# Alfonso Ros

# Curriculum Vitae

St.-Veit-Str. 28
81673 München

\$\(^\*\) +49 173 6523397

\times alfonso.ros.88@gmail.com

Alfonso Ros Dos Santos

\$\(^\*\) alfonsoros88

# Work Experience

November Software Engineer, Autonomous Intelligent Driving GmbH, Germany.

2019 - present • Development of the communication layer for the Vehicle's Platform (C++11, DDS, Linux).

2018 – 2019 Project Engineer, TTTECH AUTO AG, Germany.

• Development of BMW's Keep Lane Assistant customer function (C++14, ROS).

2016 – 2018 Software Engineer, EVOSOFT GMBH, Germany.

• Implementation of monitoring system for electrical substations (C/C++, DPDK, RTLinux).

o Setup of Continuous Integration for embedded testing (Yocto-Linux, LAVA, Python, Go)

2015 – 2016 Working Student, SIEMENS CORPORATE TECHNOLOGY, Germany.

• Development of *Internet of Things* services (C/C++, Cortex-M4, CoAP).

2012 – 2013 Software Engineer, TALPOR SOLUTIONS C.A., Venezuela.

• Web Development using Python (Django).

2008 – 2011 System Administrator, Universidad Simón Bolívar, Venezuela.

• Network and System administration (e.g. DHCP, DNS, E-Mail, NFS, LDAP).

• Teaching Linux and C Programming courses.

#### Technical skills

Programming Proficient: C++17, Python

Languages Familiar: Rust, CUDA, Go, shell scripting, LUA, Matlab, Haskell.

Libraries Familiar: GTest, Catch2, Boost, Point Cloud Library (PCL), Eigen, OpenCV

Software Proficient: VI, Git, CMake, Bazel, GDB.

Familiar: valgrind, Ansible, Docker, Blender, Unity.

### Education

2013–2016 M.Sc. Informatics, Technische Universität München, Germany.

Major: Computer Vision and Machine Learning.

2006–2012 B.S. Computer Science and Engineering, Universidad Simón Bolívar, Venezuela.

Major: Machine Learning and Computer Graphics.

Award: 2011's Best Computer Science thesis – IEEE & Inelectra Venezuela.

## Languages

Spanish Mother tongue

English Professional working proficiency

German Intermediate proficiency

## Hobbies

playing Video and Board games, painting and a bit of piano playing