

when started

set drive velocity to 100 %

set turn velocity to 100 %

drive reverse for 500 mm ►

move pen down

repeat (4)

drive forward for 800 mm ►

turn left for 90 degrees ►

move pen up

drive forward for 400 mm ►

turn right for 90 degrees ►

garasi

move pen down

set pen to color red

drive forward for 800 mm ►

turn right for 90 degrees ►

drive forward for 400 mm ►

turn right for 90 degrees ►

drive forward for 350 mm ►

turn left for 90 degrees ►

drive forward for 700 mm ►

turn left for 90 degrees ►

drive forward for 350 mm ►

turn right for 90 degrees ►

drive forward for 300 mm ►

turn right for 45 degrees ►

move pen down

set pen to color blue

drive forward for 100 mm ►

turn left for 90 degrees ►

drive forward for 100 mm ►

move pen up

turn to heading 90 degrees ►

drive forward for 800 mm ►

stop project