

HULL DETECTION BASED ON LARGEST EMPTY SECTOR ANGLE WITH APPLICATION TO ANALYSIS OF REALTIME MR IMAGES

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Hull Detection

Definition. Given a set of points X, the subset $S \subset X$ such that the polygon defined by the points in S contains all points in X, is called the hull of X.

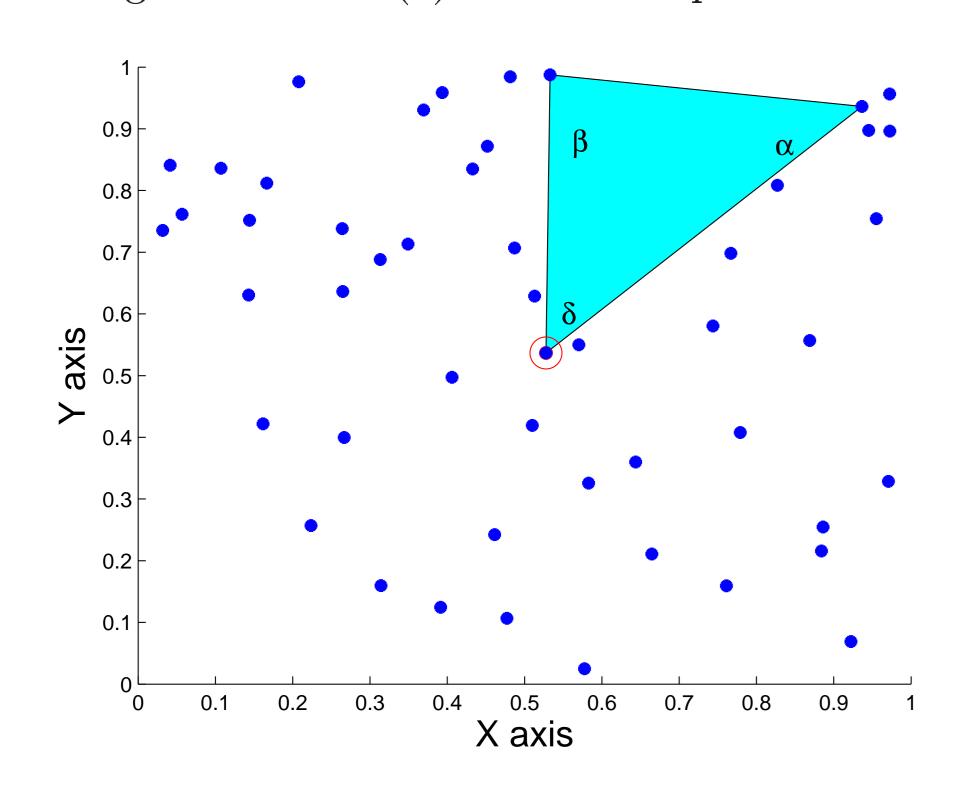
Hull for a set of points can be defined based on

- Convexity
- Minimum footprint/ area
- Shape templates

We define based on Largest Empty Sector Angle (LESA) criterion.

Largest Empty Sector Angle

The largest angular sector (δ) around a point x that is empty.

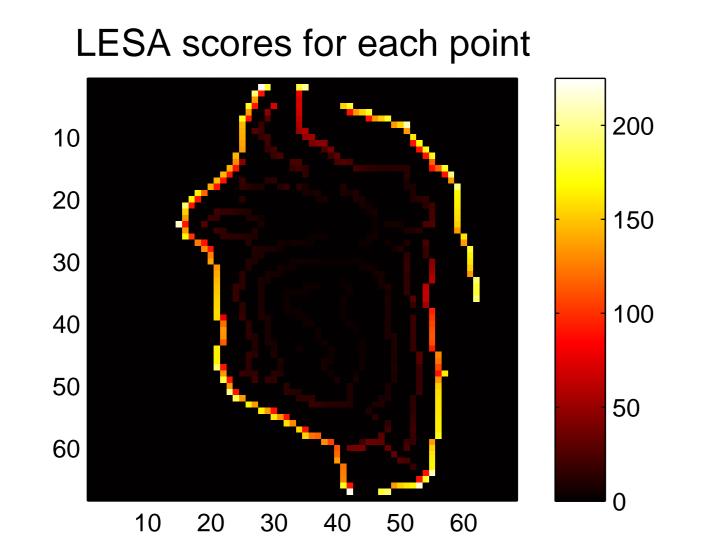


Suppose $\theta_i, i = 1 \cdots n - 1$ are the angles subtended by each point. $\max_{\alpha,\beta} \delta = |\alpha - \beta|$

s.t. $(\theta_i - \alpha)(\theta_i - \beta) \ge 0, \forall i = 1 \dots n-1$

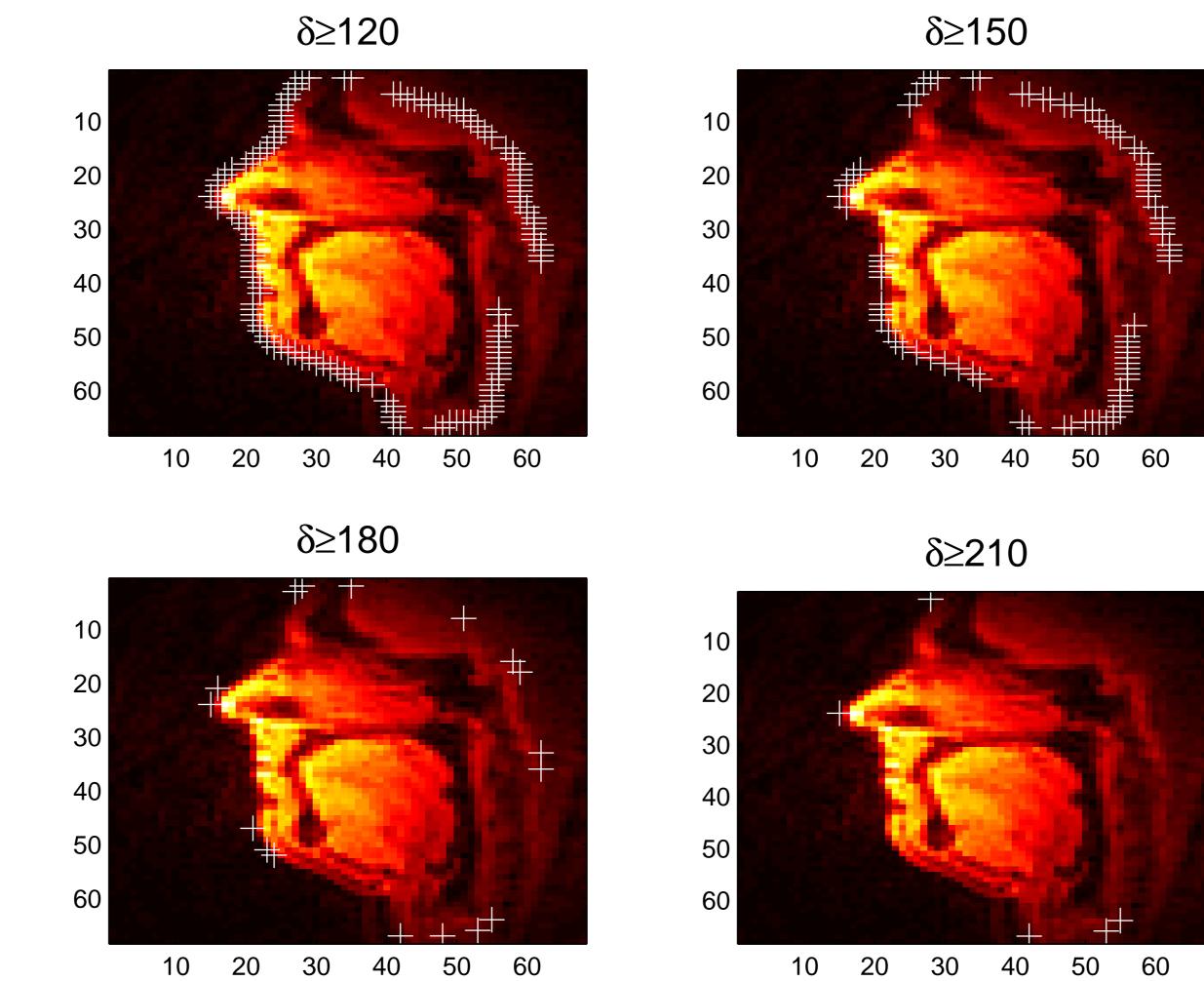
Example

Image with detected edge points 10 20 30 40



Geometry of the Hull

 $H(\theta) = \{x \mid x \in X, \delta(x) \ge \theta\}$



- It can be shown that $H(180^{\circ})$ is a convex hull.
- $H(\theta), \theta < 180^{\circ}$ is a hull of increasing convexity
- $H(\theta), \theta > 180^{\circ}$ is not a hull but highlight sharp points

Application to vocal tract realtime MR images

Data:

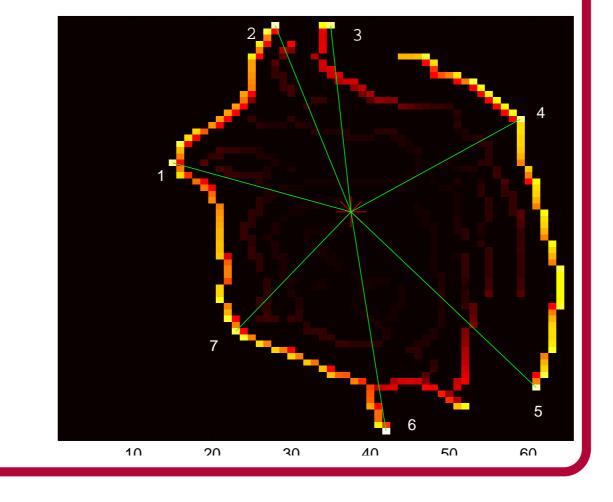
- The *USC-TIMIT* corpus comprising moving vocal tract images
- Common problem is the subject's **head motion**

Approach:

- Detect **nosetip** and **chin** as sharp points in rtMRI contour
- Estimate rotation and translation to correct for head motion

Algorithm:

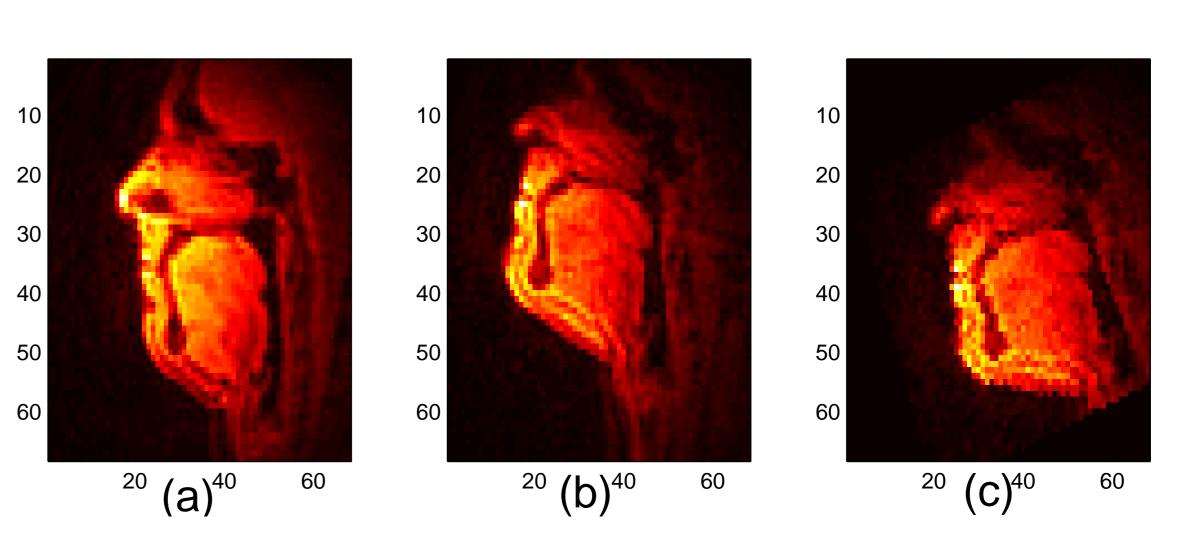
- $\delta(x) \ge 195^{\circ} \to H_1, H_2 \dots$
- Center of points in $H \to H_0$
- Sort by angle at H_0
- Choose nosetip and chin by sorting index



Nosetip and Chin Detection Tracking Tracking Nosetip and Chin Detection Tracking Nosetip Nosetip Nosetip Chin

Head motion correction

Check a demo of the algorithm at work.



a) First frame b)Frame with head movement c) Frame corrected for head movement **Head movement correction algorithm**

- Match nosetip points
- Estimate angle of rotation about matched nosetip points

Discussion and Future Work

- Chin point is on a non-rigid structure
- Vocal tract shape changes during head motion
- Use nosetip and chin to find other landmark points e.g. lips
- Direct adaptive tracking of the vocal tract

