

# EE302 Spring 2018 Homework 3 - Guide Solution Afkar Saranli

Q1.) a)  $q(s) = s^3 + 20s^2 + 10s + 400$

|       |           |     |   |
|-------|-----------|-----|---|
| $s^3$ | 1         | 10  | 0 |
| $s^2$ | 20        | 400 | 0 |
| $s^1$ | $a = -10$ | 0   |   |
| $s^0$ | $b = 400$ |     |   |

$$a = \frac{20 \cdot 10 - 400}{20} = \frac{200 - 400}{20} = \frac{-200}{20} = -10$$

There are two sign changes in the first column. System unstable with 2 right half plane (RHP) poles.

b)  $q(s) = s^5 + 3s^4 + 2s^3 + 6s^2 + 3s + 1$

|       |                          |               |   |   |
|-------|--------------------------|---------------|---|---|
| $s^5$ | 1                        | 2             | 3 | 0 |
| $s^4$ | 3                        | 6             | 1 | 0 |
| $s^3$ | $\epsilon$               | $\frac{8}{3}$ | 0 |   |
| $s^2$ | $6 - \frac{8}{\epsilon}$ | 1             | 0 |   |
| $s^1$ | $\frac{8}{3}$            | 0             |   |   |
| $s^0$ | 1                        |               |   |   |

$$\frac{3 \cdot 2 - 6}{3} = 0! \text{ replace with } \epsilon$$

zero first column

$$\frac{6\epsilon - 8}{\epsilon} = 6 - \frac{8}{\epsilon} < 0$$

$$\frac{(6 - \frac{8}{\epsilon}) \frac{8}{3} - \epsilon}{6 - \frac{8}{\epsilon}} = \frac{8}{3} - \frac{\epsilon}{6\epsilon - 8}$$

$$= \frac{8}{3} - \frac{\epsilon^2}{6\epsilon - 8} \approx \frac{8}{3}$$

very small positive number.

for  $\epsilon > 0 \rightarrow 6 - \frac{8}{\epsilon} < 0 \rightarrow$  2 sign changes

for  $\epsilon < 0 \rightarrow 6 - \frac{8}{\epsilon} > 0 \rightarrow$  2 sign changes.

$\epsilon$  very large negative  $\frac{8}{\epsilon}$

$\rightarrow$  system unstable with 2 RHP poles.

Alternatively, you may try to multiply  $q(s)$  by known factors  $(s + \alpha)$  and attempt to get rid of zero first column.

Q.1. c)  $q(s) = s^4 - s^3 + 2s^2 - 4s - 8$

Routh array:

|       |    |    |    |
|-------|----|----|----|
| $s^4$ | 1  | 2  | -8 |
| $s^3$ | -1 | -4 | 0  |
| $s^2$ | -2 | -8 | 0  |
| $s^1$ | 0  | 0  |    |
| $s^0$ | -4 | 0  |    |
|       | -8 |    |    |

sign changes in  $q(s)$   
immediately concludes system  
is unstable.

$$\frac{-1 \cdot 2 - (-4)}{-1} = \frac{-2}{-1} = 2$$

$$\frac{-2(-4) - (-1)(-8)}{-2} = \frac{8 - 8}{-2} = 0!$$

We have a zero row on  $s^1$ .

Auxiliary polynomial

$$r(s) = -2s^2 - 8$$

$\frac{dr(s)}{ds} = -4s$  replace zero row  
by this coefficient  
and continue with Routh array.

→ One sign change in the  
first column. System has  
one unstable pole in R.H.P

But zero row indicates that we  
also have poles on the jw axis.  
complex-conjugate.

Use the auxiliary polynomial  
to solve for them:

$$r(s) = -2s^2 - 8 = 0 \rightarrow 2s^2 = -8$$

$$s^2 = -4$$

$$s = \pm j2$$

Q.1. d)  $q(s) = s^5 + 2s^4 + 16s^3 + 32s^2 + 100s + 200$

|       |     |     |     |   |
|-------|-----|-----|-----|---|
| $s^5$ | 1   | 16  | 100 | 0 |
| $s^4$ | 2   | 32  | 200 | 0 |
| $s^3$ | 0   | 0   | 0   |   |
| $s^2$ | 8   | 64  | 0   |   |
| $s^1$ | 16  | 200 | 0   |   |
| $s^0$ | 36  | 0   |     |   |
|       | 200 |     |     |   |

$$\left. \begin{aligned} \frac{2 \cdot 16 - 32}{2} &= 0! \\ \frac{2 \cdot 100 - 200}{2} &= 0! \end{aligned} \right\} \text{zero row.}$$

Auxiliary polynomial:

$$r(s) = 2s^4 + 32s^2 + 200$$

$$\frac{dr(s)}{ds} = 8s^3 + 64s$$

Replace the zero row with these coefficients.

$$\frac{8 \cdot 32 - 2(64)}{8} = 32 - 16 = 16$$

$$\frac{16 \cdot 64 - 8(200)}{16} = 64 - 100 = -36$$

Two sign changes in the first column. System unstable

We are not asked to find the poles causing the symmetry but solving  $r(s) = 0$  (e.g. using Matlab `roots(.)` command) gives:

$$\left. \begin{aligned} s_{1,2} &= -1 \pm j3 \\ s_{3,4} &= 1 \pm j3 \end{aligned} \right\} \text{symmetry around the } j\omega \text{ axis with two complex conjugate poles.}$$

Q2.  $G(s)H(s) = \frac{K(s+2)}{s(1+Ts)(1+2s)}$  stability regions in T-K plane are requested.

Routh-Hurwitz can be used to obtain these regions. First calculate the closed-loop characteristic Equation.

$$q(s) = 1 + \frac{K(s+2)}{s(1+Ts)(1+2s)} = 0$$

$$(s+Ts^2)(1+2s) + Ks + 2K$$

$$s + 2s^2 + Ts^2 + 2Ts^3 + Ks + 2K = 0$$

$$q(s) = 2Ts^3 + (2+T)s^2 + (K+1)s + 2K = 0$$

Construct the Routh-Array:

|       |       |       |   |
|-------|-------|-------|---|
| $s^3$ | $2T$  | $K+1$ | 0 |
| $s^2$ | $2+T$ | $2K$  | 0 |
| $s^1$ | $a$   | 0     |   |
| $s^0$ | $2K$  |       |   |

$$a = \frac{(2+T)(K+1) - 4KT}{2+T}$$

For stability, we need no sign change in first column. This can happen in two ways: all terms positive (Case I) and all terms negative (Case II)

Case I: All terms in first column positive.

$$\left. \begin{array}{l} \text{This requires } 2T > 0 \rightarrow T > 0 \\ 2+T > 0 \rightarrow T > -2 \end{array} \right\} \boxed{T > 0}$$

$$2K > 0 \rightarrow \boxed{K > 0}$$

We also need  $a > 0$   $\rightarrow$





Now let us check the boundaries: (including internal asymptote)

1)  $K=0$   $q(s) = 2Ts^3 + (2+T)s^2 + s = s(2Ts^2 + (2+T)s + 1)$

are pole at the origin - stability boundary.

2.)  $K = \frac{1}{3}$   $q(s) = 2Ts^3 + (2+T)s^2 + \left(\frac{1}{3} + 1\right)s + \frac{2}{3}$   
 $\frac{4}{3}$  with  $T > 0$

|       |               |               |   |
|-------|---------------|---------------|---|
| $s^3$ | $2T$          | $\frac{4}{3}$ | 0 |
| $s^2$ | $2+T$         | $\frac{2}{3}$ | 0 |
| $s^1$ | $a$           | 0             |   |
| $s^0$ | $\frac{2}{3}$ |               |   |

$$a = \frac{\frac{4}{3}(2+T) - \frac{4T}{3}}{\frac{4T}{3}} = \frac{\frac{8}{3} + \frac{4T}{3} - \frac{4T}{3}}{\frac{4T}{3}}$$

$a > 0$   
 $2T > 0$   
 $2+T > 0$  } system stable.

3.)  $T=0$   $q(s) = 2s^2 + (K+1)s + 2K = 0$  with  $K > 0$

|       |     |    |
|-------|-----|----|
| $s^2$ | 2   | 2K |
| $s^1$ | K+1 | 0  |
| $s^0$ | 2K  |    |

$2 > 0$   
 $K+1 > 0$   
 $2K > 0$  } system stable.  
 but of reduced order.  
 (2<sup>nd</sup> order)

Case II: Now let us consider first column all negative and see whether any extra stable regions are provided.

Original Routh array: on page 4.

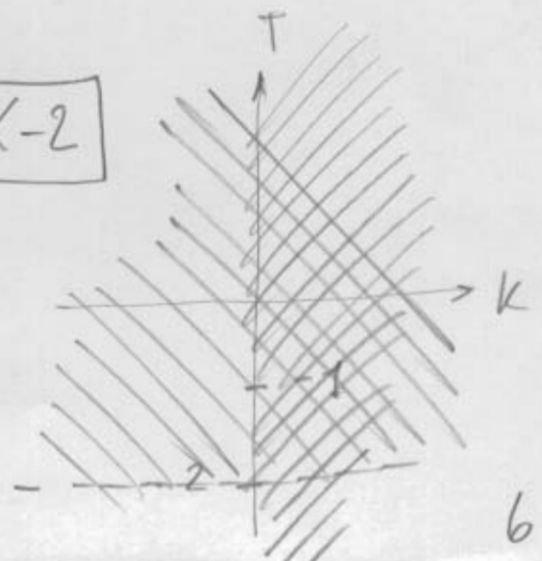
We need  $2T < 0 \rightarrow T < 0$

$2+T < 0 \rightarrow T < -2$

$2K < 0 \rightarrow K < 0$

$T < -2$

We also need  $a < 0$



$$a < 0 \rightarrow \frac{(2+T)(K+1) - 4KT}{2+T} < 0$$

But we already need  $2+T < 0$  so, we additionally need  $(2+T)(K+1) - 4KT > 0$

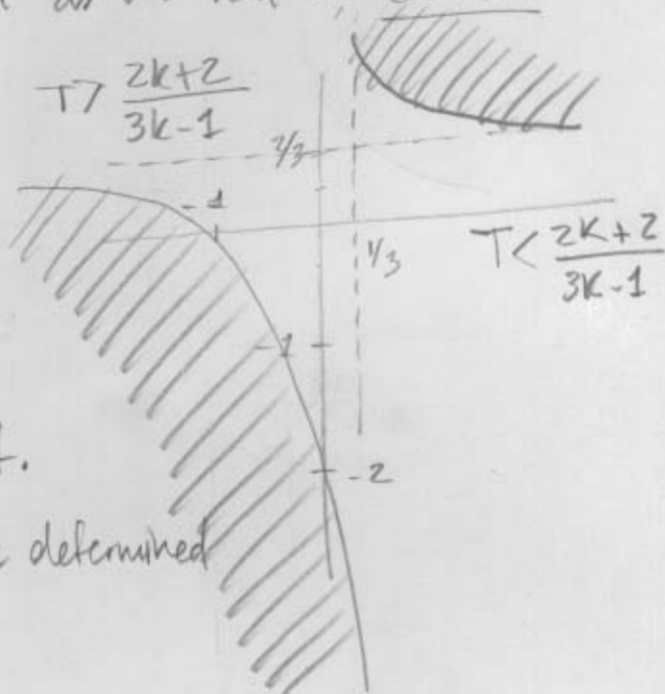
This is the same condition as we had in Case I.

When we combine this with  $T < -2$

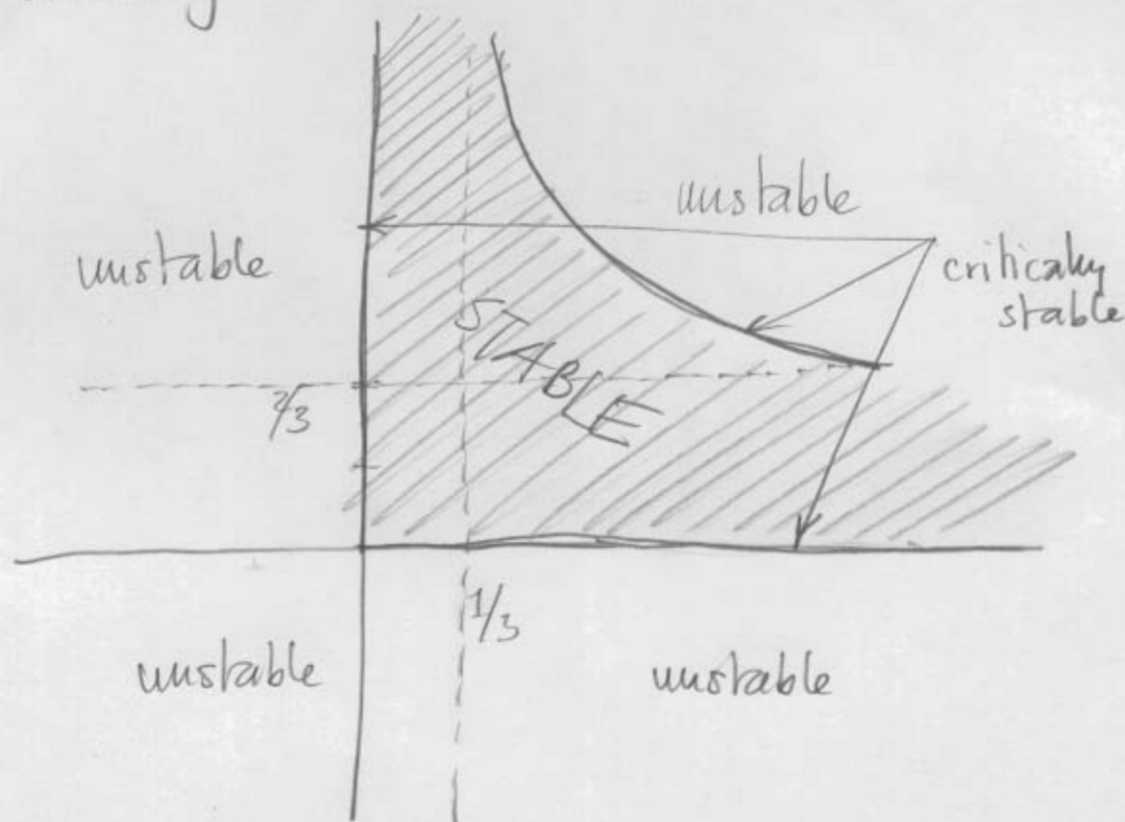
$$K < 0$$

The overlap is non-existent.

→ No other stable regions are determined from Case II.



The stable region is illustrated again below



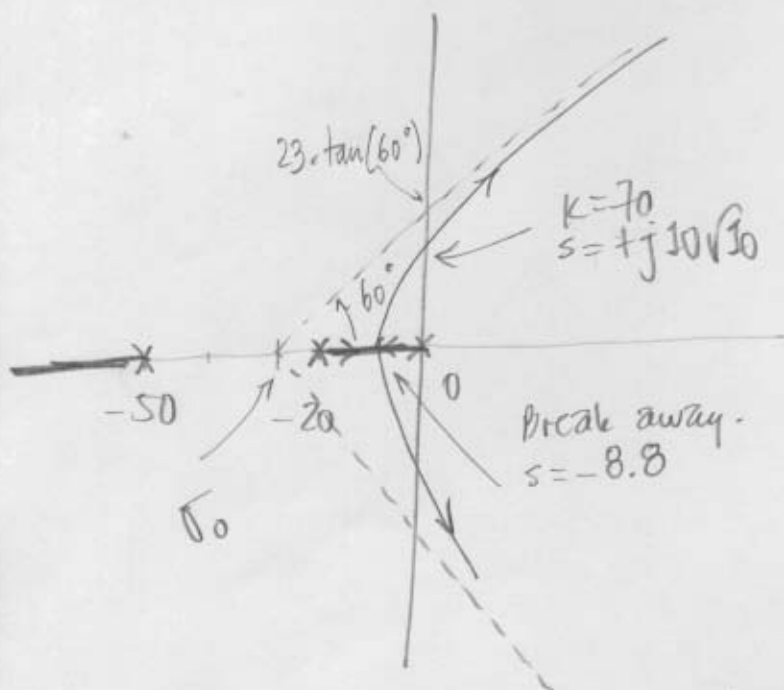
Q.3 a)  $G(s) = \frac{K}{s(1+0.02s)(1+0.05s)}$  for  $K > 0$

We want to sketch the root locus. But careful about the denominator:

$$G(s) = \frac{K}{s(0.02)(s+50)(0.05)(s+20)} = \frac{1000K}{s(s+50)(s+20)}$$

let  $\bar{K} = 1000K$

$$q(s) = 1 + \bar{K} \frac{1}{s(s+50)(s+20)}$$



Rule 1: # of branches:

$$\max(m, n) = 3$$

Rule 2: Branches start at poles and end up at the three asymptotes.

Rule 3: root-locus is symmetric wrt the real line.

Rule 4: asymptotes:  $|m-n| = 3$

$$\phi = \frac{\pm 180}{3}(2l+1) = +60, -60, +180^\circ$$

Rule 5: Centroid (real axis intersection of asymptotes)

$$\sigma_0 = \frac{\sum p - \sum z}{\#p - \#z} = \frac{0 - 20 - 50 - (0)}{3 - 0} = -\frac{70}{3} \approx -23.33$$

Rule 6: Locus on real line

Rule 7: Break away point: Between -20 and 0.

$$\frac{d}{ds} \left[ \frac{1}{s(s+50)(s+20)} \right] = \frac{d}{ds} \left( \frac{1}{s^3 + 70s^2 + 1000s} \right) = \frac{-3s^2 - 140s - 1000}{(s^3 + 70s^2 + 1000s)^2}$$

$$\left( \frac{u}{v} \right)' = \frac{u'v - uv'}{v^2}$$

Solve  $-3s^2 - 140s - 1000 = 0$

let  $q(s)|_{s=-8.8} = 0 \rightarrow$  Find  $\bar{K}$  and then  $K$ .

$$s = -37.9$$

$$s = -8.8$$



Q3.2) Continued

$$q(-8.8) = 1 + \bar{K} \frac{1}{(-8.8)(-8.8+50)(-8.8+20)} = 0 \rightarrow \bar{K} \approx 4060$$

$$\rightarrow \boxed{\bar{K} \approx 4.06}$$

Rule 8:

For jw axis crossing:

$$q(s) = 1 + \bar{K} \frac{1}{s(s+50)(s+20)} = 0$$

$$(s^2 + 50s)(s+20) + \bar{K} = 0$$

$$s^3 + \underbrace{20s^2 + 50s^2}_{70s^2} + 1000s + \bar{K} = 0$$

jw axis crossing at  $7 \times 10^4 - \bar{K} = 0$

$$\bar{K} = 7 \times 10^4 \rightarrow \boxed{K = 70}$$

Auxiliary equation  $r(s) = 70s^2 + \bar{K} = 0$

$$70s^2 + 7 \times 10^4 = 0$$

$$s^2 = -\frac{70000}{70} = -1000 \rightarrow \boxed{s = \pm j10\sqrt{10}}$$

Routh-Array:

|       |                                      |           |   |
|-------|--------------------------------------|-----------|---|
| $s^3$ | 1                                    | 1000      | 0 |
| $s^2$ | 70                                   | $\bar{K}$ | 0 |
| $s^1$ | $\frac{7 \times 10^4 - \bar{K}}{70}$ | 0         |   |
| $s^0$ | $\bar{K}$                            |           |   |

Q.3 b)  $G(s) = \frac{K}{s(s+1)(s+2)(s+5)}$  for  $K > 0$

$$q(s) = 1 + K \frac{1}{s(s+1)(s+2)(s+5)}$$

Rule 1: # of branches  
 $= \max(m, n) = 4$

Rule 2: 4 branches start at OL poles. No open-loop zeros.  
 (all will go to asymptotes)

Rule 3: Symmetry ✓

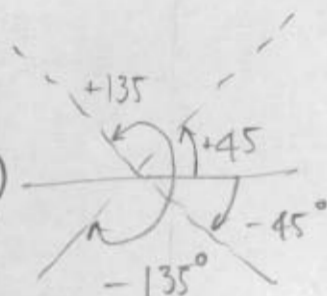
Rule 4: # of asymptotes  $= |m - n| = 4$

Angles of asymptotes:  $\phi = \frac{\pm 180}{4}(2l+1)$

Rule 5: Centroid:

$$= \pm 45(2l+1)$$

$$\sigma_0 = \frac{\sum p - \sum z}{\#p - \#z} = \frac{-1-2-5}{4} = \frac{-8}{4} = -2$$



Rule 6: Locus on the real line: shown.

Rule 7: Break-away points.

$$\frac{d}{ds} \left( \frac{1}{s^4 + 8s^3 + 17s^2 + 10s} \right) = 0$$

$$= \frac{-4s^3 - 24s^2 - 34s - 10}{(\dots)^2} = 0$$

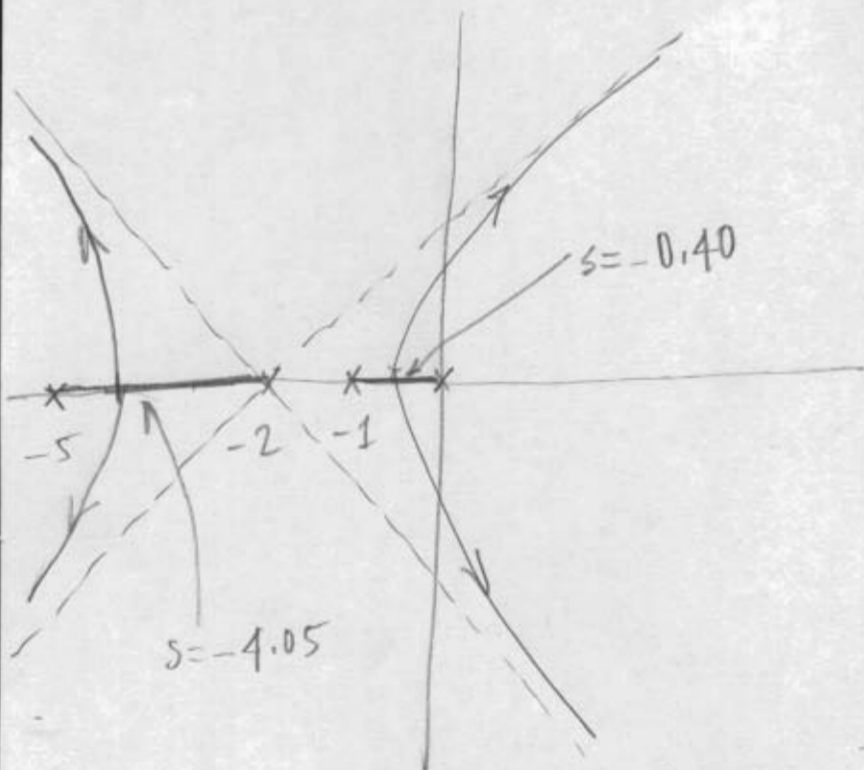
→ Using roots(.) in Matlab

$$s_1 = -4.05 \checkmark$$

$$s_2 = -1.54 \times$$

$$s_3 = -0.40$$

Put these  $s$  into  $q(s) = 0$  to get corresponding  $K$  values.



Rule 8: jw axis crossing

$$q(s) = 1 + K \frac{1}{s(s+1)(s+2)(s+3)} = 0$$

$$q(s) = s(s+1)(s+2)(s+3) + K$$

$$= s^4 + 6s^3 + 11s^2 + 6s + K$$

Routh array:

|       |      |    |   |
|-------|------|----|---|
| $s^4$ | 1    | 17 | K |
| $s^3$ | 6    | 10 | 0 |
| $s^2$ | 5.75 | K  | 0 |
| $s^1$ | a    | 0  |   |
| $s^0$ | K    |    |   |

$$\frac{6 \cdot 17 - 10}{6} = 17 - \frac{10}{6} = 15.75$$

$$\frac{(15.75)(10) - 6K}{15.75}$$

jw axis crossing when  $a = 0$

$$6K = (15.75)(10)$$

$$K \approx 19.69$$

The corresponding poles are found from the auxiliary polynomial equation

$$17.75s^2 + K = 0$$

$$15.75s^2 + 19.69 = 0 \rightarrow$$

$$s^2 = -\frac{19.69}{15.75} \approx -1.25$$

$$s \approx \pm j1.12$$

Q.3 c)  $G(s) = \frac{10(s+\alpha)(s+3)}{s(s^2-1)} \quad \alpha > 0$

First find the characteristic polynomial:

$$q(s) = 1 + \frac{10(s+\alpha)(s+3)}{s(s^2-1)} = \frac{s(s^2-1) + 10(s+\alpha)(s+3)}{s(s^2-1)} = 0$$

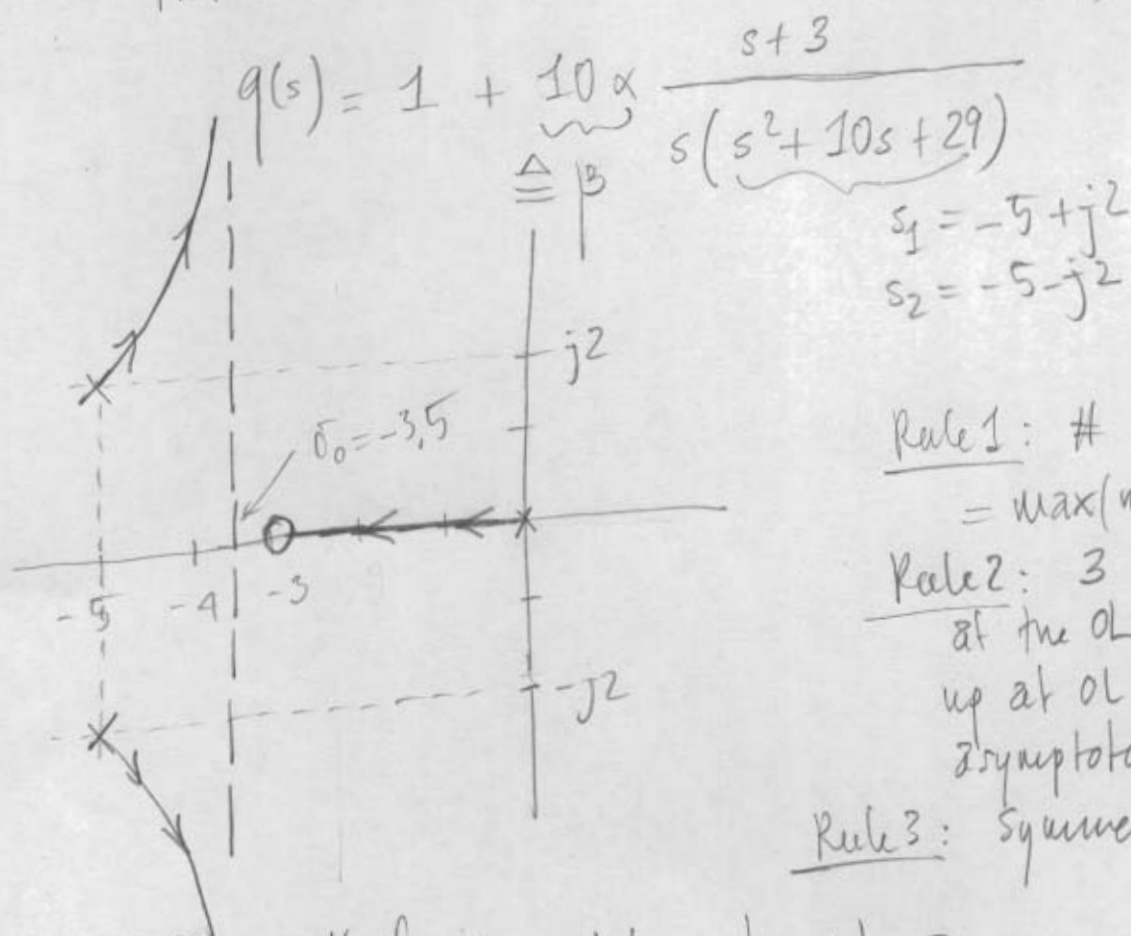
numerator  
of

$$\rightarrow q(s) = s^3 - s + 10(s^2 + 3s + \alpha s + 3\alpha) = 0$$

$$q(s) = s^3 + 10s^2 + 30s + 10\alpha s + 30\alpha = 0$$

$$q(s) = s^3 + 10s^2 + 29s + 10\alpha(s+3) = 0$$

Put into standard form  $q(s) = 1 + K \frac{N(s)}{D(s)}$



Rule 1: # of branches  
=  $\max(m, n) = 3$

Rule 2: 3 branches start at the OL poles. One ends up at OL zero, others at asymptotes.

Rule 3: Symmetry.

Rule 4: # of asymptotes =  $|m-n| = 2$

Angles  $\phi = \frac{\pm 180}{2}(2l+1) \begin{matrix} +90^\circ \\ -90^\circ \end{matrix}$

Rule 5: Centroid

$$\sigma_0 = \frac{\sum p - \sum z}{\#p - \#z} = \frac{0 - 5 + j2 - 5 - j2 - (-3)}{3 - 1} = \frac{-10 + 3}{2} = -\frac{7}{2}$$



Rule 6: Locus on the real-line: shown.

Rule 7: We do not expect any break-in/break-away points.

Rule 8: jw axis crossings. We do not expect any because of the asymptote location. If branches cross to the RHP, they need to come back requiring at least 4 jw axis crossing. That requires an auxiliary polynomial of order 4. Which is not possible since  $q(s)$  is of order 3 only.

Without solving for the angle of departure from the complex conjugate poles; the simplest sketch is shown.

Note: Note that the sketch is for  $\beta > 0$ .  
Since there are no critical points for which we find  $\beta$ ; we do not need to compute the corresponding  $\alpha$ .  
But note that we move on the branches  $\alpha = \frac{\beta}{10}$   
(10 times slower) with  $\alpha$  parameter.

