1 Monge-Kantorovich duality in the discrete case

$$\begin{aligned} \max_{\pi_{xy} \geq 0} \qquad & \sum_{xy} \pi_{xy} \Phi_{xy} \\ & \sum_{y} \pi_{xy} = p_x \ [u_x] \\ & \sum_{x} \pi_{xy} = q_y \ [v_y] \end{aligned}$$

$$\max_{\pi_{xy} \ge 0} \sum_{xy} \pi_{xy} \Phi_{xy} + \sum_{x} \min_{u_x} u_x \left(p_x - \sum_{y} \pi_{xy} \right) + \sum_{y} \min_{v_y} v_y \left(q_y - \sum_{x} \pi_{xy} \right)$$

$$\max_{\pi_{xy} \ge 0} \min_{u_x, v_y} \sum_{xy} \pi_{xy} \Phi_{xy} + \sum_{x} u_x p_x + \sum_{y} v_y q_y - \sum_{xy} \pi_{xy} \left(u_x + v_y \right)$$

$$\min_{u_x, v_y} \sum_{x} u_x p_x + \sum_{y} v_y q_y + \max_{\pi_{xy} \ge 0} \sum_{xy} \pi_{xy} \left(\Phi_{xy} - u_x - v_y \right)$$

thus

$$\begin{aligned} & \min_{u_x, v_y} & & & \sum_x u_x p_x + \sum_y v_y q_y \\ & s.t. & & & u_x + v_y \geq \Phi_{xy} \end{aligned}$$

1.1 Kantorovich duality

Primal

$$\begin{aligned} \max_{\pi_{xy} \geq 0} & & \sum_{xy} \pi_{xy} \Phi_{xy} \\ & & \sum_{y} \pi_{xy} = p_x \ [u_x] \\ & & \sum_{x} \pi_{xy} = q_y \ [v_y] \end{aligned}$$

Dual

$$\begin{split} \min_{u_x,v_y} & & \sum_x u_x p_x + \sum_y v_y q_y \\ s.t. & & u_x + v_y \geq \Phi_{xy} \ [\pi_{xy} \geq 0] \end{split}$$

By complementary slackness, $\pi_{xy} > 0 \implies u_x + v_y = \Phi_{xy}$.

INterpretation: u_x =equilibrium wage of worker x v_y =equilibrium profit of firm y.

$$u_x + v_y \ge \Phi_{xy}$$
.

Claim: If (u, v) is a solution to the dual problem, then

$$v_y = \max_{x \in \mathcal{X}} \left\{ \Phi_{xy} - u_x \right\} \text{ and } u_x = \max_{y \in \mathcal{Y}} \left\{ \Phi_{xy} - v_y \right\}.$$

Economic interpretation: u_x and v_y are the worker's and firm's indirect utilities.

2 One-dimensional case

Consider the case $\mathcal{X} = \mathcal{Y} = \mathbb{R}$

and
$$\Phi(x,y) = xy$$

Monge-Kantorovich duality: primal

$$\label{eq:energy_energy} \begin{aligned} \max_{(X,Y)} & & E\left[XY\right] \\ s.t.X & \sim & P,Y \sim Q \end{aligned}$$

and the dual

$$\min_{u,v} \int u(x) dP(x) + \int v(y) dQ(y)$$
s.t.
$$u(x) + v(y) \ge xy$$

If u and v (solutions to the dual) exist then

$$v\left(y\right) = \max_{x \in R} \left\{ xy - u\left(x\right) \right\} \text{ and } u\left(x\right) = \max_{y \in R} \left\{ xy - v\left(y\right) \right\}.$$

by first order conditions if $x \in \arg\max_{x \in R} \{xy - u(x)\}$, then

$$u'(x) = y$$
.

Assume P and Q is absolutely continuous with respect Lebesgue.

Theorem: the solution to the primal problem

$$\label{eq:energy_energy} \begin{aligned} & \max_{(X,Y)} & & E\left[XY\right] \\ & s.t.X & \sim & P,Y \sim Q \end{aligned}$$

is such that T(.) is increasing and continuous, and such that T#P=Q.

Claim: in this case, part (1) $T(x) = F_Q^{-1}(F_P(x))$. Indeed, $T(X) \sim Q$ when $X \sim P$ implies

$$P\left(T\left(X\right) \le y\right) = F_Q\left(y\right)$$

thus

$$Pr\left(X \leq T^{-1}(y)\right) = F_Q(y)$$

$$F_P\left(T^{-1}(y)\right) = F_Q(y)$$

$$T^{-1}(y) = F_P^{-1} \circ F_Q$$

$$T = F_Q^{-1} \circ F_P.$$

part (2) a solution (u, v) to the dual problem is given using

$$u\left(x\right) = \int_{0}^{x} F_{Q}^{-1}\left(F_{P}\left(z\right)\right) dz$$

and $v(y) = \max_{x} \{xy - u(x)\}.$

Particular case: when $P = \mathcal{U}([0,1])$, $F_P(x) = x$ on [0,1], and

$$T\left(x\right) = F_O^{-1}\left(x\right)$$

is the quantile map of Q and also

$$u'\left(x\right) = F_{Q}^{-1}\left(x\right).$$

This could have given us a definition of quantile!

3 Multivariate case and a notion of multivariate quantiles

Now assume that $\mathcal{X} = \mathcal{Y} = \mathbb{R}^d$ and $\Phi(x, y) = x^\top y$.

Assume that we are in the conditions that give existence of dual solutions (u, v) (e.g. compactness of support of P and Q).

Then we have

$$v\left(y\right) = \max_{x \in \mathbb{R}^d} \left\{ x^\top y - u\left(x\right) \right\} \text{ and } u\left(x\right) = \max_{y \in \mathbb{R}^d} \left\{ x^\top y - v\left(y\right) \right\}.$$

Note that u(x) and v(y) are convex functions.

If x is matched to y, we get by FOC

$$\frac{\partial u\left(x\right)}{\partial x_{i}} = y_{i}$$

hence

$$\nabla u\left(x\right) = y$$

Hence, we are looking for a convex function $u: \mathbb{R}^d \to \mathbb{R}$ such that if $X \sim P$, then

$$\nabla u(X) \sim Q$$
.

Because $\nabla u(x)$ is the gradient of a convex function

$$\left(\nabla u\left(x\right) - \nabla u\left(x'\right)\right)^{\top}\left(x - x'\right) \ge 0$$

Let's see what this problem is in dimension 1. In dimension 1, $\nabla u(x) = u'(x)$. The derivative of a convex function is a nondecreasing function, call it T(x). Thus, in dimension 1, this problem consists of looking for a nondecreasing function T such that

$$T(X) \sim Q$$

which is $T(x) = F_Q^{-1} \circ F_P(x)$.

4 Day 2

4.1 Computation of discrete OT problems as LP problems

$$\begin{aligned} \max_{\pi_{xy} \geq 0} & \sum_{xy} \pi_{xy} \Phi_{xy} \\ & \sum_{y} \pi_{xy} = p_x \ [u_x] \\ & \sum_{x} \pi_{xy} = q_y \ [v_y] \end{aligned}$$

 $vec\left(\Pi\right)$ using the Fortran convention $\Pi_{11},\Pi_{21},\Pi_{31}$ -stack the columns

$$\max_{\pi_{xy} \ge 0} \qquad \sum_{xy} \pi_{xy} \Phi_{xy}$$

$$\Pi 1_{\mathcal{Y}} = p$$

$$\Pi^{\top} 1_{\mathcal{X}} = q$$

One has

$$vec(BXA^{\top}) = (A \otimes B) vec(X)$$

thus

$$vec(I_{\mathcal{X}}\Pi 1_{\mathcal{Y}}) = p$$
$$(1_{\mathcal{Y}}^{\top} \otimes I_{\mathcal{X}}) vec(\Pi) = p$$

similarly

$$\begin{array}{rcl} vec\left(\mathbf{1}_{\mathcal{X}}^{\top}\Pi I_{\mathcal{Y}}\right) & = & vec\left(q^{\top}\right) = q \\ \left(I_{\mathcal{Y}} \otimes \mathbf{1}_{\mathcal{X}}^{\top}\right) vec\left(\Pi\right) & = & q \end{array}$$

therefore, calling $\pi = vec(\Pi)$

$$\max_{\pi \geq 0} \pi^{\top} vec(\Phi)$$
s.t. $(1_{\mathcal{Y}}^{\top} \otimes I_{\mathcal{X}}) \pi = p$
 $(I_{\mathcal{Y}} \otimes 1_{\mathcal{X}}^{\top}) \pi = q$

thus the constraint matrix

$$A = \begin{pmatrix} 1_{\mathcal{Y}}^{\top} \otimes I_{\mathcal{X}} \\ I_{\mathcal{Y}} \otimes 1_{\mathcal{X}}^{\top} \end{pmatrix}$$

4.2 Quantile regression with shape constraints

$$V\left(\tau\right) = 1\left\{Y \ge X^{\top}\beta\left(\tau\right)\right\}$$

Natural shape restriction

$$\tau \in [0,1] \to x^{\top} \beta(\tau)$$
 is increasing

this implies that

$$\tau \to V\left(\tau\right) = \mathbf{1}\left\{Y \geq X^{\top}\beta\left(\tau\right)\right\}$$
 is weakly decreasing a.s.

We have transformed the problem into

$$\max_{\pi \ge 0} \qquad U^{\top} \pi Y$$

$$s.t. \qquad \pi X = \mu \ \bar{x}$$

$$\pi^{\top} 1_T = p$$

The objective function

$$\sum_{tj} \pi_{tj} U_t Y_j = E_{\pi} \left[U Y \right]$$

the constraints

$$\sum_{j} \pi_{tj} X_{jk} = \mu_t \bar{x}_k$$

Let's assume 1 is included in the regressors, i.e. $X_{j1}=1$. In this case

$$\sum_j \pi_{tj} = \mu_t$$

Finally

$$\sum_{j} \pi_{tj} X_{jk} = \mu_t \bar{x}_k, \ k \ge 2$$

rewrites as

$$\frac{\sum_{j} \pi_{tj} X_{jk}}{\sum_{j} \pi_{tj}} = \bar{x}_k, \ k \ge 2$$

that is

$$E_{\pi}\left[X_k|U\right] = \bar{x}_k$$

therefore, we are led

$$\begin{aligned} \max_{\pi(u,(x,y)) \geq 0} & E_{\pi} \left[UY \right] \\ s.t. & U \sim \mu \\ & (X,Y) \sim P \\ & E \left[X^k | U \right] = E \left[X^k \right], k \geq 2 \end{aligned}$$

The last constraint $E\left[X^k|U\right]=E\left[X^k\right]$ means that X should be mean-independent from U.

Let's see a version of the problem with full independence

$$\max_{\pi(u,(x,y))\geq 0} \qquad E_{\pi}\left[UY\right]$$
 s.t.
$$U\sim \mu$$

$$(X,Y)\sim P$$

$$X \text{ and } U \text{ independent}$$

write

$$E_{\pi}[UY] = E[E[UY|X]]$$

this is maximized by taking for each x the optimal coupling between $U \sim \mathcal{U}([0,1])$ and $P_{Y|X=x}$. This is given to us by $Y = Q_{Y|X}(U|x)$. Thus the soluton to the problem with full independence is given to us by

$$Y = Q_{Y|X} \left(U|X \right)$$

and hence

$$U = F_{Y|X}(Y|X).$$

Back to mean-independence, write the dual of the above primal problem

$$\max_{\pi(u,(x,y))\geq 0} E_{\pi}\left[UY\right]$$
 s.t.
$$U \sim \mu$$

$$(X,Y) \sim P$$

$$E\left[X^{k}|U\right] = E\left[X^{k}\right], k \geq 2$$

the dual to this problem is

$$\begin{aligned} \min_{\varphi(u),\psi(x,y),b^{k}(u)} & & E\left[\varphi\left(U\right)\right] + E\left[\psi\left(X,Y\right)\right] + E\left[\bar{x}^{\top}b\left(U\right)\right] \\ s.t. & & \varphi\left(u\right) + \psi\left(x,y\right) + x^{\top}b\left(u\right) \geq x^{\top}y \end{aligned}$$