

# 8g. Type Stability with Higher-Order Functions

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## INTRODUCTION

Functions in Julia are **first-class objects**, a concept also referred to as **first-class citizens**. This means that functions can be handled just like any other variable. In this way, we can define vectors of functions, have functions whose outputs are other functions, and do many more sophisticated things that would be impossible if functions were treated as a special case.

In particular, this property makes it possible to define **higher-order functions**, which are functions that take another function as an argument. Throughout the explanations, we'll refer to the function passed as an argument as the *callback function*.

We've already encountered several examples of higher-order functions, often in the form of anonymous functions passed as function arguments. A familiar example is `map(<function>, <collection>)`, which applies `<function>` to every element of `<collection>`.

In this section, the focus will be on conditions under which higher-order functions are type-stable. As we'll discover, these functions present some challenges in this regard.

## FUNCTIONS AS ARGUMENTS: THE ISSUE

In Julia, *each function defines its own unique concrete type*. In turn, this concrete type is a subtype of an abstract type called `Function`, which encompasses all possible functions defined in Julia. This type system creates challenges when specializing the computation method of higher-order functions, as it can potentially lead to a combinatorial explosion of methods, where a unique method is generated for each callback function.

To address this issue, Julia takes a conservative stance, **often choosing not to specialize the methods of high-order functions**. In particular, we'll see that Julia avoids specialization if the callback function isn't explicitly called. The performance in such cases can drop sharply, as the execution runtime would become similar to performing operations in the global scope.

Given this, it's important to pinpoint the scenarios where specialization is inhibited and monitor its consequences. If you notice that performance is severely impaired, there are still ways to enforce specialization. In the following section, we explore them.

## AN EXAMPLE OF NO SPECIALIZATION

Let's illustrate the conditions under which higher-order functions fail to specialize. Consider a scenario where we want to sum the transformed elements of a vector `x`. The only requirement we impose is that the transforming function should be generic, allowing us to possibly apply different functions for the transformation.

We implement this via a higher-order function `foo`. This function first uses `map` to transform `x` through some function `f`, and then applies the function `sum` to add the transformed elements. To demonstrate how `foo` works, we call it with the function `abs` as the transformation function.

```
x = rand(100)

function foo(f, x)
    y = map(f, x)

    sum(y)
end
```

```
julia> @code_warntype foo(abs,x)
```

Even when `foo(abs,x)` isn't specialized, `@code_warntype` **fails to detect any type-stability issues**. This is a consequence of `@code_warntype` evaluating type stability *under the assumption that specialization is attempted*. In our example, this assumption doesn't hold and therefore `@code_warntype` is of no use.

Type instability arises because Julia **avoids specialization when a callback function isn't explicitly called within the function**. In the example, the function `f` only enters `foo` as an argument of `map`, but there's no explicit line calling `f`.

To obtain indirect evidence about the lack of specialization, we can compare the execution times of the original `foo` function with a version that explicitly calls `f`.

```
x = rand(100)

function foo(f, x)
    y = map(f, x)

    sum(y)
end
```

```
julia> foo(abs, x)
48.447
```

```
julia> @btime foo(abs, $x)
195.579 ns (3 allocations: 928 bytes)
```

```
x = rand(100)

function foo(f, x)
    y = map(f, x)
    f(1)           # irrelevant computation to force specialization

    sum(y)
end
```

```
julia> foo(abs, x)
48.447

julia> @btime foo(abs, $x)
45.745 ns (1 allocation: 896 bytes)
```

The comparison reveals a significant reduction in execution time when `f(1)` is added, along with a notable decrease in memory allocations. As we'll demonstrate in future sections, excessive allocations are often indicative of type instability.

## **FORCING SPECIALIZATION**

### **Warning!**

Exercise caution when forcing specialization. Overly aggressive specialization can degrade performance severely, explaining why Julia's default approach is deliberately conservative. In particular, you should avoid specialization when your script repeatedly calls a high-order function with many unique functions. <sup>1</sup>

Explicitly calling the callback function to circumvent the no-specialization issue isn't ideal, as it introduces an unnecessary computation. Fortunately, alternative solutions exist. One of them is to type-annotate `f`, which provides Julia with a hint to specialize the code for that type of function.

Another solution involves wrapping the function in a tuple before passing it as an argument. This ensures the identification of the function's type, as tuples define a concrete type for each of their elements.

Below, we outline both approaches.

```
x = rand(100)

function foo(f::F, x) where F
    y = map(f, x)

    sum(y)
end
```

```
julia> foo(abs, x)
48.447
```

```
julia> @btime foo(abs, $x)
46.686 ns (1 allocation: 896 bytes)
```

```
x = rand(100)
f_tup = (abs,)

function foo(f_tup, x)
    y = map(f_tup[1], x)

    sum(y)
end
```

```
julia> foo(f_tup, x)
48.447
```

```
julia> @btime foo($f_tup, $x)
45.101 ns (1 allocation: 896 bytes)
```

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## FOOTNOTES

- <sup>1</sup>. For discussions about the issue of excessive specialization, see [here](#) and [here](#).