

Communication Systems

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Overview

- 1 History of Communication
- 2 Communication Systems
- 3 Modeling, Analysis, and Design

Communication History

Visual Era

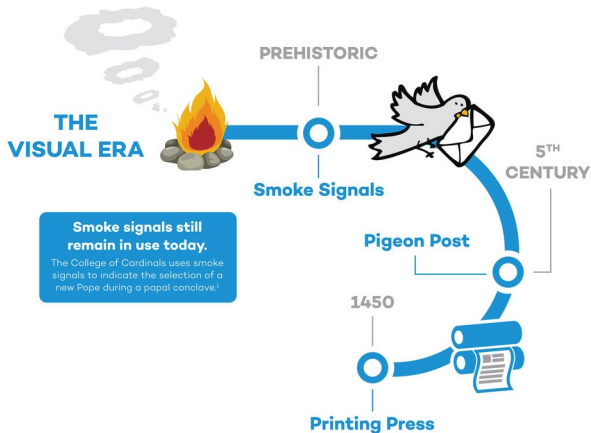


Figure: Visual era.

Wired Era

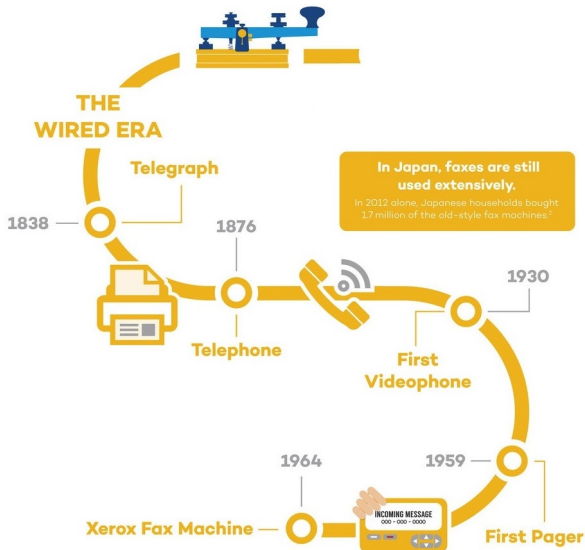


Figure: **Wired** Era.

Wireless Era

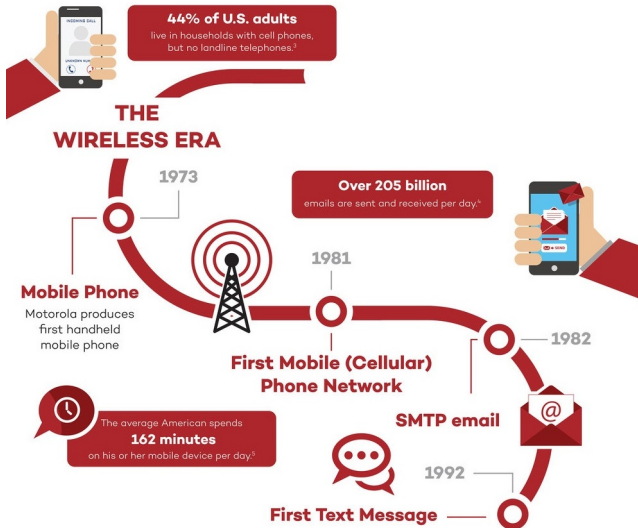


Figure: Wireless Era.

IP Cloud Era

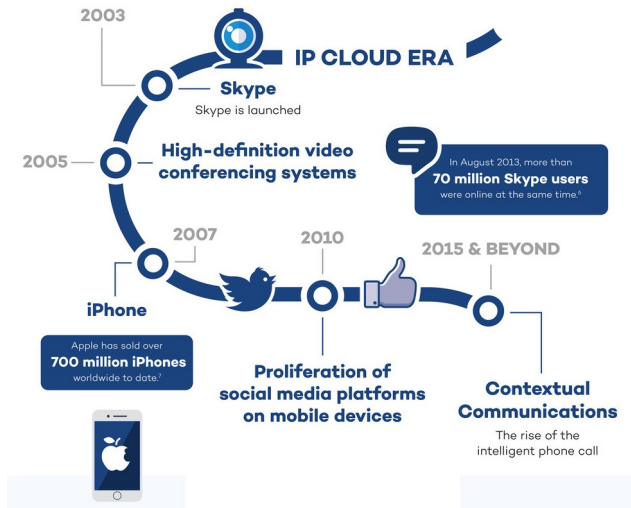


Figure: IP cloud Era.

Communication Systems

Communication Systems

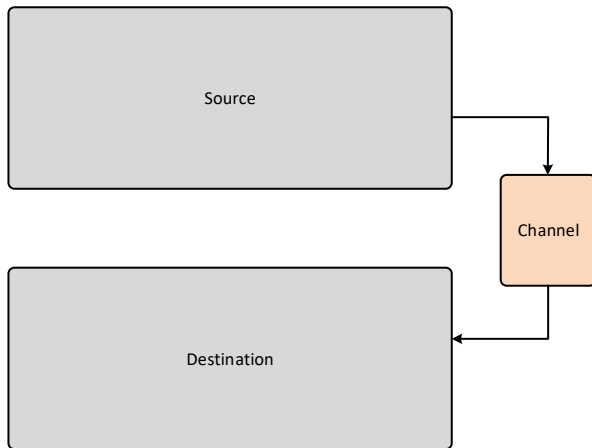


Figure: Abstract diagram of a **communication system**.

- **Channel** is the **physical medium** that is used to send a signal from the source to the destination.
- Channel has two important **limitations**
 - 1 **Physical impairments**
 - 1 **Noise**
 - 2 **Attenuation**
 - 3 **Delay**
 - 4 **Distortion**
 - 5 **Fading**
 - 2 **Working constraints**
 - 1 **Available bandwidth**
 - 2 **Central Frequency**
 - 3 **Injected power**
 - 4 **Usage time**

Communication Systems

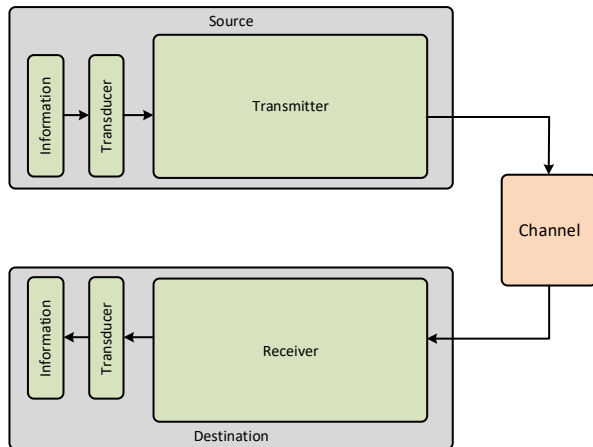


Figure: Functional diagram of a **communication system**.

- The **information** is generated **randomly** in the **source**.
- The **source transducer converts** the information to a signal, which can be fed to the transmitter.
- The **transmitter transforms** its input signal into a signal, which can effectively cope with the **channel limitations**.
- The **receiver extracts** its output signal from the signal polluted by the **undesirable effects** of the channel.
- The **destination transducer converts** the extracted signal to a desirable information.
- The **information** may have a **different format** in the **destination**.

Electrical Communication Systems

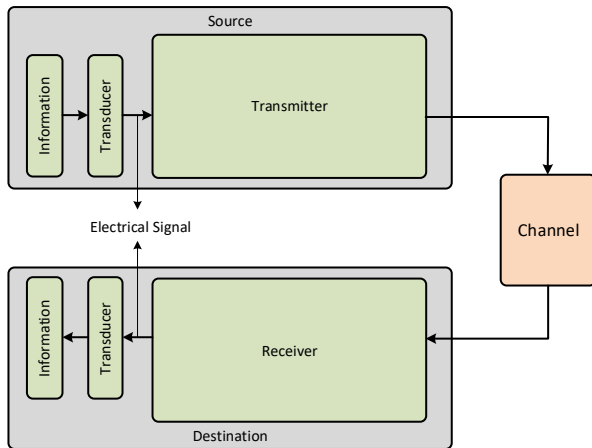


Figure: Functional diagram of an **electrical communication system**.

Analog Communication Systems

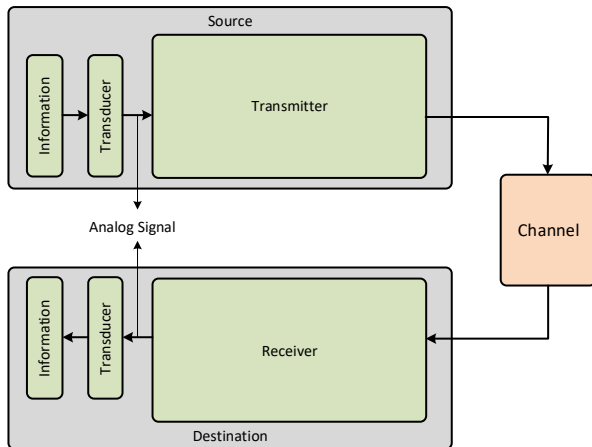


Figure: Functional diagram of an **analog communication system**.

Digital Communication Systems

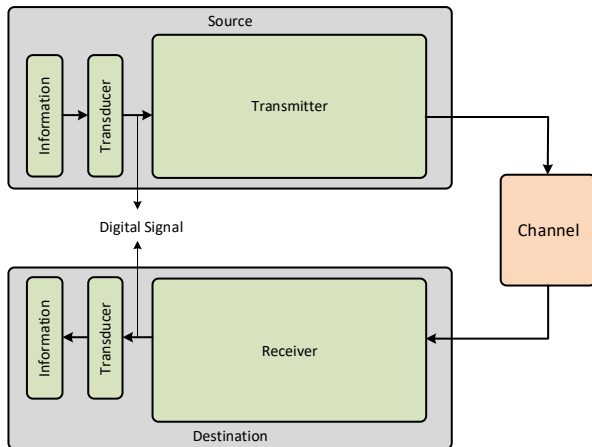


Figure: Functional diagram of a **digital communication system**.

Analog and Digital Electrical Communication System

The input signal to the transmitter or the output signal from the receiver is

- **electrical** in an **electrical communication system**.
- **analog** in an **analog communication system**.
- **digital** in a **digital communication system**.

Analog Communication Systems

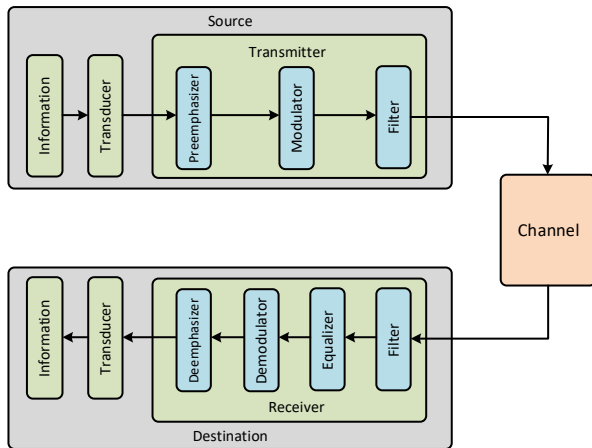


Figure: Detailed diagram of an **analog communication system**.

Analog Communication Systems

- ✓ The **preemphasizer** manipulates the signal to better cope with the **physical impairments** of the channel.
- ✓ The **modulator** manipulates the signal to better meet the **working constraints** of the channel.
- ✓ The **filter** manipulates the signal to better cope with the **working constraints** of the channel.
- ✓ The **deemphasizer**, **demodulator**, and **filter** in the receiver are the **inverse** counterparts of their corresponding blocks in the transmitter.
- ✓ The **equalizer** mitigates the undesired effects imposed by the **physical impairments** of the channel.

Digital Communication Systems

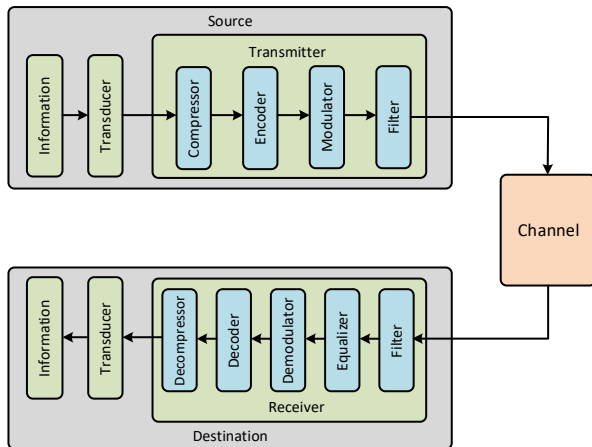


Figure: Detailed diagram of a digital communication system.

Digital Communication Systems

- ✓ The **compressor** removes the redundant data from the input information signal and helps to better meet the **working constraint** of the channel.
- ✓ The **encoder** adds a controllable amount of redundancy to the information signal to better cope with the **physical impairments** of the channel.
- ✓ The **modulator** manipulates the signal to better fit the **working constraints** of the channel.
- ✓ The **filter** manipulates the signal to better cope with the **working constraints** of the channel.
- ✓ The **decompressor**, **decoder**, **demodulator**, and **filter** in the receiver are the **inverse** counterparts of their corresponding blocks in the transmitter.
- ✓ The **equalizer** mitigates the undesired effects imposed by the **physical impairments** of the channel.

Modeling, Analysis, and Design

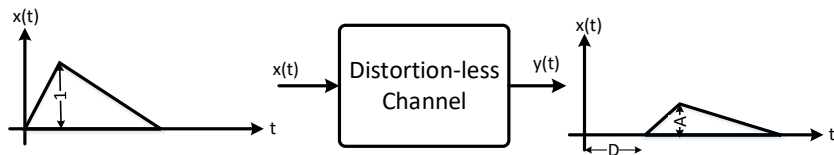
Modeling, Analysis, and Design

Roughly,

- ✓ In the **modeling**, the system **structure** is determined.
- ✓ In the **analysis**, the system **performance** is determined.
- ✓ In the **design**, the system **setting** is determined.

Example (Distortionless channel)

The distortionless channel is modeled by a linear time-invariant system with the transfer function $H_c(f) = Ae^{-j2\pi ft}$, whose amplitude $A \leq 1$ is constant and whose phase $-2\pi fD$ is a linear function of f .

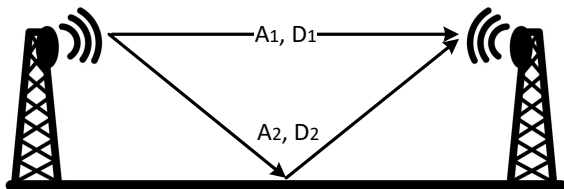


$$y(t) = Ax(t - D) \Rightarrow Y(f) = Ae^{-j2\pi fD}X(f)$$

$$\Rightarrow H_c(f) = \frac{Y(f)}{X(f)} = Ae^{-j2\pi fD}$$

Example (Point-to-point microwave radio channel)

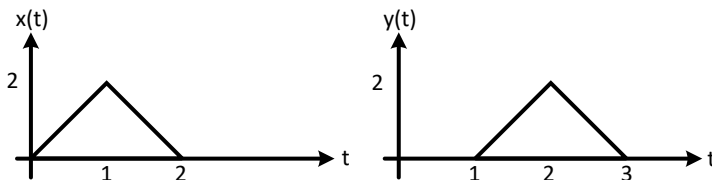
A point-to-point microwave radio channel can be modeled by a linear time-invariant system with the transfer function $H_c(f) = A_1 e^{-j2\pi f D_1} (1 + A e^{-j2\pi f D})$, where $A = A_2/A_1 < 1$ and $D = D_2 - D_1 \geq 0$.



$$y(t) = A_1 x(t - D_1) + A_2 x(t - D_2) \Rightarrow Y(f) = [A_1 e^{-j2\pi f D_1} + A_2 e^{-j2\pi f D_2}] X(f)$$
$$\Rightarrow H_c(f) = A_1 e^{-j2\pi f D_1} (1 + A e^{-j2\pi f D})$$

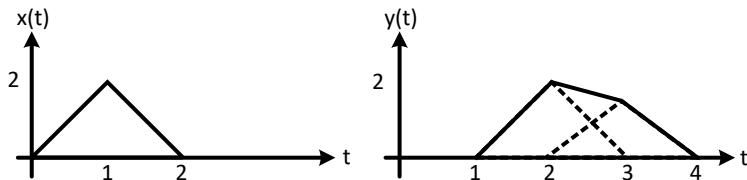
Example (Customized distortion-less channel)

Passing $x(t)$ through the distortion-less channel with $A = 1$ and $D = 1$, the output $y(t) = x(t - 1)$ appears.



Example (Customized point-to-point microwave radio channel)

Passing $x(t)$ through the point-to-point microwave radio channel with $A_1 = 1$, $A_2 = 0.75$, $D_1 = 1$, and $D_2 = 2$, the output $y(t) = x(t-1) + 0.75x(t-2)$ appears.



Example (Point-to-point microwave radio channel equalizer)

The distortion imposed by the point-to-point microwave radio channel can be equalized by a linear time-invariant system with the transfer function $H_e(f) = 1/(1 + Ae^{-j2\pi fD})$, where $A = A_2/A_1 < 1$ and $D = D_2 - D_1 \geq 0$.

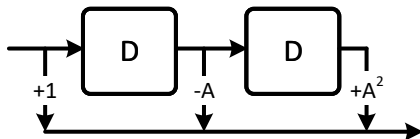
$$H_c(f)H_e(f) = A_1 e^{-j2\pi fD_1} (1 + Ae^{-j2\pi fD}) H_e(f) = A_1 e^{-j2\pi fD_1}$$
$$\Rightarrow H_e(f) = \frac{1}{1 + Ae^{-j2\pi fD}}$$

Example (Point-to-point microwave radio channel equalizer)

For $A \ll 1$, the point-to-point microwave radio channel equalizer can be practically implemented using a tapped delay line structure.

$$|Ae^{-j2\pi fD}| < 1 \Rightarrow H_e(f) = \frac{1}{1 - [-Ae^{-j2\pi fD}]} = 1 - Ae^{-j2\pi fD} + A^2e^{-j4\pi fD} - \dots$$

$$A \ll 1 \Rightarrow H_e(f) = \frac{1}{1 - [-Ae^{-j2\pi fD}]} \approx 1 - Ae^{-j2\pi fD} + A^2e^{-j4\pi fD}$$



The End