

when started

clear all rows

set turn velocity to 100 %

set drive velocity to 100 %

drive forward for 1600 mm ▶

turn right for 90 degrees ▶

repeat 8

set cursor to next row

repeat 8

if ◀ DownEye detects green ? ▶ then

print ■ ▶

else

print ○ ▶

drive forward for 200 mm ▶

drive reverse for 1600 mm ▶

turn right for 90 degrees ▶

drive forward for 200 mm ▶

turn left for 90 degrees ▶