```
clear
clc
rot2(0)
ans = 2 \times 2
  1 0
0 1
R = rot2(30, 'deg')
R = 2 \times 2
    0.8660 -0.5000
    0.5000 0.8660
c1 = R(:,1)
c1 = 2 \times 1
   0.8660
   0.5000
c2 = R(:,2)
c2 = 2 \times 1
  -0.5000
   0.8660
dot(c1, c2)
ans = 0
det(R)
ans = 1
%trplot2(R)
axis equal
transl2(1,2)
ans = 3 \times 3
    1 0 1
0 1 2
0 0 1
trot2(30, 'deg')
ans = 3 \times 3
    0.8660 -0.5000
    0.5000 0.8660
             0 1.0000
       0
transl2(1,2) * trot2(30, 'deg')
```

```
ans = 3 \times 3
   0.8660 -0.5000 1.0000
   0.5000 0.8660 2.0000
      0
            0 1.0000
SE2(1, 2, 30, 'deg') %same as line above
ans =
                    1 2
   0.8660 -0.5000
   0.5000 0.8660
                       1
          0
      0
axis([0 5 0 5]) %x from 0 to 5 and y from 0 to 5
axis square
hold on
T1 = SE2(1, 2, 30, 'deg')
T1 =
   0.5000 0.8660
                       1
           0
       0
trplot(T1, 'frame', '1', 'color', 'b')
T2 = SE2(2, 1, 0)
T2 =
       1 0 2
0 1 1
trplot(T2, 'frame', '2', 'color', 'r')
T3 = T1*T2
T3 =
   0.8660 -0.5000 2.232
   0.5000 0.8660 3.866
      0
            0
trplot(T3, 'frame', '3', 'color', 'g')
T4 = T2*T1 %different order than T3
T4 =

      0.8660
      -0.5000
      3

      0.5000
      0.8660
      3

       0
            0
trplot(T4, 'frame', '4', 'color', 'c')
```

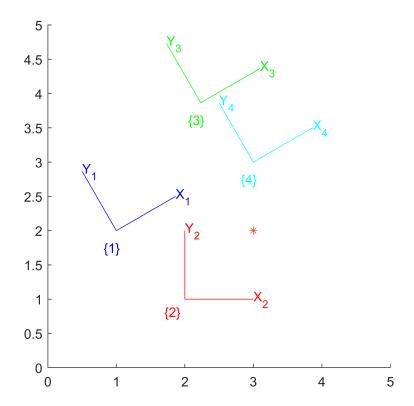
$P = [3 \ 2]'$

$$P = 2 \times 1$$

$$3$$

$$2$$

plot_point(P, '*')



P1 = double(inv(T1)) * [P;1] %P wrt frame 1

- $P1 = 3 \times 1$
 - 1.7321
 - -1.0000
 - 1.0000