A Methodology to Define QoS and SLA Requirements in Service Choreographies

Authors

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Agenda

- Introduction
- 2 Problem
- Methodology
- 4 Performance Evaluation
- **5** Conclusions and Future Works

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- Performance Evaluation
- Conclusions and Future Works

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Key elements:

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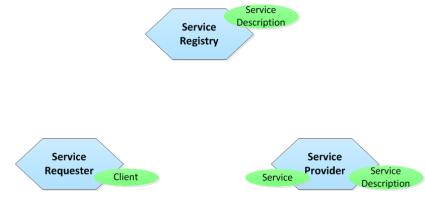


Figure: SOA triangle (based on [W3C, 2002])

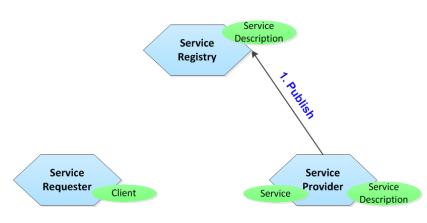


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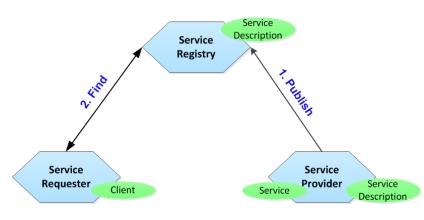


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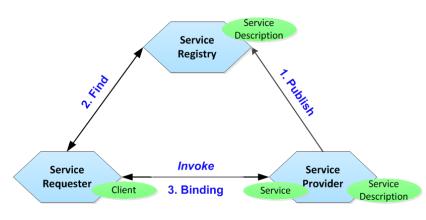


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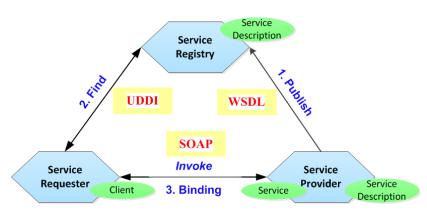


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Service Orchestration

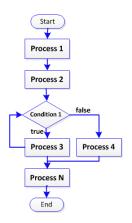


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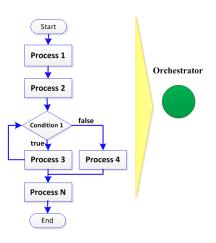


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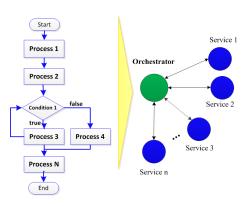


Figure: Service Orchestration

Service Choreography

- Allows service composition in a collaborative manner.
- Describes the P2P interactions of the externally observable behavior of its participants.
- Don't have a single point of control or coordination.

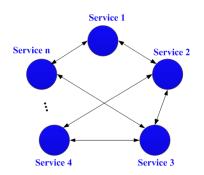


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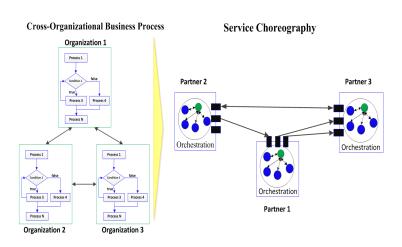


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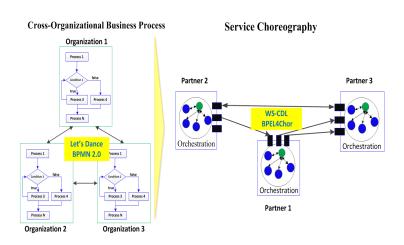


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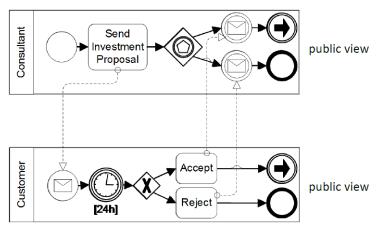
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- Two approaches:
 - ► Interconnection Model: With collaborations diagrams.
 - ► Interaction Model: BPMN Choreographies. using special activities (*Choreography Activity*).

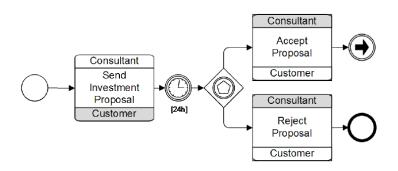
Interconnection Model

- Interconnected public views.
- Use of standard activities.
- "Collaboration" in BPMN 2.0.



Interaction Model

- Interactions globally captured.
- Basic building block: atomic interaction between two parties.
- "Choreography" in BPMN 2.0.



BPMN Choreography

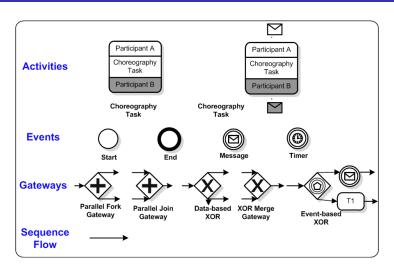


Figure: BPMN elements for modeling choreographies (BPMN 2.0).

Generalized Stochastic Petri Net (GSPN) (I)

Generalized Stochastic Petri Net (GSPN) (II)

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Problem to Solve

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- Planning of resources before/during development of choreography.
- Little approaches don't evaluate choreographies:
 - focusing on QoS or
 - ▶ in earlier stages of development.
- To guarantee QoS about communications (network) is important.

Objectives

- To assess the impact of QoS attributes in a choreography interaction model.
- To propose a novel methodology to establish requirements for QoS and SLA in early stages of development.
- To plan the capacity of the network elements in choreographies.
- To convert a interaction model to a GSPN (Generalized Stochastic Petri Net) with QoS.

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Description

- Mapping of a choreography to a GSPN.
 - ▶ The choreography is specified according "interaction model".
 - ▶ The choreography is specified in BPMN 2.0.
 - ► The resulting GSPN include a QoS model.

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 - ► The resulting GSPN include a QoS model.
- 2 Configurations of resulting GSPN.
- Simulations of scenarios.

Definition: Process Choreography

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A process choreography is a tuple:

$$PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F})$$
 where:

• \mathcal{O} is a set of objects and it's partitioned in **activities** \mathcal{A} , **events** \mathcal{E} and **gateways** \mathcal{G} .

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- A, is the set of **choreography tasks** T.

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- A, is the set of **choreography tasks** T.
- \mathcal{E} is the set of **events** and it's is partitioned in **Start event** $e^{\mathcal{S}}$, **Intermediate events** $\mathcal{E}^{\mathcal{I}}$ and **End event** $e^{\mathcal{E}}$.
- \mathcal{G} é the set of gateways and is partitioned in parallel fork gateways \mathcal{G}^F , parallel join gateways \mathcal{G}^J , data-based XOR gateways \mathcal{G}^X , XOR merge gateways \mathcal{G}^V and event-based XOR gateways \mathcal{G}^M .

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- $\mathcal{F} \subseteq \mathcal{O} \times \mathcal{O}$ is the control flow relation, i.e. a **set of sequence flows** connecting objects.

QoS Model

- Defining the QoS attributes involved in service, network and message aspects.
- QoS attributes:
 - In service operation: time to complete the service.
 - ► In network: delay and communication errors.
 - ► In message : message format.

Mapping BPMN to Petri Net (I)

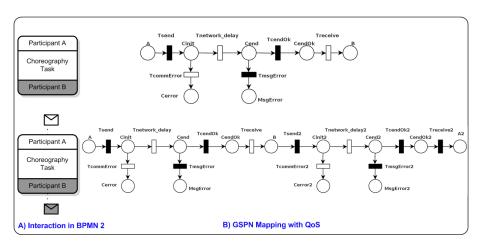
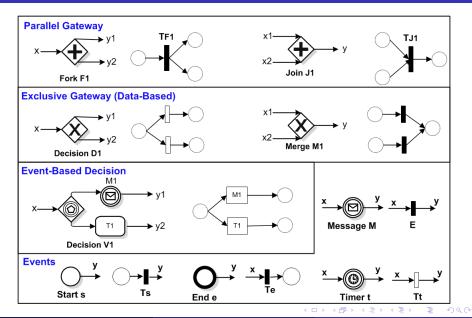


Figure: Mapping of two different choreography tasks with the QoS model

Mapping BPMN to Petri Net (II)



Algorithm 1 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

 $\begin{array}{ll} \textbf{Input:} & \textbf{Process Choreography} \ \ PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \\ \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F}) & \text{in BPMN 2.0.} \end{array}$

Output: Generalized Stochastic Petri Net $GSPN_{QoS}$.

Algorithm 2 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

 $\begin{array}{ll} \textbf{Input:} & \textbf{Process Choreography} \ \ PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \\ \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F}) & \text{in BPMN 2.0.} \end{array}$

Output: Generalized Stochastic Petri Net $GSPN_{QoS}$.

Consider $CT_i \in \mathcal{T}$, $G_j \in \mathcal{G}$ and $E_k \in \mathcal{E}$. where $i, j, k \in \mathbb{N}$.

Algorithm 3 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

 $\begin{array}{ll} \textbf{Input:} & \textbf{Process Choreography} \ \ PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \\ \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F}) & \text{in BPMN 2.0.} \end{array}$

Output: Generalized Stochastic Petri Net $GSPN_{QoS}$.

Consider $CT_i \in \mathcal{T}$, $G_j \in \mathcal{G}$ and $E_k \in \mathcal{E}$. where $i, j, k \in \mathbb{N}$.

Consider $PNQoS(CT_i)$ is a function of the type of CT_i that returns a GSPN according to mapping rules.

Algorithm 4 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

 $\begin{array}{ll} \textbf{Input:} & \textbf{Process Choreography} \ \ PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \\ \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F}) & \text{in BPMN 2.0.} \end{array}$

Output: Generalized Stochastic Petri Net $GSPN_{QoS}$.

Consider $CT_i \in \mathcal{T}$, $G_j \in \mathcal{G}$ and $E_k \in \mathcal{E}$. where $i, j, k \in \mathbb{N}$.

Consider $PNQoS(CT_i)$ is a function of the type of CT_i that returns a GSPN according to mapping rules.

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Algorithm 5 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

Input: Process Choreography $PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F})$ in BPMN 2.0.

Output: Generalized Stochastic Petri Net GSPN_{QoS} .

Consider $CT_i \in \mathcal{T}$, $G_j \in \mathcal{G}$ and $E_k \in \mathcal{E}$. where $i, j, k \in \mathbb{N}$.

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Algorithm 6 Mapping of choreography specified in BPMN 2.0 to a GSPN with QoS model

Input: Process Choreography $PC = (\mathcal{O}, \mathcal{A}, \mathcal{E}, \mathcal{G}, \mathcal{T}, \{e^S\}, \mathcal{E}^I, \{e^E\}, \mathcal{E}^{I_M}, \mathcal{E}^{I_T}, \mathcal{G}^F, \mathcal{G}^J, \mathcal{G}^X, \mathcal{G}^M, \mathcal{G}^V, \mathcal{F})$ in BPMN 2.0.

Output: Generalized Stochastic Petri Net GSPN_{QoS} .

Consider $CT_i \in \mathcal{T}$, $G_j \in \mathcal{G}$ and $E_k \in \mathcal{E}$. where $i, j, k \in \mathbb{N}$.

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Consider $PNQoS(G_j)$ is a function of the type of G_j that returns a GSPN according to mapping rules.

Consider $PNQoS(E_k)$ is a function of the type of E_k that returns a GSPN according to mapping rules.

Consider \oplus the binary operator of composition of two GSPNs that returns other GSPN.

 $GSPN_{QoS} \leftarrow Empty \ Petri \ Net$

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End

```
\begin{aligned} \textit{GSPN}_{QoS} \leftarrow \textit{Empty Petri Net} \\ \textbf{For } \textit{CT}_i \in \mathcal{T} \quad \textbf{Do} \\ \textit{GSPN}_{QoS} \leftarrow \textit{GSPN}_{QoS} \oplus \textit{PNQoS}(\textit{CT}_i) \end{aligned}
```

End

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GSPN_{QoS} \leftarrow Empty \ Petri \ Net
For CT_i \in \mathcal{T} Do
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Add a arrival timed Transition at beginning of the GSPN_{QoS}.
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End
For G_j \in \mathcal{G} Do
End
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Add a arrival timed Transition at beginning of the GSPN_{QoS}.
End
For \ G_j \in \mathcal{G} \quad \textbf{Do}
GSPN_{QoS} \leftarrow GSPN_{QoS} \oplus PN(G_j)
End
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```
GSPN_{OoS} \leftarrow Empty \ Petri \ Net
For CT_i \in \mathcal{T} Do
   GSPN_{QoS} \leftarrow GSPN_{QoS} \oplus PNQoS(CT_i)
   Add a arrival timed Transition at beginning of the GSPN<sub>QoS</sub>.
End
For G_i \in \mathcal{G} Do
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For G_i \in \mathcal{G} Do
   GSPN_{OoS} \leftarrow GSPN_{OoS} \oplus PN(G_i)
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For E_k \in \mathcal{E} Do
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Add a starting Place and immediate Transition at the beginning of the GSPNQoS.

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For CT_i \in \mathcal{T} Do
GSPN_{QoS} \leftarrow GSPN_{QoS} \oplus PNQoS(CT_i)
Add a arrival timed Transition at beginning of the GSPN_{QoS}.

End

For G_j \in \mathcal{G} Do
GSPN_{QoS} \leftarrow GSPN_{QoS} \oplus PN(G_j)
End

For E_k \in \mathcal{E} Do
GSPN_{QoS} \leftarrow GSPN_{QoS} \oplus PN(E_k)
End
```

Add a starting Place and **immediate Transition** at the beginning of the $GSPN_{QoS}$. Add a ending Place and **immediate Transition** at the end of the $GSPN_{QoS}$.

```
\begin{aligned} & \textit{GSPN}_{QoS} \leftarrow \textit{Empty Petri Net} \\ & \textbf{For } & \textit{CT}_i \in \mathcal{T} \quad \textbf{Do} \\ & \textit{GSPN}_{QoS} \leftarrow \textit{GSPN}_{QoS} \oplus \textit{PNQoS}(\textit{CT}_i) \\ & \textit{Add a arrival timed Transition at beginning of the } & \textit{GSPN}_{QoS}. \\ & \textbf{End} \\ & \textbf{For } & \textit{G}_j \in \mathcal{G} \quad \textbf{Do} \\ & \textit{GSPN}_{QoS} \leftarrow & \textit{GSPN}_{QoS} \oplus \textit{PN}(\textit{G}_j) \\ & \textbf{End} \\ & \textbf{For } & \textit{E}_k \in \mathcal{E} \quad \textbf{Do} \\ & \textit{GSPN}_{QoS} \leftarrow & \textit{GSPN}_{QoS} \oplus \textit{PN}(\textit{E}_k) \\ & \textbf{End} \end{aligned}
```

Add a starting Place and **immediate Transition** at the beginning of the $GSPN_{QoS}$. Add a ending Place and **immediate Transition** at the end of the $GSPN_{QoS}$.

Return GSPN_{QoS}

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Scenario

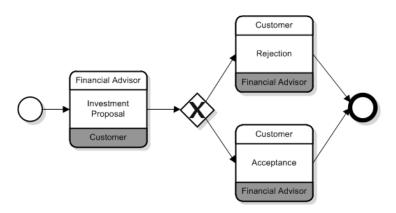


Figure: Example of choreography using BPMN2 elements.

Mapping

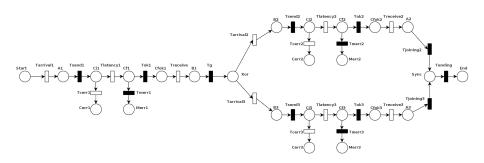


Figure: GSPN obtained from the choreography.

Configuration

Table: Weights of Scenario 1 and Scenario 2

| | Weights | |
|---|------------|------------|
| Transition | Scenario 1 | Scenario 2 |
| $T_{latency1}, T_{latency2}, T_{latency3}$ | 0.99 | 0.94 |
| $T_{cerr1}, T_{cerr2}, T_{cerr3}$ | 0.01 | 0.06 |
| $T_{receive}$, $T_{receive2}$, $T_{receive3}$ | 99 | 97 |
| T_{merr1} , T_{merr2} , T_{merr3} | 1 | 3 |
| $T_{arrival2}, T_{arrival3}$ | 0.5 | 0.5 |

Simulation

 \bullet 1 token = 1 choreography instance.

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- 100 tokens are considered to each scenario at the place Start.
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- 1500 fires and 10 replications.
- Confidence level of 95%.

Results (I)

Table: Results (in %)

| | Average number of tokens | | 95% Confidence interval (+/-) | |
|-------------------|--------------------------|------------|-------------------------------|------------|
| Place | Scenario 1 | Scenario 2 | Scenario 1 | Scenario 2 |
| Start | 35.28 | 40.15 | 5.83 | 6.23 |
| End | 41.95 | 38.78 | 2.53 | 3.82 |
| M_{err1} | 0.39 | 0.91 | 0.95 | 1.92 |
| M_{err2} | 0.00 | 0.93 | 0.63 | 0.64 |
| M_{err3} | 0.00 | 0.66 | 0.87 | 0.74 |
| C _{err1} | 0.74 | 2.94 | 0.82 | 2.02 |
| C_{err2} | 0.00 | 0.00 | 0.67 | 1.75 |
| C _{err3} | 0.78 | 0.16 | 0.92 | 1.52 |
| C_{i1} | 8.32 | 8.90 | 5.33 | 7.48 |
| C_{i2} | 0.63 | 0.69 | 0.23 | 0.52 |
| C_{i3} | 0.75 | 8.90 | 0.39 | 0.21 |

Results (II)

- Communication errors: An average of $C_{err1} + C_{err2} + C_{err3}$ of instances didn't finish the process.
 - Scenario 1: 1.52%.
 - ► Scenario 2: 3.10% (more errors).

Results (II)

- Communication errors: An average of $C_{err1} + C_{err2} + C_{err3}$ of instances didn't finish the process.
 - Scenario 1: 1.52%.
 - ► Scenario 2: 3.10% (more errors).
- Invalid format message: An average of $M_{err1} + M_{err2} + M_{err3}$ of instances didn't finish the process.
 - Scenario 1: 0.39%.
 - Scenario 2: 2.50% (more invalid messages).

Results (II)

- Communication errors: An average of $C_{err1} + C_{err2} + C_{err3}$ of instances didn't finish the process.
 - Scenario 1: 1.52%.
 - ► Scenario 2: 3.10% (more errors).
- Invalid format message: An average of $M_{err1} + M_{err2} + M_{err3}$ of instances didn't finish the process.
 - Scenario 1: 0.39%.
 - Scenario 2: 2.50% (more invalid messages).
- **Bottleneck**: It was found a communication bottleneck in the first interaction (C_i place).
 - Scenario 1: 8.32%.
 - Scenario 2: 8.90%.

- Introduction
- 2 Problem
- Methodology
- Performance Evaluation
- **5** Conclusions and Future Works

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- The GSPN is good to model and analyze several aspects involved into service choreography.
- The simulation is needed for supporting analysis of complex process (e.g. process choreography).
- The simulation results can be used to establish early QoS and SLA constraints.
 - Integration is expensive, then early detections are needed.
 - ▶ Establishing SLAs according to resources.
 - ▶ Planning in order to reduce failures.
 - ► For example: the detected bottleneck can be solved by changing the interaction (modeling issues) or by employing QoS mechanisms in the network to prioritize the traffic affected (resource planning).

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- To expand our methodology to support generic probability distributions in the decision points. Using Colored Petri Nets (CPNs) can be a alternative.
- To make more analysis and to use complex scenarios, where correlations problems could happen.
- To include more QoS attributes.

Thanks so much!