

Session 6

- Markov process / Markov chain
- Entropy (Information Entropy)

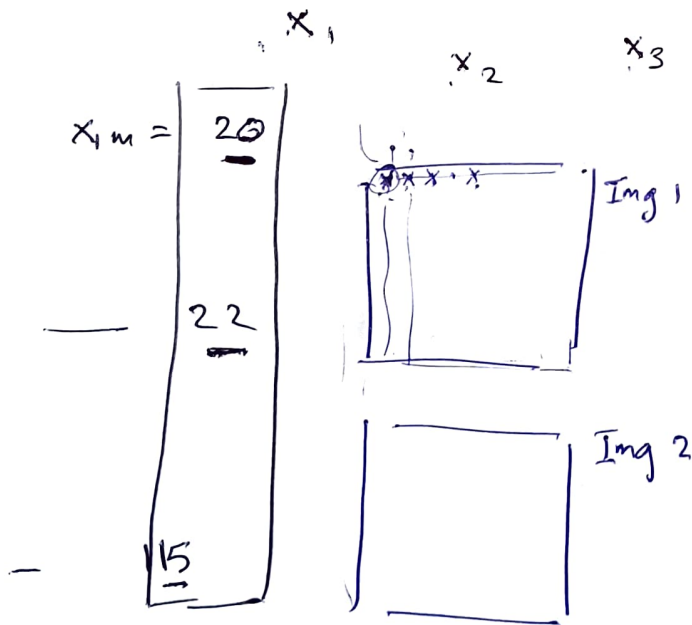
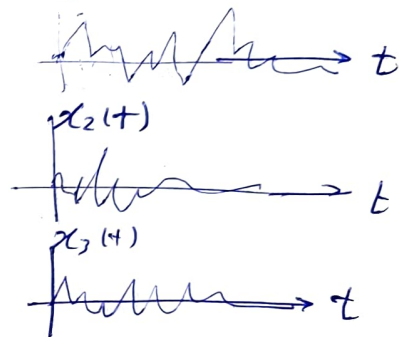
Random Process (stochastic Process)

vs. Random Variable $\Leftarrow X = x_i$

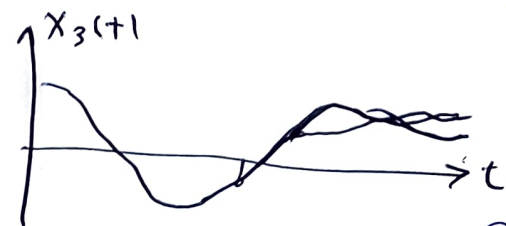
$X(\underline{z}; t)$

↓
Random Variable

$x_1(t)$



Images : Random process
"spatial domain"
space



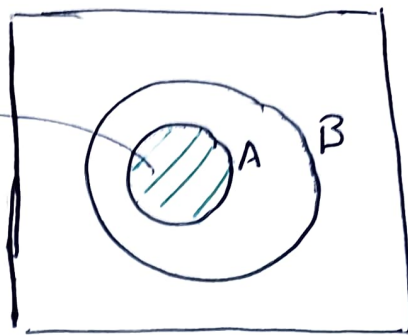
possible
ensemble of different
Realizations of process

Review

(1)

$$P(A) = 1/4$$

$$P(A|B) = \frac{P(A \cap B)}{P(B)} \quad \checkmark$$

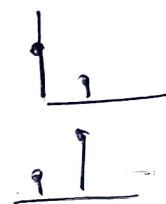


$$P_x(1) = p \quad P_x(0) = 1 - p = q$$

$$P(x=1) = p = 1 - P(x=0) = 1 - q$$

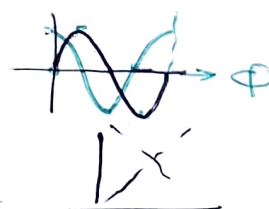
$$E[x] = \sum_i x P(x)$$

$$= 0 \times P_x(0) + 1 \times P_x(1) = p = 1 - q$$



$$x = \cos \phi \quad y = \sin \phi \rightarrow \text{not indep.}$$

$$y = \sin(\cos^{-1} x)$$



Discrete Markov Random Process;

2

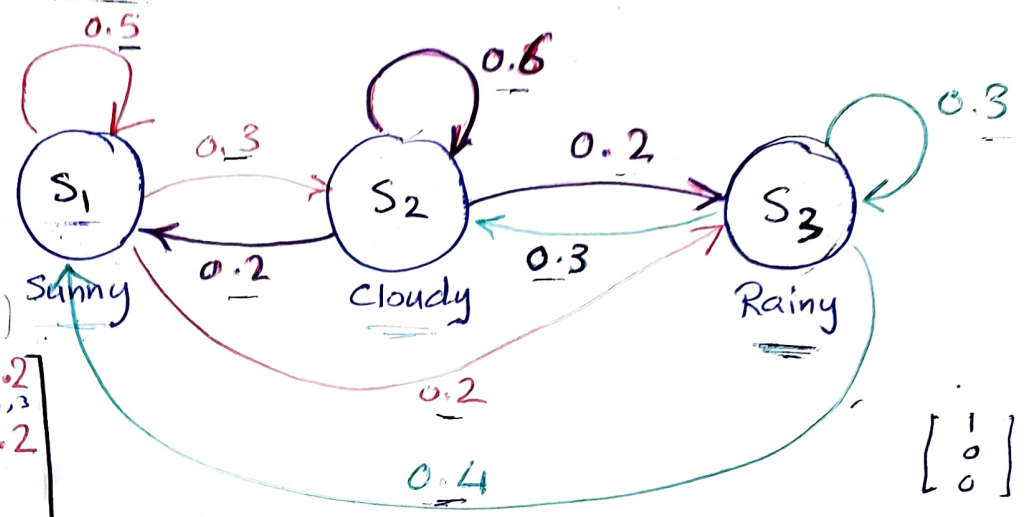
memoryless ✓

short-term memory

next state

	s_1^+	s_2^+	s_3^+
s_1	0.5	0.3	0.2
s_2	0.2	0.6	0.2
s_3	0.4	0.3	0.3

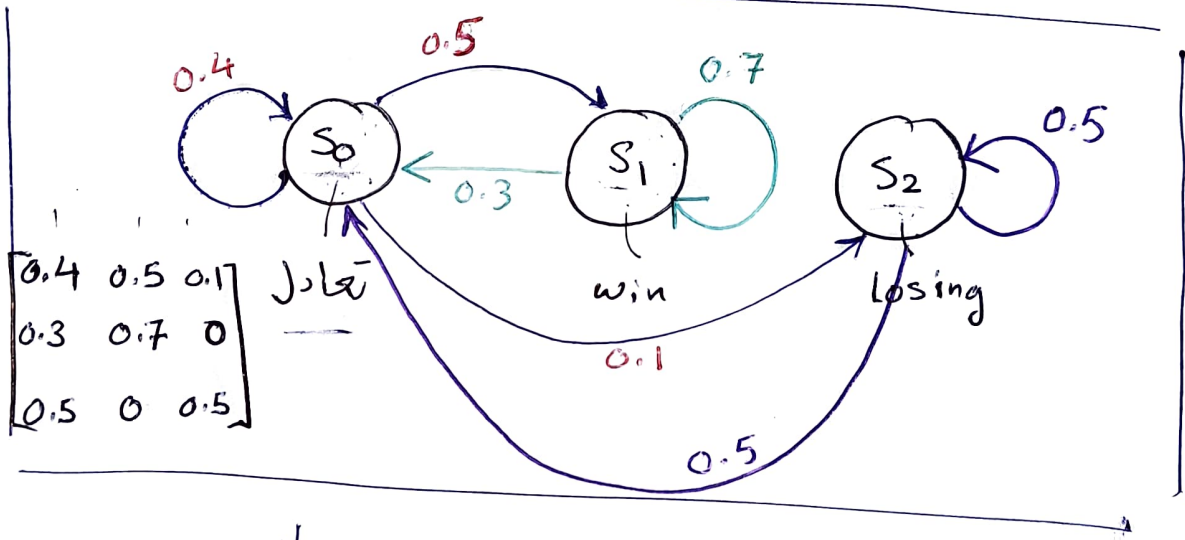
current state



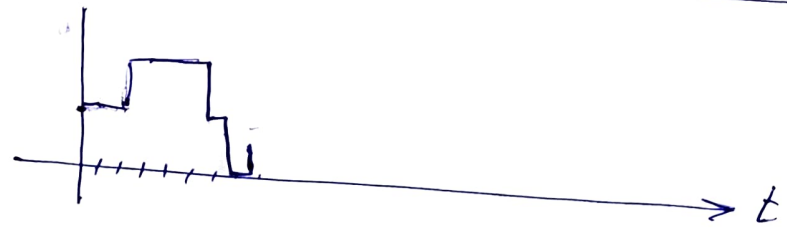
← transition Probability matrix

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0.5 \\ 0.5 \\ 0 \end{bmatrix}$$



0.4	0.5	0.1
0.3	0.7	0
0.5	0	0.5



next state vector $\vec{X}^+ = \underline{A} \vec{X}$

$X^{(0)} \quad X^{(1)}$

initial state vector

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \leftarrow \text{Initially}$$

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.4 & 0.5 & 0.1 \\ 0.3 & 0.7 & 0 \\ 0.5 & 0 & 0.5 \end{bmatrix} = \begin{bmatrix} 0.4 & 0.5 & 0.1 \end{bmatrix}$$

current state

next state vector

(3)

$$\frac{S_u - S_d}{2}$$

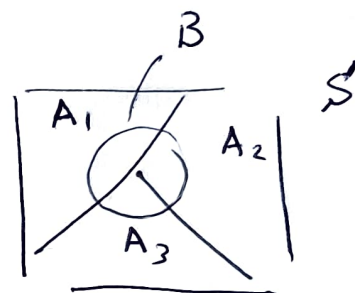


Recall conditional Probability.

$$P(B/A) = P(BA) / P(A)$$

$$P(BA) = P(B/A) P(A)$$

$$P(B) = P(BA_1) + P(BA_2) + P(BA_3)$$



$$P(B) = P(B/A_1)P(A_1) + P(B/A_2)P(A_2) + P(B/A_3)P(A_3)$$

$$P(B) = \sum_i P(B/A_i) P(A_i)$$

$$P(S_j^+) = \sum_i P(S_j^+/S_i) P(S_i)$$

$$\begin{matrix} S_1^{(0)} \\ S_1^{(1)} \\ S_1^{(2)} \end{matrix}$$

$$P(S_j^+/S_0)P(S_0) + P(S_j^+/S_1)P(S_1) + P(S_j^+/S_2)P(S_2)$$

$$\begin{aligned} P_{0,0} &\equiv P(S_0^+/S_0) \\ P_{0,1} &\equiv P(S_1^+/S_0) \\ P_{i,j} &\equiv P(S_j^+/S_i) \end{aligned}$$

notations of Markov transition probabilities.

$$\begin{bmatrix} P_{0,0} \\ P_{0,1} \\ P_{1,0} \\ P_{1,1} \\ P_{2,0} \\ P_{2,1} \end{bmatrix} \begin{bmatrix} P(S_0) \\ P(S_1) \\ P(S_2) \end{bmatrix}$$

$$= P_{0,j} P(S_0) + P_{1,j} P(S_1) + P_{2,j} P(S_2) = P(S_j^+)$$

(4)

$$P = \begin{bmatrix} P_{0,0} & P_{0,1} & P_{0,2} \\ P_{1,0} & P_{1,1} & P_{1,2} \\ P_{2,0} & P_{2,1} & P_{2,2} \end{bmatrix}$$

~~$$P_{1,0}^+ = P_{0,0} \cdot P(0) + P_{1,0} \cdot P(1) + P_{2,0} \cdot P(2)$$~~

$$P(s_0^+) = P_{0,0} \times P(s_0) + P_{1,0} \times P(s_1) + P_{2,0} \times P(s_2)$$

$$\vec{X}^+ =$$

$$\begin{bmatrix} P(s_0^+) & P(s_1^+) & P(s_2^+) \end{bmatrix} = \begin{bmatrix} P(s_0) & P(s_1) & P(s_2) \end{bmatrix} \begin{bmatrix} P_{0,0} & P_{0,1} & P_{0,2} \\ P_{1,0} & P_{1,1} & P_{1,2} \\ P_{2,0} & P_{2,1} & P_{2,2} \end{bmatrix}$$

next state "column number"

5

current state "row number"

$$P = \begin{bmatrix} 0.5 & 0.3 & 0.2 \\ 0.2 & 0.6 & 0.2 \\ 0.4 & 0.3 & 0.3 \end{bmatrix}$$

$$P = [\leftarrow P_{i,j} \rightarrow]$$

Initially

$$\vec{X}_0 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{X}^{(1)T} = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0.5 & 0.3 & 0.2 \\ 0.2 & 0.6 & 0.2 \\ 0.4 & 0.3 & 0.3 \end{bmatrix}$$

$$\vec{X}^{(1)T} = \begin{bmatrix} 0.5 & 0.3 & 0.2 \end{bmatrix}$$

$$\vec{X}^2 = \vec{X}^{(1)T} [P] = \begin{bmatrix} 0.5 & 0.3 & 0.2 \end{bmatrix} \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

$\begin{bmatrix} x & x & x \end{bmatrix}$

IF WE TRANSPOSED
THE PROPABILITY
MATRIX TO BE:

Current state index $\hat{=}$ column number

(6)

next
state
index
 $\hat{=}$ row
number

$\vec{X}^{(1)}$

$$P = \begin{bmatrix} P_{0,0} & P_{0,1} & P_{0,2} \\ P_{1,0} & P_{1,1} & P_{1,2} \\ P_{2,0} & P_{2,1} & P_{2,2} \end{bmatrix}$$

$\vec{X}^{(0)}$

$\vec{X}^{(n)}$

$=$

$$P^n \vec{X}^{(0)}$$

$P \times P \times \dots \times P \leftarrow n \text{ times.}$

if P is diagonalizable.

$$P \times P = \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_i \end{bmatrix} \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix}^{-1} \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_i \end{bmatrix} \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix}^{-1}$$

$$P^n \vec{X}^{(0)} = \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix} \begin{bmatrix} \lambda_1^n & & \\ & \ddots & \\ & & \lambda_i^n \end{bmatrix} \begin{bmatrix} \uparrow \\ \downarrow \end{bmatrix}^{-1} \vec{X}^{(0)} = \vec{X}^{(n)}$$

steady state ? هل الـ steady state ؟

$\vec{X}^{(n)}$

$$= \begin{bmatrix} \\ \\ \end{bmatrix}$$

P

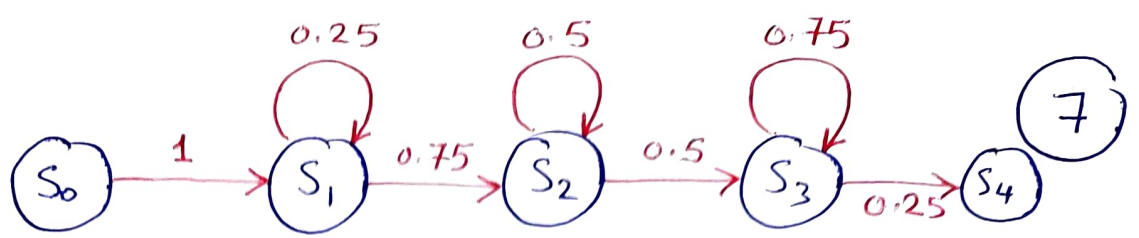
$\vec{X}^{(n-1)}$

$$= \vec{X}^{(n-1)}$$

eigendecomposition

$$\lambda_i = 1 \Rightarrow \vec{v}_i$$

$$P \vec{X} = \vec{X}$$



$$\begin{bmatrix} 0 \\ \vdots \end{bmatrix}$$

$$\vec{x}^{(6)} = P^6 \vec{x}^{(0)} \quad \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Information Entropy

0101010011010110

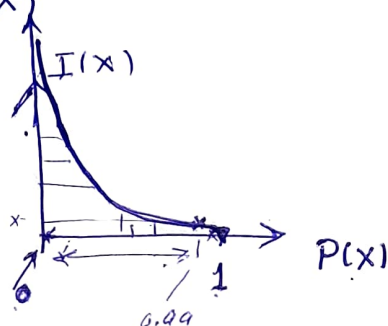
000001000000101

$$\underline{I(x)} \propto \frac{1}{f(P(x))}$$

$$I(x_1, x_2) = I(x_1) + I(x_2)$$

$$\underline{I(x)} = \log_2 \frac{1}{P(x)} \quad \text{bits} = -\log P(x)$$

↓
Information



Information entropy

$$P(H) = 0.5$$

$$P(T) = 0.5$$

$$I(H) = -\log_2(0.5)$$

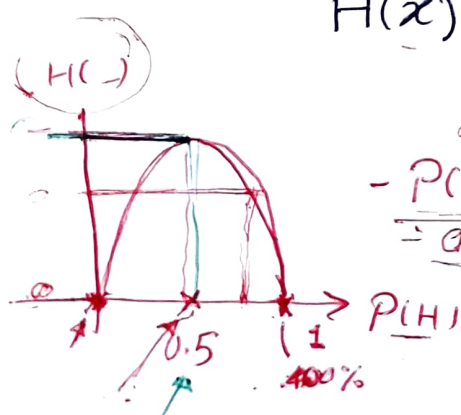
$$I(T) = -\log_2(0.5)$$

$$\underline{\text{average information}} = \sum_i \underline{I(x_i)} \underline{P(x_i)}$$

Entropy

$$H(x) = \sum_i (-\log_2 P(x_i)) P(x_i)$$

$$H(x) = -\sum_i P(x_i) \log P(x_i)$$



$$= -P(H) \log P(H) - P(T) \log P(T)$$

= 0.5 x 0.0 - 0.5 x 1.0

$$= 0.5$$

(9)

Cross-Entropy loss function (Classification)

$$H(P, q) = - \sum_i P(x_i) \log q(x_i)$$

↓ ↓

true Prob.

prediction prob.



$$\rightarrow \frac{0.6}{0.4} \leftarrow$$