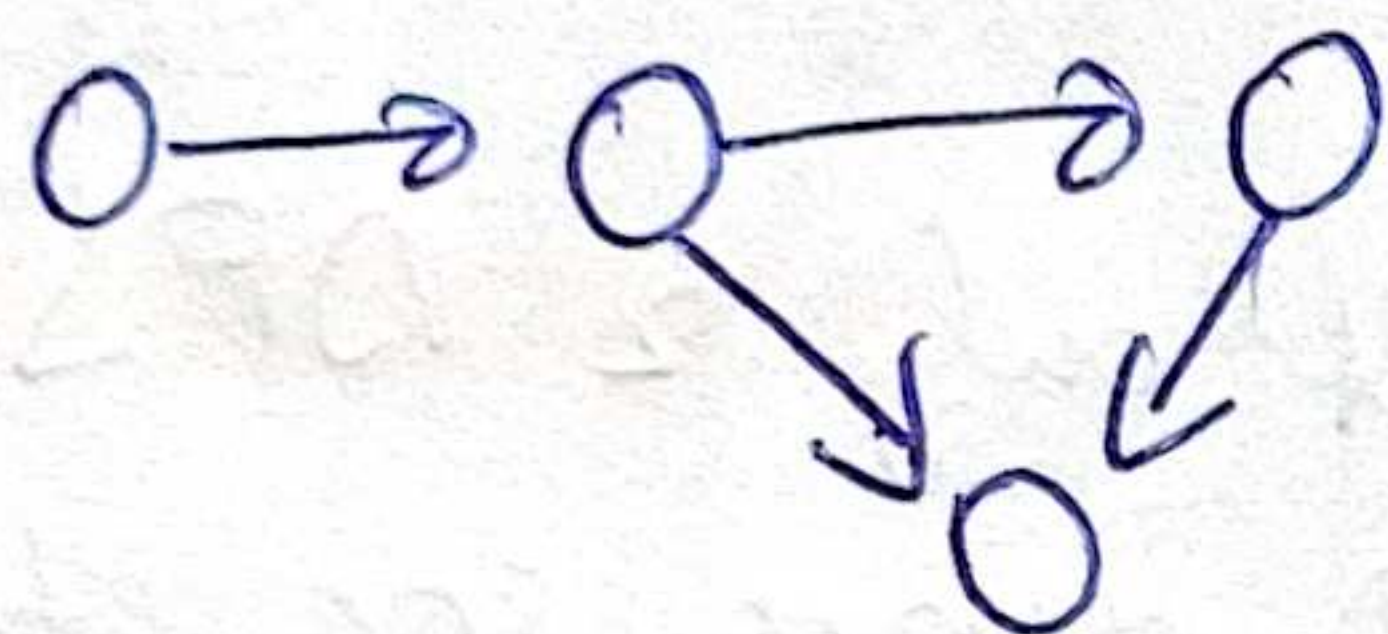


Debugging order.

↳ topological ~~sort~~ sort $B \rightarrow A$

↳ DFS (decr. postorder)

SCC: Strongly Connected Components



source

indeg 0

sink

outdeg 0

need source SCC

un

sink SCC \leftarrow DFS

lemma if we start a DFS at a vertex in a sink SCC
↳ get sink SCC before jumping

problem: find a vertex in a sink SCC
- run DFS, smallest postorder \rightarrow FALSE

lemma largest postorder v in the source SCC
proof by contradiction: assume $\text{postorder}(v) < \text{postorder}(u)$



can 1

u is on stack before v
contradiction

can 2

v is on stack before u
there is a path from v to u
contradiction

lemma reverse the graph \Rightarrow

sinks become sources

sources become sinks

- ① take G , form G^R
- ② Do a DFS on G^R
find source vertex in G^R , sink vertex in G
- ③ Run DFS on sink vertex in G
and remove it

$O(2V) = O(V)$ DFS
 $O(E)$ per DFS

$O(EV)$

but only 2 DFSs !

get tighter bound:

② remove scc, then
get largest postorder
from remaining

③ go through each edge
once

$O(E + V)$

Breadth First Search (BFS)

(notion of distance)

BFS \leftrightarrow queue

Breadth First Search

pick start vertex s

$\text{dist}[s] := 0$

inject (q, s)

$\text{placed}(s) := 1$

while ($\text{size}(q) > 0$)

$v := \text{pop}(q)$

for $(v, w) \in E$

if $\text{placed}(w) = 0$

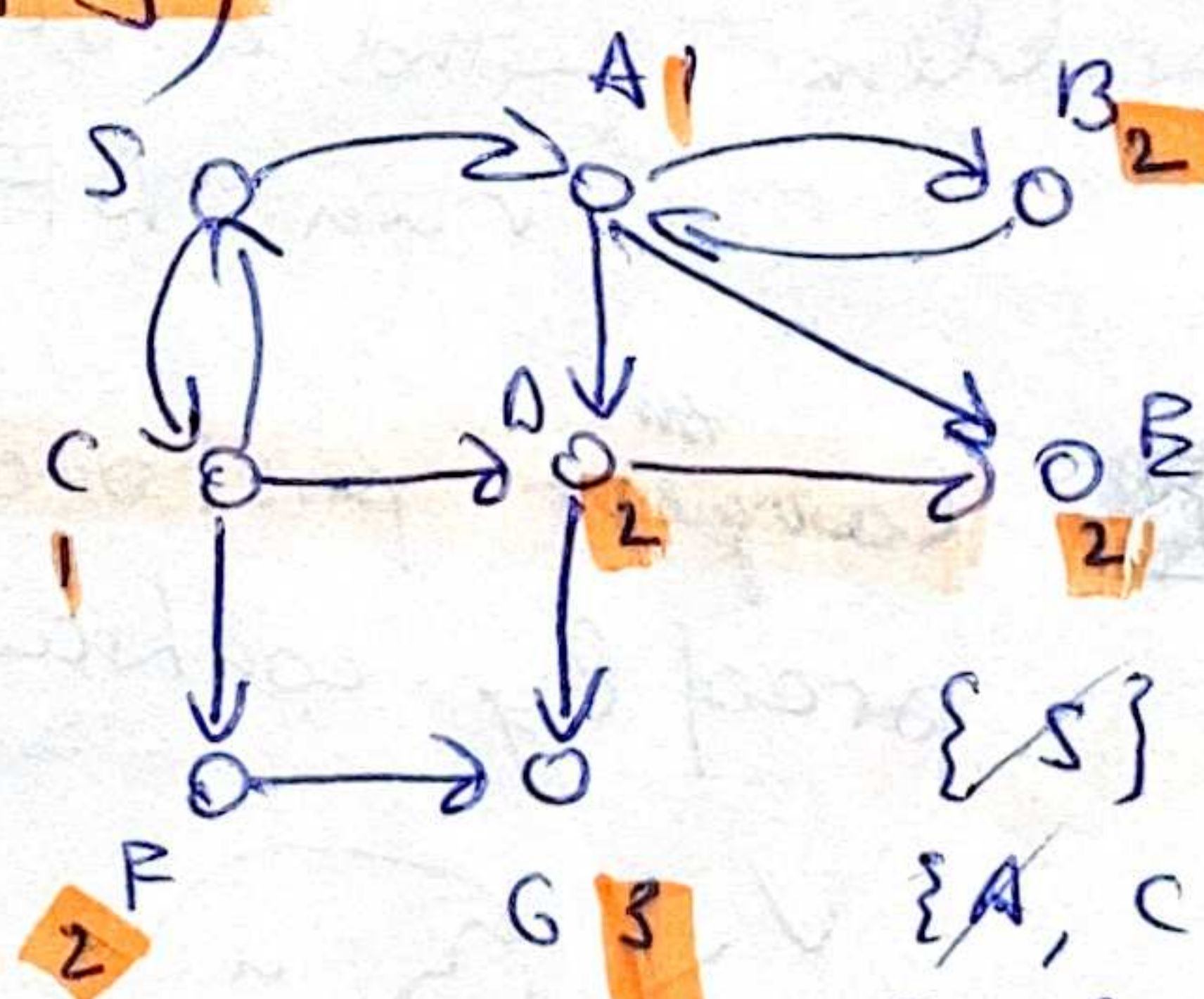
inject (q, w)

$\text{placed}(w) := 1$

$\text{dist}[w] := \text{dist}[v] + 1$

$O(E)$
total

$O(E + V)$



$\{s\}$

$\{A, C\}$

$\{C, B, D, E\}$

$\{B, D, E, F\}$

$\{E, F, G\}$

shortest # of edges distance from
 s to any vertex that can be reached

// # of edges distance
 \rightarrow very basic

queue pop inject

pop min

only 2 levels

level by level

By s By induction

$O(V)$

BFS variations

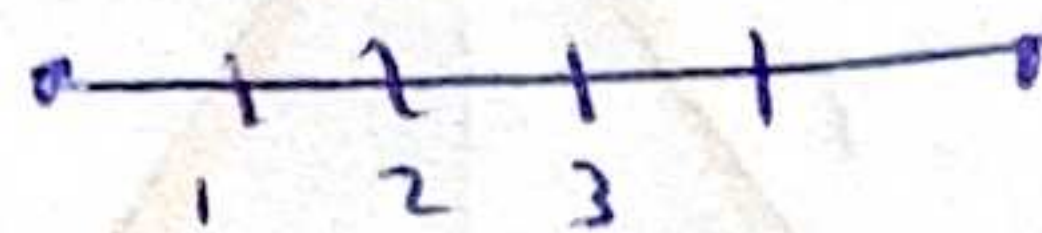
(2)

- queue is sufficient to pop minimums
- each node in the queue has shortest path

Add weights

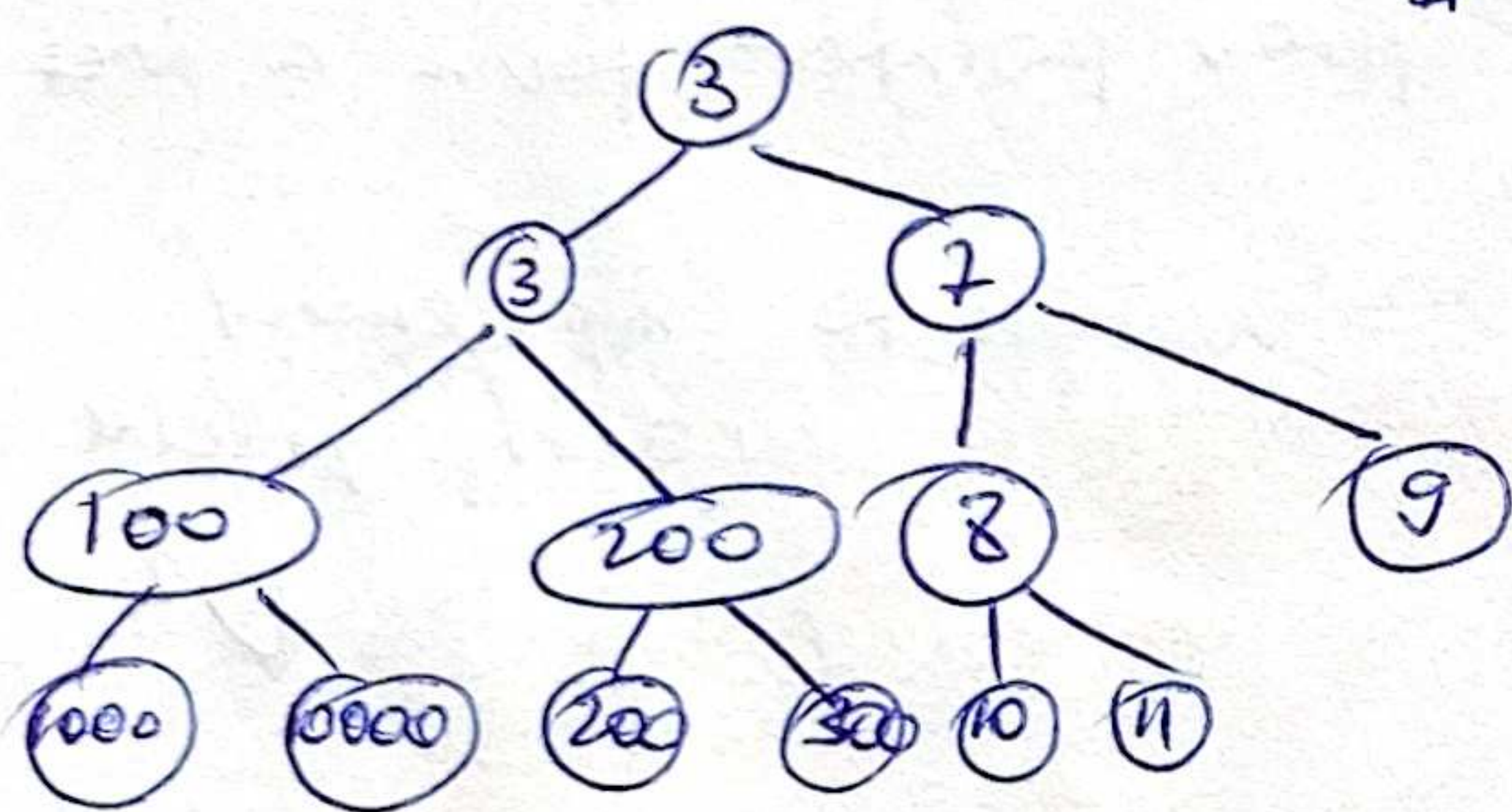
idea reduce to BFS

$O(\sum \text{length all edges})$



Priority queue: different implementations

Heap min-heap (Binary tree to some level)
increases as go down any path



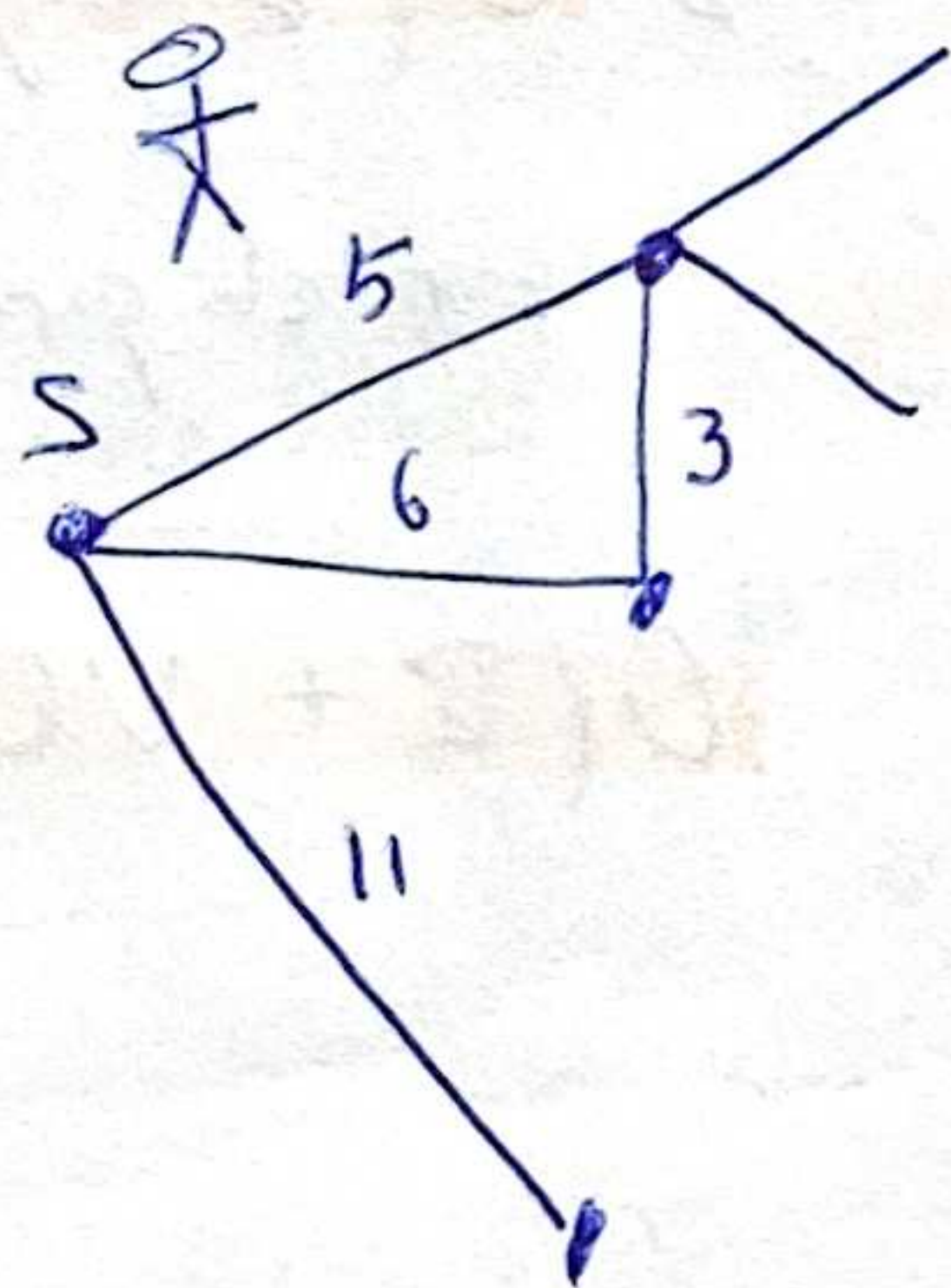
delete min - return object w/
smallest value
and restructure

insert (x, y, h)

- insert item x with
value y in the heap

change (x, y, h)

- if the current value for x
is $> y$, change its value



Dijkstra's shortest path alg

dist, prev. arrays, heap H

$H := \{S, 0\}$

for $v \in V$ do

$\text{dist}[v] := \infty$

$\text{prev}[v] := \text{null}$

$\text{dist}[S] := 0$

while $H \neq \emptyset$

$v := \text{delete min}(H)$

for $(v, w) \in E$

if $\text{dist}[w] > \text{dist}[v] + \text{length}(v, w)$

$\text{dist}[w] := \text{dist}[v] + \text{length}(v, w)$

$\text{prev}[w] := v$

change / insert $(w, \text{dist}[w], H)$

Observation on

popped vertices

→ each vertex deleted,

→ a shortest path to it is

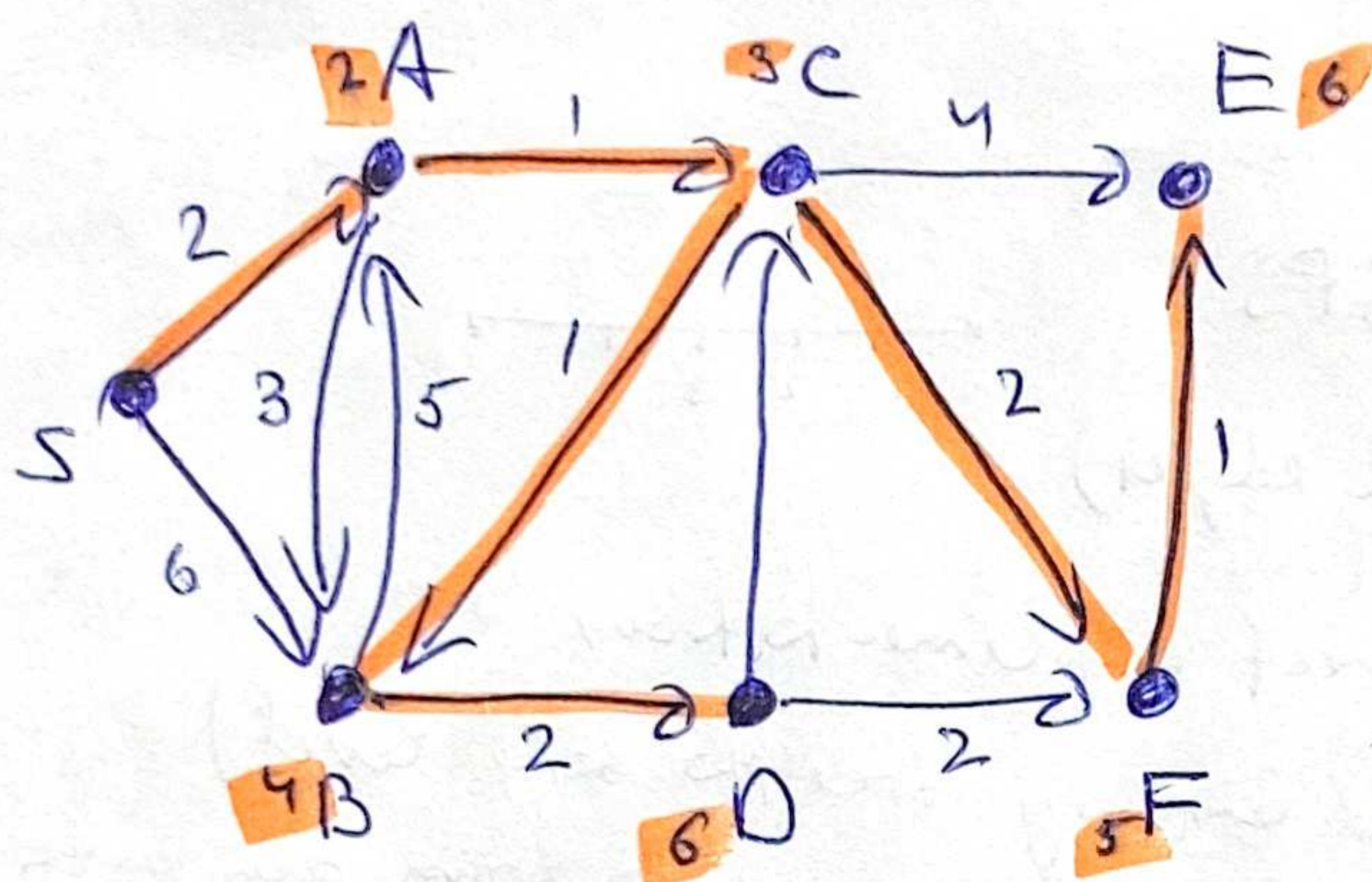
found.

All positive
distances, ~~the~~ paths to other
fringe nodes are longer / as long

invariants :



min node in priority queue has shortest path



S: 0

~~A: 2, B: 6~~

~~C: 3, A: 5~~

~~C: 4, E: 7, F: 5~~

~~C: 5, D: 6, E: 7~~

~~F: 6, D: 6~~

prev pointer from a tree

$O(V \text{ deletemin} + E \text{ insert/change})$

Linked list

$O(V)$

Binary heap

$O(\log V)$

d-ary heap

Fibonacci heap

$O(\log V)$

$O(1)$ ← array of pointers to change

$O(\log V)$

$O(1)$ amortizes

on average over the course of all ops

ways to implement priority queue

better if $E = V^2$

→ $O(V^2)$

→ $O(E \log V)$

↑
rich graph

$O(E + V \log V)$