

8e. Barrier Functions

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INTRODUCTION

This section presents an approach to mitigating type instability based on the so-called **barrier functions**. These are defined as type-stable functions embedded within a type-unstable function, where variables having uncertain types are passed as arguments. By doing so, the compiler is prompted to infer a concrete type for the variables, effectively creating a "barrier" that prevents the spread of type instability to subsequent operations.

A key benefit of this approach is that **barrier functions are agnostic to the underlying cause of type instability, making them widely applicable.**

Warning! - Barrier Functions Should Be Considered as a Second Option

Typically, barrier functions should be reserved for situations where type instability is either difficult to fix or inherent to the operations performed. This is because the original function will still be type unstable, with different consequences depending on the instability nature. Considering this, it's best to aim for type-stable code from the outset, whenever possible.

APPLYING BARRIER FUNCTIONS

To illustrate the technique, let's revisit a type-unstable function from a previous section. This function defines a variable `y` based on `x`, and subsequently performs an operation involving `y`.

```
function foo(x)
    y = (x < 0) ? 0 : x

    [y * i for i in 1:100]
end

@code_warntype foo(1)          # type stable
@code_warntype foo(1.)        # type UNSTABLE
```

In the example, `0` is an `Int64`, whereas `x` could be either an `Int64` or `Float64`. When `x` is an `Int64`, `y` will also be an `Int64`, making `foo(1)` type stable. However, when `x` is a `Float64`, the compiler can't determine whether `y` will be an `Int64` or a `Float64`, rendering `foo(1.)` type unstable.

Addressing this type instability through a barrier functions requires embedding a type-stable function into `foo`, passing `y` as an argument. By doing so, the function will attempt to deduce `y`'s type, allowing the compiler to use this information for subsequent operations. The example below in particular defines `operation` as a barrier function.¹

```
operation(y) = [y * i for i in 1:100]

function foo(x)
    y = (x < 0) ? 0 : x

    operation(y)
end

@code_warntype operation(1)      # barrier function is type stable
@code_warntype operation(1.)    # barrier function is type stable

@code_warntype foo(1)           # type stable
@code_warntype foo(1.)         # barrier-function solution
```

With the introduction of the barrier function `operation`, the variable `y` in `foo(1.)` can still be either an `Int64` or a `Float64`. Nevertheless, this ambiguity no longer matters, as `operation(y)` will determine the type of `y` before the array comprehension is executed. As a result, the expression `[y * i for i in 1:100]` will be computed using a method specialized for the specific type of `y`, ensuring type stability.

Warning!

Barrier Functions should solve the type instability *before* the type unstable operation is executed. Otherwise, we're back to the original issue, where the compiler has to check `y`'s type at each iteration and select a method accordingly.

For example, `foo` in the example below doesn't apply correctly the barrier-function technique: `y` can be either `Float64` or `Int64`, and `operation(y,i)` only identifies the type inside the for-loop. This determines that the compiler is forced to check `y`'s type at each iteration of the loop, which is the original problem the barrier function was intended to solve.

```
operation(y,i) = y * i

function foo(x)
    y = (x < 0) ? 0 : x

    [operation(y,i) for i in 1:100]
end

@code_warntype foo(1)           # type stable
@code_warntype foo(1.)         # type UNSTABLE
```

REMARKS ON @CODE WARNTYPE

Functions introducing barrier functions hinder the interpretation of `@code_warntype`. This is because barrier functions typically mitigate type instability, rather than completely eliminating it. And even if the barrier function successfully eliminates the type instability, we could still receive a red warning.

To illustrate this, let's start presenting a scenario where the barrier function completely eliminates the type instability. Yet, a red warning shows up.

```
x = ["a", 1]                                     # variable with type 'Any'

function foo(x)
    y = x[2]

    [y * i for i in 1:100]
end
```

```
julia> @code_warntype foo(x)
```

```
x = ["a", 1]                                     # variable with type 'Any'

operation(y) = [y * i for i in 1:100]

function foo(x)
    y = x[2]

    operation(y)
end
```

```
julia> @code_warntype foo(x)
```

In this example, `y` is defined from an object with type `Vector{Any}`. This leads to a red warning, as `x[2]` has type `Any` and therefore the compiler can't infer a concrete type for `y`. However, no operation is involved at that point, as we're only performing an assignment. Since the only operation performed uses a barrier function, the lack of type information is inconsequential. Therefore, type instability is never impacting performance after introducing a barrier function.

In contrast, the example below demonstrates that a barrier function may only alleviate type instability, rather than eliminate it entirely. In this scenario, the operation `2 * x[2]` is type unstable, forcing the compiler to generate code for each possible concrete type of `x[2]`. Nonetheless, this operation has a negligible performance impact on `foo`, justifying why the barrier function only targets the more demanding operation.

```
x = ["a", 1] # variable with type 'Any'

function foo(x)
    y = 2 * x[2]

    [y * i for i in 1:100]
end
```

```
julia> @code_warntype foo(x)
```

```
x = ["a", 1] # variable with type 'Any'

operation(y) = [y * i for i in 1:100]

function foo(x)
    y = 2 * x[2]

    operation(y)
end
```

```
julia> @code_warntype foo(x)
```

```
x = ["a", 1] # variable with type 'Any'

operation(y) = [y * i for i in 1:100]

function foo(z)
    y = 2 * z

    operation(y)
end
```

```
julia> @code_warntype foo(x)
```

Notice that whether a barrier function is effective in solving performance issues ultimately depends on how the function is applied. In the given example, the barrier-function solution would be sufficient if `foo` is called only once. Instead, if `foo` is eventually called in a tight loop, the type instability of `2 * x[2]` would be incurred multiple times. In such cases, additionally addressing the type instability of `2 * x[2]` could lead to substantial performance benefits.

FOOTNOTES

¹ In this particular example, there's an easier solution for the type instability, where `0` is substituted with `zero(x)`. The function `zero(x)` has been designed to return the null element for the type identified of `x`.