

# Ali Hassan Khan

MASTER OF SCIENCE IN EE(AI & AUTONOMOUS SYSTEM) · NUST, ISLAMABAD, PAKISTAN

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## Education

### NUST(National University of Science and Technology)

M.S. IN ELECTRICAL ENGINEERING (AI&AUTONOMOUS SYSTEM)

- GPA: 3.79/4.0

Islamabad, Pakistan

Oct 2020 - Dec 2022 (Expected)

### FAST-NUCES(National University of Computer and Emerging Sciences)

B.S. IN ELECTRICAL ENGINEERING (ELECTRONICS)

- GPA: 3.45/4.0

Islamabad, Pakistan

Aug 2015 - Jul 2019

## Skills

<b>Back-end</b>	Basic: REST API
<b>Programming</b>	Matlab, Python, C/C++, Assembly Language (8051&AVR Microcontrollers), JAVA, LaTeX
<b>Libraries</b>	Tensorflow, PyTorch, Keras,OpenCV, Transformers, Pandas, Scikit-learn, OpenAI Gym, NumPy, CVXPY, CVXPYLayer
<b>Software and Tools</b>	Latex, Matlab, Android Studio, ROS//ROS2
<b>Languages</b>	English, Urdu, Punjabi

## Experience

### TUCL Deep Learning Lab., NCAI

MACHINE LEARNING DEVELOPMENT INTERNSHIP

- Developed and tested multiple transformer models, including GPT, XLNet, BERT and BART, using PyTorch to generate Extractive and Abstractive summary of input Legal text, achieving near state-of-the-art accuracy.
- Identified different factors that affects our Evaluation scores (e.g. ROUGE).

Islamabad, Pakistan

Jul 2021 - Oct 2021

### Niocraft BV., Ltd.

MACHINE LEARNING ENGINEER (FREELANCE CONTRACTOR)

- Process and extract features from medical signals and images.
- Develop, simulate, test, and improved Algorithms, Android Apps Machine Learning and Deep Learning models to detect diseases and predict health indicators.
- Deployed Medical Imaging based Deep Learning models in Android Apps using Android Studio, Google Cloud and Firebase.

Amsterdam, The Netherlands

Jul 2019 - Sep 2020

## Relevant Coursework

<b>Going On</b>	Online: Reinforcement Learning and Optimal Control (Prof. Demetri Bertsekas, ASU), Reinforcement Learning (DeepMinds, UCL), Dynamic Optimization
<b>Completed</b>	Online: Generative Adversarial Networks (GANs), DeepLearning.AI TensorFlow Developer, Machine Learning Engineering for Production (MLOps), TensorFlow: Data and Deployment Specialization
<b>Completed</b>	Graduate: Machine Learning, Deep Learning, Stochastic Systems, Convex Optimization, Mobile Robotics, Computer Vision
<b>Programming</b>	Undergraduate: Introduction to Computing, Programming Fundamentals, Data Structures and Algorithms, Micro-Processor Interfacing and Programming
	Undergraduate: Applied Calculus, Differential Equations, Linear Algebra, Numerical Methods, Probability and Random Processes,
<b>Others</b>	Complex Variables and Transforms, Signal and Systems, Analogue and Digital Communication, Digital Signal Processing, Feedback Control Systems, Digital Control Systems

## Research Experience and Projects

### Deep Reinforcement Learning for HVAC Control

RESEARCH

- Performed literature review on the existing methods of HVAC Control using model-free and model based Policy.
- Implemented the state-of-the-art Deep RL algorithms (e.g. Q-Learning, REINFORCE, PPO, A2C) to control HVAC System.

SEECs, NUST

2021

## Integration of Domain Knowledge into Deep Learning Architectures

SEECs, NUST

### RESEARCH

Jan. 2020

- Surveyed different techniques for injection of domain specific knowledge via constraints into Deep Neural Network to ease the learning process.
- Implemented different Deep Neural Network architectures with Convex Optimization problems as layers to enforce expert knowledge via constraints.
- Analyzed the efficiency of Convex Optimization Layers.

## Improve the performance of Faster RCNN on Maize Plant Detection using Hybrid Dilated Convolution

SEECs, NUST

### COURSE PROJECT:

Jul. 2020

- Collected images of Maize Plants from fields.
- Utilized different state-of-the-art One Step (e.g. Fast RCNN and Faster RCNN) and two step (YOLOv5) Object Detection architectures for maize plant detection.
- Improved the performance of Faster RCNN by using Hybrid Dilated Convolution.

## Semi-Autonomous Weed Sprayer Robot

NUCES, CFD Campus

### UNDERGRADUATE FINAL YEAR PROJECT:

Aug 2018

- Designed an agriculture four wheel robot to spray unwanted weeds from a field.
- Used a set of different Image processing techniques to detect plants and Deep Learning models to classify plants into weed and potato.
- Used 2D CNC machine to move sprayer nozzle at the location of weed and spray it precisely.

## Awards & Achievements

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### DOMESTIC

2019	<b>FYP Funding Awardee</b> , Awarded by Ignite National Technology Fund under NGIRI	FAST NUCES
2019	<b>National Championship</b> , FYP selected by Ignite to compete for the National Championship	FAST NUCES
2015-2019	<b>Academic Semester Excellence Award</b> , Four Medals (1 Gold, 1 Silver, 2 Bronze)	FAST NUCES
2015-2019	<b>Dean List</b> , Appeared 4 times on the Dean List of FAST NUCES CFD during undergraduate	FAST NUCES

## Program Committees

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2019	<b>Teacher Assistant</b> , Micro-Processor Interfacing and Programming	NUCES
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