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# Modern Classical Physics

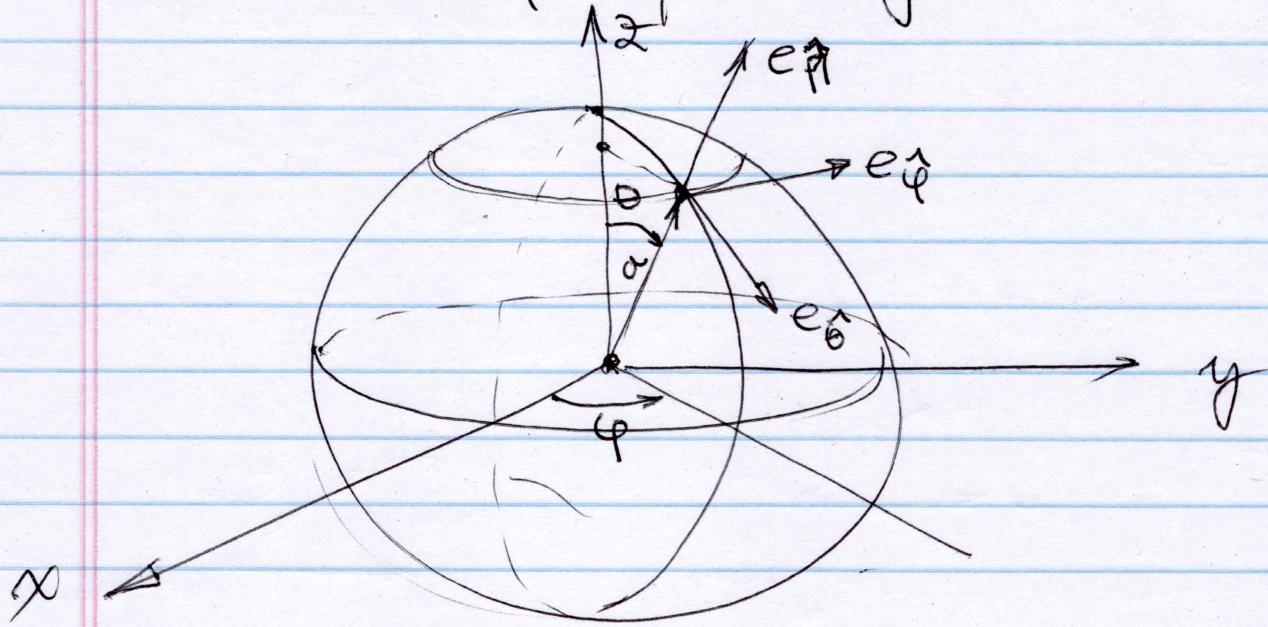
## (Thorne & Blandford)

### Exercise 1.11: Integral of vector field over sphere

Integrate the vector field  $A = 2\hat{e}_z$  over a sphere with radius  $a$ , centered at the origin of the Cartesian coordinate system (i.e., compute  $\int A \cdot d\Sigma$ ).

- a) Introduce spherical coordinates on the sphere, and construct the vectorial element,  $d\Sigma$ , using the two legs:  $a d\theta e_\theta$  and  $a \sin\theta d\varphi e_\varphi$ .

$e_\theta$  &  $e_\varphi$  are unit length vectors along the directions  $\theta$  &  $\varphi$ , respectively -



$(e_\theta, e_\varphi, e_z)$  spherical basis vectors  
(orthonormal basis) -

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Explain the factors  $a\cos\theta$  and  $a\sin\theta$  in the definition of the legs.

$e_{\theta}$  &  $e_{\varphi}$  are unit vectors tangent to the coordinate lines of  $\theta$  &  $\varphi$ , respectively.

Legs to construct the vectorial element,  $d\bar{S}$ .

$$\left\{ \begin{array}{l} A = \frac{\partial \bar{R}}{\partial \theta} d\theta = \left| \frac{\partial \bar{R}}{\partial \theta} \right| e_{\theta} d\theta \quad \& \\ B = \frac{\partial \bar{R}}{\partial \varphi} d\varphi = \left| \frac{\partial \bar{R}}{\partial \varphi} \right| e_{\varphi} d\varphi; \text{ but} \end{array} \right.$$

$$\bar{R} = x e_x + y e_y + z e_z$$

$$= (a\sin\theta\cos\varphi) e_x + (a\sin\theta\sin\varphi) e_y + a\cos\theta e_z$$

from which:

$$\left\{ \begin{array}{l} \frac{\partial \bar{R}}{\partial \theta} = (a\cos\theta\cos\varphi) e_x + (a\cos\theta\sin\varphi) e_y - a\sin\theta e_z \\ \frac{\partial \bar{R}}{\partial \varphi} = (-a\sin\theta\sin\varphi) e_x + (a\sin\theta\cos\varphi) e_y \end{array} \right.$$

We can now calculate the norms (lengths) of these two tangent vectors:

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$$\begin{aligned}
 \left| \frac{\partial \bar{R}}{\partial \theta} \right|^2 &= a^2 \cos^2 \theta \cos^2 \varphi + a^2 \cos^2 \theta \sin^2 \varphi + a^2 \sin^2 \theta \\
 &= a^2 \cos^2 \theta (\cos^2 \varphi + \sin^2 \varphi) + a^2 \sin^2 \theta \\
 &= a^2 (\cos^2 \theta + \sin^2 \theta) = a^2 ;
 \end{aligned}$$

$$\left| \frac{\partial \bar{R}}{\partial \theta} \right| = a.$$

Also,

$$\begin{aligned}
 \left| \frac{\partial \bar{R}}{\partial \varphi} \right|^2 &= a^2 \sin^2 \theta \sin^2 \varphi + a^2 \sin^2 \theta \cos^2 \varphi \\
 &= a^2 \sin^2 \theta (\sin^2 \varphi + \cos^2 \varphi) = a^2 \sin^2 \theta
 \end{aligned}$$

$$\left| \frac{\partial \bar{R}}{\partial \varphi} \right| = a \sin \theta$$

Consequently, the legs A & B are:

$$A = a \cos \theta e_{\hat{\theta}} \quad B = a \sin \theta \cos \varphi e_{\hat{\varphi}} \quad \checkmark$$

We can then construct the vectorial element  $d\Sigma$  as:

$$d\Sigma = A \times B = \epsilon(-, A, B).$$

$$= \epsilon(-, a \cos \theta e_{\hat{\theta}}, a \sin \theta \cos \varphi e_{\hat{\varphi}}).$$

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Due to the linearity of the Levi-Civita tensor,  $\epsilon$ , we can write:

$$d\Sigma = \epsilon(-, e_\theta, e_\varphi) a^2 \sin\theta dy d\theta \checkmark$$

b) Using  $z = a \cos\theta$  and

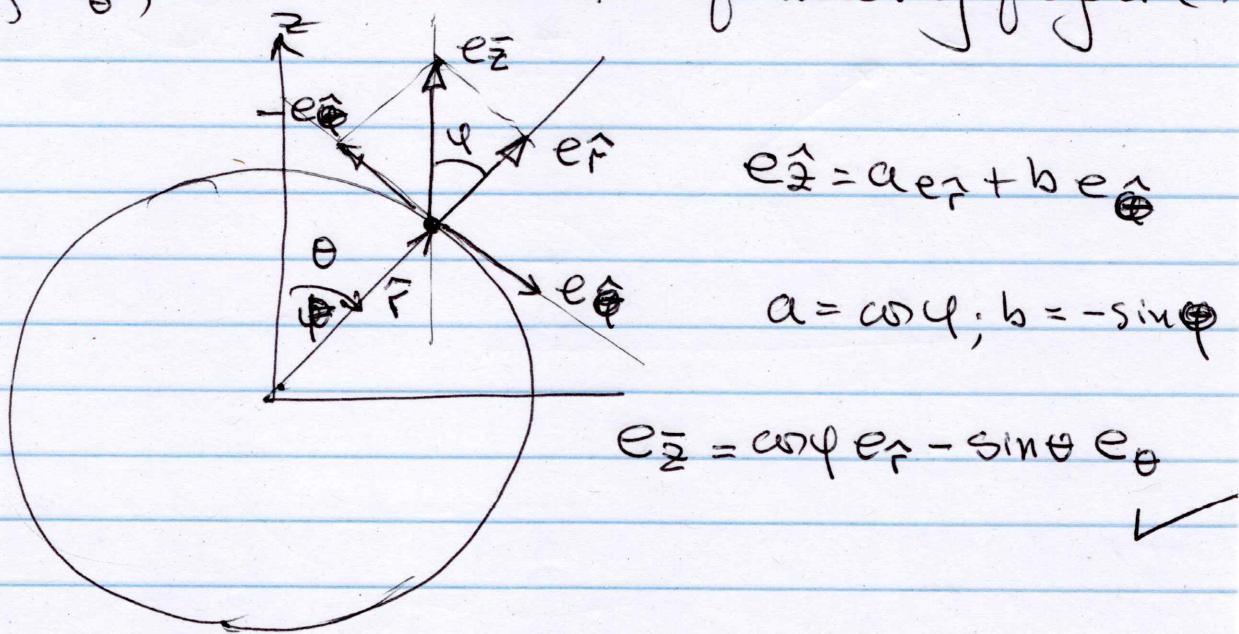
$$e_{\bar{z}} = \cos\theta e_{\hat{r}} - \sin\theta e_{\hat{\theta}},$$

Show that:

$$A \cdot d\Sigma = a \cos^2\theta \epsilon(e_{\hat{r}}, e_{\hat{\theta}}, e_{\varphi}) a^2 \sin\theta dy d\theta$$

Note:  $A = z e_{\bar{z}}$ . is the vector field here, not one of the legs used above-

To derive the expression of  $e_{\bar{z}}$  in terms of  $e_{\hat{r}}$  &  $e_{\hat{\theta}}$ , we can use the following figure.



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So that:

$$\begin{aligned} A \cdot \hat{e}_z &= a \cos \theta (\cos \theta \hat{e}_r - \sin \theta \hat{e}_\theta) \\ &= a \cos^2 \theta \hat{e}_r - a \cos \theta \sin \theta \hat{e}_\theta. \end{aligned}$$

Consequently:

$$A \cdot d\Sigma = (a \cos^2 \theta \hat{e}_r - a \cos \theta \sin \theta \hat{e}_\theta) \cdot$$

$$\begin{aligned} &\epsilon(-, \hat{e}_\theta, \hat{e}_\varphi) a^2 \sin \theta d\theta dy \\ &= a \cos^2 \theta \hat{e}_r \cdot \epsilon(-, \hat{e}_\theta, \hat{e}_\varphi) a^2 \sin \theta d\varphi dy \\ &- a \cos \theta \sin \theta \hat{e}_\theta \cdot \epsilon(-, \hat{e}_\theta, \hat{e}_\varphi) a^2 \sin \theta d\theta dy \end{aligned}$$

$$\text{Now: } \hat{e}_r \cdot \epsilon(-, \hat{e}_\theta, \hat{e}_\varphi) = \hat{e}_r \cdot (\hat{e}_\theta \times \hat{e}_\varphi)$$

$$= \epsilon(\hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi) = 1$$

and:

$$\begin{aligned} \hat{e}_\theta \cdot \epsilon(-, \hat{e}_\theta, \hat{e}_\varphi) &= \hat{e}_\theta \cdot (\hat{e}_\theta \times \hat{e}_\varphi) \\ &= \epsilon(\hat{e}_\theta, \hat{e}_\theta, \hat{e}_\varphi) = 0. \end{aligned}$$

Then:

$$A \cdot d\Sigma = a \cos^2 \theta \epsilon(\hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi) a^2 \sin \theta d\theta dy.$$

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c) Explain  $\epsilon(e_1^*, e_0^*, e_{\varphi}^*) = 1$ .

Since  $(e_1^*, e_0^*, e_{\varphi}^*)$  is an orthonormal, right-sided basis;  $\epsilon(e_1^*, e_0^*, e_{\varphi}^*)$  represents a positive, unit volume.

$$\epsilon(e_1^*, e_0^*, e_{\varphi}^*) = +1 \quad \checkmark$$

d) Perform the integral  $\int A \cdot d\Sigma$  over the entire sphere -

$$\begin{aligned} \int_{\Sigma} A \cdot d\Sigma &= \int_{\varphi=0}^{2\pi} d\varphi \int_{\theta=0}^{\pi} a^3 \sin^2 \theta \sin \theta d\theta \\ &= a^3 \int_{\varphi=0}^{2\pi} d\varphi \int_{\theta=0}^{\pi} \sin^2 \theta \sin \theta d\theta. \end{aligned}$$

It is easy to see that

$$\frac{d}{d\theta} \left( -\frac{1}{3} \sin^3 \theta \right) = \sin^2 \theta \sin \theta; \text{ so that,}$$

$$\int \sin^2 \theta \sin \theta d\theta = \frac{-1}{3} \sin^3 \theta + C.$$

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Consequently,

$$\int_{\varphi=0}^{\pi} \cos^2 \theta \sin \theta d\theta = -\frac{1}{3} \cos^3 \theta \Big|_0^{\pi} = \left(-\frac{1}{3}\right)(-1-1) = \frac{2}{3}$$

$$\therefore \int_{\Sigma} A \cdot d\Sigma = a^3 \int_{\varphi=0}^{2\pi} d\varphi \left(\frac{2}{3}\right) = \frac{2}{3} a^3 \varphi \Big|_0^{2\pi} = \frac{4}{3} \pi a^3$$

$$\int_{\Sigma} A \cdot d\Sigma = \frac{4}{3} \pi a^3$$

✓ Volume of sphere.