

when started

set turn velocity to 100 %

set drive velocity to 100 %

clear all rows

drive forward for 1600 mm ▶

turn right for 90 degrees ▶

repeat 8

set cursor to next row

repeat 8

if DownEye detects green ? then

print 0 ▶

else

print ◯ ▶

drive forward for 200 mm ▶

drive reverse for 1600 mm ▶

turn right for 90 degrees ▶

drive forward for 200 mm ▶

turn left for 90 degrees ▶