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**Homework 7**  
**EE 513 — Stochastic Systems Theory**

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**Problem 7.1**

((a))

$$\begin{aligned}\mathbb{E}_{\Theta}[X(t)] &= \int_{-\pi}^{\pi} \frac{1}{2\pi} 2 \sin(2\pi(1000)t + \theta) d\theta \\ &= -\frac{1}{\pi} \cos(2\pi(1000)t + \pi) + \frac{1}{\pi} \cos(2\pi(1000)t - \pi) \\ &= -\frac{1}{\pi} [\cos 2\pi(1000)t \cos \pi - \sin \pi \sin 2\pi(1000)t] + \cos 2\pi(1000)t \cos \pi + \sin \pi \sin 2\pi(1000)t \\ &= 0 \quad \checkmark\end{aligned}$$

((b))

$$\begin{aligned}R_{XX}(t, u) &= \mathbb{E}_{\Theta}[X(t)X(u)] \\ &= \mathbb{E}_{\Theta}[2 \sin(2\pi(1000)t + \theta) \times 2 \sin(2\pi(1000)u + \theta)] \\ &= 2\mathbb{E}_{\Theta}[\cos(2\pi(1000)(t - u))] - 2\mathbb{E}_{\Theta}[\cos(2\pi(1000)(t + u) + 2\theta)] \\ &= 2 \cos(2\pi(1000)(t - u)) \quad \checkmark\end{aligned}$$

((c))  $X(t)$  IS wide sense stationary (WSS), since it satisfies following 2 conditions: ✓

- $\mathbb{E}_{\Theta}[X(t)]$  is constant with respect to time.
- Autocorrelation function ( $R_{XX}(t, u)$ ) can be written as a function of difference in time, i.e.  $R_{XX}(t, u) = R_{XX}(t - u) = R_{XX}(\tau) = 2 \cos(2\pi(1000)\tau)$ .

Then the power spectral density will be the Fourier transform of autocorrelation function:

$$\begin{aligned}S_X(f) &= \int_{-\infty}^{+\infty} R_{XX}(\tau) e^{-j2\pi f\tau} d\tau \\ &= \int_{-\infty}^{+\infty} \frac{e^{j2\pi 1000\tau} + e^{-j2\pi 1000\tau}}{2} e^{-j2\pi f\tau} d\tau \\ &= \delta(f - 1000) + \delta(f + 1000) \quad \checkmark\end{aligned}$$

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## Problem 7.2

- ((a)) For a WSS process, the autocorrelation function is the inverse Fourier transform of its power spectral density:

$$S_W(f) \xrightarrow{\mathcal{F}^{-1}} R_W(\tau) = \frac{N_0}{2} \delta(\tau) = 0.1 \delta(\tau)$$

- ((b)) For an LTI system we have:

$$m_{\widetilde{W}} = m_W H(0) = 0 \times 2 = 0 \quad \checkmark$$

- ((c))

$$\begin{aligned} \widetilde{W}(t) &= W(t) * h(t) \xrightarrow{\mathcal{F}} S_{\widetilde{W}}(f) = S_W(f) |H(f)|^2 \\ &= \frac{N_0}{2} \times 4 \text{rect}\left(\frac{f}{20}\right) \\ &= 0.4 \text{rect}\left(\frac{f}{20}\right) \quad \checkmark \end{aligned}$$

- ((d))

$$\begin{aligned} S_{\widetilde{W}}(f) &= 0.4 \text{rect}\left(\frac{f}{20}\right) \xrightarrow{\mathcal{F}^{-1}} R_{\widetilde{W}}(\tau) = 8 \text{sinc}(20\tau) \\ \mathbb{E}[\widetilde{W}^2(t)] &= R_{\widetilde{W}}(0) = 8 \text{sinc}(20 \times 0) = 8 \quad \checkmark \end{aligned}$$

- ((e)) A Gaussian process at any specific time is a Gaussian random variable. Since the filter is LTI, the output will also be a Gaussian process and by considering it at time  $t_1$  it will be a Gaussian random variable, which is characterized only by its mean and variance:

$$\begin{aligned} \mathbb{E}[\widetilde{W}(t_1)] &= \int_{-\infty}^{\infty} h(x) W(t_1 - x) dx \\ &= \int_{-\infty}^{\infty} h(x) \mathbb{E}[W(t_1 - x)] dx \\ &= 0 \end{aligned}$$

$$\begin{aligned} \text{Var}[\widetilde{W}(t_1)] &= \mathbb{E}[\widetilde{W}^2(t_1)] - \mathbb{E}^2[\widetilde{W}(t_1)] \\ &= 8 - 0 \end{aligned}$$

therefore the the output at time  $t_1$  is a Gaussian random variable:  $\widetilde{W}(t_1) \sim \mathcal{N}(0, 8)$  ✓

((f)) Using Q-function it is easy to calculate:

$$P(\widetilde{W}(t_1) > 3) = Q\left(\frac{3}{\sqrt{8}}\right) \quad \checkmark$$

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### Problem 7.3

Signal to Noise Ratio at the output can be written as:

$$SNR = \frac{P_Y}{P_{N_{output}}}$$

where power is the area under the curve of power spectral density for each targeted signal.

$$\begin{aligned} P_{N_{output}} &= \int_{-\infty}^{+\infty} \frac{N_0}{2} |H(f)|^2 df \\ &= 0.001 \times (25) \times (2000) + 2 \times 0.001 \times (4) \times (1000) \\ &= 58 \quad [\text{WATTS}] \end{aligned}$$

$$\begin{aligned} P_Y &= \int_{-\infty}^{+\infty} \frac{6000}{3000} \text{rect}\left(\frac{f}{3000}\right) |H(f)|^2 df \\ &= 50 \times (2000) + 2 \times 8 \times (500) \\ &= 108,000 \quad [\text{WATTS}] \end{aligned}$$

Therefore to have the SNR in decibels, we have:

$$SNR_{dB} = 10 \log \frac{P_Y}{P_{N_{output}}} = 10 \log \frac{108000}{58} = 32.7$$

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# Problem 7.4

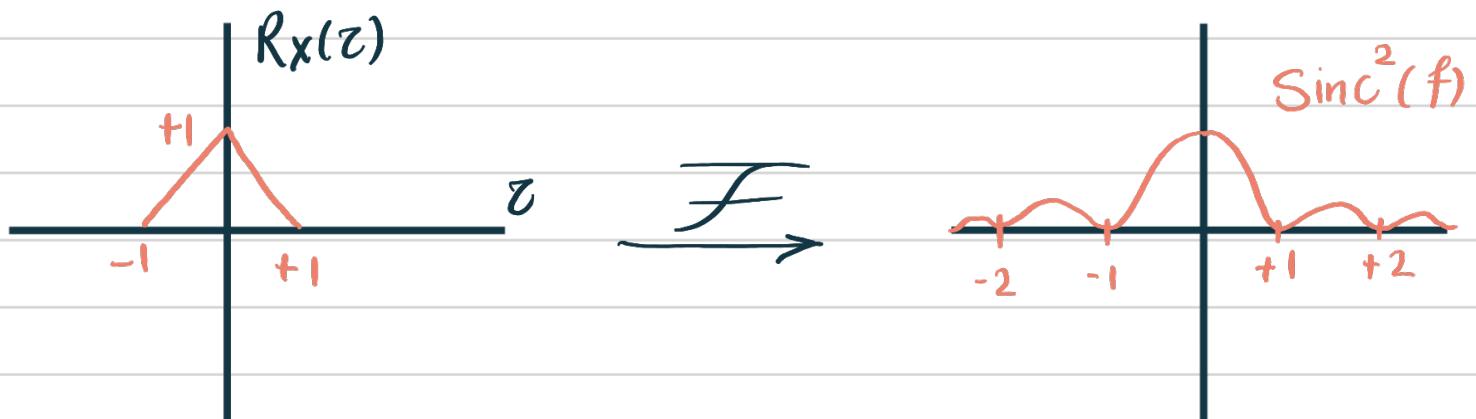
Before answering the problem,  
some few properties of autocorrelation  
function and its Fourier transform

For a real-valued stationary process:

- $R_X(\tau)$  is continuous.
- $R_X(\tau)$  is even.
- $R_X(\tau) \leq R_X(0)$ .
- $R_X(\tau)$  is real-valued.

- $S_X(f)$  is real-valued.
- $S_X(f)$  is even.
- $S_X(f) \geq 0$

((a))



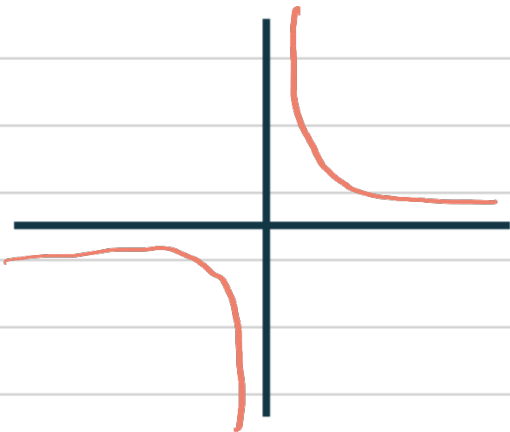
Legitimate Autocorrelation Function. ✓

1. continuous

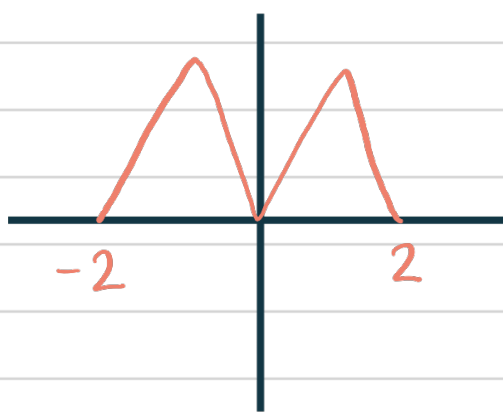
4. real

2.  $|R_x(\tau)| \leq R_x(0) = 1$

3. even function

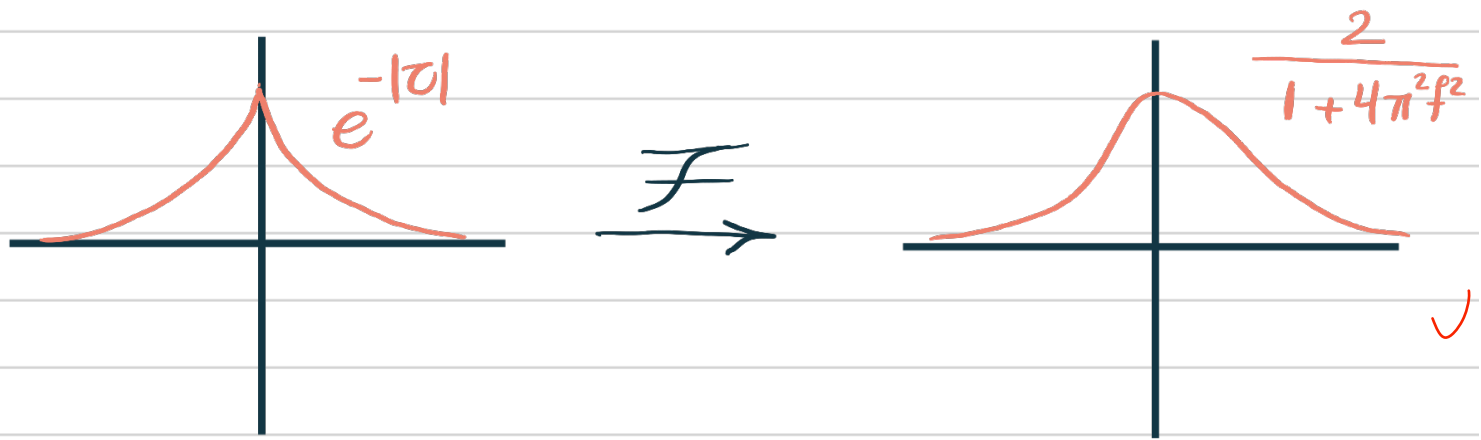


Not a legitimate autocorrelation function, since it's not continuous at  $\tau = 0$ . ✓



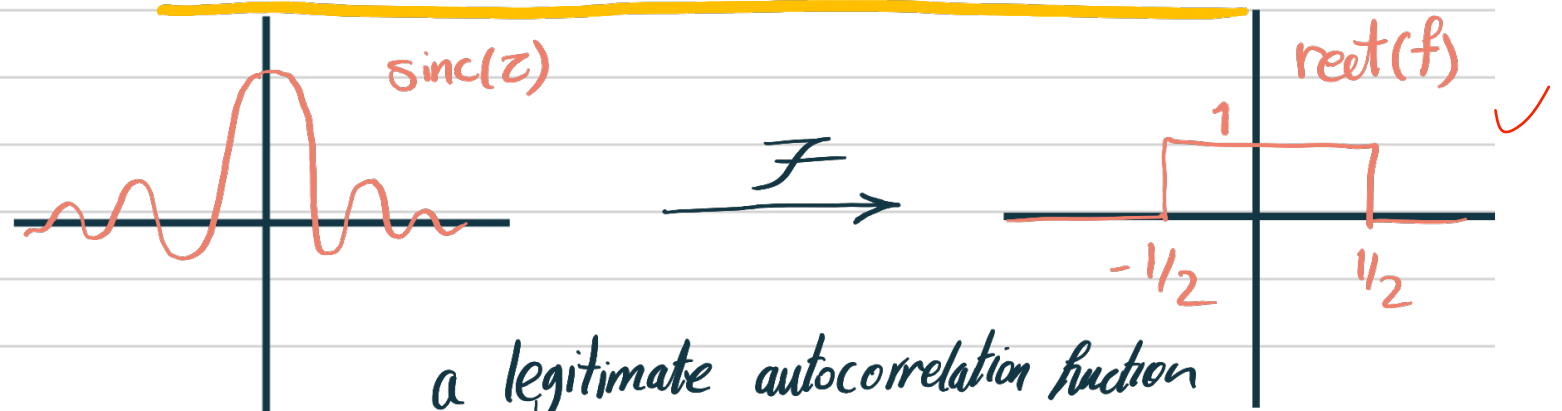
Not a legitimate autocorrelation function, since

$$R_x(\tau) \not\leq R_x(0)$$



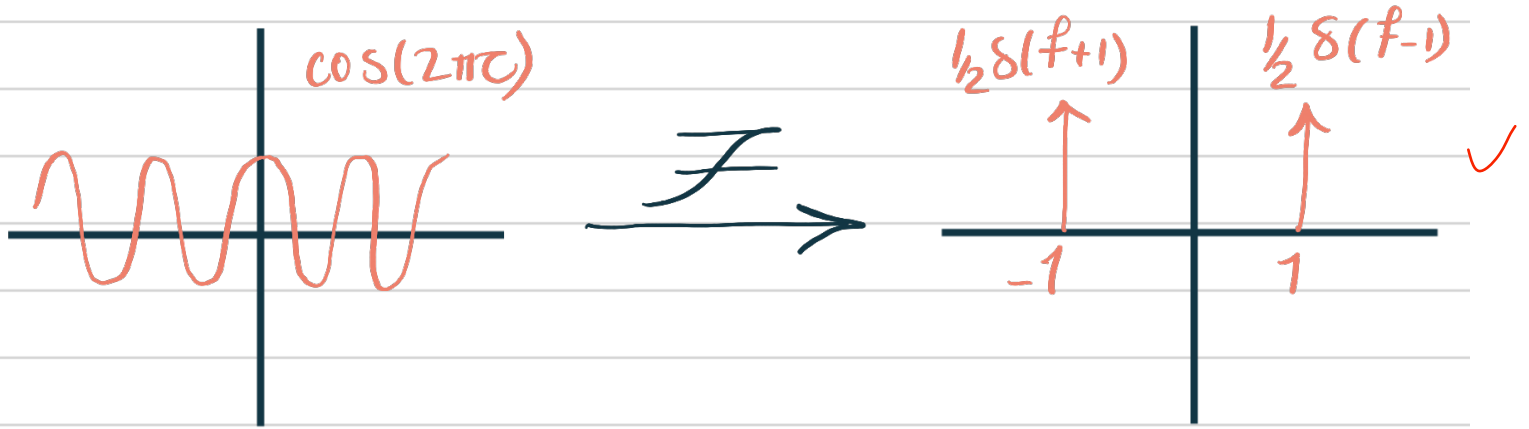
A legitimate autocorrelation function.

1. continuous
2.  $R_x(\tau) \leq R_x(0) = 1$
3. even
4. real



a legitimate autocorrelation function

1. continuous
2.  $R_x(\tau) \leq R_x(0) = 1$
3. even
4. real



A legitimate autocorrelation function.

1. continuous
2.  $R_x(\tau) \leq R_x(0) = 1$
3. even
4. real

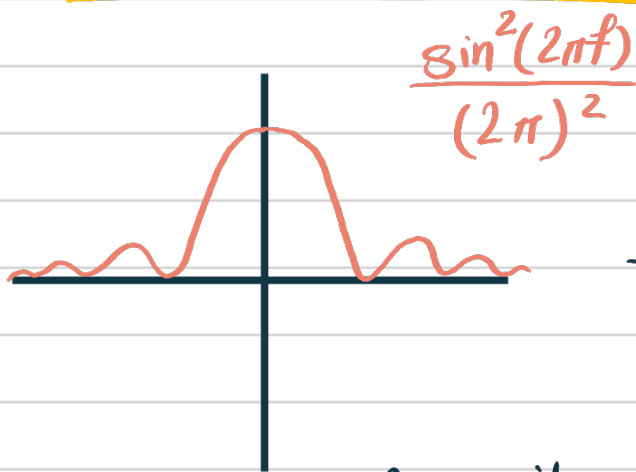


Not a legitimate autocorrelation function, since it is not continuous.

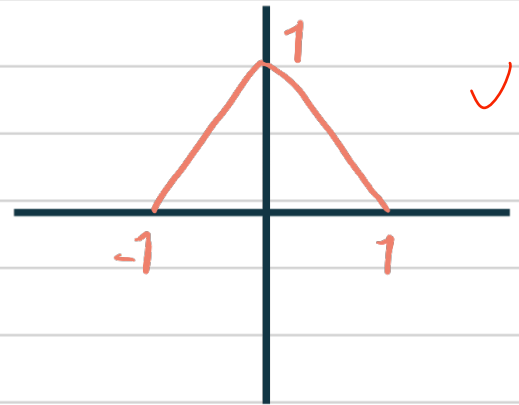
# ((b))



Not a legitimate PSD function, since it has negative values. ✓



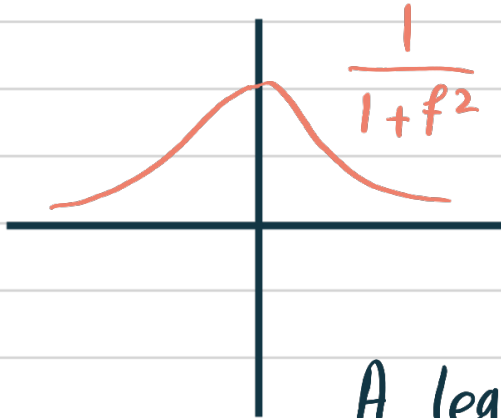
$\mathcal{F}^{-1}$



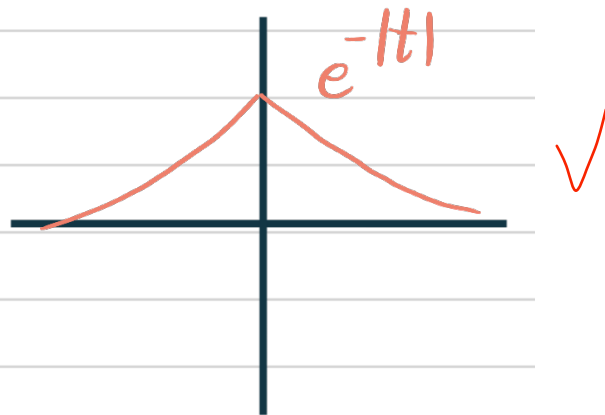
A legitimate PSD.

1. even
2. real-valued
3. positive-valued



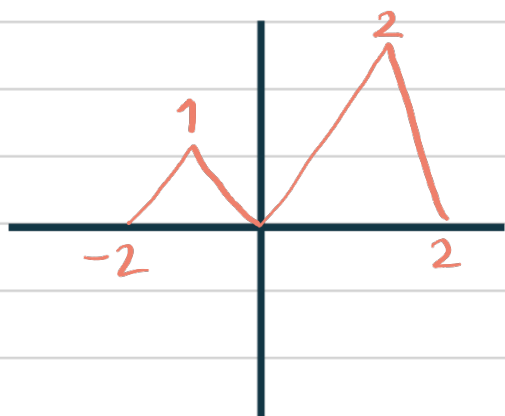


$\mathcal{F}^{-1} \rightarrow$



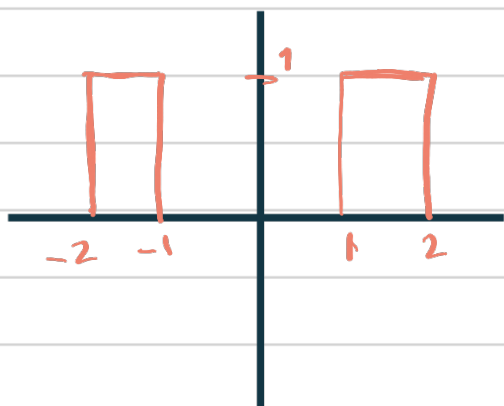
A legitimate PSD.

1. even
2. real-valued
3. positive-valued



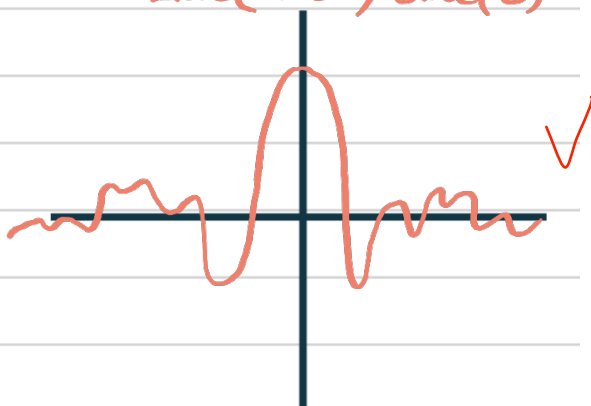
Not a legitimate PSD,  
since it's not even.

$$\text{rect}(f-1.5) + \text{rect}(f+1.5)$$



$\mathcal{F}^{-1} \rightarrow$

$$2\cos(2\pi \cdot 1.5\tau) \text{sinc}(\tau)$$



$$\mathcal{F}^{-1} \rightarrow e^{j2\pi \cdot 1.5\tau} \text{sinc}(\tau) + e^{-j2\pi \cdot 1.5\tau} \text{sinc}(\tau) = 2\cos(2\pi \cdot 1.5\tau) \text{sinc}(\tau)$$

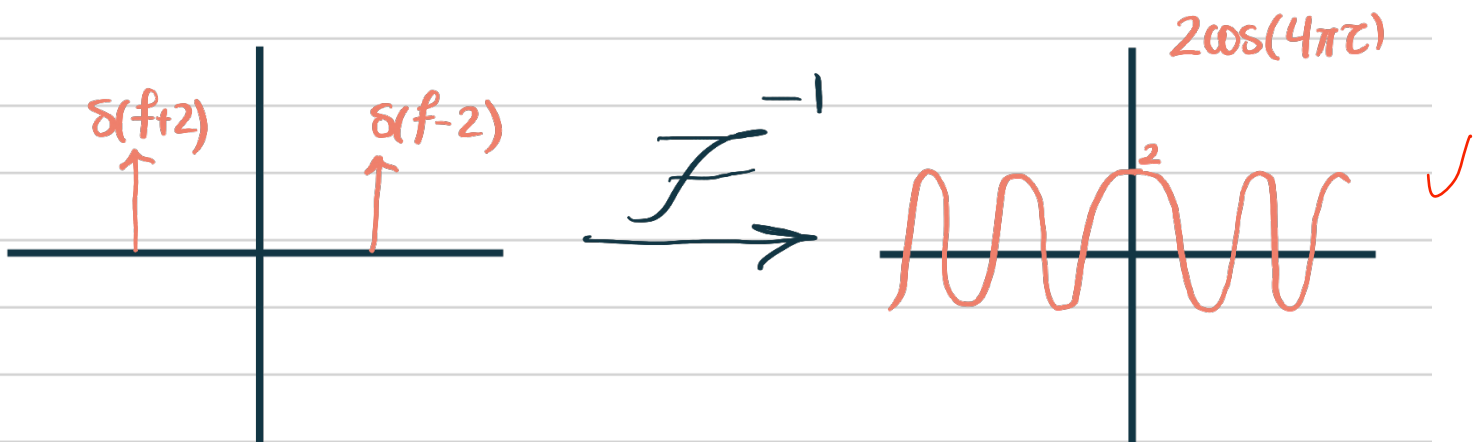
A legitimate PSD {

1. even
2. real valued
3. positive valued



A legitimate PSD.

1. even
2. real-valued
3. positive-valued



A legitimate PSD.

1. even
2. real-valued
3. positive-valued