

<http://cs.nyu.edu/courses/spring15/CSCI-GA.2250-001/labs/lab2/>

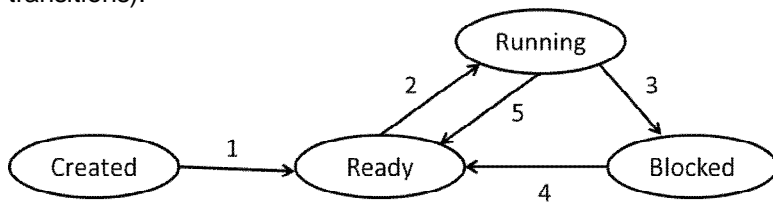
You are to implement a Scheduler in C, C++ (not Java) and submit the **source** code, which we will compile and run. Both are to be delivered to the TA as source code only (please don't submit inputs and outputs, our mailbox is already full).

In this lab we explore the effects of different scheduling policies discussed in class on a set of processes executing on a system. The system is to be implemented as a Discrete Event Simulation (DES) (http://en.wikipedia.org/wiki/Discrete_event_simulation). In discrete-event simulation, the operation of a system is represented as a chronological sequence of events. Each event occurs at an instant in time and marks a change of state in the system. This implies that the system progresses in time through defining and executing the events (state transitions) and by progressing time discretely between the events as opposed to incrementing time continuously (e.g. don't do "sim_time++").

A process is characterized by 4 parameters:

Arrival Time (AT), Total CPU Time (TC), CPU Burst (CB) and IO Burst (IO).

Each process follows the following state diagram that should be used to guide you in defining the events (state transitions):



Initially when a process arrives at the system it is put into CREATED mode. Both the CPU and the IO bursts are statistically defined. When a process is scheduled (becomes RUNNING (transition 2)) the CPU burst is defined as a random number between $[0, CB]$. If the remaining execution time is smaller than the random number chosen, reduce the random number to the remaining execution time. When a process finishes its current CPU burst (assuming it has not yet reached its total CPU time), it enters into a period of IO (aka BLOCKED) (transition 3) at which point the IO burst is defined as a random number between $[0, IO]$. If the previous CPU burst was not yet exhausted due to preemption, then no new CPU burst has to be computed yet in transition 5.

Note, you are not implementing this as a multi-program or multi-threaded application. From the DES a process is simply an object that goes through discrete state transitions.

We make a few simplifications:

- (a) all time is based on integers not float, hence nothing will happen or has to be simulated between integer numbers;
- (b) to enforce a uniform repeatable behavior, a file with random numbers is provided (see website) that your program must read in and use (note the first line defines the count of random numbers in the file) a random number is then created by using:
`"int myrandom(int burst) { return 1 + (randvals[ofs] % burst); }"`

You should increase ofs with each invocation and **wrap around** when you run out of numbers in the file/array. It is therefore important that you call the random function only when you have to, namely for transitions 1 and 3 (with noted exceptions) and the initial assignment of the static priority.

- (c) IOs are independent from each other, i.e. they can commensurate concurrently without affecting each others IO burst time.

The input file provides a separate process specification (see above) in each line: AT TC CB IO

You can make the assumption that the input file is well formed and that the ATs are not decreasing. So no fancy parsing is required. It is possible that multiple processes have the same arrival times. Then the order at which they are presented to the system is based on the order they appear in the file. Simply, Create a process start

event for all processes in the input file and enter these events into the event queue. Then and only then start the event simulation. Naturally, when the even queue is empty the simulation is completed.

The scheduling algorithms to be simulated are:

FCFS, LCFS, SJF, RR (RoundRobin), and PRIO (PriorityScheduler). In RR & PRIO your program should accept the quantum as an input (see below *"Execution and Invocation Format"*). The context switching overhead is "0".

You have to implement the scheduler as "objects" without replicating the event simulation infrastructure for each case, i.e. you define one interface to the scheduler/dispatcher (e.g. put_event/get_event) and implement the schedulers using object oriented programming. The proper "scheduler object" is selected at program starttime based on the "-s" parameter. The rest of the simulation must stay the same. The code must be properly documented. When reading in the process specification, assign a static_priority to the process using myrandom(4) (see above) which will select a priority between 1..4. A process's dynamic priority is defined between [0 .. (static_priority-1)]. With every quantum expiration the dynamic priority decreases by one. When "-1" is reached the prio is reset to (static_priority-1). Please do this for all schedulers though it only has implications for the PRIO scheduler as all other schedulers do not take priority into account. However uniformly calculating this will enable a simpler and scheduler independent state transition implementation.

A few things you need to pay attention to:

Round Robin: you should only regenerate a new CPU burst, when the current one has expired.

SJF: schedule is based on the shortest remaining execution time, not shortest CPU burst.

PRIO: same as Round Robin plus: the scheduler has exactly 4 priority levels [0..3], 3 the highest. Please use the concept of an active and an expired queue as discussed in class. When "-1" is reached the process's dynamic priority is reset to (static_priority-1) and it is enqueue into the expired queue. When the active queue is empty, active and expired are switched.

Output:

At the end of the program you should print the following information and the example outputs on the web provide the proper expected formatting (including precision); this is necessary to automate the results checking; all required output should go to the console (stdout).

- a) Scheduler information (which scheduler algorithm and if RR the quantum)
- b) Per process information (see below):
for each process (assume processes start with pid=0), the correct desired format is shown below:
pid: AT TC CB IO PRIO | FT TT IT CW
FT: Finishing time
TT: Turnaround time (finishing time - AT)
IT: I/O Time (time in blocked state)
PRIO: static priority assigned to the process (note this only has meaning in PRIO case)
- c) CW: CPU Waiting time (time in Ready state)
- d) Summary Information - Finally print a summary for the simulation:
Finishing time of the last event (i.e. the last process finished execution)
CPU utilization (i.e. percentage (0.0 – 100.0) of time at least one process is running)
IO utilization (i.e. percentage (0.0 – 100.0) of time at least one process is performing IO)
Average turnaround time among processes
Average cpu waiting time among processes
Throughput of number processes per 100 time units

CPU / IO utilizations and throughput are computed from time=0 till the finishing time.

Example:

```
FCFS
0000:      0  100   10   10 0 |  223  223  123   0
0001:    500  100   20   10 0 |  638  138   38   0
```

SUM: 638 31.35 25.24 180.50 0.00 0.313

You must **strictly** adhere to this format. The programs results will be graded by a testing harness that uses "diff -b". In particular you must pay attention to separate the tokens and to the rounding. In the past we have noticed that different runtimes (C vs. C++) use different rounding. For instance 1/3 was rounded to 0.334 in one environment vs. 0.333 in the other (similar 0.666 should be rounded to 0.667). Use double (instead of float) variables where non-integer computation occurs. See *outformat.c* in assignment file. In C++ you must specify the precision and the rounding behavior.

If in doubt, here is a small C program (gcc) to test your behavior (you can transfer to C++ and verify):

```
#include <stdio.h>

main()
{
    double a,b;
    a = 1.0/3.0;
    b = 2.0/3.0;
    printf("%.2lf %.2lf\n", a, b);
    printf("%.3lf %.3lf\n", a, b);
}
```

Should produce the following output

0.33 0.67
0.333 0.667

Deterministic Behavior:

There will be scenarios where events will have the same time stamp and you **must** follow these rules to break the ties in order to create consistent behavior:

- (a) On the same process: termination takes precedence over scheduling the next IO burst over preempting the process on quantum expiration
- (b) Processes with the same arrival time should be entered into the ready queue in the order of their occurrence in the input file.
- (c) Events with the same time stamp (e.g. IO completing at time X for process 1 and cpu burst expiring at time X for process 2) should be processed in the order they were generated, i.e. if the IO start event (process 1 blocked event) occurred before the event that made process 2 running (naturally has to be) then the IO event should be processed first. If two IO bursts expire at the same time, then first process the one that was generated earlier.
- (d) You must process all events at a given time stamp before invoking the scheduler/dispatcher.

Not following these rules implies that fetching the next random number will be out of order and a different event sequence will be generated. The net is that such situations are very difficult to debug (see for relieve further down).

ALSO:

Do not keep events in separate queues and then every time stamp figure which of the events might have fired. E.g. keeping different queues for when various I/O will complete vs a queue for when new processes will arrive etc. will result in incorrect behavior. There should be effectively two queues:

An event queue and the ready queue(s) implemented inside the scheduler.

Submitting the lab: please submit to your assigned TA your source code and a makefile/README on how to build it.

Please, do **NOT** submit any input or output files (we already have them or will generate them)

Execution and Invocation Format:

Your program should follow the following invocation:

`<program> [-v] [-s<schedspec>] inputfile randfile`

Options should be able to be passed in any order. This is the way a good programmer will do that.

http://www.gnu.org/software/libc/manual/html_node/Example-of-Getopt.html

Test input files and the sample file with random numbers are on the website.

The scheduler specification is “-s [FLS | R<num> | P<num>]”, where F=FCFS, L=LCFS, S=SJF and R10 and P10 are RR and PRIO with quantum 10. (e.g. “./sched -v -sR10”). Supporting this parameter is required.

The -v option stands for verbose and should print out some tracing information that allows one to follow the state transition. Though this is **not** mandatory, it is highly suggested you build this into your program to allow you to follow the state transition and to verify the program. I include samples from my tracing for some inputs. Matching my format will allow you to run diffs and identify why results and where the results don't match up.

Two scripts “runit.sh” and “diffit.sh” are provided that will allow you to simulate the grading process. “runit.sh” will generate the entire output files and “diffit.sh” will compare with the outputs supplied. SEE <README.txt>

Please ensure the following:

- (a) The input and randfile must accept any path and should not assume a specific location relative to the code or executable.
- (b) All output must go to the console (due to the harness testing)
- (c) **All code/grading will be executed on machine <energon1.cims.nyu.edu>** to which you can log in using “ssh <userid>@energon1.cims.nyu.edu”. You should have an account by default, but you might have to tunnel through access.cims.nyu.edu.

This is the only way we can guarantee that we execute the right version of compiler (C/C++). It is your responsibility to test your code on the target machine. Note if you use latest C++ make sure it works on energon. If not likely you need to use a higher compiler. Energon provides gcc48 and g++48 (also 49).

If the code does not compile or does not run or does not allow any path (relative or absolute), the code will be returned with appropriate score reduction and additional reduction for the resulting delays.

As always, if you detect errors in the sample inputs and outputs, let me know immediately so I can verify and correct if necessary.

Explanation of the verbose output:

Two examples of an event in my trace

Example 1:

57 0 12: BLOCK -> READY

At timestamp 57 process 0 is going from BLOCKED into READY state. The process has been in its current state for 12 units (hence it must have been BLOCKED at time 45).

Example 2:

42 2 7: RUNNG -> BLOCK ib=3 rem=77

At time unit 42 the transition for process 2 to BLOCKED state is executed.

It was in RUNNING state since time timeunit 35.

The IO burst created is ib=3 and there remains 77 time units (rem=77) left for executing this job.

By providing this extended output you will be able to create a detailed trace for your execution and compare it to the reference and identify where you start to differ. At a point of difference you should see which rule potentially was deployed that choose a different job/event in the reference vs. your program.