

1.

$$\frac{\partial \phi}{\partial t} = \alpha \frac{\partial^2 \phi}{\partial x^2}$$

$$\phi = e^{-\alpha k^2 t} e^{ikx}$$

$$= G(k)$$

$$\frac{\phi_j^{n+1} - \phi_j^n}{\Delta t} = \alpha \frac{-\phi_{j+3}^n + 4\phi_{j+2}^n - 5\phi_{j+1}^n + 2\phi_j^n}{\Delta x^2}$$

$$\Rightarrow \phi_j^{n+1} = \phi_j^n + \underbrace{\frac{\alpha \Delta t}{\Delta x^2}}_r (-\phi_{j+3}^n + 4\phi_{j+2}^n - 5\phi_{j+1}^n + 2\phi_j^n)$$

$$\Rightarrow \phi_j^{n+1} = e^{ik\Delta x j} + r \left[-e^{ik\Delta x (j+3)} + 4e^{ik\Delta x (j+2)} - 5e^{ik\Delta x (j+1)} + 2e^{ik\Delta x j} \right]$$

$$= \left[1 + r (-e^{-ik\Delta x} + 4e^{ik\Delta x} - 5e^{ik\Delta x} + 2) \right] e^{ik\Delta x j}$$

$$= G(k) e^{ik\Delta x j}$$

it will be stable if $G(k) \leq 1$

which is not possible condition

2.

$$\frac{\partial u}{\partial t} = c \frac{\partial u}{\partial x}$$

$$\Rightarrow \frac{1}{\Delta t} [u_j^{n+1} - \frac{1}{2}(u_{j+1}^n + u_{j-1}^n)] = \frac{c}{2\Delta x} [u_{j+1}^n - u_{j-1}^n]$$

$$\Rightarrow u_j^{n+1} = \frac{c\Delta t}{2\Delta x} [u_{j+1}^n - u_{j-1}^n] + \frac{1}{2}(u_{j+1}^n + u_{j-1}^n)$$

$$= \left(\frac{c\Delta t}{2\Delta x} + \frac{1}{2} \right) (u_{j+1}^n + u_{j-1}^n)$$

$$= \left(\frac{c\Delta t}{\Delta x} + 1 \right) \left(\frac{u_{j+1}^n + u_{j-1}^n}{2} \right)$$

$\frac{c\Delta t}{\Delta x} < 1$