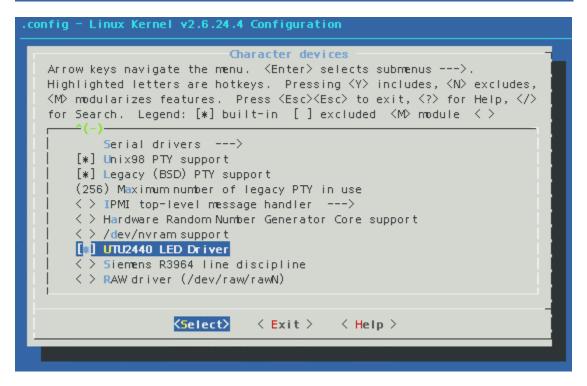
8.10 Configure LED

At main menu, select Device Drivers->Character devices.

```
Device Drivers
Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
    -(-)-

    ATA/ATAPI/MFM/RLL support --->

       SCSI device support --->
   Serial ATA (prod) and Parallel ATA (experimental) drivers
    [ ] Multiple devices driver support (RAID and LVM) --->
    [*] Network device support --->
    < > ISDN support --->
        Input device support --->
    Character devices --->
    <*> I2C support --->
       SPI support --->
                 <Select>
                             く Exit >
                                         < Help >
```



8.11 Configure serial ports

At main menu, select Device Drivers -> Character devices -> Serial drivers.

```
Serial drivers

Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉.
Highlighted letters are hotkeys. Pressing 〈Y〉 includes, 〈N〉 excludes,
〈M〉 modularizes features. Press 〈Esc〉〈Esc〉 to exit, 〈?〉 for Help, 〈/〉
for Search. Legend: [*] built-in [ ] excluded 〈M〉 module 〈〉

〈 〉 8250/16550 and compatible serial support

**** Non-8250 serial port support ***

〈 〉 Sansung 53C2410/53C2440/53C2442/53C2412 Serial port support

[*] Support for console on S3C2410 serial port

《Select》 〈 Exit 〉 〈 Help 〉
```

8.12 Configure RTC

At main menu, select Device Drivers->Real Time Clock.

```
config - Linux Kernel v2.6.24.4 Configuration
                             Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
  Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
  ⟨M⟩ modularizes features. Press ⟨Esc⟩⟨Esc⟩ to exit, ⟨?⟩ for Help, ⟨/⟩
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
          L3 serial bus support --->
          Multifunction device drivers --->
          Multimedia devices --->
          Graphics support --->
          Sound --->
       [*] HID Devices --->
       [*] USB support --->
       <*> MMC/SD card support --->
       [ ] LED Support --->
       <⊪ Real Time Clock –
                    <5elect>
                                < Exit >
                                            < Help >
```

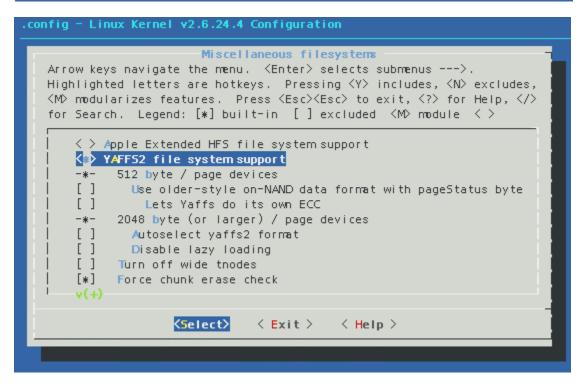
```
Real Time Clock
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
          *** Platform RTC drivers ***
         PC-style 'CMO5'
         Dallas DS1553
         Simtek STK17TA8
         Dallas D51742/1743
         5T M48T86/Dallas D512887
         5T M48T59
         EM Microelectronic V3020
          *** on-CPU RTC drivers ***
          Samsung 53C series 5oC RTC
                  <5elect>
                              < Exit >
                                          < Help >
```

8.13 Configure yaffs file system support

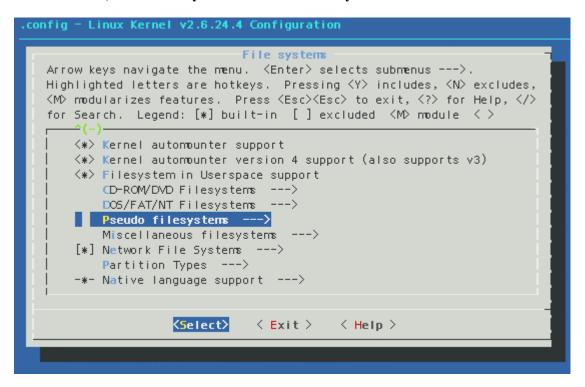
At main menu, select File Systems -> Miscellaneous filesystems.

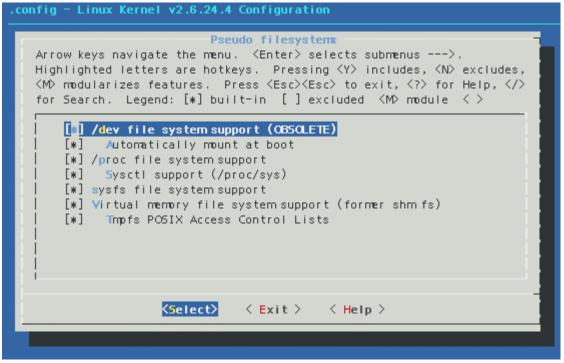
```
.config - Linux Kernel v2.6.24.4 Configuration
                        Linux Kernel Configuration
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>
   for Search. Legend: [*] built-in [ ] excluded 〈M〉 module 〈 〉
           Device Drivers --->
          File systems --->
       [ ] Instrumentation Support --->
           Kernel hacking --->
           Security options --->
       [ ] Cryptographic API --->
           Library routines --->
           Load an Alternate Configuration File
           Save an Alternate Configuration File
                     くSelect〉
                                 < Exit >
                                             < Help >
```

```
File systems
Arrow keys navigate the menu. 〈Enter〉 selects submenus ---〉.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
   -(-)-
   [ ] Dnotify support
   <*> Kernel automounter support
   Kernel automounter version 4 support (also supports v3)
   <*> Filesystem in Userspace support
       CD-ROM/DVD Filesystems --->
       DOS/FAT/NT Filesystems --->
       Pseudo filesystems --->
   Miscellaneous filesystems --->
    [*] Network File Systems --->
       Partition Types --->
                 <5elect>
                          < Exit > < Help >
```



At main menu, select File Systems -> Pseudo filesystems.

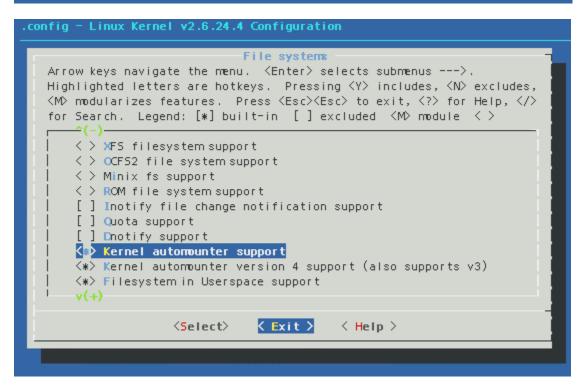




8.14 Configure EXT2/VFAT/ NFS file system support

At main menu, select File Systems.

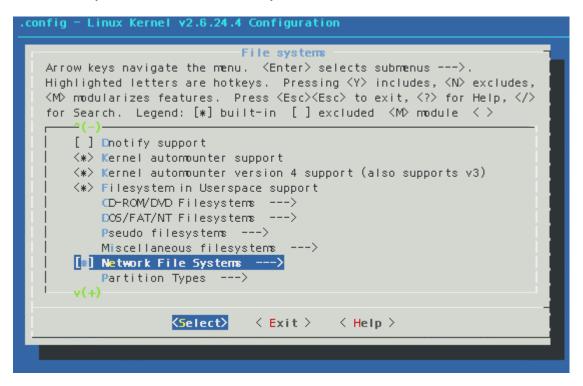
```
.config - Linux Kernel v2.6.24.4 Configuration
                               File systems
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       <*> Second extended fs support
       Ext2 extended attributes
             Ext2 POSIX Access Control Lists
              Ext2 Security Labels
       [ ] Ext2 execute in place support
       <*> Ext3 journalling file system support
       [*] Ext3 extended attributes
            Ext3 POSIX Access Control Lists
Ext3 Security Labels
       [ ]
       Reiserfs support
                      <Select>
                                  K Exit >
                                             < Help >
```



Select File Systems -> DOS/FAT/NT Filesystems.

```
.config - Linux Kernel v2.6.24.4 Configuration
                           DO5/FAT/NT Filesystems
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing \langle Y \rangle includes, \langle N \rangle excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded 〈M〉 module 〈 〉
       K M5DO5 fs support
       <∗> ∀FAT (Windows-95) fs support
       (437) Default codepage for FAT
       (iso8859-1) Default iocharset for FAT
       <*> NTFS file system support
       [ ] NTFS debugging support
       [*] NTFS write support
                      <5elect>
                                  < Exit >
                                              < Help >
```

Select File Systems -> Network File Systems.

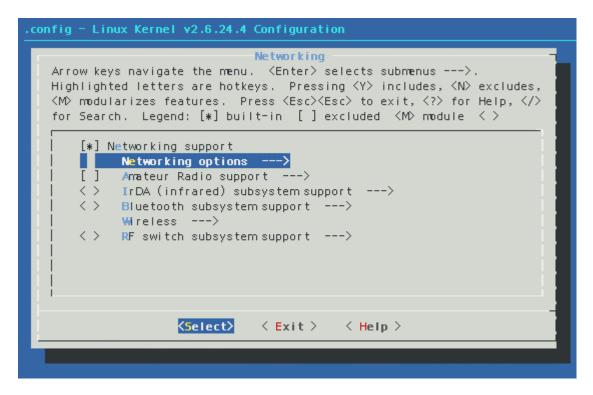


```
Linux Kernel v2.6.24.4 Configuration
                       Network File Systems
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes,
<M> modularizes features. Press <Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module
    --- Network File Systems
   <*> NFS file system support
        Provide NFSv3 client support
    [*]
    [*]
            Provide client support for the NFSv3 ACL protocol exten
          Allow direct I/O on NFS files
    []
        NFS server support
   < >
   [ ] Root file system on NFS
        SMB file system support (to mount Windows shares etc.)
    < >
       CIFS support (advanced network filesystem for Samba, Window
    < >
         NCP file system support (to mount NetWare volumes)
                 <Select>
                             < Exit >
                                        < Help >
```

8.15 Configure network

At main menu, select **Networking -> Networking support.**

```
Linux Kernel Configuration
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
<M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
for Search. Legend: [*] built-in [ ] excluded <M> module < >
   -^(-)-
       Kernel Features --->
       Boot options --->
       Floating point emulation --->
       Userspace binary formats --->
       Power management options --->
    Networking --->
        Device Drivers --->
       File systems --->
    [ ] Instrumentation Support --->
        Kernel hacking --->
                  <5elect>
                             < Exit >
                                         < Help >
```



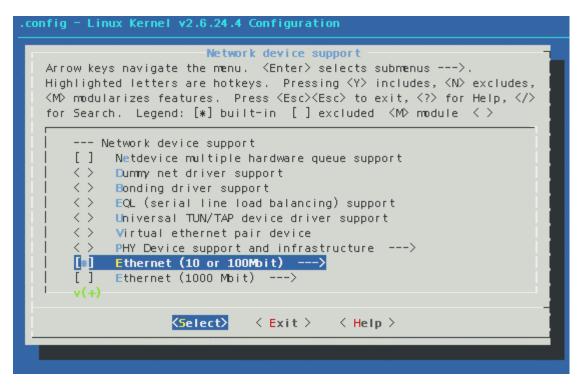
Select Networking options, and press Enter. Select some as below.

```
.config - Linux Kernel v2.6.24.4 Configuration
                            Networking options
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing ⟨Y⟩ includes, ⟨N⟩ excludes,
   <MD modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       <₽ Packet socket
       [ ] Packet socket: mmapped IO
       <*> Unix domain sockets
       < > PF_KEY sockets
       [*] TCP/IP networking
            IP: multicasting
       [ ]
            IP: advanced router
       [*]
            IP: kernel level autoconfiguration
             IP: DHCP support
       [*]
              IP: BOOTP support
                     K5elect>
                                 < Exit >
                                            < Help >
```

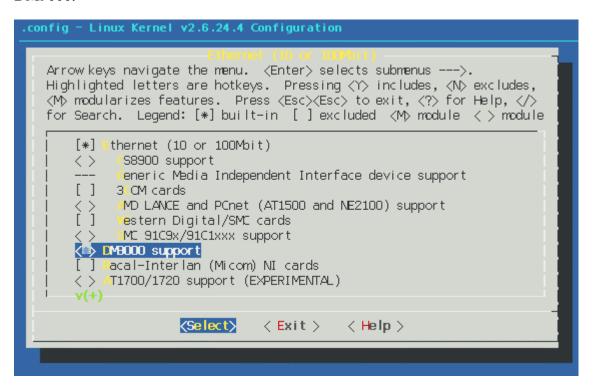
At main menu, select **Device Drivers** -> **Network device support.**

```
.config - Linux Kernel v2.6.24.4 Configuration
                               Device Drivers
   Arrow keys navigate the menu. <Enter> selects submenus --->.
   Highlighted letters are hotkeys. Pressing \langle Y \rangle includes, \langle N \rangle excludes,
   <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </>>
   for Search. Legend: [*] built-in [ ] excluded <M> module < >
       Serial ATA (prod) and Parallel ATA (experimental) drivers
       [ ] Multiple devices driver support (RAID and LVM) --->
       Network device support --->
       < > ISDN support --->
           Input device support --->
           Character devices --->
       <*> I2C support --->
           5PI support --->
       < > Dallas's 1-wire support --->
       Power supply class support --->
                      <5elect>
                                 < Exit >
                                              < Help >
```

Select Ethernet (10 or 100Mbit), and press Enter.



Select **DM9000 support** if your main board is V4.1 or later whose network IC is DM9000.



9 Common u-boot Commands

Display commands' usage #help

Display environment variables #printenv

Set IP address #setenv ipaddr XXX.XXX.XXX

Set CMD_LINE (mount a nand flash root file system)
#setenv bootargs 'noinitrd root=/dev/mtdblock2 init=/linuxrc console=ttySAC0,115200'

Set IP address of TFTP server #setenv serverip 192.168.2.3

Save enviroment variables #saveenv

Restore the default environment variables #run erase-env

Check bad block #nand bad

Erase nand flash #nand scrub

10 Change logo

Assume you have a picture file - logo.png. (Use GIMP to convert it to png format first)

#pngtopnm logo.png > 1.pnm

#pnmquant 224 l.pnm > 2.pnm

#pnmtoplainpnm 2.pnm > 3.ppm

If your LCD size is 320*240, replace

/drivers/video/logo/logo_linux_320240_clut224.ppm with 3.ppm, re-compile the kernel, and copy the kernel image "uImage" to flash as described in 5.2. You will see your new logo the next time you boot the target.

11 Build Qtopia Core Opensource

Qtopia is a product of Trolltech, having rich toolkit, intuitive API and comprehensive documentation. It shares the same API as Qt. You can use Qt designder to design your GUI at your Linux desktop (like VB) and then cross-compile the same codes for running on the embedded Linux system. The Trolltech website is http://trolltech.com/. Qtopia is free for open source projects. If you want to use it to develop a commercial product and keep your application source codes private, you have to purchase some sort of licenses.

This board is pre-loaded with a Qtopia PDA edition, and its open source codes are provided in the CD. It is ready to use, and you will experience how powerful it is. However this version is old and will be replaced by Qtopia Phone edition.

Qtopia Core Open Source Edition 4.3.2 is a subset of the latest Qt. From the views of the developers, it is much simpler to configure, compile and program compared to the previous Qt embedded versions. If you have experiences of Qt embedded, now you will notice how simpler it is to get it run on the embedded Linux target. It is freely download at http://trolltech.com/developer/downloads/, and its detailed documentation is at http://doc.trolltech.com/4.3/index.html.

11.1 Download

Download qtopia-core-opensource-src-4.3.2.tar.gz from the above website to host PC directory such as /opt

#cd /opt

#tar zxvf qtopia-core-opensource-src-4.3.2.tar.gz

11.2 Configure

Assume you have installed cross-compiler as said in **3.4**.

#cd qtopia-core-opensource-src-4.3.2

#echo "yes"|./configure -embedded arm -no-stl -no-qt3support -no-nis -no-cups -no-iconv -no-qdbus -no-freetype -depths 4,8,16,32 -qt-mouse-linuxtp -little-endian

#gmake

#gmake install

Now the compiled results are in /usr/local/Trolltech/QtopiaCore-4.3.2-arm/. The size of this directory is about 120 MB, however you don't have to copy all of them to target. The

required directory is /usr/local/Trolltech/QtopiaCore-4.3.2-arm/lib. You **must** copy them to the **same** location of the target for use.

To trim down the size of Qtopia, please refer to Qtopia's documentation.

11.3 Copy to a root file system

Assume that you have a root file system /opt/rootfs on your host PC that is NFS exported.

#cd /opt

#rm -r rootfs/opt/* (delete old Qtopia if any)

#rm rootfs/bin/qtopia (delete old Qtopia if any)

#mkdir -p rootfs/usr/local/Trolltech/QtopiaCore-4.3.2-arm/lib

#cp -a /usr/local/Trolltech/QtopiaCore-4.3.2-arm/lib/* rootfs/usr/local/Trolltech/QtopiaCore-4.3.2-arm/lib

#cp -a /usr/local/Trolltech/QtopiaCore-4.3.2-arm/examples rootfs/usr/local/Trolltech/QtopiaCore-4.3.2-arm/

#cp -a /usr/local/Trolltech/QtopiaCore-4.3.2-arm/demos rootfs/usr/local/Trolltech/QtopiaCore-4.3.2-arm/

To copy the root file system to the nand flash of the target, please refer to 5.3.

11.4 Configure touchscreen

Edit /opt/rootfs/etc/profile, add the following 2 lines: QWS_MOUSE_PROTO="LinuxTP:/dev/h3600_tsraw" export QWS_MOUSE_PROTO

11.5 Run application

Boot your target so that it NFS-mounts a previously-prepared root file system on host PC - /opt/rootfs. Go to the examples and demos directories to run those applications.

For example, at the minicom terminal: #./analogclock –qws

Now analogolock is running, and touch screen is working.

12 Build Microwindows/Nano-X

The Nano-X Window System is another Open Source project aimed at bringing the features of modern graphical windowing environments to smaller devices and platforms. The Nano-X Window System was previously named Microwindows. Its website is http://www.microwindows.org/.

Compared to Qtopia, it has less documentations and functionalities. However it is licensed under the MPL, which means that it can be used with designs under non-disclosure, without having to release proprietary source code. If it meets your need and you want to keep your commercial products' source codes private without paying expensive license fees, it is a very good choice.

If you require some rich features and commercial support, you can go to seek help from http://embedded.centurysoftware.com/.

12.1 Install

```
#cp microwindows-full-0.91.tar.gz /opt
#cd /opt
#tar xvfz microwindows-full-0.91.tar.gz
```

12.2 Build and install binaries

#cd microwindows-0.91/src

```
Manually modify microwindows-0.91/src/config as below:

ARCH = LINUX_ARM

ARMTOOLSPREFIX = arm-linux-

MICROWIN = N

NANOX = Y

SHAREDLIES - N
```

SHAREDLIBS = N MICROWINDEMO = N NANOXDEMO = Y NANOWM = N

HAVE_JPEG_SUPPORT = N HAVE_FNTGZ_SUPPORT = N HAVE_FREETYPE_SUPPORT = N HAVE_PCF_SUPPORT = N

 $HAVE_PCFGZ_SUPPORT = N$

X11 = N

IPAQMOUSE = Y (N for others) NOKBD = Y (N for others)

#make clean

#make

#make INSTALL PREFIX=/opt/rootfs install

The /opt/rootfs is where your root file system is. The default INSTALL_PREFIX=/usr if you don't specify it.

After the above is done, we have the following results:

/opt/rootfs /bin/nano-X (server)

/opt/rootfs /lib/*.a (libraries)

/opt/rootfs /include/microwin/*.h (header files, must be included when you compile your applications)

All programs are created in the bin directory. Now copy them to root file system. #cp –a bin /opt/rootfs/opt

12.3 Run demo applications

Boot your target board.

#cd /opt/rootfs

#nano-X &

#./ntetris &

#./nxcal -d nxcal.dat

12.4 Touch screen

The above "./nxcal -d nxcal.dat" is called touchscreen calibration. It actually loads calibration file – nxcal.dat. If the file does not exist, it will ask you to touch the LCD panel to do calibration, and then save this file for future use.

13 Build Busybox

#cp busybox-1.3.2.tar.gz /opt

#tar xvfz busybox-1.3.2.tar.gz

#cd busybox-1.3.2

#make menuconfig (if you want to modify some configuration)

#make ARCH=arm CROSS_COMPILE=arm-linux-

#make ARCH=arm CROSS COMPILE=arm-linux- install

Now busybox is installed in /opt/busybox-1.3.2/install