



Shading Clipping

Wolfgang Heidrich

Wolfgang Heidrich



Course News

Assignment 2

- Due Monday, Feb 28

Homework 3

- Discussed in labs this week

Homework 4

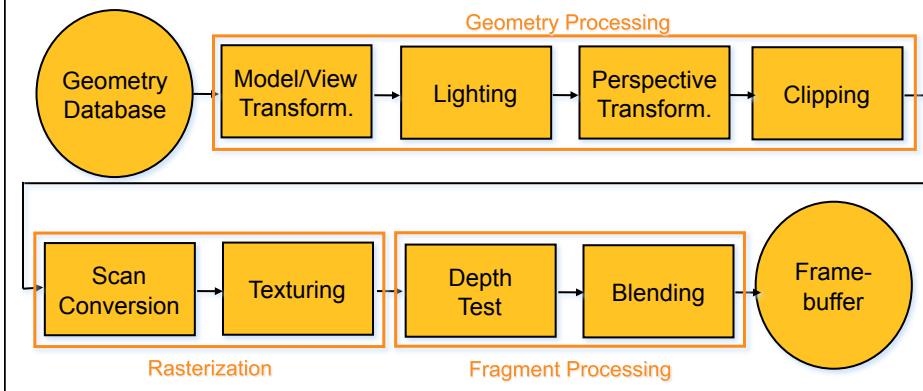
Reading

- Chapters 8, 9
- Hidden surface removal, shading

Wolfgang Heidrich



The Rendering Pipeline



Wolfgang Heidrich



Shading

Input to Scan Conversion:

- Vertices of triangles (lines, quadrilaterals...)
- Color (per vertex)
 - Specified with `glColor`
 - Or: computed with *lighting*
- World-space normal (per vertex)
 - Left over from *lighting* stage

Shading Task:

- Determine color of every pixel in the triangle

Wolfgang Heidrich



Shading

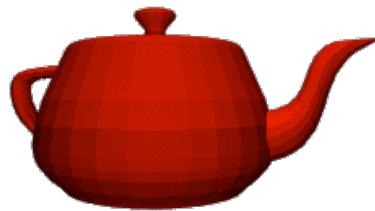
How can we assign pixel colors using this information?

- Easiest: flat shading
 - Whole triangle gets one color (color of 1st vertex)
- Better: Gouraud shading
 - Linearly interpolate color across triangle
- Even better:
 - Linearly interpolate the normal vector
 - Compute lighting for every pixel
 - Note: not supported by rendering pipeline as discussed so far

Wolfgang Heidrich

Flat Shading

- Simplest approach calculates illumination at a single point for each polygon



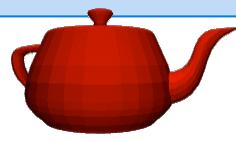
- Obviously inaccurate for smooth surfaces

Wolfgang Heidrich



Flat Shading Approximations

If an object really is faceted, is this accurate?



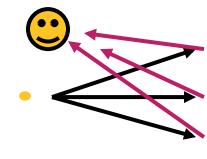
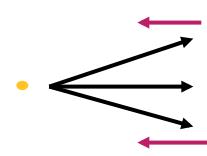
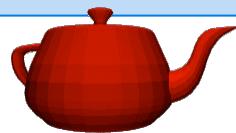
Wolfgang Heidrich

Flat Shading Approximations

If an object really is faceted, is this accurate?

no!

- For point sources, the direction to light varies across the facet
- For specular reflectance, direction to eye varies across the facet



Wolfgang Heidrich



Improving Flat Shading

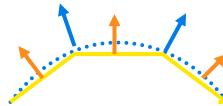
What if evaluate Phong lighting model at each pixel of the polygon?

- Better, but result still clearly faceted



For smoother-looking surfaces we introduce vertex normals at each vertex

- Usually different from facet normal
- Used **only** for shading
- Think of as a better approximation of the **real** surface that the polygons approximate



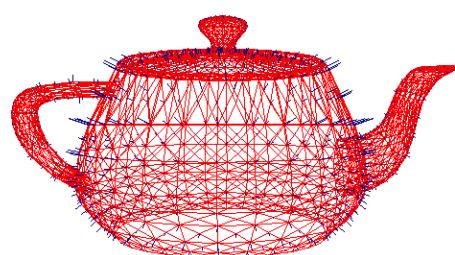
Wolfgang Heidrich



Vertex Normals

Vertex normals may be

- Provided with the model
- Computed from first principles
- Approximated by averaging the normals of the facets that share the vertex



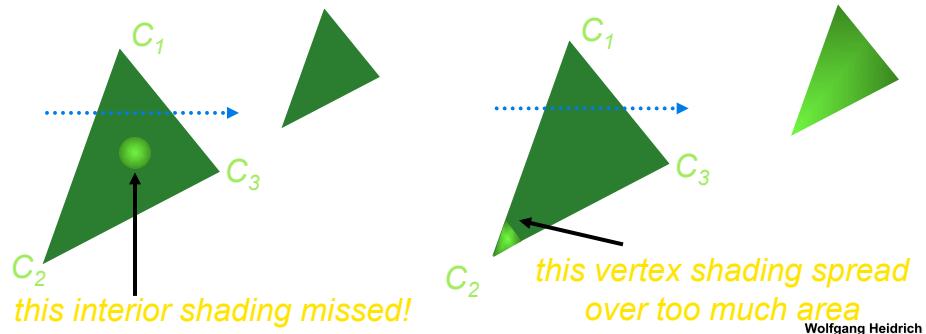
Wolfgang Heidrich



Gouraud Shading Artifacts

**often appears dull, chalky
lacks accurate specular component**

- if included, will be averaged over entire polygon



Gouraud Shading Artifacts

Mach bands

- Eye enhances discontinuity in first derivative
- Very disturbing, especially for highlights



Wolfgang Heidrich



Phong Shading

Linearly interpolating surface normal across the facet, applying Phong lighting model at every pixel

- Same input as Gouraud shading
- Pro: much smoother results
- Con: considerably more expensive



Not the same as Phong lighting

- Common confusion
- Phong lighting: empirical model to calculate illumination at a point on a surface

Wolfgang Heidrich

Phong Shading

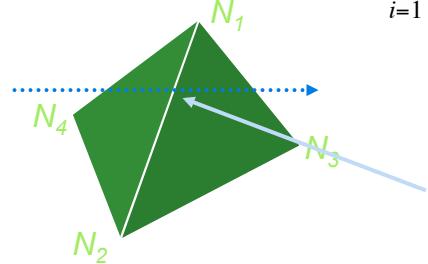


Linearly interpolate the vertex normals

- Compute lighting equations at each pixel
- Can use specular component

$$I_{total} = k_a I_{ambient} + \sum_{i=1}^{\#lights} I_i \left(k_d (\mathbf{n} \cdot \mathbf{l}_i) + k_s (\mathbf{v} \cdot \mathbf{r}_i)^{n_{shiny}} \right)$$

remember: normals used in diffuse and specular terms



discontinuity in normal's rate of change harder to detect

Wolfgang Heidrich



Phong Shading Difficulties

Computationally expensive

- Per-pixel vector normalization and lighting computation!
- Floating point operations required

Lighting after perspective projection

- Messes up the angles between vectors
- Have to keep eye-space vectors around

No direct support in standard rendering pipeline

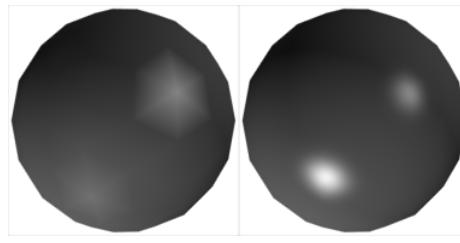
- But can be simulated with texture mapping, procedural shading hardware (see later)

Wolfgang Heidrich



Shading Artifacts: Silhouettes

Polygonal silhouettes remain



Wolfgang Heidrich



How to Interpolate?

Need to propagate vertex attributes to pixels

- Interpolate between vertices:
 - z (*depth*)
 - r,g,b *color components*
 - N_x, N_y, N_z *surface normals*
 - u,v *texture coordinates (talk about these later)*
- Three equivalent ways of viewing this (for triangles)
 1. *Linear interpolation*
 2. *Barycentric coordinates*
 3. *Plane Equation*

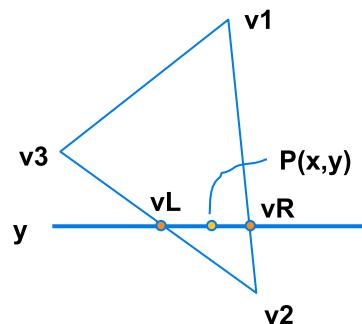
Wolfgang Heidrich



1. Linear Interpolation

Interpolate quantity along L and R edges

- (as a function of y)
- Then interpolate quantity as a function of x



Wolfgang Heidrich



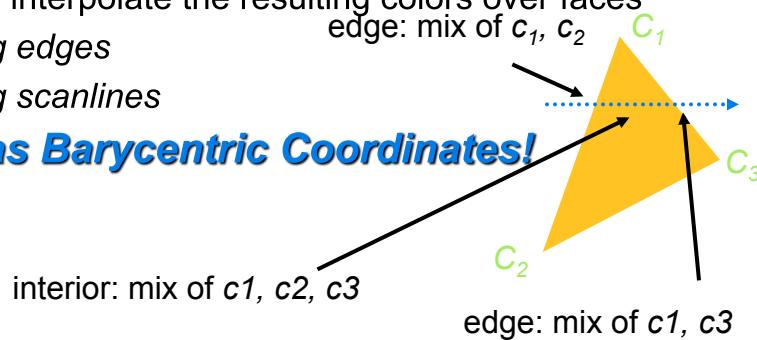
Linear Interpolation

Most common approach, and what OpenGL does

- Perform Phong lighting at the vertices

- Linearly interpolate the resulting colors over faces
 - Along edges
 - Along scanlines

Same as Barycentric Coordinates!



Wolfgang Heidrich

2. Barycentric Coordinates

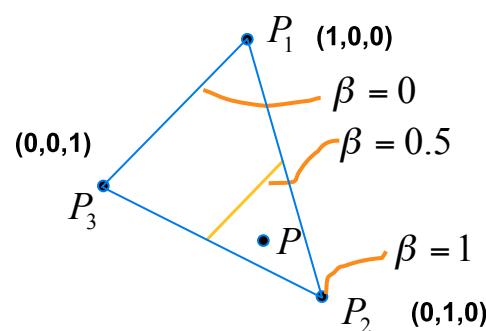
Have seen this before

- Barycentric Coordinates: weighted combination of vertices, with weights summing to 1

$$P = \alpha \cdot P_1 + \beta \cdot P_2 + \gamma \cdot P_3$$

$$\alpha + \beta + \gamma = 1$$

$$0 \leq \alpha, \beta, \gamma \leq 1$$



Wolfgang Heidrich



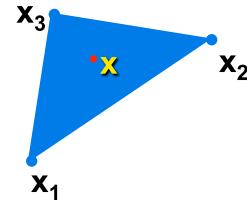
Barycentric Coordinates

- Convex combination of 3 points

$$\mathbf{x} = \alpha \cdot \mathbf{x}_1 + \beta \cdot \mathbf{x}_2 + \gamma \cdot \mathbf{x}_3$$

with $\alpha + \beta + \gamma = 1, 0 \leq \alpha, \beta, \gamma \leq 1$

- α, β , and γ are called barycentric coordinates



Wolfgang Heidrich

Barycentric Coordinates

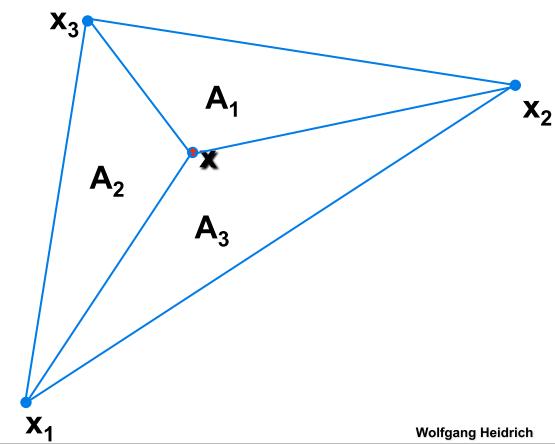
One way to compute them:

$$\mathbf{x} = \alpha \mathbf{x}_1 + \beta \mathbf{x}_2 + \gamma \mathbf{x}_3 \text{ with}$$

$$\alpha = A_1 / A$$

$$\beta = A_2 / A$$

$$\gamma = A_3 / A$$



Wolfgang Heidrich

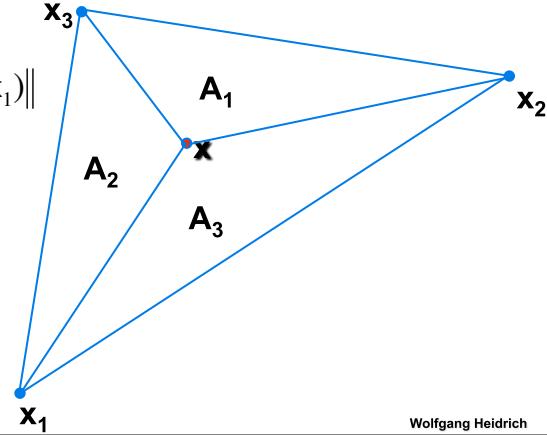


Barycentric Coordinates

How to compute areas?

- Cross products!
- e.g:

$$A_3 = \frac{1}{2} \|(\mathbf{x}_2 - \mathbf{x}_1) \times (\mathbf{x}_3 - \mathbf{x}_1)\|$$



Wolfgang Heidrich



3. Plane Equation

Observation: Quantities vary linearly across image plane

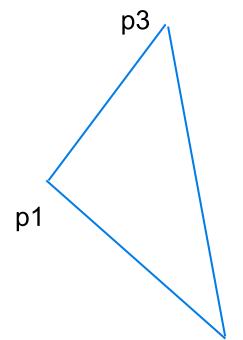
- E.g.: $r = Ax + By + C$
 - r = red channel of the color
 - Same for $g, b, Nx, Ny, Nz, z\dots$
- From info at vertices we know:

$$r_1 = Ax_1 + By_1 + C$$

$$r_2 = Ax_2 + By_2 + C$$

$$r_3 = Ax_3 + By_3 + C$$

- Solve for A, B, C
- One-time set-up cost per triangle and interpolated quantity



Wolfgang Heidrich



Discussion

Which algorithm to use when?

- Scanline interpolation
 - Together with trapezoid scan conversion
- Plane equations
 - Together with edge equation scan conversion
- Barycentric coordinates
 - Not useful in the current context
 - But: method of choice for ray-tracing
 - Whenever you only need to compute the value for a single pixel

Wolfgang Heidrich



Clipping

Wolfgang Heidrich

Wolfgang Heidrich



Line Clipping

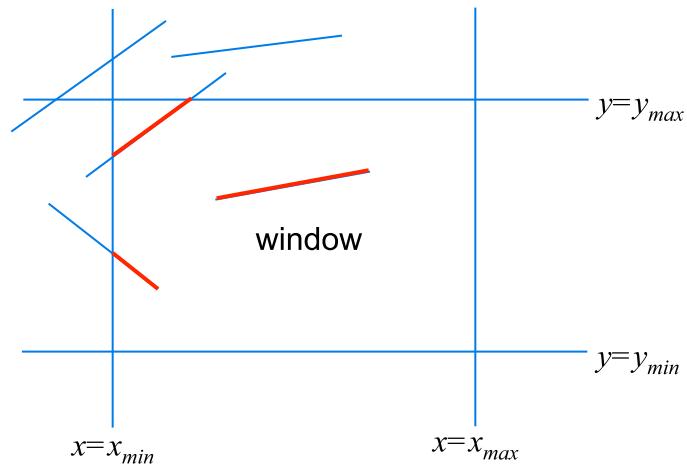
Purpose

- Originally: 2D
 - Determine portion of line inside an axis-aligned rectangle (screen or window)
- 3D
 - Determine portion of line inside axis-aligned parallelepiped (viewing frustum in NDC)
 - Simple extension to the 2D algorithms

Wolfgang Heidrich



Line Clipping



Wolfgang Heidrich



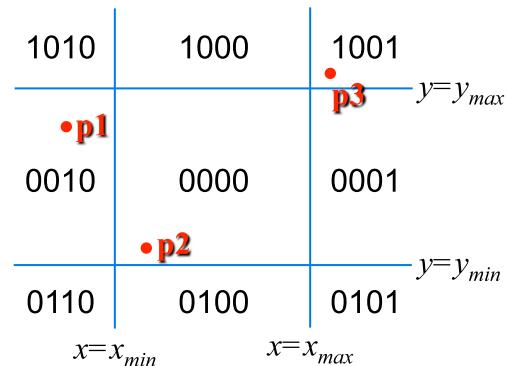
Line Clipping

Outcodes (Cohen, Sutherland '74)

- 4 flags encoding position of a point relative to top, bottom, left, and right boundary

- E.g.:

- $OC(p1)=0010$
- $OC(p2)=0000$
- $OC(p3)=1001$



Wolfgang Heidrich

Line Clipping



Line segment:

- $(p1, p2)$

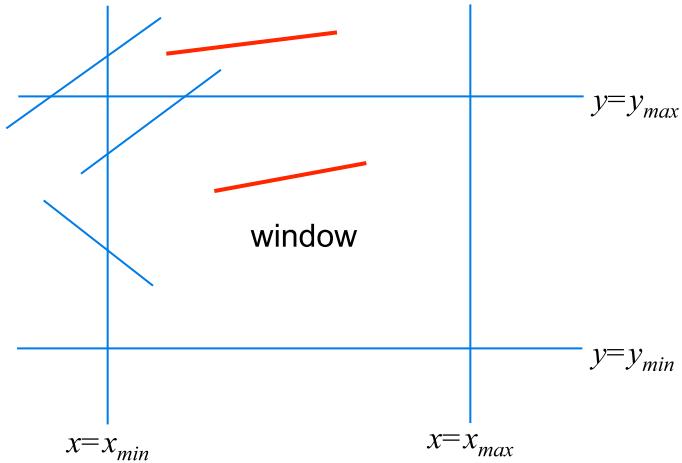
Trivial cases:

- $OC(p1) == 0 \ \&\& OC(p2) == 0$
 - Both points inside window, thus line segment completely visible (trivial accept)
- $(OC(p1) \ \&\& OC(p2)) != 0$ (i.e. **bitwise** “and”!)
 - There is (at least) one boundary for which both points are outside (same flag set in both outcodes)
 - Thus line segment completely outside window (trivial reject)

Wolfgang Heidrich



Line Clipping



Wolfgang Heidrich



Line Clipping

α -Clipping

- Handling of all the non-trivial cases
- Improvement of earlier algorithms (Cohen/Sutherland, Cyrus/Beck, Liang/Barsky)
- Define window-edge-coordinates of a point $\mathbf{p}=(x,y)^T$
 - $WEC_L(\mathbf{p})=x-x_{min}$
 - $WEC_R(\mathbf{p})=x_{max}-x$
 - $WEC_B(\mathbf{p})=y-y_{min}$
 - $WEC_T(\mathbf{p})=y_{max}-y$

Negative if outside!

Wolfgang Heidrich

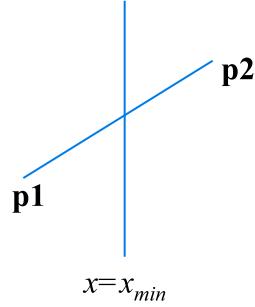


Line Clipping

α -Clipping

- Line segment defined as: $p1 + \alpha(p2-p1)$
- Intersection point with one of the borders (say, left):

$$\begin{aligned}x_1 + \alpha(x_2 - x_1) &= x_{min} \Leftrightarrow \\ \alpha &= \frac{x_{min} - x_1}{x_2 - x_1} \\ &= \frac{x_{min} - x_1}{(x_2 - x_{min}) - (x_1 - x_{min})} \\ &= \frac{\text{WEC}_L(x_1)}{\text{WEC}_L(x_1) - \text{WEC}_L(x_2)}\end{aligned}$$



Wolfgang Heidrich

Line Clipping



α -Clipping: algorithm

```
alphaClip( p1, p2, window ) {
```

Determine window-edge-coordinates of p1, p2

Determine outcodes OC(p1), OC(p2)

Handle trivial accept and reject

```
alpha1 = 0; // line parameter for first point
```

```
alpha2 = 1; // line parameter for second point
```

```
...
```

Wolfgang Heidrich



Line Clipping

α -Clipping: algorithm (cont.)

```
...
// now clip point p1 against all edges
if( OC(p1) & LEFT_FLAG ) {
     $\alpha = \text{WEC}_L(p1)/(\text{WEC}_L(p1) - \text{WEC}_L(p2));$ 
     $\alpha_1 = \max(\alpha_1, \alpha);$ 
}
```

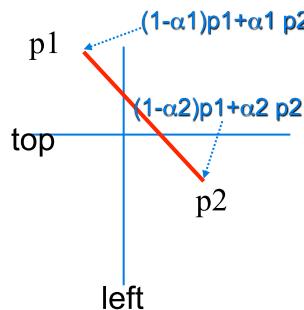
Similarly clip p1 against other edges

...

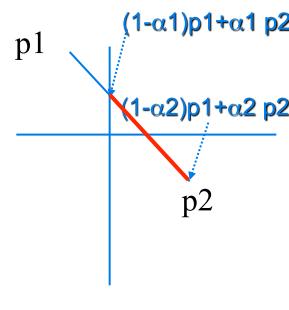
Wolfgang Heidrich

Line Clipping

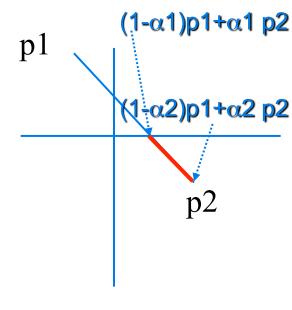
α -Clipping: example for clipping p1



Start configuration



After clipping to left



After clipping to top

Wolfgang Heidrich



Line Clipping

α-Clipping: algorithm (cont.)

```
...
// now clip point p2 against all edges
if( OC(p2) & LEFT_FLAG ) {
    α= WECL(p2)/(WECL(p1) - WECL(p2));
    α2= min(α2, α );
}
```

Similarly clip p1 against other edges

```
...
```

Wolfgang Heidrich

Line Clipping

α-Clipping: algorithm (cont.)

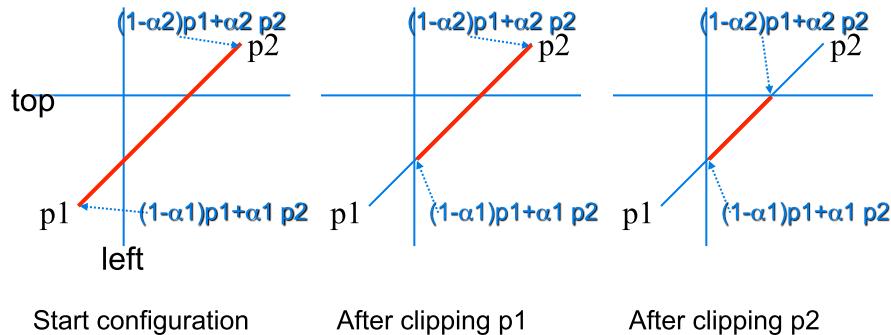
```
...
// wrap-up
if(α1 > α2 )
    no output;
else
    output line from p1+α1(p2-p1) to p1+α2(p2-p1)
} // end of algorithm
```

Wolfgang Heidrich



Line Clipping

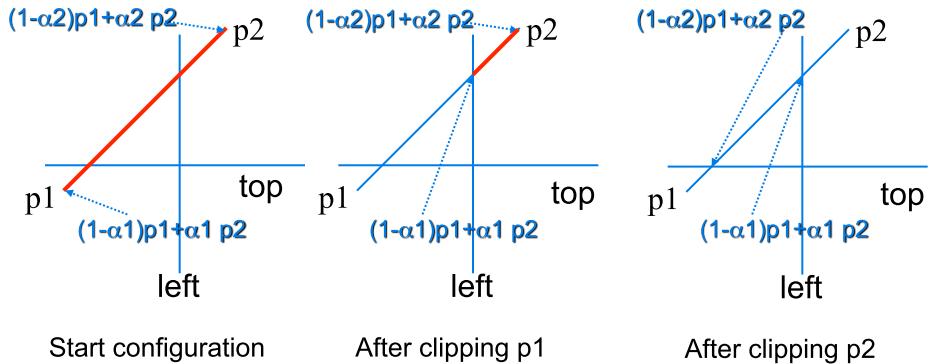
Example



Wolfgang Heidrich

Line Clipping

Another Example



Wolfgang Heidrich



Line Clipping in 3D

Approach:

- Clip against parallelepiped in NDC (*after* perspective transform)
- Means that the clipping volume is always the same!
 - OpenGL: $x_{min}=y_{min} = -1$, $x_{max}=y_{max} = 1$
- Boundary lines become boundary planes
 - *But outcodes and WECs still work the same way*
 - *Additional front and back clipping plane*
 - $z_{min}=0, z_{max}=1$ in OpenGL

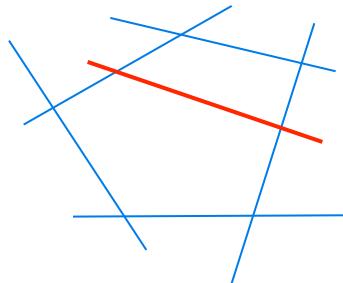
Wolfgang Heidrich



Line Clipping

Extensions

- Algorithm can be extended to clipping lines against
 - *Arbitrary convex polygons (2D)*
 - *Arbitrary convex polytopes (3D)*



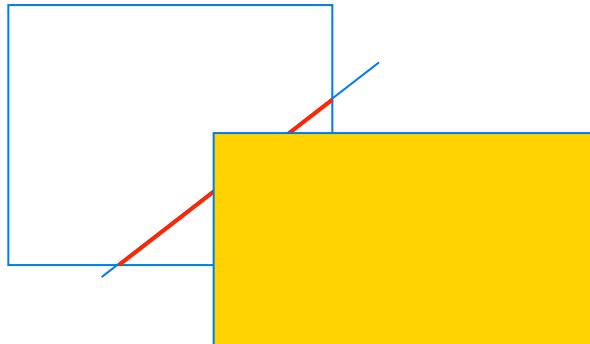
Wolfgang Heidrich



Line Clipping

Non-convex clipping regions

- E.g.: windows in a window system!



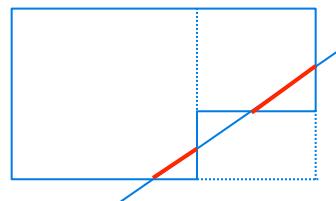
Wolfgang Heidrich



Line Clipping

Non-convex clipping regions

- Problem: arbitrary number of visible line segments
- Different approaches:
 - Break down polygon into convex parts
 - Scan convert for full window, and discard hidden pixels



Wolfgang Heidrich



Polygon Clipping

Objective

- 2D: clip polygon against rectangular window
 - Or general convex polygons
 - Extensions for non-convex or general polygons
- 3D: clip polygon against parallelepiped

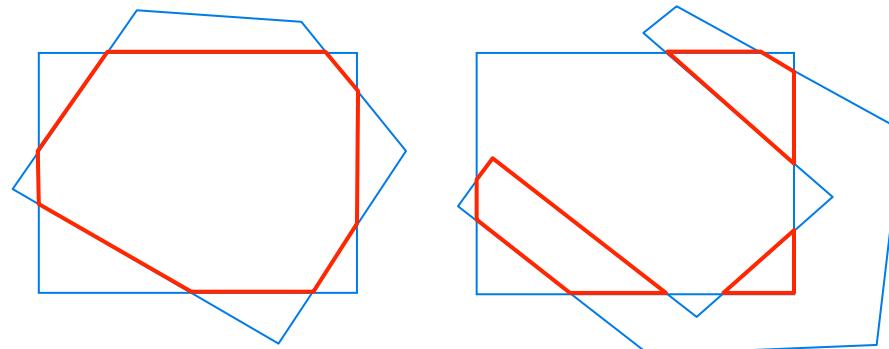
Wolfgang Heidrich

Polygon Clipping



Not just clipping all boundary lines

- May have to introduce new line segments



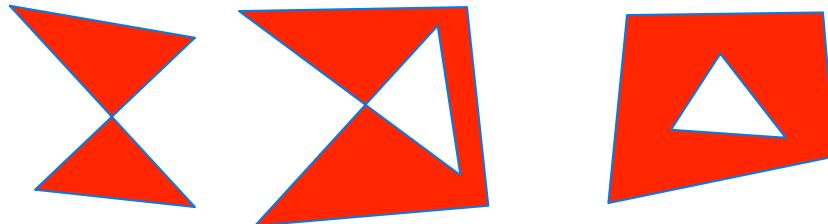
Wolfgang Heidrich



Polygon Clipping

Classes of Polygons

- Triangles
- Convex
- Concave
- Holes and self-intersection



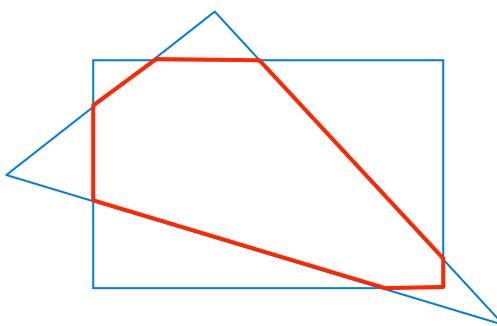
Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm ('74)

- Arbitrary convex or concave object polygon
 - Restriction to triangles does not simplify things
- Convex subject polygon (window)



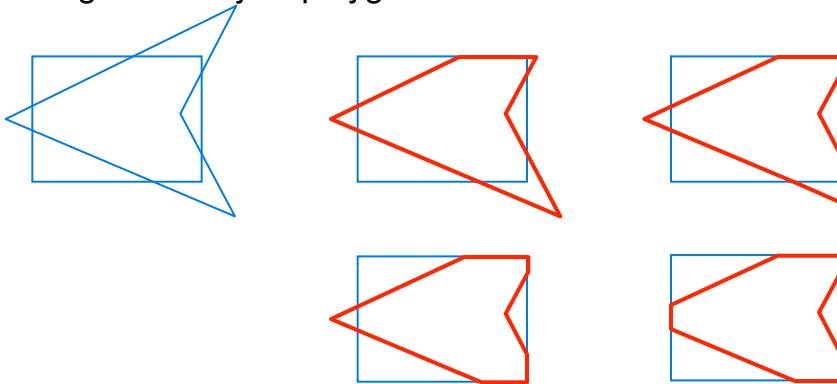
Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm ('74)

- Approach: clip object polygon independently against all edges of subject polygon



Wolfgang Heidrich



Polygon Clipping

Clipping against one edge:

```
clipPolygonToEdge( p[n], edge ) {  
    for( i= 0 ; i< n ; i++ ) {  
        if( p[i] inside edge ) {  
            if( p[i-1] inside edge ) // p[-1]= p[n-1]  
                output p[i];  
            else {  
                p= intersect( p[i-1], p[i], edge );  
                output p, p[i];  
            }  
        } else...  
    }  
}
```

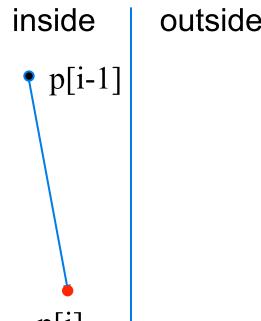
Wolfgang Heidrich



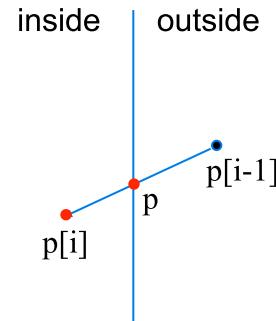
Polygon Clipping

Clipping against one edge (cont)

- $p[i]$ inside: 2 cases



Output: $p[i]$



Output: $p, p[i]$

Wolfgang Heidrich

Polygon Clipping

Clipping against one edge (cont)

```
...
else {           //  $p[i]$  is outside edge
    if(  $p[i-1]$  inside edge ) {
        p= intersect( $p[i-1]$ ,  $p[i]$ , edge );
        output p;
    }
} // end of algorithm
```

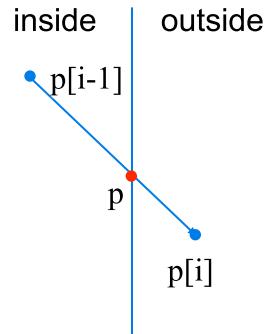
Wolfgang Heidrich



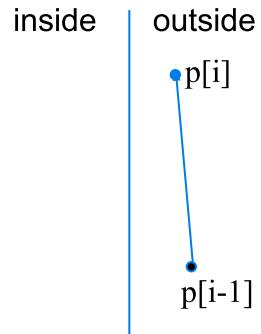
Polygon Clipping

Clipping against one edge (cont)

- $p[i]$ outside: 2 cases



Output: p

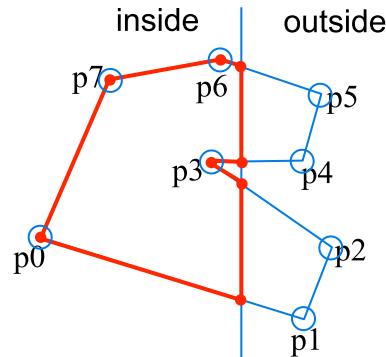


Output:nothing

Wolfgang Heidrich

Polygon Clipping

Example



Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm

- Inside/outside tests: outcodes
- Intersection of line segment with edge: window-edge coordinates
- Similar to Cohen/Sutherland algorithm for line clipping

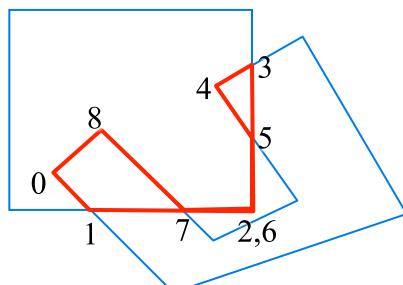
Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm

- Discussion:
 - Works for concave polygons
 - But generates degenerate cases



Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm

- Discussion:
 - Clipping against individual edges independent
 - Great for hardware (pipelining)
 - All vertices required in memory at the same time
 - Not so good, but unavoidable
 - Another reason for using triangles only in hardware rendering

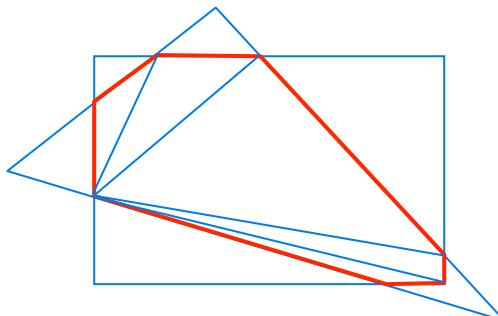
Wolfgang Heidrich



Polygon Clipping

Sutherland/Hodgeman Algorithm

- For Rendering Pipeline:
 - Re-triangulate resulting polygon
(can be done for every individual clipping edge)



Wolfgang Heidrich



Polygon Clipping

Other Polygon Clipping Algorithms

- Weiler/Aetherton '77:
 - Arbitrary concave polygons with holes both as subject and as object polygon
- Vatti '92:
 - Self intersection allowed as well
- ... many more
 - Improved handling of degenerate cases
 - But not often used in practice due to high complexity

Wolfgang Heidrich

Coming Up:



Friday

- More clipping, hidden surface removal

Wolfgang Heidrich