

Clase 14

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1 Tensores en variedades

$$T = t_{\nu_1, \dots, \nu_r}^{\mu_1, \dots, \mu_q} \frac{\partial}{\partial x^{\mu_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{\mu_q}} \otimes dx^{\nu_1} \otimes \dots \otimes dx^{\nu_r}$$

Tensor tipo (q, r)

$$\begin{aligned} T(\omega_1, \dots, \omega_q; V_1, \dots, V_r)(2, 3) &\rightarrow T(\omega_1, \omega_2; V_1, V_2, V_3) \\ (0, 1) &\rightarrow \omega(V) = \langle \omega | V \rangle = \omega_\mu V^\mu \end{aligned}$$

1.1 Ejemplos de tensores en fisica

Vector velocidad $(1, 0)$

$$v = v^i e_i, \quad v^i = \frac{dx^i}{dt}$$

Metrica $(0, 2)$

$$ds^2 = g_{ij} dx^i dx^j$$

1.2 Comportamiento de tensores ante mapeos

Sea f un mapa entre M y N .

$$\begin{aligned} (f_* V) &= W \in T_{f(p)} N \\ W^\alpha &= V^\beta \frac{\partial y^\alpha}{\partial x^\beta} \rightarrow \text{Mapeo de } V \text{ sobre } f \\ &\quad (f_* V) \text{ "Restriccion"} \end{aligned}$$

Ejemplo 1: Vamos a mapear $f : M \rightarrow N$ el vector $V = V^1 \frac{\partial}{\partial x^1} + V^2 \frac{\partial}{\partial x^2}$ con V^1, V^2 constantes. Vamos a usar las x para M y y para N .

$$\begin{aligned} f : (x^1, x^2) &\rightarrow (y^1, y^2, y^3) = (x^1, x^2, h(x^1, x^2)) \\ (f_* V) &= W^\alpha \frac{\partial}{\partial y^\alpha} = V^i \frac{\partial y^\alpha}{\partial x^i} \frac{\partial}{\partial y^\alpha} \\ \left(V^1 \frac{\partial y^\alpha}{\partial x^1} + V^2 \frac{\partial y^\alpha}{\partial x^2} \right) \frac{\partial}{\partial y^\alpha} &= \left(V^1 \frac{\partial y^1}{\partial x^1} \frac{\partial}{\partial y^1} + V^1 \frac{\partial y^2}{\partial x^1} \frac{\partial}{\partial y^2} + V^1 \frac{\partial y^3}{\partial x^1} \frac{\partial}{\partial y^3} \right) \\ &+ \left(V^2 \frac{\partial y^1}{\partial x^2} \frac{\partial}{\partial y^1} + V^2 \frac{\partial y^2}{\partial x^2} \frac{\partial}{\partial y^2} + V^2 \frac{\partial y^3}{\partial x^2} \frac{\partial}{\partial y^3} \right) = V^1 \left(\frac{\partial}{\partial y^1} + \frac{\partial h}{\partial x^1} \frac{\partial}{\partial y^2} \right) + V^2 \left(\frac{\partial}{\partial y^2} + \frac{\partial h}{\partial x^2} \frac{\partial}{\partial y^3} \right) \end{aligned}$$

Comportamiento de T ante mapeos

$$\begin{aligned}
W &= V^1 \frac{\partial}{\partial y^1} + V^2 \frac{\partial}{\partial y^2} + \left(V^1 \frac{\partial h}{\partial x^1} + V^2 \frac{\partial h}{\partial x^2} \right) \frac{\partial}{\partial y^3} \\
h &= (1 - (x^1)^2 - (x^2)^2)^{\frac{1}{2}} \\
\frac{\partial h}{\partial x^1} &= \frac{1}{2} \frac{1}{h} (-2x^1) = -\frac{x^1}{h} = -\frac{y^1}{y^3} \quad \frac{\partial h}{\partial x^2} = -\frac{y^2}{y^3} \\
W &= V^1 \frac{\partial}{\partial y^1} + V^2 \frac{\partial}{\partial y^2} - \frac{1}{y^3} (V^1 y^1 + V^2 y^2) \frac{\partial}{\partial y^3} \\
W &= \frac{\partial}{\partial y^1} + \frac{\partial}{\partial y^2} - \frac{1}{y^3} (y^1 + y^2) \frac{\partial}{\partial y^3} \\
x_{(1)} &= (0, \frac{1}{2}) \rightarrow W_{(1)} = \frac{\partial}{\partial y^1} + \frac{\partial}{\partial y^2} - \frac{1}{\sqrt{3/4}} \left(\frac{1}{2} \right) \frac{\partial}{\partial y^3} \\
x_{(2)} &= (\frac{1}{2}, 0) \rightarrow W_{(2)} = \frac{\partial}{\partial y^1} + \frac{\partial}{\partial y^2} - \frac{1}{\sqrt{3/4}} \left(\frac{1}{2} \right) \frac{\partial}{\partial y^3}
\end{aligned}$$

Podemos ver que $W_{(1)} = W_{(2)}$.

Ahora en el sentido contrario $f : M \rightarrow n \quad f^* : T_{f(P)}^* N \rightarrow T_P^* M$. A esto se le llama **pullback**.

$$\begin{array}{ccc}
\langle f^* \omega | V \rangle & = & \langle \omega | f_* V \rangle \\
\text{Definido en } M & & \text{Definido en } N
\end{array}$$

Componentes:

$$\begin{aligned}
\omega &= \omega_\alpha dy^\alpha \in T_{f(P)}^* N \\
(f^* \omega) &= \bar{\omega}_k dx^k \quad \bar{\omega} = ? \\
\text{Segun la definicion:} \\
\left\langle \bar{\omega}_k dx^k \left| V^i \frac{\partial}{\partial x^i} \right. \right\rangle &= \left\langle \omega_\alpha dy^\alpha \left| V^\beta \frac{\partial y^\sigma}{\partial x^\beta} \frac{\partial}{\partial y^\sigma} \right. \right\rangle \\
\bar{\omega}_k V^i \delta_i^k &= \omega_\alpha V^\beta \frac{\partial y^\sigma}{\partial x^\beta} \delta_\sigma^\alpha = \bar{\omega}_k V^k = \omega_\alpha V^\beta \frac{\partial y^\alpha}{\partial x^\beta} \\
\text{De la ec. anterior podemos deducir que:} \\
\bar{\omega}_k &= \omega_\alpha \frac{\partial y^\alpha}{\partial x^k} \rightarrow \xi_k = \omega_\alpha \frac{\partial y^\alpha}{\partial x^k}
\end{aligned}$$

Ejemplo $g_{ij} \rightarrow \mathbb{R}^3 \quad g_{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$

$$f : (\theta, \phi) \rightarrow (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$$

estamos en la variedad de la esfera y vamos a ir hacia \mathbb{R}^2 .

$$\begin{aligned}
\bar{g}_{V_1, V_2}(\theta, \phi) &= g_{ij} \frac{\partial x^i}{\partial y^\mu} \frac{\partial x^j}{\partial y^\nu} \quad (y^1, y^2) = (\theta, \phi) \\
\bar{g}_{11} &= g_{ij} \frac{\partial x^i}{\partial \theta} \frac{\partial x^j}{\partial \theta} = \left(\frac{\partial x^1}{\partial \theta} \right)^2 + \left(\frac{\partial x^2}{\partial \theta} \right)^2 + \left(\frac{\partial x^3}{\partial \theta} \right)^2 = 1 \\
\bar{g}_{12} &= g_{ij} \frac{\partial x^i}{\partial \theta} \frac{\partial x^j}{\partial \phi} = \frac{\partial x^1}{\partial \theta} \frac{\partial x^1}{\partial \phi} + \frac{\partial x^2}{\partial \theta} \frac{\partial x^2}{\partial \phi} + \frac{\partial x^3}{\partial \theta} \frac{\partial x^3}{\partial \phi} = 0 \\
g_{22} &= \left(\frac{\partial x^1}{\partial \phi} \right)^2 + \left(\frac{\partial x^2}{\partial \phi} \right)^2 = \sin^2 \theta
\end{aligned}$$

1.3 Tensores $(0, k)$ totalmente antisimetricos

$$T_{\sigma}(v_1, \dots, v_k) = \text{sign}(\sigma) T_{v_1, \dots, v_k} \quad \text{sign}(\sigma) = \begin{cases} +1 & \sigma \text{ es par} \\ -1 & \sigma \text{ es impar} \end{cases}$$

$\sigma(v_1, \dots, v_k)$ Permutaciones de v_1, \dots, v_k

$$T = T_{v_1, \dots, v_k} dx^1 \otimes \dots \otimes dx^k$$

$$T(V^1, \dots, V^k)$$

$$T_{v_1 v_2} \rightarrow T_{v_2 v_1}$$