



MIDDLE EAST TECHNICAL UNIVERSITY
MECHANICAL ENGINEERING DEPARTMENT
ME 205 STATICS – FALL 2018
SECTION 1

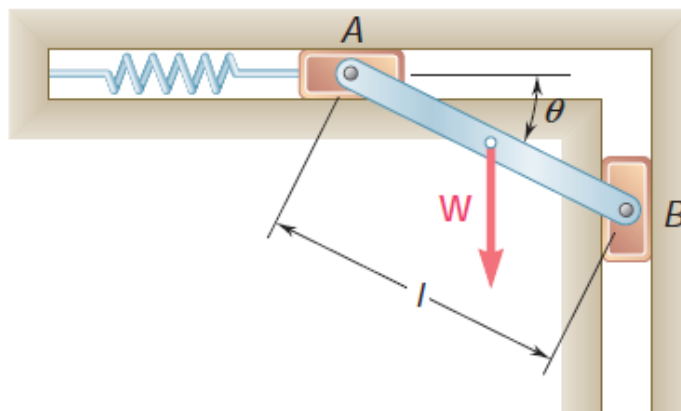
HOMEWORK #3

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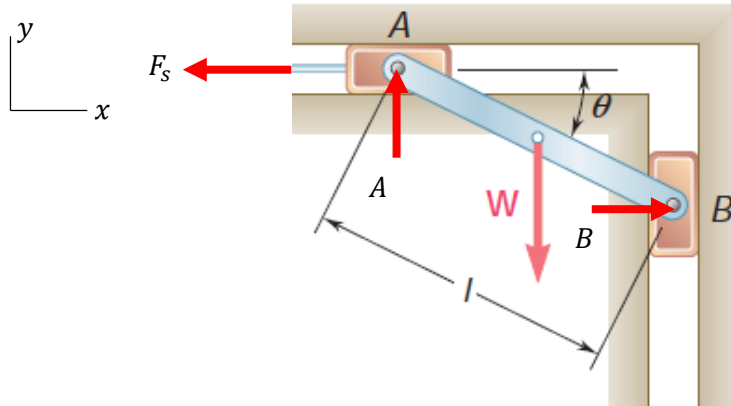
Assigned Date: 28.11.2018
Due Date: 05.12.2018
Due Time: 14.00
Grading Due Date: 12.12.2018

Please include your name, student ID, due date, a proper headline, page number with total page number, and units in your homework. Neatness will be graded.

1. The rod AB is attached to the block A which can translate freely in the x – axis and the block B which can translate freely in the y – axis. The weight of the rod is W , the length of the rod is l , and the spring constant is k . The spring is unstretched when $\theta = 0$. The weights of the blocks are neglected. Determine,
 - a. The equilibrium equation in terms of W , k , l , and θ ,
 - b. The value of θ when $W = 2kl$.



Solution:



$$F_s = k(l - l \cos \theta) = kl(1 - \cos \theta)$$

$$\sum F_y = 0; \quad A - W = 0$$

$$\rightarrow A = W$$

$$\sum M_B = 0; \quad W \frac{l \cos \theta}{2} - Al \cos \theta + F_s l \sin \theta = 0$$

$$\rightarrow kl^2(1 - \cos \theta) \sin \theta = W \frac{l \cos \theta}{2}$$

$$(1 - \cos \theta) \tan \theta = \frac{W}{2kl} \quad (a)$$

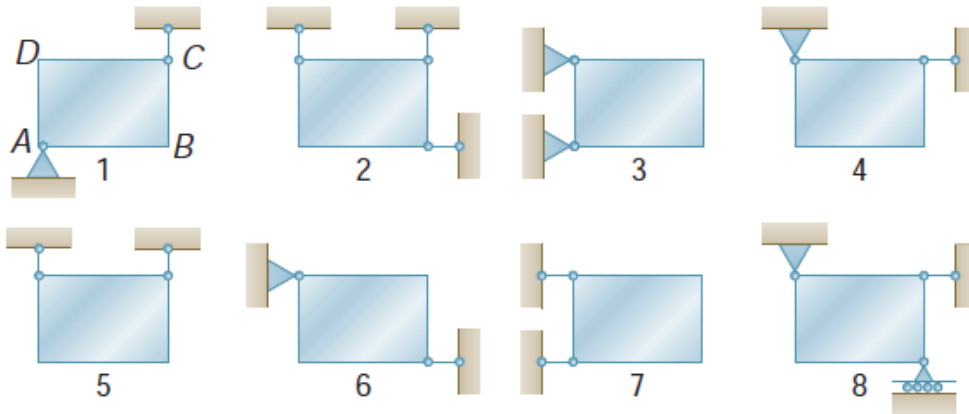
When $W = 2kl$,

$$(1 - \cos \theta) \tan \theta = 1$$

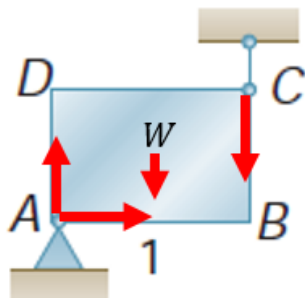
Solving numerically to obtain,

$$\theta = 62.03^\circ \quad (b)$$

2. In the following figure, there are 8 plates, each of dimensions 400 x 250-mm and weight 200-N. The plates are held in vertical plane and take. In each case, determine
- Whether the reactions are statically determinate or indeterminate,
 - Whether the equilibrium statically exist,
 - The reaction forces if possible.

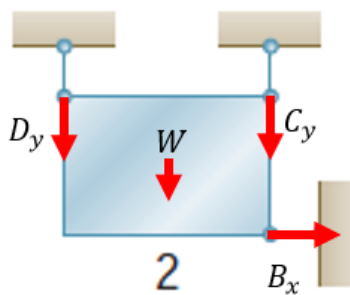


Solution:



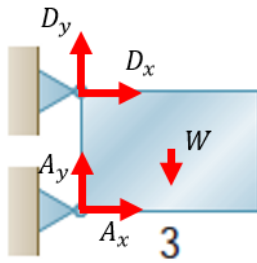
Reactions are determinate and equilibrium exists.

$$\begin{aligned} A_x &= 0 \\ A_y &= -100 \text{ N} \\ C_y &= 100 \text{ N} \end{aligned}$$



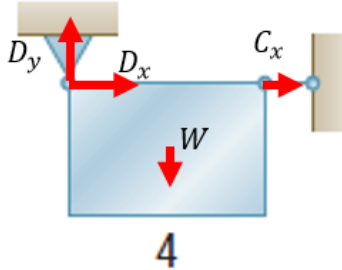
Reactions are determinate and equilibrium exists.

$$\begin{aligned} B_x &= 0 \\ C_y &= D_y = -100 \text{ N} \end{aligned}$$



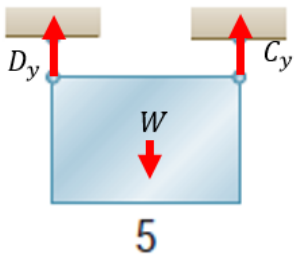
Reactions are indeterminate and equilibrium exists.

$$\begin{aligned} A_x &= 160 \text{ N} \\ D_x &= -160 \text{ N} \\ A_y + D_y &= 200 \text{ N} \end{aligned}$$



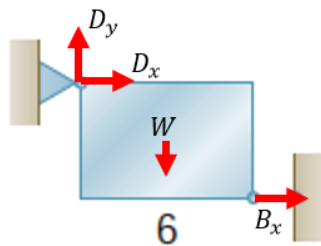
Reactions are indeterminate and equilibrium does not exist.

$$\sum M_D \neq 0$$



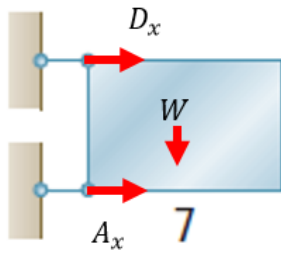
Reactions are determinate and equilibrium exists.

$$C_y = D_y = 100 \text{ N}$$



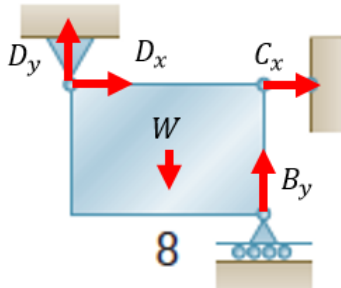
Reactions are determinate and equilibrium exists.

$$\begin{aligned} B_x &= 160 \text{ N} \\ D_x &= -160 \text{ N} \\ D_y &= 200 \text{ N} \end{aligned}$$



Reactions are determinate but equilibrium does not exist.

$$\sum F_y \neq 0$$

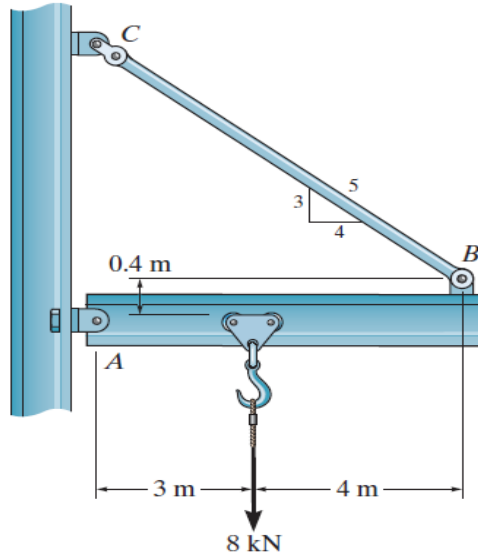


Reactions are indeterminate but equilibrium exists.

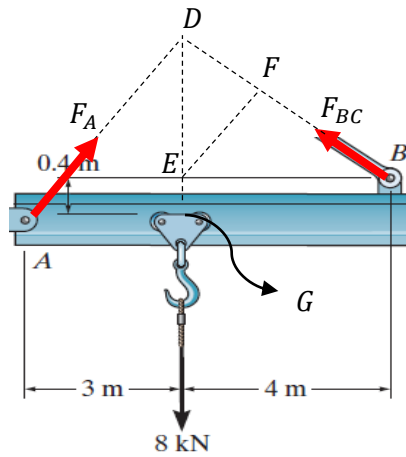
$$B_y = D_y = 100 \text{ N}$$

$$C_x + D_x = 0$$

3. In the following figure, find the reaction force at the pin A and the tension force at the link CB by using the properties of a three – force member.



Solution:



$$|EB| = 4 \text{ m}, |DE| = 3 \text{ m}, |EG| = 0.4 \text{ m}, |AG| = 3 \text{ m}, |AD| \parallel |EF|$$

$$\angle DAG = \angle FEB = \theta = \tan^{-1} \frac{|DE| + |EG|}{|AG|} = \tan^{-1} \frac{3.4}{3} = 48.58^\circ$$

$$\angle EDF = \alpha = \tan^{-1} \frac{|EB|}{|DE|} = \tan^{-1} \frac{4}{3} = 53.13^\circ$$

$$\angle FED = \beta = 90 - \theta = 41.42^\circ$$

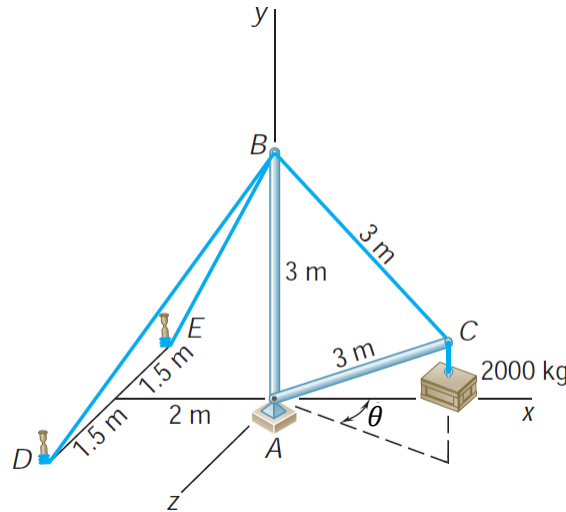
$$\angle EFD = \gamma = 180 - \alpha - \beta = 85.45^\circ$$

The force triangle is DEF . Apply the law of sines to get

$$\frac{8 \text{ kN}}{\sin \gamma} = \frac{F_{BC}}{\sin \beta} = \frac{F_A}{\sin \alpha}$$

$$\rightarrow F_{BC} = 5.31 \text{ kN} \quad \& \quad F_A = 6.42 \text{ kN}$$

4. The 2000-kg crate is supported by a link-and-cable system which is held by a ball-and-socket joint at A and by two cables attached at D and E as shown in the figure. The link AC forms an angle θ with the xy – plane and $0 < \theta < 90^\circ$. Determine
- The tension forces \vec{F}_{BD} and \vec{F}_{BE} in terms of θ ,
 - The magnitude of the reaction force at A when $\theta = 30^\circ$,



Solution:

$$\vec{F}_{BD} = F_{BD}\vec{u}_{BD} \quad \& \quad \vec{F}_{BE} = F_{BE}\vec{u}_{BE}$$

$$\vec{u}_{BD} = \frac{-2\mathbf{i} - 3\mathbf{j} + 1.5\mathbf{k}}{\sqrt{(-2)^2 + (-3)^2 + 1.5^2}} = -0.51\mathbf{i} - 0.77\mathbf{j} + 0.384\mathbf{k}$$

$$\vec{u}_{BE} = \frac{-2\mathbf{i} - 3\mathbf{j} - 1.5\mathbf{k}}{\sqrt{(-2)^2 + (-3)^2 + 1.5^2}} = -0.51\mathbf{i} - 0.77\mathbf{j} - 0.384\mathbf{k}$$

$$W = (2000)(9.81) = 19.62 \text{ kN}$$

$$\sum F_x = 0; \quad A_x - 0.51F_{BD} - 0.51F_{BE} = 0 \quad (1)$$

$$\sum F_y = 0; \quad A_y - 0.77F_{BD} - 0.77F_{BE} - W = 0 \quad (2)$$

$$\sum F_z = 0; \quad A_z + 0.384F_{BD} - 0.384F_{BE} = 0 \quad (3)$$

$$\sum (M_A)_x = 0; \quad (0.384F_{BD} - 0.384F_{BE})(3) + (W)(3 \cos 30^\circ \sin \theta) = 0 \quad (4)$$

$$\sum (M_A)_z = 0; \quad (0.51F_{BD} + 0.51F_{BE})(3) - (W)(3 \cos 30^\circ \cos \theta) = 0 \quad (5)$$

From (4)

$$F_{BD} - F_{BE} = -2.255W \sin \theta \quad (6)$$

From (5)

$$F_{BD} + F_{BE} = 1.7W \cos \theta \quad (7)$$

By solving (6) & (7)

$$\begin{aligned}F_{BD} &= 16.677 \cos \theta - 22.12 \sin \theta \text{ kN} \\F_{BE} &= 16.677 \cos \theta + 22.12 \sin \theta \text{ kN}\end{aligned}$$

Then,

$$\begin{aligned}\vec{F}_{BD} &= (-8.51 \cos \theta + 11.28 \sin \theta)\mathbf{i} + (-12.84 \cos \theta + 17 \sin \theta)\mathbf{j} \\&\quad + (6.4 \cos \theta - 8.5 \sin \theta)\mathbf{k} \text{ kN} \\ \vec{F}_{BE} &= (-8.51 \cos \theta + 11.28 \sin \theta)\mathbf{i} + (-12.84 \cos \theta + 17 \sin \theta)\mathbf{j} \\&\quad + (-6.4 \cos \theta + 8.5 \sin \theta)\mathbf{k} \text{ kN}\end{aligned}$$

At $\theta = 30^\circ$

$$\begin{aligned}A_x &= 0.51F_{BD} + 0.51F_{BE} = 14.73 \text{ kN} \\A_y &= 0.77F_{BD} + 0.77F_{BE} + W = 41.864 \text{ kN} \\A_z &= -0.384F_{BD} + 0.384F_{BE} = 8.5 \text{ kN} \\F_A &= \sqrt{A_x^2 + A_y^2 + A_z^2} = 45.1857 \text{ kN}\end{aligned}$$