

# Construction and Verification of Software

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**MIEI - Integrated Master in Computer Science and Informatics**  
Consolidation block

### **Lecture 6 - Separation Logic**

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# Part II

## Interference, Separation Logic and Verifast for Java

# Account ADT (Java)

---

```
public class Account {  
  
    int balance;  
  
    // RepInv() = balance >= 0;  
    public Account()  
    { balance = 0; }  
  
    void deposit(int v)  
    { balance += v; }  
  
    void withdraw(int v)  
    // requires v >= 0;  
    { balance -= v; }  
}
```

# Account ADT (Java)

---

```
public class Account {  
  
    int balance;  
  
    int getBalance()  
    { return balance; }  
  
    ...  
  
    static void main (String args[] )  
    {  
        Account b1 = new Account();  
        Account b2 = new Account();  
        b1.deposit(10);  
        // assert: b1.getBalance() == 10  
    }  
}
```

# Account ADT (Java)

---

- Consider the following code fragment and Hoare triple, intended to transfer  $v$  from  $a1$  to  $a2$

```
{ v > 0 && a1.getBalance() >= v }
{
    int v1;
    v1 = a1.getBalance();
    if (v1 >= v) {
        a1.withdraw(v);
        a2.deposit(v);
    }
}
{a1.getBalance() < old(a1.getBalance()) }
```

- Is this Hoare triple valid?

# Account ADT (Java)

---

- Consider the following code fragment and Hoare triple, intended to transfer  $v$  from  $a1$  to  $a2$

```
{ v > 0 && a1.getBalance() >= v }
{
    int v1;
    v1 = a1.getBalance();
    if (v1 >= v) {
        a1.withdraw(v);
        a2.deposit(v);
    }
}
{a1.getBalance() < old(a1.getBalance()) }
```

- Only if  $a1$  and  $a2$  refer to different account objects!
- If they are aliases, the Hoare triple is invalid.

# Account ADT (Java)

---

- Tracking aliasing is challenging, e.g.,

```
static void test(Account a1, Account a2, int v)
{
    int v1;
    v1 = a1.getBalance();
    if (v1 >= v) {
        a1.withdraw(v);
        a2.deposit(v);
    }
}

static void main (String args[] )
{
    Account b1 = new Account();
    Account b2 = new Account();
    b1.deposit(10);
    test(b1,b2,2);
    test(b1,b1,2);
}
```

- Effect of test depends on whether a1 and a2 are aliases

# Aliasing and Interference

---

- Two programming language expressions are aliases if they refer to the same memory location
- Aliasing occurs in any programming language with pointers (e.g., C, C++) or references (Java, C#)
- Two program fragments interfere if the execution of one may change the effect of the other
- Interference is particularly important in the context of concurrent programs (we will see more on this later)
- Interference and aliasing is hard to detect syntactically, and hard to reason about semantically.



# Hoare Logic is unsound for aliasing

---

- Recall the basic Hoare Logic Rule:

$$\{A[E/x]\} x := E \{A\}$$

- The soundness of this reasoning principle is rooted on the fact that no other variable aliases  $x$ . We have:

$$\{y \geq 0 \wedge x \geq 0\} x := -1 \{y \geq 0 \wedge x < 0\}$$

- But, if  $y$  and  $x$  are aliases, we would have, e.g.

$$\{y \geq 0 \wedge x \geq 0\} x := -1 \{y < 0 \wedge x < 0\}$$

# Hoare Logic is unsound for aliasing

---

- In our Account ADT example:

$\{ x.balance() == K \ \&\& \ y.balance() > 0 \}$   
 $x.withdraw(K)$

$\{ x.balance() == 0 \ \&\& \ y.balance() > 0 \}$

- Again, if  $y$  and  $x$  are aliases, we would have, e.g.

$\{ x.balance() == K \ \&\& \ y.balance() > 0 \}$   
 $x.withdraw(K)$

$\{ x.balance() == 0 \ \&\& \ y.balance() == 0 \}$

- To reason about programs with interference (aliasing or concurrency) a different approach is needed.

# Aliasing in Dafny (&others)

---

- Dafny and others are conservative with relation to aliasing by not assuming that objects from the same class are different.

```
method M(a:C, b:C)
  requires a != b // This precondition is essential
  modifies a
{
  a.f := 2+b.f;
  assert b.f == old(b.f);
}
```

- Framing conditions (reads, modifies) help to manage knowledge about objects.

# Aliasing in Dafny (&others)

---

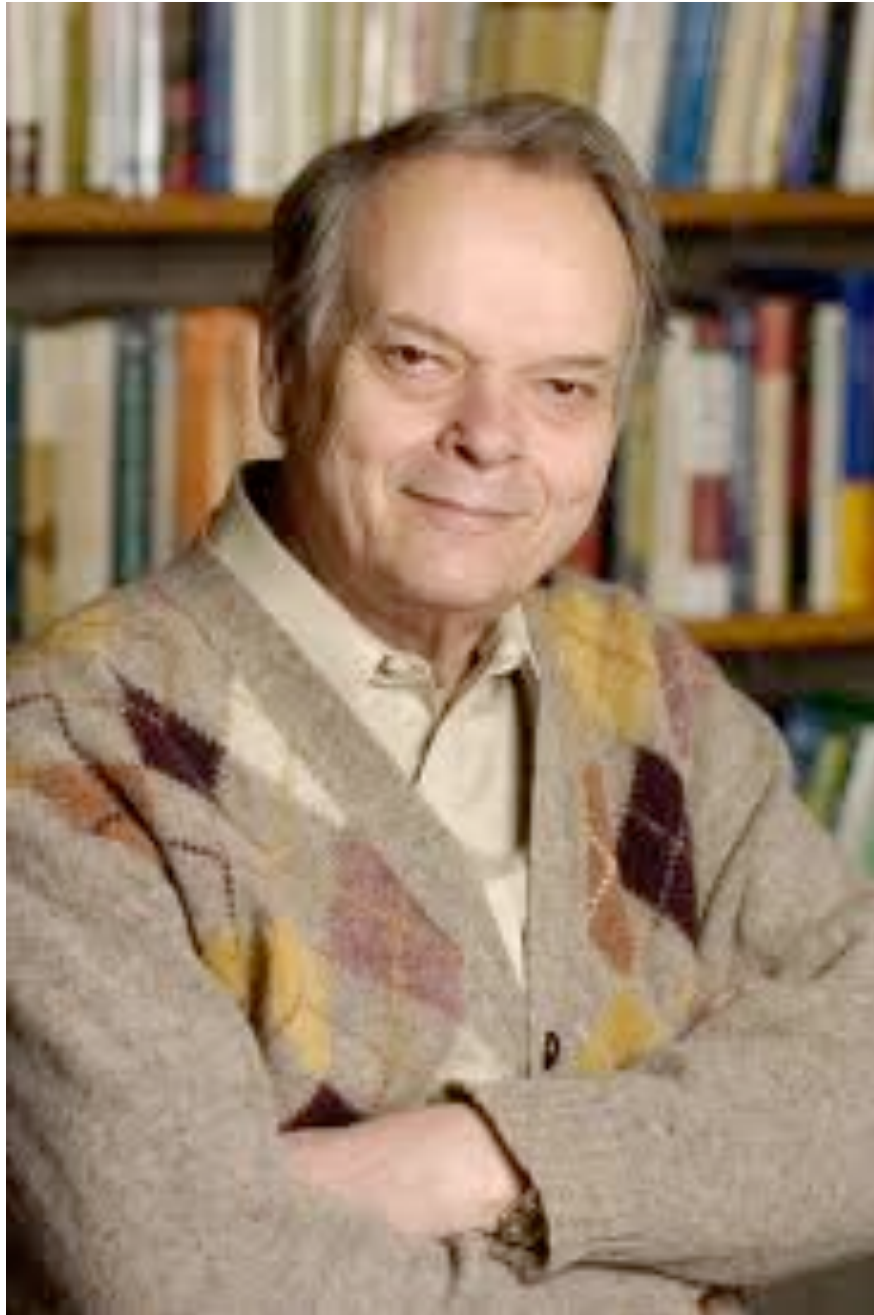
- Dafny and others are conservative with relation to aliasing by not assuming that objects from the same class are different.

```
method N() {  
    var a := new C();  
    var b := new C();  
  
    M(a,b);  
    assert b.f == 0; // Cannot be proven...  
}
```

- Framing conditions (reads, modifies) help to manage knowledge about objects.
- Other approaches include ownership hierarchy (Spec#), Ownership and data groups (JML), and **separation logic** (which we will study next) uses small footprint reasoning.

# Separation Logic

---

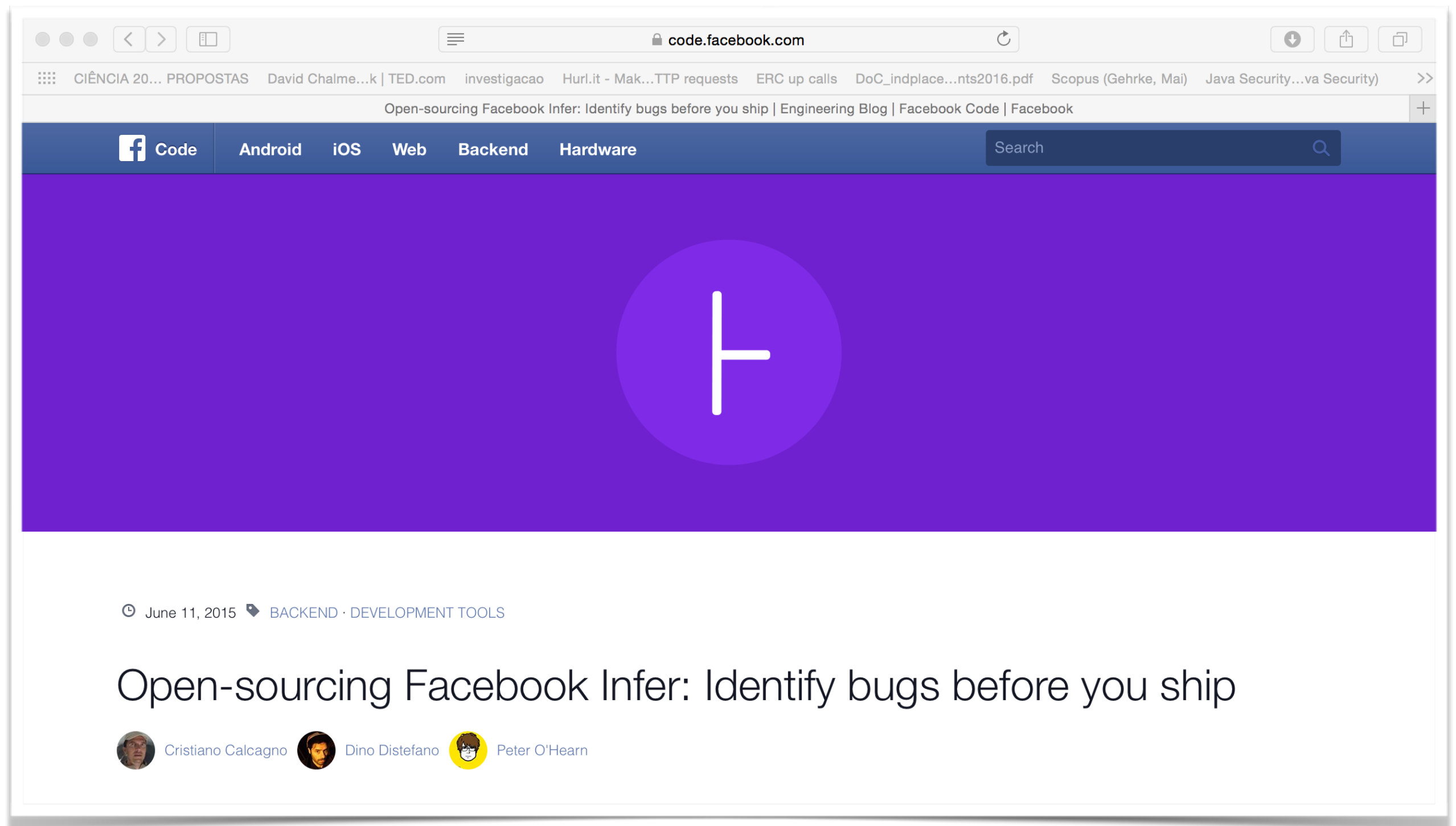


**John C. Reynolds**  
<https://www.cs.cmu.edu/~jcr/>



**Peter O'Hearn**

# Separation Logic @ facebook



# Separation Logic

---

- Separation logic is based in two key principles:

## (1) Small footprint

The precondition of a code fragment describes the part of the memory (heap) that the fragment needs to use.

## (2) Implicit framing

No need to explicitly specify the properties of state that is changed / not changed by the program (modifies)

- It adds to Hoare Logic two key novel primitives
  - the separating conjunction operator
  - the “precise” memory access assertion

$$A * B$$

$$L \mapsto V$$



# Separation Logic

---

Separation logic assertions used in our CVS course are described by the following grammar:

$A$	$::=$	Separation Logic Assertions
	$L \mapsto V$	Memory Access
	$  A * A$	Separating Conjunction
	$  \text{emp}$	Empty heap
	$  B$	Boolean condition (pure, not spatial)
	$  B?A : A$	Conditional
$B$	$::= B \wedge B \mid B \vee B \mid V = V \mid V \neq V \mid \dots$	
$V$	$::= \dots$	Pure Expressions
$L$	$::= x.\ell$	Object field



# Separation Logic

---

the **memory access** assertion

$$L \mapsto V$$

Assertion  $L \mapsto V$  holds of the “piece” of the state consisting precisely of memory location  $L$  holding  $V$

the **empty assertion**

$$\text{emp}$$

Assertion  $\text{emp}$  holds of the empty heap

the **separating conjunction**

$$A * B$$

Assertion  $A * B$  holds of any “piece” of the state that can be **disjointly** decomposed in a “piece” that satisfies  $A$  and another piece that satisfies  $B$ .

**NOTE:** if  $B$  is “pure” then  $A * B \Leftrightarrow A \wedge B$

# Digression: The Stack and the Heap

---

## **Stack**

Stores local variables and method parameters

The so-called call-stack, also stores return addresses

Memory recover discipline: FIFO, release on block exit

## **Heap**

Stores dynamically allocated objects (e.g. new / malloc)

Recover discipline: explicit release or garbage collection

## **Heap Model**

A sequence of mem locations (L) with their contents (V)

Memory contents are value of basic type (e.g. ints) or references (pointers) to memory locations

# Separation Logic

---

pure assertion (remember this from Dafny)

an assertion that does not depend on the state (e.g., a boolean expression not referring to memory locations).

precise assertion

an assertion that uniquely specifies some part of the memory heap (that has a unique footprint)

examples:

- no pure assertion is precise
- $L \mapsto V$  is precise, for a unique value  $V$
- $L \mapsto 3 * \text{true}$  is not precise — how many (sub)heaps satisfy this condition?

<https://www.cs.cmu.edu/~jcr/mfps2005.ps>

# Examples (SL / HL)

---

$$\{x \mapsto 2\} x := 4 \{x \mapsto 4\}$$

holds in SL

$$\{\} x := 4 \{x \mapsto 4\}$$

does not hold in SL

$$\{\} x := 4 \{x = 4\}$$

holds in HL

$$\{x \mapsto 2 * y \mapsto 3\} x := y \{x \mapsto 3 * y \mapsto 3\}$$

holds in SL

$$\{x \mapsto V * x \mapsto U\}$$

never holds in SL

$$\{x = V \wedge x = U\}$$

may hold in HL

# Basic Rules of Separation Logic

---

# Assignment Rule (SL)

---

- Recall the basic Hoare Logic Rule:

$$\{A[E/x]\} x := E \{A\}$$

- The assignment rule in separation logic is

$$\{x \mapsto V\} x := E \{x \mapsto E\}$$

- Note the small footprint principle, the precondition refers exactly to the part of the memory used by the fragment

# Frame Rule (SL)

---

- A key principle in SL is the Frame Rule

$$\frac{\{A\} P \{B\}}{\{A * C\} P \{B * C\}}$$

- This frame rule allows us to preserve info about the “rest of the world”, and locally reason about the effects of a program that only manipulates a given piece of the state
- The given piece footprint is specified by precondition  $A$
- There is no need to specify what is modified (it is clear from the pre-condition  $A$ ) neither what is not modified (it is framed away, as  $C$  above).

# Lookup Rule (SL)

---

- The memory lookup rule in SL is

$$\{L \mapsto V\} \ y := L \ \{L \mapsto V \wedge y = V\}$$

- Here  $y$  is a stack variable, not a heap location  $L$

$$\{L \mapsto V\} \ L := L + 1 \ \{L \mapsto V + 1\}$$

$$\{L \mapsto V\} \ y := L$$

$$\{L \mapsto V \wedge y = V\} \ L := y + 1$$

$$\{L \mapsto y + 1 \wedge y = V\}$$

$$\{L \mapsto V + 1\}$$



# Verifast

## Verifast

VeriFast is a verifier for single-threaded and multithreaded C and Java programs annotated with preconditions and postconditions written in separation logic.

Jacobs, Smans, Piessens, 2010-14

NB: separation logic is a spec language for talking about programs that allocate memory and use references

<https://people.cs.kuleuven.be/~bart.jacobs/verifast/>

<https://github.com/verifast/verifast>

```
public void broadcast_message(String message) throws IOException
    //@ requires room(this) && message != null;
    //@ ensures room(this);
{
    //@ open room(this);
    //@ assert foreach(?members0, _);
    List membersList = this.members;
    Iterator iter = membersList.iterator();
    boolean hasNext = iter.hasNext();
    //@ length_nonnegative(members0);
    while (hasNext)
        /*@
           invariant
               foreach<Member>(?members, @member) && iter(iter, membersList, members, ?i)
               && hasNext == (i < length(members)) && 0 <= i && i <= length(members);
        @*/
    {
        Object o = iter.next();
        Member member = (Member)o;
        //@ mem_nth(i, members);
        //@ foreach_remove<Member>(member, members);
        //@ open member(member);
        Writer writer = member.writer;
        writer.write(message);
        writer.write("\r\n");
        writer.flush();
        //@ close member(member);
        //@ foreach_unremove<Member>(member, members);
        hasNext = iter.hasNext();
    }
    //@ iter_dispose(iter);
    //@ close room(this);
}
```



# Account ADT (Java + Verifast)

---

```
public class Account {  
  
    int balance;  
  
    /*@  
    predicate AccountInv(int b) = this.balance == b && b >= 0;  
    @*/  
  
    public Account()  
    //@ requires true;  
    //@ ensures AccountInv(0);  
    {  
        balance = 0;  
    }  
  
    ...  
  
}
```

# Account ADT (Java + Verifast)

---

```
public class Account {  
  
    int balance;  
  
    ...  
    void deposit(int v)  
        //@ requires AccountInv(?b) &*& v >= 0;  
        //@ ensures AccountInv(b+v);  
    {  
        balance += v;  
    }  
  
    void withdraw(int v)  
        //@ requires AccountInv(?b) &*& b >= v;  
        //@ ensures AccountInv(b-v);  
    {  
        balance -= v;  
    }  
    ...  
}
```

# Account ADT (Java + Verifast)

---

```
public class Account {  
    int balance;  
  
    ...  
    void deposit(int v)  
        //@ requires AccountInv(?b) &*& v>=0;  
        //@ ensures AccountInv(b+v);  
    {  
        //@ open AccountInv(_)  
        balance += v;  
        //@ close AccountInv(_)  
    }  
}
```

- Verifast sometimes requires the programmer to explicitly open and close predicates, if assertions are not precise
- Not needed here, since `AccountInv(_)` is precise

# Account ADT (Java + Verifast)

---

```
public class Account {  
  
    int balance;  
  
    ...  
    int getBalance()  
    //@ requires AccountInv(?b);  
    //@ ensures AccountInv(b) &*& result==b ;  
    {  
        return balance;  
    }  
  
    ...  
}
```

# Stack ADT (using a linked list)

---

- Separation logic allows us to precisely define the shape and memory layout (footprint) of arbitrary heap allocated data structures.
- The framing principles allow us to easily express the functionality of heap manipulating operations using separation logic pre and post conditions
- Let's look to a simple example, a stack ADT implemented using a linked list.
- Again, we will use Verifast to annotate Java code.

# Stack ADT (using a linked list)

---

```
/*@
  predicate Node(Node n; Node nxt, int v) = n.next |-> nxt &*& n.val |-> v;
  predicate List(Node n;) = n == null ? emp : Node(n,?h,_) &*& List(h);
@*/

public class Node {
  Node next;
  int val;

  public Node()
  //@ requires true;
  //@ ensures Node(this,null,0);
  {
    next = null;
    val = 0;
  }
}
...
}
```

# Stack ADT (using a linked list)

---

- The predicate **Node(node n; node nxt, int v)** represents a single node object in the heap.

N.B. In Verifast, the “;” separates the input parameters, from i/o parameters, which may be queried using “?”.

- The predicate **List(node n;)** represents the shape and layout of properly formed linked list in the heap.

N.B. **List(node n;)** is recursively defined. A list is either empty (no memory) or contains an allocated head node linked to a possibly empty list.

- N.B. Note that our definition forbids cycles in the list.



# Stack ADT (using a linked list)

---

```
/*@
  predicate Node(Node n;Node nxt,int v) = n.next |-> nxt &*& n.val |-> v;
  predicate List(Node n;) = n == null ? emp : Node(n,?h,_) &*& List(h);
@*/
public class Node {
  Node next;
  int val;

  public void setnext(Node n)
  //@ requires Node(this,_,?v);
  //@ ensures Node(this,n,v);
  {
    next = n;
  }
  public void setval(int v)
  //@ requires Node(this,?n, _);
  //@ ensures Node(this,n, v);
  {
    val = v;
  }
  ...
}
```

# Stack ADT (using a linked list)

---

```
/*@
    predicate Node(Node n;Node nxt,int v) = n.next |-> nxt &*& n.val |-> v;
    predicate List(Node n;) = n == null ? emp : Node(n,?h,_) &*& List(h);
@*/
public class Node {
    Node next;
    int val;

    public Node getNext()
    //@ requires Node(this,?n,?v);
    //@ ensures Node(this,n,v) &*& result == n;
    {
        return next;
    }
    public int getval()
    //@ requires Node(this,?n,?v);
    //@ ensures Node(this,n,v) &*& result == v;;
    {
        return val;
    }
}
```

# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
@*/

public class Stack {

    Node head;

    public Stack()
    //@ requires true;
    //@ ensures StackInv(this);
    {
        head = null;
    }

    ...

}
```

# Stack ADT (using a linked list)

---

```
/*@
    predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
@*/

public class Stack {

    Node head;

    public void push(int v)
    //@ requires StackInv(this);
    //@ ensures StackInv(this);
    {
        node n = new Node();
        n.setval(v);
        n.setnext(head);
        head = n;
    }

    ...

}
```

# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
@*/

public class Stack {

    Node head;

    public void push_buggy(int v)
    //@ requires StackInv(this);
    //@ ensures StackInv(this);
    {
        node n = new Node();
        n.setval(v);
        n.setnext(n);
        head = n;
    }

    ...

}
```

This code will not compile in Verifast. Why?

# Stack ADT (using a linked list)

---

```
/*@
    predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);

@*/

public class Stack {

    Node head;

    public int pop()
    //@ requires StackInv(this);
    //@ ensures StackInv(this);
    {
        if(head != null) {
            int v = head.getval();
            head = head.getnext();
            return v;
        }
        return -1; // ??? how to deal with partiality ?
    }
}
```

# Stack ADT (using a linked list)

---

```
/*@
    predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
@*/

class StackEmptyE extends Exception {}

public class Stack {
    Node head;

    public int pop_maybe()
        throws StackEmptyE //@ ensures StackInv(this);
    //@ requires StackInv(this);
    //@ ensures StackInv(this);
    {
        if(head!=null) {
            int v = head.getval();
            head = head.getnext();
            return v;
        } else throw new StackEmptyE();
    }
}
```

# Exceptions in method contracts

---

- Java method contracts need to deal with exceptional behaviour, so Verifast allows postconditions to be specified at every exception thrown
- In the previous example, the `pop_maybe` method is partial and throws `StackEmptyE` if the stack is empty.
- Instead of making a method partial, we may try to define an appropriate precondition.
- so to make `pop` total we may add a special pre-condition expressing the typestate “non-empty-stack”.
- This will require client code to be able to dynamically check the ADT state (e.g. via an `isEmpty` method).



# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
  predicate NonEmptyStack(Stack s;) = s.head |-> ?h &* & h != null &* & List(h);
@*/

public class Stack {

    Node head;

    public int pop()
    //@ requires NonEmptyStack(this);
    //@ ensures StackInv(this);
    {
        int v = head.getval();
        head = head.getnext();
        return v;
    }

    ...
}
```

# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
  predicate NonEmptyStack(Stack s;) = s.head |-> ?h &* & h != null &* & List(h);
@*/

public class Stack {

    Node head;

    public boolean isEmpty()
    //@ requires StackInv(this);
    //@ ensures (result?StackInv(this):NonEmptyStack(this));
    {
        return head == null;
    }
    ...
}
```

# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
  predicate NonEmptyStack(Stack s;) = s.head |-> ?h &* & h != null &* & List(h);
@*/

public class Stack {

    Node head;

    public void push(int v)
    //@ requires StackInv(this);
    //@ ensures NonEmptyStack(this);
    {
        node n = new node();
        n.setval(v);
        n.setnext(head);
        head = n;
    }
    ...
}
```

# Abstract States and Substates

---

- In general, it is very useful to introduce abstract substates representing particular cases of the general representation invariant of an ADT.
- All abstract substates logically imply the most general representation invariant, for instance, in our examples, for every Stack  $s$ , the following implication is valid:

$$\text{NonEmptyStack}(s) \Rightarrow \text{StackInv}(s)$$

- Often these kinds of implications are not automatically derived by Verifast, but the programmer may give an hint, using **open** and **close** annotations (next slide).

# Stack ADT (using a linked list)

---

```
/*@
  predicate StackInv(Stack s;) = s.head |-> ?h &* & List(h);
  predicate NonEmptyStack(Stack s;) = s.head |-> ?h &* & h != null &* & List(h);
@*/

static void main()
//@ requires true;
//@ ensures true;
{
    stack s = new Stack();
    s.push(1);
    if (! s.isEmpty()) {
        s.pop();
    }
    s.push(2);
    //@ open NonEmptyStack(s);
    s.push(3);
    s.pop();
}
```