

矩阵论 第八次作业

第 1 章 线性空间和线性变换

1.3 两个特殊的线性空间

ppt 例题

P8 设矩阵空间 $R^{2 \times 2}$ 的子空间为

$$V = \{X = (x_{ij})_{2 \times 2} \mid x_{11} + x_{12} + x_{21} = 0, x_{ij} \in R\}$$

V 中的线性变换为 $T(X) = X + X^T$.

求 $(T^3)(X)$, $X = \begin{bmatrix} 4 & -4 \\ 0 & -3 \end{bmatrix} \in V$.

求 $(T^k)(X)$, $\forall X \in V$.

解 任意找一组基, 利用 Schmidt 正交化方法得到 V 的一组标准正交基 e_1, \dots, e_n , $x = k_1 e_1 + \dots + k_n e_n$, 其中 $k_i = (x, e_i)$.

令 $x_{11} = -x_{12} - x_{21}$

$$X = \begin{bmatrix} -x_{12} - x_{21} & x_{12} \\ x_{21} & x_{22} \end{bmatrix}, \quad Y = \begin{bmatrix} -y_{12} - y_{21} & y_{12} \\ y_{21} & y_{22} \end{bmatrix}$$

定义 V 的内积为 $(X, Y) = \text{tr}(XY^T) = (x_{12} + x_{21})(y_{12} + y_{21}) + x_{12}y_{12} + x_{21}y_{21} + x_{22}y_{22}$.

任意找一组基

$$X = \begin{bmatrix} -x_{12} - x_{21} & x_{12} \\ x_{21} & x_{22} \end{bmatrix} = x_{12} \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} + x_{21} \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix} + x_{22} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = x_{12}X_1 + x_{21}X_2 + x_{22}X_3$$

则,

$$\begin{aligned} Y'_1 &= X_1 = \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} \\ Y'_2 &= X_2 - \frac{(X_2, Y'_1)}{(Y'_1, Y'_1)} Y'_1 \\ &= \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 & -1 \\ 2 & 0 \end{bmatrix} \\ Y'_3 &= X_3 - \frac{(X_3, Y'_2)}{(Y'_2, Y'_2)} Y'_2 - \frac{(X_3, Y'_1)}{(Y'_1, Y'_1)} Y'_1 \\ &= \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} - \frac{3}{2} \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2} \\ 1 & 0 \end{bmatrix} - 0 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

单位化,

$$\begin{aligned} e_1 &= \frac{1}{|Y'_1|} Y'_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} \\ e_2 &= \frac{1}{|Y'_2|} Y'_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 & -1 \\ 2 & 0 \end{bmatrix} \\ e_3 &= \frac{1}{|Y'_3|} Y'_3 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

则,

$$\begin{aligned} x = \begin{bmatrix} 4 & -4 \\ 0 & -3 \end{bmatrix} &= (e_1, e_2, e_3) \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} \begin{cases} k_1 = (x, e_1) = -4\sqrt{2} \\ k_2 = (x, e_2) = 0 \\ k_3 = (x, e_3) = -3 \end{cases} \\ Te_1 &= \frac{1}{\sqrt{2}} \begin{bmatrix} -3 & 1 \\ 2 & 0 \end{bmatrix}, \quad Te_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -3 & 3 \\ 0 & 0 \end{bmatrix}, \quad Te_3 = \begin{bmatrix} 0 & 0 \\ 0 & 3 \end{bmatrix} \end{aligned}$$

解得,

$$\begin{aligned} Te_1 &= (e_1, e_2, e_3) \begin{bmatrix} 2 \\ \sqrt{3} \\ 0 \end{bmatrix} \\ Te_2 &= (e_1, e_2, e_3) \begin{bmatrix} \sqrt{3} \\ 0 \\ 0 \end{bmatrix} Te_3 = (e_1, e_2, e_3) \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} \end{aligned}$$

得到

$$T(e_1 \cdots e_n) = (e_1 \cdots e_n) \begin{bmatrix} 2 & \sqrt{3} & 0 \\ \sqrt{3} & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix} = (e_1 \cdots e_n) A_0$$

其中 $A_0 = PJP^{-1}$, J 是 Jordan 标准型 $\Rightarrow T(e_1 \cdots e_n) = (e_1 \cdots e_n)PJP^{-1}$.

$$\begin{aligned}
 \lambda I - A_0 &= \begin{bmatrix} \lambda - 2 & -\sqrt{3} & 0 \\ -\sqrt{3} & \lambda & 0 \\ 0 & 0 & \lambda - 3 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} -\sqrt{3} & \lambda - 2 & 0 \\ \lambda & -\sqrt{3} & 0 \\ 0 & 0 & \lambda - 3 \end{bmatrix} \rightarrow \begin{bmatrix} -\sqrt{3} & 0 & 0 \\ \lambda & \frac{\lambda-2}{\sqrt{3}}\lambda - \sqrt{3} & 0 \\ 0 & 0 & \lambda - 3 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} -\sqrt{3} & 0 & 0 \\ \lambda & \frac{1}{\sqrt{3}}(\lambda+1)(\lambda-3) & 0 \\ 0 & 0 & \lambda - 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & \lambda - 3 \\ 0 & (\lambda+1)(\lambda-3) & 0 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & \lambda - 3 & 0 \\ 0 & 0 & (\lambda+1)(\lambda-3) \end{bmatrix}
 \end{aligned}$$

不变因子: $d_1(\lambda) = 1$, $d_2(\lambda) = \lambda - 3$, $d_3(\lambda) = (\lambda + 1)(\lambda - 3)$

初等因子: $(\lambda - 3)$; $(\lambda + 1)$, $(\lambda - 3)$

初等因子组: $(\lambda - 3)$, $(\lambda + 1)$, $(\lambda - 3)$

Jordan 块: $J_1(\lambda_1) = (3)$, $J_2(\lambda_2) = (-1)$, $J_3(\lambda_3) = (3)$ Jordan 标准型: $J = \begin{bmatrix} 3 & & \\ & -1 & \\ & & 3 \end{bmatrix}$ 则

$P = (x_1, x_2, x_3)$, $PJ = A_0P \Rightarrow (3x_1, -x_2, 3x_3) = (A_0x_1, A_1x_2, A_0x_3)$.

$$\begin{aligned}
 (3I - A_0)x_1 &= \begin{bmatrix} 1 & -\sqrt{3} \\ -\sqrt{3} & 3 \\ & & 0 \end{bmatrix} x_1 = 0 \\
 (-I - A_0)x_2 &= \begin{bmatrix} -3 & -\sqrt{3} \\ -\sqrt{3} & -1 \\ & & -4 \end{bmatrix} x_2 = 0 \\
 (3I - A_0)x_3 &= \begin{bmatrix} 1 & -\sqrt{3} \\ -\sqrt{3} & 3 \\ & & 0 \end{bmatrix} x_3 = 0
 \end{aligned}$$

解得

$$x_1 = \begin{bmatrix} \sqrt{3} \\ 1 \\ 0 \end{bmatrix}, \quad x_2 = \begin{bmatrix} -1 \\ \sqrt{3} \\ 0 \end{bmatrix}, \quad x_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

因此

$$P = (x_1, x_2, x_3) = \begin{bmatrix} \sqrt{3} & -1 & 0 \\ 1 & \sqrt{3} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad P^{-1} = \begin{bmatrix} \frac{\sqrt{3}}{4} & \frac{1}{4} & 0 \\ -\frac{1}{4} & \frac{\sqrt{3}}{4} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

有

$$E_1 = (e_1, e_2, e_3) \begin{bmatrix} \sqrt{3} \\ 1 \\ 0 \end{bmatrix} = \frac{2}{\sqrt{6}} \begin{bmatrix} -2 & 1 \\ 1 & 0 \end{bmatrix}$$

$$E_2 = (e_1, e_2, e_3) \begin{bmatrix} -1 \\ \sqrt{3} \\ 0 \end{bmatrix} = \sqrt{2} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$E_3 = (e_1, e_2, e_3) \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

且 $T(E_1, E_2, E_3) = (E_1, E_2, E_3)J$, 通过坐标变换得到

$$x = (E_1, \dots, E_n)P^{-1} \begin{bmatrix} k_1 \\ \vdots \\ k_n \end{bmatrix} = (E_1, \dots, E_n) \begin{bmatrix} l_1 \\ \vdots \\ l_n \end{bmatrix}$$

$$\begin{aligned} x &= \begin{bmatrix} 4 & -4 \\ 0 & -3 \end{bmatrix} = (e_1, e_2, e_3) \begin{bmatrix} -4\sqrt{2} \\ 0 \\ -3 \end{bmatrix} \\ &= (E_1, E_2, E_3)P^{-1} \begin{bmatrix} -4\sqrt{2} \\ 0 \\ -3 \end{bmatrix} = (E_1, E_2, E_3) \begin{bmatrix} -\sqrt{6} \\ \sqrt{2} \\ -3 \end{bmatrix} \end{aligned}$$

于是

$$\begin{aligned} (T^3)(x) &= (E_1, E_2, E_3) \begin{bmatrix} 27 & & \\ & -1 & \\ & & 27 \end{bmatrix} \begin{bmatrix} -\sqrt{6} \\ \sqrt{2} \\ -3 \end{bmatrix} = \begin{bmatrix} 108 & -52 \\ -56 & -81 \end{bmatrix} \\ (T^k)(x) &= (E_1, E_2, E_3) \begin{bmatrix} 3^k & & \\ & (-1)^k & \\ & & 3^k \end{bmatrix} \begin{bmatrix} \frac{\sqrt{3}}{4} & \frac{1}{4} & 0 \\ -\frac{1}{4} & \frac{\sqrt{3}}{4} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} (x, e_1) \\ (x, e_2) \\ (x, e_3) \end{bmatrix} \end{aligned}$$

例题

例 1.36 在欧式空间 $R^{2 \times 2}$ 中, 矩阵 A 和 B 的内积定义为 $(A, B) = \text{tr}(A^T B)$, 子空间

$$V = \left\{ \mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \mid x_3 - x_4 = 0 \right\}$$

V 中的线性变换为

$$T(\mathbf{X}) = \mathbf{X}\mathbf{B} + \mathbf{X}^T \quad (\forall \mathbf{X} \in V), \quad \mathbf{P} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$$

- (1) 求 V 的一个标准正交基;
- (2) 验证 T 是 V 中的对称变换;
- (3) 求 V 的一个标准正交基, 使 T 在该基下的矩阵为对角矩阵.

解

- (1) 设 $\mathbf{X} \in V$, 则

$$\mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_3 \end{bmatrix} = x_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}$$

故 V 的一个标准正交基为

$$\mathbf{X}_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{X}_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{X}_3 = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}$$

- (2) 计算基象组:

$$T(\mathbf{X}_1) = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} = 1\mathbf{X}_1 + 2\mathbf{X}_2 + 0\mathbf{X}_3$$

$$T(\mathbf{X}_2) = \begin{bmatrix} 2 & 1 \\ 0 & 0 \end{bmatrix} = 2\mathbf{X}_1 + 1\mathbf{X}_2 + 0\mathbf{X}_3$$

$$T(\mathbf{X}_3) = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 0 \\ 3 & 3 \end{bmatrix} = 0\mathbf{X}_1 + 0\mathbf{X}_2 + 3\mathbf{X}_3$$

设 $T(\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3) = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3)\mathbf{A}$, 则

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

\mathbf{A} 为对称矩阵, 因此 T 是对称变换.

- (3) 求正交矩阵 \mathbf{Q} 使得 $\mathbf{Q}^{-1}\mathbf{A}\mathbf{Q} = \mathbf{A}$, 解得

$$\mathbf{A} = \begin{bmatrix} 3 & & \\ & 3 & \\ & & -1 \end{bmatrix} \quad \mathbf{Q} = \begin{bmatrix} 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 1 & 0 & 0 \end{bmatrix}$$

令 $(\mathbf{Y}_1, \mathbf{Y}_2, \mathbf{Y}_3) = (\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3)\mathbf{Q}$, 求得标准正交基

$$\mathbf{Y}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, \quad \mathbf{Y}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{Y}_3 = -\frac{1}{\sqrt{2}} \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix}$$

且有 $T(\mathbf{Y}_1, \mathbf{Y}_2, \mathbf{Y}_3) = (\mathbf{Y}_1, \mathbf{Y}_2, \mathbf{Y}_3)\mathbf{A}$.

习题

习题 1.3.15 在欧式空间 $R^{2 \times 2}$ 中, 矩阵 A 和 B 的内积定义为 $(A, B) = \text{tr}(A^T B)$, 子空间

$$V = \left\{ \mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \mid \begin{array}{l} x_1 - x_4 = 0 \\ x_2 - x_3 = 0 \end{array} \right\}$$

V 中的线性变换为

$$T(\mathbf{X}) = \mathbf{X}\mathbf{P} + \mathbf{X}^T \quad (\forall \mathbf{X} \in V), \quad \mathbf{P} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- (1) 求 V 的一个标准正交基;
- (2) 验证 T 是 V 中的对称变换;
- (3) 求 V 的一个标准正交基, 使 T 在该基下的矩阵为对角矩阵.

解

- (1) 设 $\mathbf{X} \in V$, 则

$$\mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_2 & x_1 \end{bmatrix} = x_1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

故 V 的一个标准正交基为

$$\mathbf{X}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{X}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- (2) 计算基象组

$$\begin{aligned} T(\mathbf{X}_1) &= \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = 1\mathbf{X}_1 + 1\mathbf{X}_2 \\ T(\mathbf{X}_2) &= \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = 1\mathbf{X}_1 + 1\mathbf{X}_2 \end{aligned}$$

设 $T(\mathbf{X}_1, \mathbf{X}_2) = (\mathbf{X}_1, \mathbf{X}_2)\mathbf{A}$, 则

$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

- (3)

$$\begin{aligned} \lambda I - \mathbf{A} &= \begin{bmatrix} \lambda - 1 & -1 \\ -1 & \lambda - 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} \lambda & -\lambda \\ -1 & \lambda - 1 \end{bmatrix} \rightarrow \begin{bmatrix} \lambda & 0 \\ -1 & \lambda - 2 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} \lambda & 0 \\ 0 & \lambda - 2 \end{bmatrix} \end{aligned}$$

所以

$$\begin{aligned}(-\mathbf{A})x_1 &= \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} x_1 = 0 \\ (2I - \mathbf{A})x_2 &= \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} x_2 = 0\end{aligned}$$

解得 $x_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad x_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

所以

$$A = \begin{bmatrix} 0 & \\ & 2 \end{bmatrix} \quad P = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

于是有

$$\begin{aligned}\mathbf{Y}_1 &= \frac{1}{2} \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \\ \mathbf{Y}_2 &= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}\end{aligned}$$