Title might include words such as: {approximate, auctions, substitutes, budgets}

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- Dynamic designs—e.g., SMRA or CCA—help bidders "manage budgets", but are not always effective (Janssen et al., 2017; Marsden and Sorensen, 2017; Fookes and McKenzie, 2017).
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- Pin down and control the tradeoff between relaxing the supply and the budget constraints.
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Agent i solves

$$\max_{x_i \in \mathcal{X}_i} V_i(x_i) - p \cdot x_i$$
 subject to $p \cdot x_i \leq b_i$.

- See, e.g., Bhattacharya et al. (2010); Dobzinski et al. (2012); Pai and Vohra (2014); Gul et al. (2019); Jagadeesan and Teytelboym (2023)...
- The demand correspondence of agent *i* is

$$D_i(p) = \arg\max_{x_i \in \mathcal{X}_i} \{V_i(x_i) - p \cdot x_i \,|\, p \cdot x_i \leq b_i\}.$$

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Competitive and approximate equilibrium

Definition

A competitive equilibrium for the economy $((V_i)_{i\in N}, b, s)$ is a price vector $p \ge c$ and demands $x_i \in D_i(p)$ for all $i \in N$ such that $\sum_{i \in N} x_i \le s$, holding with equality for each $j \in M$ for which $p_j > c_j$.

Definition

An (α, β) -competitive equilibrium for the economy $((V_i)_{i \in N}, b, s)$ is a competitive equilibrium for the economy $((V_i)_{i \in M}, b', s')$ where $|s'_j - s_j| \le \alpha$ for every $j \in M$ and $|b'_i - b_i| \le \beta$ for every $i \in N$.

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First general result: additive valuations

Theorem

Suppose that V_i is an additive valuation for all i. Then every economy has a $(0, \max_j p_j)$ -competitive equilibrium. Moreover, the total cost of supply does not increase.

Main general result: substitutes

Theorem

Suppose that V_i is a substitutes valuation for all i. Then every economy has a $(1 + \lfloor \frac{2}{t} \rfloor, (2 + \lfloor 2t \rfloor) \max_j p_j)$ -competitive equilibrium for any t > 0. Moreover, the total cost of supply does not increase.

Examples of the supply-budget constraint relaxation tradeoff:

- t = 2.01, we have $(1, 6 \max_{j} p_{j})$ -CE
- t = 1.01, we have $(2, 4 \max_{j} p_{j})$ -CE
- t = 0.67, we have $(3, 3 \max_{j} p_{j})$ -CE
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Practical consequences of the results

- Can elicit budget constraints directly from bidders in the product-mix auction, assignment message auction, or final round of the CCA.
- Designer can optimize over different approximate equilibria.
- Especially useful for large-ish auctions: many items and reasonable supply.

Proof: Step 1/5

• Convexify the economy by replacing the demand correspondence with its convex hull $conv(D_i(p))$. Agents consume lotteries over bundles.

Definition (Milgrom and Strulovici, 2009)

A pseudoequilibrium for the economy $((V_i)_{i\in M}, b, s)$ is a price vector $p \geq c$ and demands $x_i \in \text{conv}(D_i(p))$ for all $i \in N$ such that $\sum_{i \in N} x_i \leq s$ with equality for each $j \in M$ for which $p_j > c_j$.

Lemma

For any economy $((V_i)_{i \in M}, b, s)$, a pseudoequilibrium exists.

• At the pseudoequilibrium, there is a market-clearing price vector p agent i buys a random bundle X_i , expected payment is $E(p \cdot X_i)$ (note that $p \cdot X_i$ can exceed the budget for some X_i), payoff is $E(V(X_i)) - E(p \cdot X_i)$. Expectations are taken over some probability distribution over bundles.

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• At the pseudoequilibrium, there is a market-clearing price vector p agent i buys a random bundle X_i , expected payment is $E(p \cdot X_i)$ (note that $p \cdot X_i$ can exceed the budget for some X_i), payoff is $E(V(X_i)) - E(p \cdot X_i)$. Expectations are taken over some probability distribution over bundles.

Need to show structure of agents' random bundles at equilibrium. Taking k to be the index of a bundle, each agent i chooses z_k to solve

$$\max \sum_k z_k (V_i(x_k) - p \cdot x_k)$$

subject to:
$$z_k \geq 0$$
, $\sum z_k = 1$, and $\sum_k z_k \cdot p \cdot x_k \leq b_i$.

Dual variables are $\alpha_i \geq 0, \omega_i \geq 0$, by dual feasibility and complementary slackness

$$\alpha + \omega a_k \le V_i(x_k) - p \cdot x_k \quad \forall k$$
; and with equality when $z_k > 0$.

Bundle x_k with +ve prob. z_k is in $\arg\max_k\{(V_i(x_k)-(p+\omega_i\cdot p)\cdot x_k)\}$ for some $\omega_i\geq 0$.

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- A binary polytope is the convex hull of a finite set of (0,1)-vectors.
- A binary polytope is *special* if the edges have at most 2 non-zero coordinates and they are of opposite signs.
- Since valuations satisfy the substitutes condition, $conv(D_i(p))$ is a special polytope Q_i (Theorem 4.1 in Nguyen and Vohra). Note that with single-copy demand Q_i is the *demand complex cell* of Baldwin and Klemperer (2019).
- A face of a convex polytope is any intersection of the polytope with a halfspace such that none of the interior points of the polytope lie on the boundary of the halfspace.
- A face containing *x* is *minimal* if there is no other face with a lower dimension containing *x*.

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- Denoting the "average" bundle is $y_i = E(X_i)$, consider an "expected equilibrium" in which expected budget constraints are met $(p \cdot y_i \leq b_i)$ and markets clear in expectation $(\sum_i y_i = s)$.
- When $y_i \in \mathcal{Q}_i$, Gul et al. (2019) show that such an "expected" equilibrium can be implemented as a lottery over allocations.
- Nguyen and Vohra (2022) show how to round capacity to ensure that markets clear ex post, but have no budget constraints.
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• We need to round each y_i to a vertex x_i of Q_i with minimal violations.

4a Solve this linear program to obtain a corner solution

$$\min \mathbf{c} \cdot \left(\sum_{i \in N} z_i\right) \text{subject to:} \tag{1}$$

$$z_1,..,z_n \in \mathcal{Q}_1 \times ... \times \mathcal{Q}_n;$$
 (2)

$$\left(\sum_{i \in N} z_i\right)_j = s_j \text{ for every good } j \tag{3}$$

$$\mathbf{p} \cdot \mathbf{z}_i \le \mathbf{b}_i$$
 for every agent i (4)

4b Let $Q' = Q'_1 \times ... \times Q'_n$ be the minimal faces that contain that solution.

- If Q' is a vertex then done.
- Else, fixing a t > 0, drop a binding budget constraint with at most $2 + \lfloor 2t \rfloor$ coordinates with fractional values or supply constraints that contains at most $1 + \lfloor \frac{2}{t} \rfloor$, coordinates with fractional values. Return to step 4a with Q'.

Lemma

Such a constraint in step 4b exists.

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Definition

- Fact 1 For $x \in \mathcal{Q}$, let \mathcal{Q}' be the minimal face of \mathcal{Q} containing x. A coordinate i is free w.r.t \mathcal{Q}' iff $0 < x_i < 1$.
- Fact 2 Let x be corner point of $Q \cap \{Ax = b\}$. Let Q' be the minimal face of Q containing x, then the dimension of Q' is at most the number of constraints in $\{Ax = b\}$.
- Fact 3 Let \mathcal{Q} be a binary polytope with edges having at most 2 non-zero coordinates, then the number of free coordinates w.r.t \mathcal{Q} is at most $2 \dim(\mathcal{Q})$.

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- Using Fact 3. Each edge of Q' has at most 2 non-zero coordinates. If the dimension of Q' is d, then the number of free coordinates w.r.t Q' is at most 2d.
- Using Fact 2, the dimension of \mathcal{Q}' is at most the number of binding budget (n_2) and supply constraints (n_1) that has not been dropped. Therefore, # free coordinates $\leq 2(n_1+n_2)$. So, for example, setting $t=2\dots$ If $n_1>2n_2$, then # free coordinates $< 2(n_1+n_1/2)=3n_1$, by pigeonhole principle, there is 1 supply constraint with at most 2 free coordinates. If $n_1\leq 2n_2$, then # free coordinates $\leq 2(2n_2+n_2)=6n_2$, by pigeonhole principle, there is 1 budget constraint with at most 6 free coordinates.
- Using Fact 1, we convert these constraint violations into size violations.
- More generally, we can compare n_1 with tn_2 to get the trade-off between the violation of capacity and budget constraint and to obtain the general result.

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Thank you!

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