

# Concurrent Sylvester Solver

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## CHAPTER 1

# **Introduction**



## CHAPTER 2

### Invariants for bilinear tensors

The following intrinsics are specialized for tensors of valence 3, but equivalent intrinsics for general tensors are presented in the proceeding subsection.

**AdjointAlgebra(t) : TenSpcElt -> AlgMat**

Returns the adjoint  $\ast$ -algebra of the given Hermitian bilinear map  $t$ , represented on  $\text{End}(U_2)$ . This is using algorithms from STARALGE, see the **AdjointAlgebra** intrinsic in [\[?BW:StarAlge\]](#). If the current version of STARALGE is not attached, the default MAGMA version will be used instead.

#### Example 2.1. AdjointAlge

Given the context of [\[?BW:isometry\]](#), we construct a tensor from a  $p$ -group and compute its adjoint algebra.

```
> G := SmallGroup(3^7, 7000);
> t := pCentralTensor(G);
> t;
Tensor of valence 3, U2 x U1 -> U0
U2 : Full Vector space of degree 4 over GF(3)
U1 : Full Vector space of degree 4 over GF(3)
U0 : Full Vector space of degree 3 over GF(3)
```

Unlike other intrinsics that compute invariants of tensors, **AdjointAlgebra** exploits the fact that  $t$  is Hermitian so that the adjoint algebra is faithfully represented on  $\text{End}(U_2) = \text{End}(U_1)$ .

```
> A := AdjointAlgebra(t);
> A;
Matrix Algebra of degree 4 and dimension 4 with 4 generators over GF(3)
> A.1;
[1 0 0 0]
[0 0 0 0]
[0 0 0 0]
[0 0 0 1]
```

Because  $A$  is constructed from algorithms in STARALGE, we can apply other algorithms from that package specifically dealing with the involution on  $A$ . See STARALGE [\[?BW:StarAlge\]](#) for descriptions of the intrinsics.

```
> RecognizeStarAlgebra(A);
true
> SimpleParameters(A);
[ <"symplectic", 2, 3> ]
> Star(A);
Mapping from: AlgMat: A to AlgMat: A given by a rule [no inverse]
```

**LeftNucleus(t) : TenSpcElt -> AlgMat**  
**op : BoolElt : false**

Returns the left nucleus of the bilinear map  $t$  as a subalgebra of  $\text{End}(U_2) \times \text{End}(U_0)$ . In previous versions of TensorSpace (and eMAGma), the left nucleus was returned as a subalgebra of  $\text{End}(U_2)^\circ \times \text{End}(U_0)^\circ$ . To enable this, set the optional argument **op** to **true**.

**MidNucleus(t) : TenSpcElt -> AlgMat**

Returns the mid nucleus of the bilinear map  $t$  as a subalgebra of  $\text{End}(U_2) \times \text{End}(U_1)^\circ$ .

`RightNucleus(t) : TenSpcElt -> AlgMat`

Returns the right nucleus of the bilinear map  $t$  as a subalgebra of  $\text{End}(U_1) \times \text{End}(U_0)$ .

### Example 2.2. GoingNuclear

We will verify a theorem from [?FMW:densors] and [?Wilson:LMR]: all the nuclei of a tensor embed into the derivation algebra. We construct the tensor given by  $(3 \times 4 \times 5)$ -matrix multiplication.

```
> K := Rationals();
> A := KMatrixSpace(K, 3, 4);
> B := KMatrixSpace(K, 4, 5);
> C := KMatrixSpace(K, 3, 5);
> F := func< x | x[1]*x[2] >;
> t := Tensor([A, B, C], F);
> t;
Tensor of valence 3, U2 x U1 -> U0
U2 : Full Vector space of degree 12 over Rational Field
U1 : Full Vector space of degree 20 over Rational Field
U0 : Full Vector space of degree 15 over Rational Field
```

Because matrix multiplication is associative, the left, middle, and right nuclei contain  $M_3(\mathbb{Q})$ ,  $M_4(\mathbb{Q})$ , and  $M_5(\mathbb{Q})$  respectively. In fact, the following computation shows that this is equality.

```
> L := LeftNucleus(t : op := true);
> M := MidNucleus(t);
> R := RightNucleus(t);
> Dimension(L), Dimension(M), Dimension(R);
9 16 25
> D := DerivationAlgebra(t);
> Dimension(D);
49
```

Now we will embed these nuclei into the derivation algebra of  $t$ .

```
> Omega := KMatrixSpace(K, 47, 47);
> Z1 := ZeroMatrix(K, 20, 20);
> L_L2, L2 := Induce(L, 2);
> L_L0, L0 := Induce(L, 0);
> embedL := map< L -> Omega | x :->
>   DiagonalJoin(<Transpose(x @ L_L2), Z1, Transpose(x @ L_L0)>) >;
>
> Z0 := ZeroMatrix(K, 15, 15);
> M_M2, M2 := Induce(M, 2);
> M_M1, M1 := Induce(M, 1);
> embedM := map< M -> Omega | x :->
>   DiagonalJoin(<x @ M_M2, -Transpose(x @ M_M1), Z0>) >;
>
> Z2 := ZeroMatrix(K, 12, 12);
> R_R1, R1 := Induce(R, 1);
> R_R0, R0 := Induce(R, 0);
> embedR := map< R -> Omega | x :->
>   DiagonalJoin(<Z2, x @ R_R1, x @ R_R0>) >;
>
> Random(Basis(L)) @ embedL in D;
true
> Random(Basis(M)) @ embedM in D;
true
> Random(Basis(R)) @ embedR in D;
```



```
true
```



## CHAPTER 3

### Invariants of general multilinear maps

The following functions can be used for general tensors.

```
Centroid(t) : TenSpcElt -> AlgMat
Centroid(t, A) : TenSpcElt, {RngIntElt} -> AlgMat
```

Returns the  $A$ -centroid of the tensor as a subalgebra of  $\prod_{a \in A} \text{End}(U_a)$ , where  $A \subseteq [1]$ . If no  $A$  is given, it is assumed that  $A = [1]$ . If  $t$  is contained in a category where coordinates  $a$  and  $b$  (also contained in  $A$ ) are fused together, then the corresponding operators on those coordinates will be equal.

#### Example 3.1. Centroid

The centroid  $C$  of a tensor  $t$  is the largest ring for which  $t$  is  $C$ -linear, see [FMW:densors, Theorem D]. To demonstrate this, we will construct the tensor given by multiplication of the splitting field of  $f(x) = x^4 - x^2 - 2$  over  $\mathbb{Q}$ . However, this field won't explicitly be given with the tensor data.

```
> A := MatrixAlgebra(Rationals(), 4);
> R<x> := PolynomialRing(Rationals());
> F := sub< A | A!1, CompanionMatrix(x^4-x^2-2) >;
> F;
Matrix Algebra of degree 4 with 2 generators over Rational Field
> t := Tensor(F);
> t;
Tensor of valence 3, U2 x U1 -> U0
U2 : Full Vector space of degree 4 over Rational Field
U1 : Full Vector space of degree 4 over Rational Field
U0 : Full Vector space of degree 4 over Rational Field
```

The centroid is the field  $\mathbb{Q}(\sqrt{2}, i)$ .

```
> C := Centroid(t);
> C;
Matrix Algebra of degree 12 with 4 generators over Rational Field
> sub< C | C.1 > eq C;
true
> forall{ c : c in Generators(C) | IsInvertible(c) };
true
> IsCommutative(C);
true
> MinimalPolynomial(C.1);
x^4 + 2*x^2 - 8
> Factorization(MinimalPolynomial(C.1));
[
  <x^2 - 2, 1>,
  <x^2 + 4, 1>
]
```

```
DerivationAlgebra(t) : TenSpcElt -> AlgMatLie
DerivationAlgebra(t, A) : TenSpcElt, {RngIntElt} -> AlgMatLie
```

Returns the  $A$ -derivation Lie algebra of the tensor as a Lie subalgebra of  $\prod_{a \in A} \text{End}(U_a)$ , where  $A \subseteq [1]$ . If no  $A$  is given, it is assumed that  $A = [1]$ . If  $t$  is contained in a category where coordinates  $a$  and  $b$  (also contained in  $A$ ) are fused together, then the corresponding operators on those coordinates will be equal.

`Nucleus(t, a, b) : TenSpcElt, RngIntElt, RngIntElt -> AlgMat`  
`Nucleus(t, A) : TenSpcElt, SetEnum -> AlgMat`

Returns the  $A$ -nucleus, for  $A = \{a, b\}$  ( $a \neq b$ ), of the tensor as a subalgebra of  $\text{End}(U_i) \times \text{End}(U_j)$ , where  $i = \max(a, b)$  and  $j = \min(a, b)$ . If  $j > 0$ , then replace  $\text{End}(U_j)$  with  $\text{End}(U_j)^\circ$ . If  $t$  is contained in a category where coordinates  $a$  and  $b$  are fused together, then the corresponding operators on those coordinates will not be forced to be equal.

### Example 3.2. RestrictDerivation

In a previous example, we embedded the nuclei of a tensor into the derivation algebra. For a tensor  $t : U_1 \times \cdots \times U_1 \rightarrow U_0$ , the derivation algebra is represented in  $\Omega = \prod_{a \in [1]} \mathfrak{gl}(U_a)$ . We will restrict the derivation algebra to  $\prod_{c \notin \{a, b\}} \mathfrak{gl}(U_c)$  for distinct  $a, b \in [1]$ . From [FMW:densors, Lemma 4.11], the kernel of this restriction is equal to  $\text{Nuc}_{\{a, b\}}(t)^\perp$ . We will just verify that the dimensions match.

We will construct a tensor given by matrix multiplication:

$$\mathbb{M}_{3 \times 4}(\mathbb{F}_2) \times \mathbb{M}_{4 \times 2}(\mathbb{F}_2) \times \mathbb{M}_{2 \times 2}(\mathbb{F}_2) \rightarrow \mathbb{M}_{3 \times 2}(\mathbb{F}_2).$$

```
> A := KMatrixSpace(GF(2), 3, 4);
> B := KMatrixSpace(GF(2), 4, 2);
> C := KMatrixSpace(GF(2), 2, 2);
> D := KMatrixSpace(GF(2), 3, 2);
> trip := func< x | x[1]*x[2]*x[3] >;
> t := Tensor([A, B, C, D], trip);
> t;
Tensor of valence 4, U3 x U2 x U1 -> U0
U3 : Full Vector space of degree 12 over GF(2)
U2 : Full Vector space of degree 8 over GF(2)
U1 : Full Vector space of degree 4 over GF(2)
U0 : Full Vector space of degree 6 over GF(2)
```

Now we will compute the derivation algebra of  $t$ . We choose  $a = 3$  and  $b = 2$ , so the  $\{3, 2\}$ -nucleus is  $\mathbb{M}_{4 \times 4}(\mathbb{F}_2)$ .

```
> D := DerivationAlgebra(t);
> Dimension(D);
32
> N32 := Nucleus(t, 3, 2);
> N32;
Matrix Algebra of degree 20 with 16 generators over GF(2)
```

To construct the restriction of  $\text{Der}(t)$  into  $\mathfrak{gl}(U_1) \times \mathfrak{gl}(U_0)$  we will use the `Induce` function.

```
> Omega_10 := KMatrixSpace(GF(2), 10, 10);
> D_vs := sub< KMatrixSpace(GF(2), 30, 30) | Basis(D) >;
> pi1, D1 := Induce(D, 1);
> pi0, D0 := Induce(D, 0);
> res := hom< D_vs -> Omega_10 |
>      [<x, DiagonalJoin(x @ pi1, x @ pi0)> : x in Basis(D)] >;
> res;
Mapping from: ModMatFld: D_vs to ModMatFld: Omega_10
> Kernel(res);
KMatrixSpace of 30 by 30 matrices and dimension 16 over GF(2)
```

`SelfAdjointAlgebra(t, a, b) : TenSpcElt, RngIntElt, RngIntElt -> ModMatFld`

Returns the self-adjoint elements of the  $ab$ -nucleus of  $t$  as a subspace of  $\text{End}(U_a)$ , with  $a, b \in [1]$  and  $a \neq b$ . It is not required that  $t$  be in a tensor category with coordinates  $a$  and  $b$  fused. Unlike other invariants associated to tensors, the self-adjoint algebra is not currently stored with the tensor.

`TensorOverCentroid(t) : TenSpcElt -> TenSpcElt, Hmtp`

If the given tensor  $t$  is framed by  $K$ -vector spaces, then the returned tensor is framed by  $E$ -vector spaces where  $E$  is the residue field of the centroid. The returned homotopism is an isotopism of the  $K$ -tensors. This only works if the centroid of  $t$  is a finite commutative local ring. We employ the algorithms developed by Brooksbank and Wilson [[?BW:Module-iso](#)] to efficiently determine if a matrix algebra is cyclic, see Appendix ??.

### Example 3.3. CentroidUnipotent

In the context of groups, centroids can be used to recover an underlying field of a matrix group, even if the given group is not input as such. Here we will construct the exponent- $p$  central tensor of the Sylow 2-subgroup of  $\text{GL}(3, \text{GF}(2^{10}))$ . We will not print the `GrpPC` version of this group as the number of relations is very large.

```
> U := ClassicalSylow(GL(3, 2^10), 2);
> U.3;
[      1      $.1^2      0]
[      0      1      0]
[      0      0      1]
> G := PCPresentation(UnipotentMatrixGroup(U));
> #G eq 2^30;
true
> t := pCentralTensor(G);
> t;
Tensor of valence 3, U2 x U1 -> U0
U2 : Full Vector space of degree 20 over GF(2)
U1 : Full Vector space of degree 20 over GF(2)
U0 : Full Vector space of degree 10 over GF(2)
```

Even though our tensor right now is  $\mathbb{F}_2^{20} \times \mathbb{F}_2^{20} \rightarrow \mathbb{F}_2^{10}$ , we know it is the 2-dimensional alternating form over  $\text{GF}(2^{10})$ . We will construct the centroid, and then rewrite our tensor over the centroid to get the tensor we expect.

```
> C := Centroid(t);
> C;
Matrix Algebra of degree 50 and dimension 10 with 1 generator over GF(2)
> IsCyclic(C) and IsSimple(C);
true
> s := TensorOverCentroid(t);
> s;
Tensor of valence 3, U2 x U1 -> U0
U2 : Full Vector space of degree 2 over GF(2^10)
U1 : Full Vector space of degree 2 over GF(2^10)
U0 : Full Vector space of degree 1 over GF(2^10)
```



## Bibliography





## Intrinsics

AdjointAlgebra, [3](#)

Centroid  
  tensor, [7](#)

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