$$\nabla \cdot \mathbf{D} = \rho$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

GPU Programming in Computational Electromagnetics

Yunlong Lian
@algorithmx

Outline

- Computational electromagnetics algorithms
 - Finite-Difference Time-Domain (FDTD)
 - Rigorous Coupled-Wave Analysis (RCWA)
 - Finite-Element Method (FEM)
- Optimization of package RigorousCoupledWaveAnalysis.jl

- Classification
 - Space
 - · differential equations
 - · integral equations
 - . Time
 - time domain discretization
 - frequency domain

- · Numerical solution of the Maxwell differential equations
 - Time domain
 - Uniform spatial discretization
 - Finite-Difference Time-Domain (FDTD)
 - · Adaptive spatial discretization
 - Time-Domain Finite-Element Method (TDFEM)

- Numerical solution of the Maxwell differential equations
 - Frequency domain
 - Static (zero frequency)
 - Finite-Element Method (FEM)
 - Time-harmonic (single frequency)
 - Rigorous Coupled-Wave Analysis (RCWA)

- Numerical solution of the Maxwell *integral* equations
 - Boundary-Element Method (BEM)
 - Method of Moments (MoM)
 - ...

Finite-Element Method (FEM)

- Noticeable open-source projects
 - Netgen/NGSolve: https://ngsolve.org/
 - FEniCSx: https://fenicsproject.org/
 - · libMesh: http://libmesh.github.io/
 - FreeFEM: https://freefem.org/
- Many commercial softwares
 - · COMSOL
 - . ANSYS

Finite-Element Method (FEM)

- Basic idea: approximate field in continium by values on finite elements (via Galerkin method)
 - . Field \rightarrow vector
 - Differential operator \rightarrow linear operator
 - Boundary condition \rightarrow constraints
- Special considerations for electromagnetic field and Maxwell equations
 - Vector field

Finite-Element Method (FEM)

- Technical challenges and potential GPU accelerations
 - Mesh generation
 - Mesh quality control
 - Sparse solver

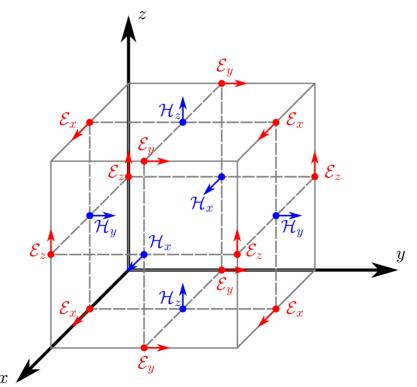
Finite-Difference Time-Domain (FDTD)

- Noticeable open-source projects
 - . gprMax : https://github.com/gprMax/gprMax
 - mumax3: http://mumax.github.io/
 - Python 3D FDTD Simulator: https://github.com/flaport/fdtd
 - Meep: https://github.com/NanoComp/meep
 - Tidy3D (commercial, FlexCompute Inc.): https://github.com/flexcompute/tidy3d

Finite-Difference Time-Domain (FDTD)

Straightforward discretization of time dependent Maxwell equation

· Yee lattice



http://opticaltweezers.org/chapter-6-computational-methods/667-2/

Finite-Difference Time-Domain (FDTD)

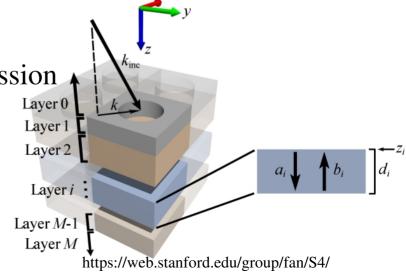
- Technical challenges and potential GPU accelerations
 - Memory cost cannot be reduced
 - Memory access patterns in updating the Yee lattice
 - Grid communications for parallelized algorithm

Rigorous Coupled-Wave Analysis (RCWA)

- Noticeable open-source projects
 - S4, or Stanford Stratified Structure Solver: https://github.com/victorliu/S4
 - GRCWA: https://github.com/weiliangjinca/grcwa
 - EMPossible course: https://github.com/zhaonat/Rigorous-Coupled-Wave-Analysis
 - Jordan Edmunds: https://github.com/edmundsj/RCWA
 - RigorousCoupledWaveAnalysis.jl: https://github.com/jonschlipf/RigorousCoupledWaveAnalysis.jl

Rigorous Coupled-Wave Analysis (RCWA)

- Enhanced Transmission Matrix algorithm by Moharam
 - major steps
 - partition the film into layers
 - perform layerwise 2D Fourier transform
 - calculate the wave amplitudes
 - along the propagation, for transmission
 - · backwards, for reflection
 - collect results



Rigorous Coupled-Wave Analysis (RCWA)

- Technical challenges and potential GPU accelerations
 - Accuracy vs efficiency: N = FT orders, $O(N^6)$ complexity, eigen solver $O(M^3)$ matrix dimension $O(N^2)$ by $O(N^2)$
 - Conformity in description of shapes
 - Multiple films on curved surface

Experiment: RCWA

Experiment: RCWA

- . Motivation
 - Wide range of applications
 - Nanophotonics (academic)
 - Optical Critical Dimension (OCD) for process control in semiconductor manufacturing (industrial)
 - RCWA has to be fast
- Use Julia and CUDA.jl
- Starting point
 - https://github.com/jonschlipf/RigorousCoupledWaveAnalysis.jl
 - Rigorous coupled-wave analysis of a multi-layered plasmonic integrated refractive index sensor, Opt. Express 29, 36201-36210 (2021)
- Project GitHub repository

Why coding with Julia and CUDA.jl?

- Features of Julia programming language
 - garbage collection
 - · array 1-based
 - support multiple dispatch and meta-programming
 - convinient profiling (@profview + VSCode)
- Features of CUDA.jl
 - using Julia syntax and grammar to write, compile and run CUDA kernels
 - · easy memory management
 - no loss of performance
 - requires experience in both Julia and CUDA C programming (to understand error messages)

Why coding with Julia and CUDA.jl?

Julia code for convolution kernel (zero padding, same size)

```
gaussian filter(n, 0) = [floor(255*exp(-(i^2+j^2)/(0^2))) for i=-(n÷2):(n÷2),j=-(n÷2):(n÷2)]
           using CUDA 🗸
                                                                                                                                                                                         dims = (8000, 4000) | (8000, 4000)
           function convolve(
                                                                                                                                                                                        nGF = 31 | 31
                     source, destination,
                                                                                                                                                                                                      = CuArray( qaussian filter(nGF, 8.0) .|> Int64 ) | 31×31 CuArray{Int64 2, CUDA.Mem.De
  5
                     filter, filter norm::Int64,
                                                                                                                                                                                         sumGF = sum(Array(GF)) 50195
                     dim1 s::Int64, dim2 s::Int64,
  6
                                                                                                                                                                              37
                     dim1 f::Int64, dim2 f::Int64
                                                                                                                                                                                        src = rand(0:255, dims) . > Int64 | 8000×4000 Matrix{Int64}:
  8
                                                                                                                                                                                        dst = zeros(Int64, dims) | 8000×4000 Matrix{Int64}:
                     # Julia array is 1-based
  9
                                                                                                                                                                                        cu src = CuArray(src) | 8000×4000 CuArray{Int64, 2, CUDA.Mem.DeviceBuffer}
                     i = (blockIdx().x-1) * blockDim().x + threadIdx().x
10
                                                                                                                                                                                        cu dst = CuArray(dst) | 8000×4000 CuArray{Int64, 2, CUDA.Mem.DeviceBuffer}:
                     j = (blockIdx().y-1) * blockDim().y + threadIdx().y
11
                     if i <= dim1 s && i <= dim2 s
12
                                                                                                                                                                                        t = 32 | 32
                             x0 = dim1 f \div 2 + 1
13
                                                                                                                                                                                         @time @cuda threads=(t,t) blocks=(dims[1]÷t+1,dims[2]÷t+1) convolve(
                             v0 = dim2 f \div 2 + 1
14
                                                                                                                                                                                                  cu src, cu dst, GF, sumGF, dims[1], dims[2], nGF, nGF) | CUDA.HostKernel{typeof(convolve
                             p0 = max(1+x0-i,1)
15
                             p1 = min(dim1 s+x0-i,dim1 f)
16
                             q0 = max(1+v0-i,1)
17
                             q1 = min(dim2 s+y0-j,dim2 f)
18
                              s = 0
19
                             for p = p0:p1
20
21
                                       for q = q0:q1
                                               @inbounds s += source[i+p-x0,j+q-y0] * filter[p,q]
                                                                                                                                                                             DUTPUT
                                                                                                                                                                                                                  DEBUG CONSOLE
22
23
                                      end
24
                             destination[i,j] = (s ÷ filter norm)
25
                                                                                                                                                                                0.000066 seconds (45 allocations: 2.234 KiB)
                                                                                                                                                                             CUDA.HostKernel{typeof(convolve), Tuple{CuDeviceMatrix{Int64, 1}, CuDeviceMatrix{Int64, 1}, CuDe
26
                     end
                                                                                                                                                                             [nt64, Int64, Int64]}(convolve, CuFunction(Ptr{Nothing} @0x0000000006462890, CuModule(Ptr{Nothing})
                     return
28
           end
```

Why coding with Julia and CUDA.jl?

- Julia code to call cuBLAS / cuSolver routines
 - Example 1
 - · CPU code : A * Y
 - GPU code : cuA * cuY |> Array
 - Example 2
 - \cdot CPU code : **A \ b**
 - GPU code : CuArray(A) \ CuArray(b) |> Array

Rigorous Coupled Wave Analysis.jl

- Enhanced Transmission Matrix (ETM) algorithm by Moharam [Moharam1995]
 - . Backward and forward iteration
 - Numerical stability (key contribution of the [Moharam1995] paper)
- RigorousCoupledWaveAnalysis.jl by Jon Schlipf
 - GitHub repo: https://github.com/jonschlipf/RigorousCoupledWaveAnalysis.jl
 - · Code is in good quality
 - Bottlenecks (identified with Julia profiling macro @profview)
 - #1: eigen(M) with **non-Hermitian M**
 - ==> cuSolver cannot help :-([need improvement on the algorithm level]
 - #2: A \ b via Lapack (solution of the linear equation A.x = b)
 - ==> Array(CuArray(A) \ CuArray(b)) via cuSolver [verified, 10x~100x speed up]

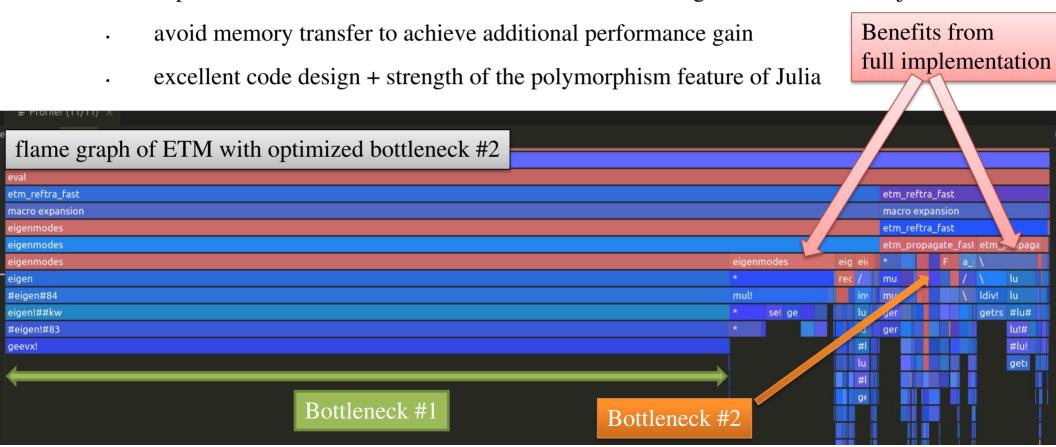
Rigorous Coupled Wave Analysis.jl

- Enable GPU acceleration with CUDA.jl
 - Install CUDA.jl into the package project: https://docs.julialang.org/en/v1/stdlib/Pkg/
 - . Minimal change leads to at least 10x performance gain for bottleneck #2

```
# 2. [forward iteration]
               # compute the reflected wave and the forward wave in the first layer
               # bottleneck
               \psi ref, \psi m1 = slicehalf( -cat([I; sup.V], F(em[1])*[em[1].X*(a[1]/b[1])*em[1].X;I], dims=2) \setminus ([I; -sup.V]*\psi in) )
                # 2. [forward iteration]
                # compute the reflected wave and the forward wave in the first layer
15
                # CUDA version : Array(CuArray(A) \ CuArray(b))
                wref.wm1 = slicehalf(
                     Array(CuArray(-cat([I;sup.V],F(em[1])*[em[1].X*(a[1]/b[1])*em[1].X;I],dims=2)) \setminus CuArray(([I;-sup.V]*\psiin))
               etm reftra fast():
                                                                              DO
                                                                                           etm reftra fast():
                8.315675 seconds (334 allocations: 394.104 MiB, 0.19% gc time)
                                                                                             1.641657 seconds (323 allocations: 85.186 MiB)
                2.548487 seconds (30.57 k allocations: 1.263 GiB, 1.41% qc time)
                                                                                             0.396935 seconds (14.41 k allocations: 277.851 MiB, 9.70% gc time)
               etm reftra():
                                                                                            etm reftra():
                8.519581 seconds (345 allocations: 394.104 MiB, 0.33% gc time)
                                                                                             1.541210 seconds (323 allocations: 85.186 MiB)
               26.735786 seconds (30.38 k allocations: 1.879 GiB, 0.90% gc time)
                                                                                             1.585677 seconds (14.24 k allocations: 414.954 MiB, 0.40% gc time)
                                                                                           julia> ∏
          P master* 🚓 🔘 🛭 🐧 0 🐔 🗎 make clean make build make run make all rm tests/*.o Pyth
```

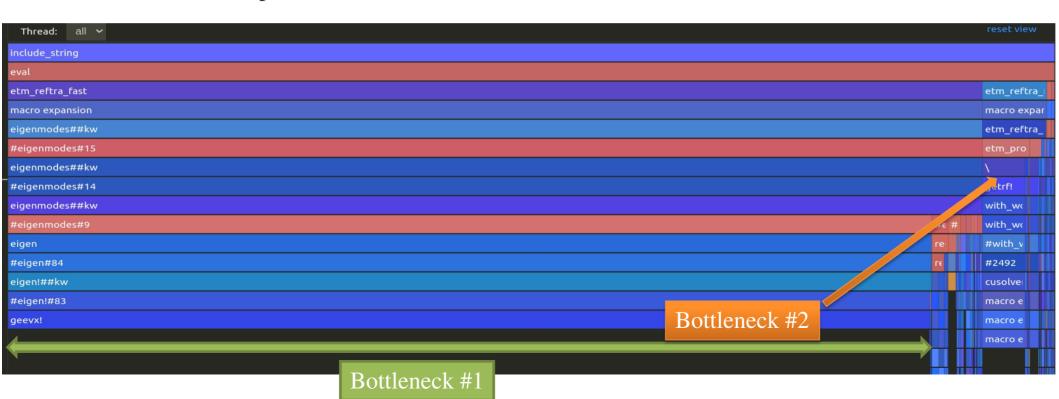
Rigorous Coupled Wave Analysis CUDA.jl

• Full implementation of the Enhanced Transmission Matrix algorithm with CUDA.jl



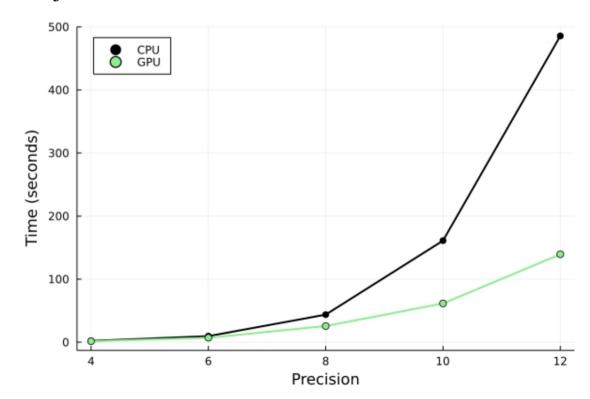
RigorousCoupledWaveAnalysisCUDA.jl

- Full implementation of the Enhanced Transmission Matrix algorithm with CUDA.jl
 - Result of optimization: Bottleneck#1 now takes 85% execution time (60% before)



Test

- Test for correctness: against CPU code
 - integrated in the package test/runtests.jl
- Overall performance gain:
- *nvprof



References / Useful materials

FEM

FDTD

RCWA

Summary

- Common algorithms in computational electromagnetics often faces unique technical challenges
- Paralellization with GPU can improve, but has limitations such as memory size and inter-node communication
- Parallelized RCWA algorithm can easily be implemented in Julia programming language, with the help of CUDA.jl package
- The performance gain is huge despite that only one of the two bottlenecks is resolved.