LA for Data Science, Mansoura, session 5

- > SVD (Singular Value Decomposition)
- PCA (Principle Component Analysis)

> Dimensionality Reduction.

- Rank Reduction

(Reduced Rank Matrix)

* Covariance Matrix; (correlation Matrix)

-> Image Compression (Lossy Compression)

$$\rightarrow$$
 Tr(A) = Trace(A)

Review

$$=$$
 $\frac{z^{m}}{z^{m}}$ a_{ii}

$$Tr(A) = \sum_{i} \lambda_{i}(A)$$

Zaii- a,+9,2+9,3

$$det(A) = \prod_{i} \lambda_{i}(A) \longrightarrow 2$$

TT a = a, x a x a 33



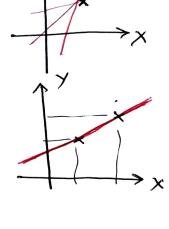


$$\frac{1}{2}$$

$$a_1X_3 + b_1Y = C_1$$

 $a_2X + b_2Y = C_2$
 $a_3X + b_3Y = C_3$
determined

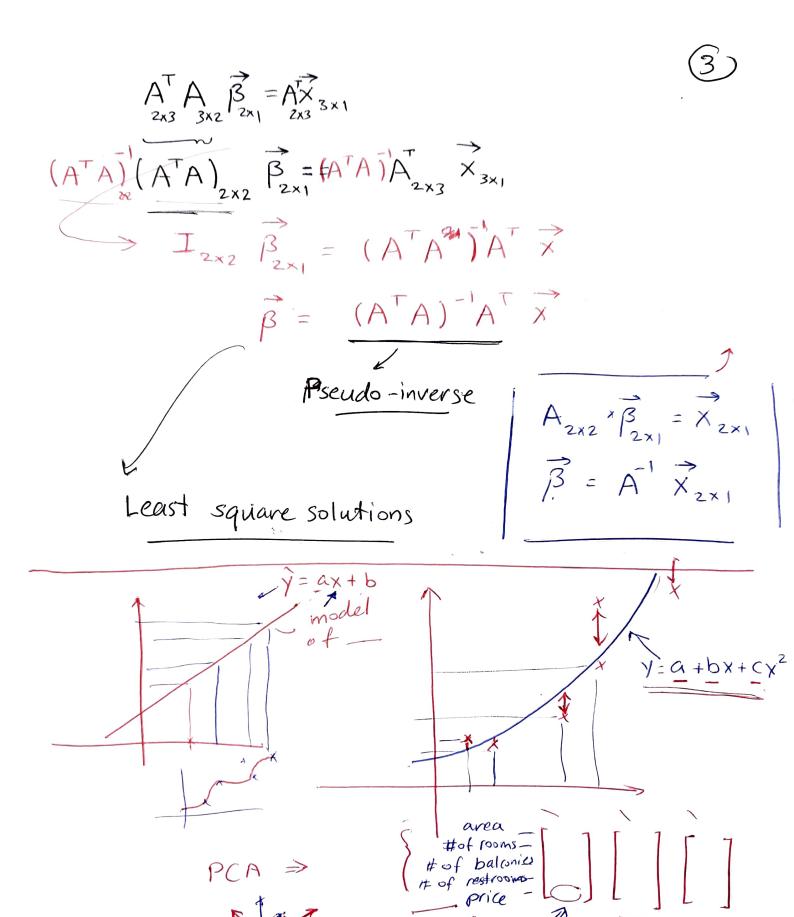
error:
$$= \hat{\gamma}_{i} - \hat{\gamma}_{i}$$



3 data points

$$\begin{bmatrix} 100 & 1 \\ 120 & 1 \\ 130 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1000 \\ 1400 \\ 1600 \end{bmatrix}$$

$$\vec{\beta}_{2\times 1}$$

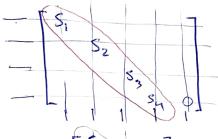


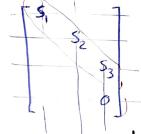
SVD

Singular Value Decomp.

matrix of singular values

$$S_1$$
, S_2 , \sim , S_K
 G_1 , G_2 , \sim , G_K





U&V;

- eigenvectors of AA
- -> Columns of V are eigenvectors of AT

eigen decomposition

"Diagonalization

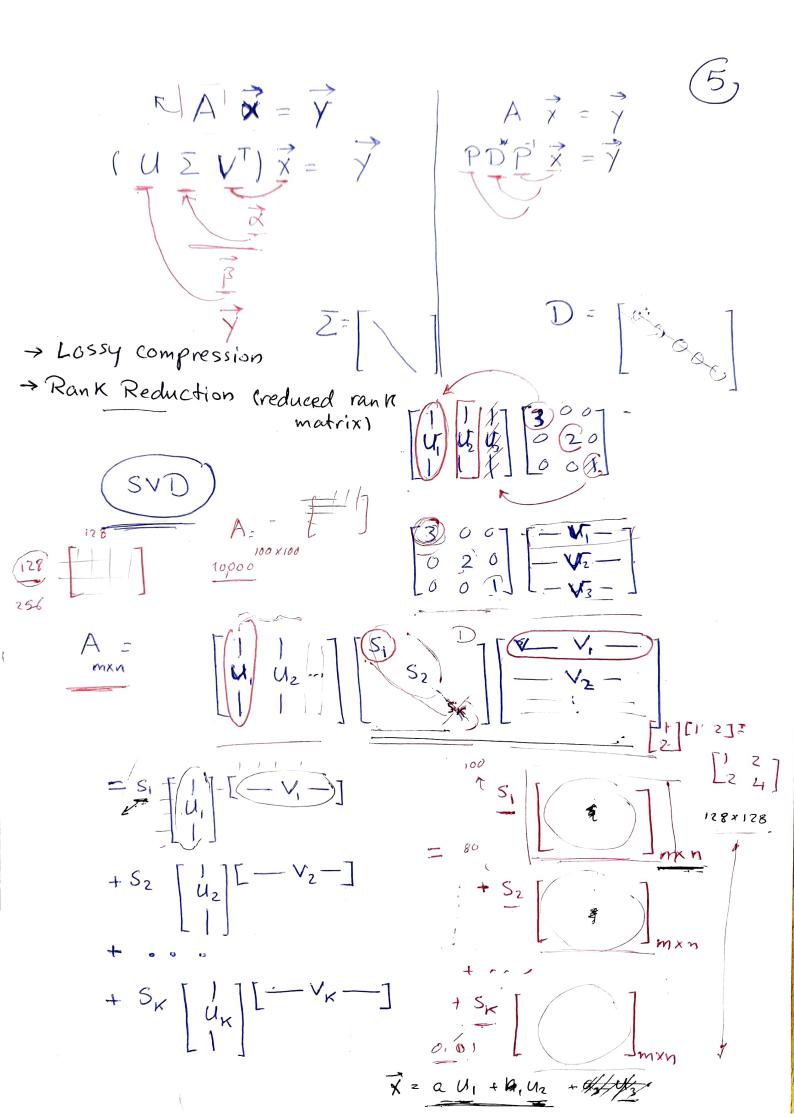
A B Ymxh nxm

~Z~;

-> singular values are square roots

e.g.,
$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 2 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 3 & 6 \end{bmatrix}$$

5, , 5



$$\frac{1}{X} = \frac{2.5 \, \hat{i}}{2 \, \text{basis}}$$

$$\frac{1}{2} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{5} \\ \frac{1}{2} & \frac{1}{5} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}$$

Principle

compon-

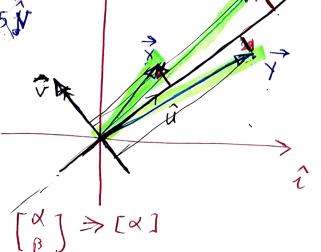
New basis
$$\vec{u}$$
, \vec{v}

$$\vec{X} = \begin{bmatrix} 2.5 \\ 0 \end{bmatrix}$$

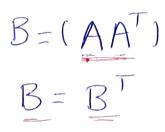
$$\vec{Y} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

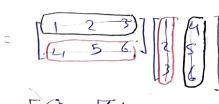
$$\vec{Z} = \begin{bmatrix} -0.5 \\ 0 \end{bmatrix}$$

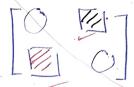
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\overrightarrow{x} = 4 \cdot 2 \cdot 1 + 3 \cdot 1 + 3$$











-> AAT is symmetric

- -> eigenvalues of a symmetric matrix are real numbers.
- -> eigenvectors of a sym. motrixes are orthogonal.

Dela A x = y

S.V.D

UZVX=Y

Standardization

> Shifting > zero mean

> scaling (variability;

to be discussed in detail in a Prob. & Stat. sessions

6 Standard deviation = 1)

Covariance matrix

