# Homework 6

## EE 513 — Stochastic Systems Theory

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## Problem 6.1

For  $x \in \{0, 1, \dots, 5\}$ :

$$H_1:$$
  $p(X = x|H_1) = {5 \choose x} (\frac{2}{3})^x (\frac{1}{3})^{5-x}$   
 $H_\circ:$   $p(X = x|H_\circ) = {5 \choose x} (\frac{1}{2})^x (\frac{1}{2})^{5-x}$ 

## ML Decision Rule:

$$\log \frac{p(X = x|H_1)}{p(X = x|H_0)} \overset{H_1}{\underset{H_0}{\gtrless}} 0$$

$$\log \frac{2^{5+x}}{3^5} \overset{H_1}{\underset{H_0}{\gtrless}} 0$$

$$x \overset{H_1}{\underset{H_0}{\gtrless}} 5 \frac{\log 3}{\log 2} - 5$$

$$x \overset{H_1}{\underset{H_0}{\gtrless}} 2.92 \qquad \checkmark$$

$$P_{FalseAlarm} = P(H_1|H_\circ) = \sum_{x \in \{3,4,5\}} p(X = x|H_\circ) = 0.5$$

$$P_{Miss} = P(H_{\circ}|H_1) = \sum_{x \in \{0,1,2\}} p(X = x|H_1) = 0.2098$$

$$P_{Error} = \frac{1}{2} P_{FalseAlarm} + \frac{1}{2} P_{Miss} = 0.3549$$

#### MAP Decision Rule:

$$\log \frac{p(X = x|H_1)}{p(X = x|H_0)} \underset{H_0}{\overset{H_1}{\gtrless}} \log \frac{\pi_0}{\pi_1}$$

$$\log \frac{2^{5+x}}{3^5} \underset{H_0}{\overset{H_1}{\gtrless}} \log \frac{0.8}{0.2}$$

$$x \underset{H_0}{\overset{H_1}{\gtrless}} 4.92$$

$$P_{FalseAlarm} = P(H_1|H_\circ) = \sum_{x \in \{5\}} p(X = x|H_\circ) = \frac{1}{2^5} = 0.03125$$

$$P_{Miss} = P(H_\circ|H_1) = \sum_{x \in \{0,1,2,3,4\}} p(X = x|H_1) = 1 - (\frac{2}{3})^5 = 0.8683$$

$$P_{Error} = 0.8P_{FalseAlarm} + 0.2P_{Miss} = 0.1987$$

## Problem 6.2

For  $y \in \{1, 2, 3, \dots\}$ :

$$H_1:$$
  $p(Y = y|H_1) = 0.5(1 - 0.5)^{y-1}$   
 $H_\circ:$   $p(Y = y|H_\circ) = 0.2(1 - 0.2)^{y-1}$ 

((a)) ML decision rule:

$$\log \frac{p(Y = y|H_1)}{p(Y = y|H_0)} \underset{H_0}{\overset{H_1}{\geqslant}} 0$$

$$y \underset{H_0}{\overset{H_1}{\geqslant}} 1 + \frac{\log(2/5)}{\log(5/8)}$$

$$y \underset{H_0}{\overset{H_1}{\geqslant}} 2.94$$

There is a flip in the unequality when dicidung by a negative number.

((b)) For the ML decision rule:

$$P_{FalseAlarm} = P(H_1|H_\circ) = \sum_{y \in \{3,4,\dots\}} p(Y = y|H_\circ) = 0.64$$

$$P_{Miss} = P(H_{\circ}|H_1) = \sum_{y \in \{1,2\}} p(Y = y|H_1) = 0.75$$

((c)) MAP decision rule:

$$\log \frac{p(Y=y|H_1)}{p(Y=y|H_0)} \overset{H_1}{\underset{H_0}{\gtrless}} \log \frac{\pi_0}{\pi_1}$$

$$\log \frac{p(Y=y|H_1)}{p(Y=y|H_0)} \overset{H_1}{\underset{H_0}{\gtrless}} \log \frac{2/3}{1/3}$$

$$(y\overset{H_1}{\underset{H_0}{\gtrless}} 2) + \frac{\log(2/5)}{\log(5/8)}$$

$$y\overset{H_1}{\underset{H_0}{\gtrless}} 3.94$$

Doublecheck the result; check the direction of the inequality.

For the MAP decision rule:

$$P_{FalseAlarm} = P(H_1|H_\circ) = \sum_{y \in \{4,5,\dots\}} p(Y = y|H_\circ) = 0.512$$

$$P_{Miss} = P(H_{\circ}|H_1) = \sum_{y \in \{1,2,3\}} p(Y = y|H_1) = 0.875$$

((d)) ML decision rule:

$$P_{Error} = \frac{2}{3} P_{FalseAlarm} + \frac{1}{3} P_{Miss} = 0.6766$$

MAP decision rule:

$$P_{Error} = \frac{2}{3} P_{FalseAlarm} + \frac{1}{3} P_{Miss} = 0.633$$

## Problem 6.3

((a)) Since S and N are independent the distribution of Y will be:

$$H_1: f_Y(y) = f_N(y) * f_S(y) = \int_0^y e^{-t} e^{-(y-t)dt} = y e^{-y} u(y)$$

$$H_0: f_Y(y) = f_N(y) = e^{-y} u(y)$$

The likelihood ratio will be:

$$\Lambda(y) = y \qquad , y \ge 0 \qquad \checkmark$$

((b)) By assuming a threshold of 1 (equal priors), we can calculate the total probability of error:

$$P_{FalseAlarm} = P(H_1|H_\circ) = \int_1^{+\infty} e^{-y} dy = e^{-1}$$

$$P_{Miss} = P(H_{\circ}|H_{1}) = \int_{0}^{1} ye^{-y}dy = 1 - 2e^{-1}$$

Therefore:

$$P_{Error} = \frac{1}{2} P_{FalseAlarm} + \frac{1}{2} P_{Miss} = \frac{1}{2} (1 - e^{-1})$$

#### Problem 6.4

We first derive the likelihood function. It is a function of both true parameters  $\mu$  and  $\sigma$ :

$$\mathcal{L} = \sum_{i} \log f(v_i) = -\frac{n}{2} \log 2\pi \sigma^2 + \sum_{i=1}^{n} \frac{(v_i - \mu)^2}{2\sigma^2}$$

now the derivatives with respect to both parameters should be found and simultaneously set to zero, to find the maximum likelihood estimates for both of them (derivation wrt to  $\sigma^2$  will make no difference for variance estimation):

$$\frac{\partial \mathcal{L}}{\partial \mu} = \sum_{1}^{n} \frac{v_{i} - \mu}{\sigma^{2}} = 0 \longrightarrow \hat{\mu} = \frac{1}{n} \sum_{1}^{n} v_{i}$$

$$\frac{\partial \mathcal{L}}{\partial \sigma^{2}} = -\frac{n}{2\sigma^{2}} - \sum_{1}^{n} \frac{(v_{i} - \hat{\mu})^{2}}{2\sigma^{4}} = 0 \longrightarrow \hat{\sigma^{2}} = \frac{1}{n} \sum_{1}^{n} (v_{i} - \hat{\mu})$$

Then we evaluate the expectations for both of the estimators:

$$\mathbb{E}[\hat{\mu}] = \frac{1}{n} \sum_{1}^{n} \mathbb{E}[v_i] = \mu \qquad \text{(UNBIASED ESTIMATOR)}$$

$$\mathbb{E}[\hat{\sigma}^2] = \frac{1}{n} \mathbb{E}[\sum_{1}^{n} (v_i - \hat{\mu})]$$

$$= \sigma^2 + \mu^2 + \frac{-\sigma^2 - \mu^2 - n\mu^2 + \mu^2}{n}$$

$$= \frac{n-1}{n} \sigma^2 \qquad \text{(BIASED ESTIMATOR)}$$

#### Problem 6.5

MAP estimate will maximize the posterior which is equivalent to maximizing the product of likelihood and prior.

$$\frac{\partial}{\partial a} \sum_{k} \log f(A|R_k) = 0 \longrightarrow \frac{\partial}{\partial a} \sum_{k} \log f(R_k|A) f(A) = 0$$

$$\frac{\partial}{\partial a} \left(\frac{-1}{\sigma_N^2} \sum_{k} (r_k - a)^2 + \frac{-1}{2\sigma_A^2} a^2 + \dots \text{ not dependent on } a \dots \right) = 0$$

$$\hat{a} = \frac{\sigma_A^2}{K\sigma_A^2 + \sigma_N^2} \sum_{k} r_k$$