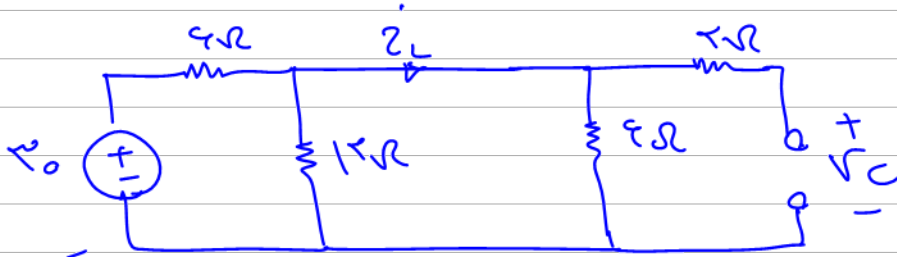


پاسخنامه تمرین سطح ۴ - مدارهای مرتبه اول

سؤال ۱)

شکل ۱:

$t = 0^-$

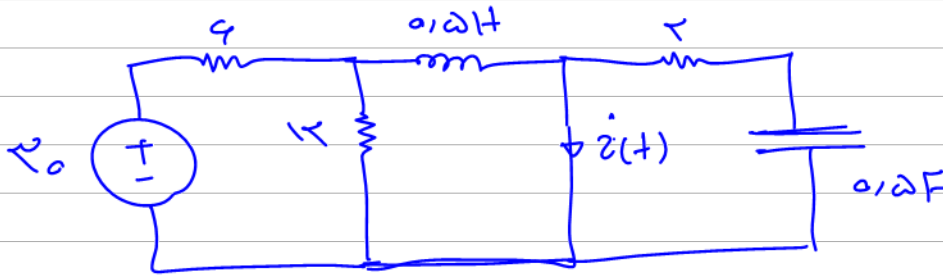


تقسیم ولتاژ

$$\Rightarrow V_C = V_0 \times \frac{4}{4+4} = 12, \quad i_L = \frac{V_C}{4} = 2A$$

$$\Rightarrow V_C(0^-) = 12, \quad i_L(0^-) = 2A \Rightarrow \begin{cases} V_C(0^+) = 12V \\ i_L(0^+) = 2A \end{cases}$$

$t > 0$:



$$V_C(t) = (12 - 0)e^{-t} + 0 = 12e^{-t} \Rightarrow V_C(t) = 12e^{-t} \quad t > 0$$

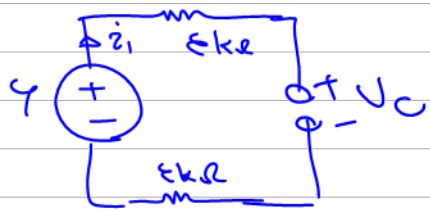
$$i_L(t) = (2 - 0)e^{-t} + 0 = 2e^{-t} \Rightarrow i_L(t) = 2e^{-t} \quad t > 0$$

$$\Rightarrow i(t) = i_L - C \frac{dV_C}{dt} = (2 - 2e^{-t}) - 4e^{-t}$$

$$\Rightarrow i(t) = 2 - 2e^{-t} + 4e^{-t} \quad t > 0$$

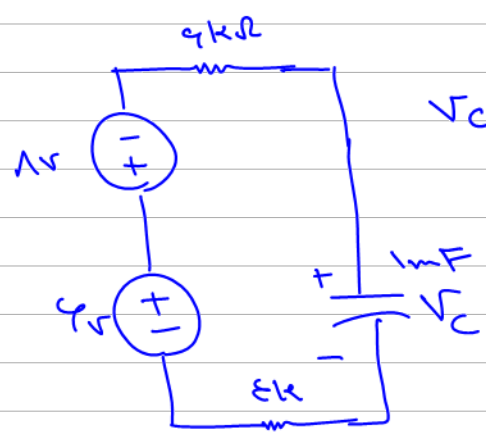
25

$t < 1$:



$$\Rightarrow V_C(t^-) = V_C(t^+) = 9V$$

$t > 1$:

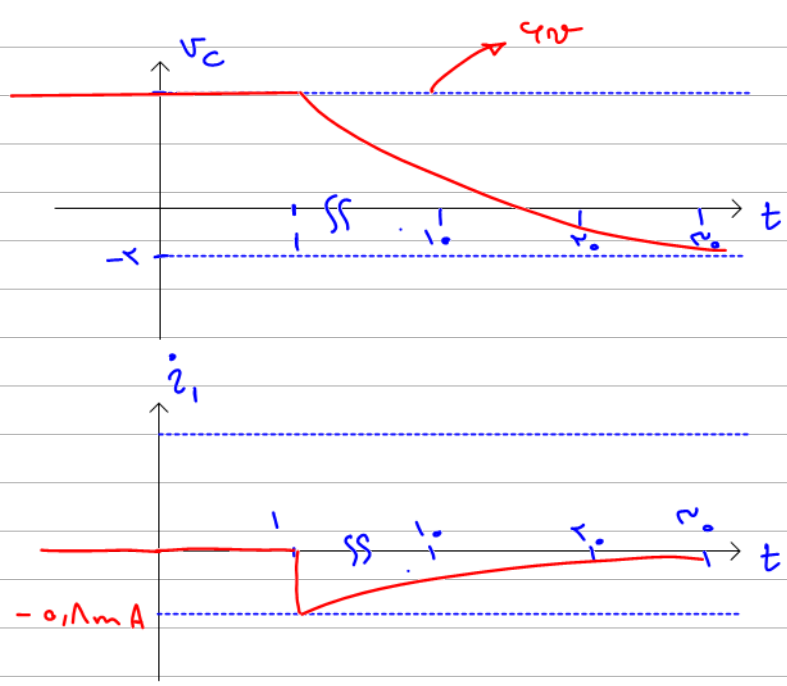


$$V_C = [V_C(t^+) - V_C(\infty)] e^{-\frac{t-1}{\tau}} + V_C(\infty)$$

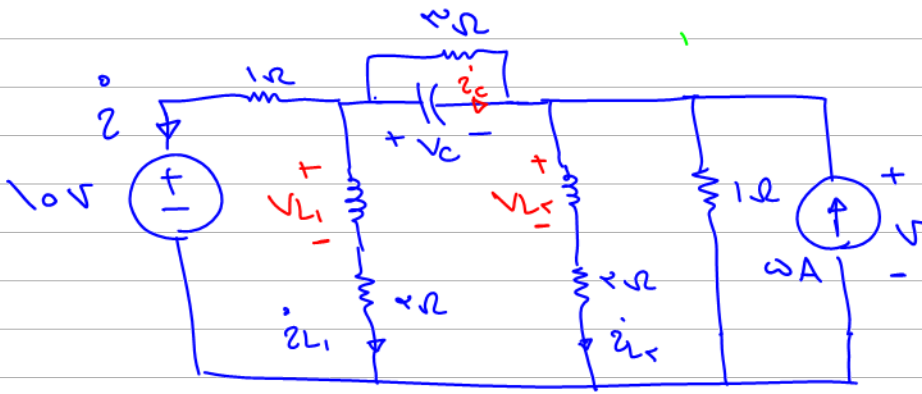
$$\begin{cases} V_C(\infty) = -1 \\ \tau = RC = 10 \times 1 = 10 \text{ s} \end{cases}$$

$$\Rightarrow V_C = (9 - (-1)) e^{-\frac{t-1}{10}} - 1$$

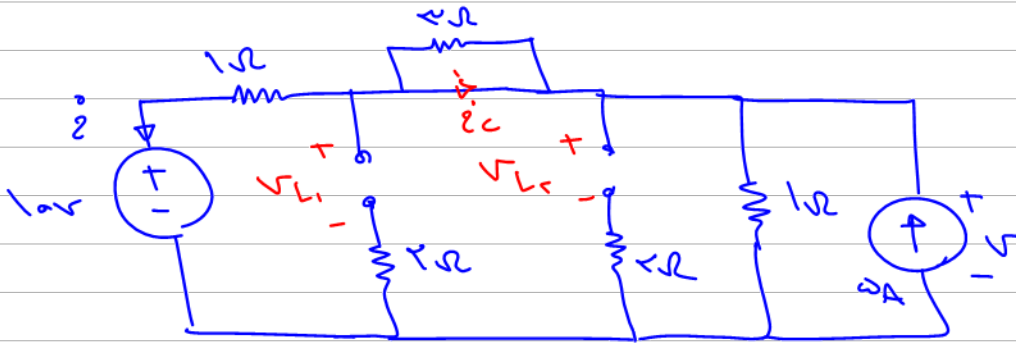
$$= 10 e^{-\frac{t-1}{10}} - 1$$



سوال ۲



پیش از $t=0$ → $i_{L1}(0^+) = i_{L1}(0^-) = 0$
 $i_{L2}(0^+) = i_{L2}(0^-) = 0$
 $V_C(0^+) = V_C(0^-) = 0$



$i = -i_C = \frac{10 - 0}{2} = 5A \Rightarrow \begin{cases} i_C = +5A \\ i = -5A \end{cases}$

$V = (10 - 0) \times 0.5 = 5V \Rightarrow V_{L1} = V_{L2} = 5V$

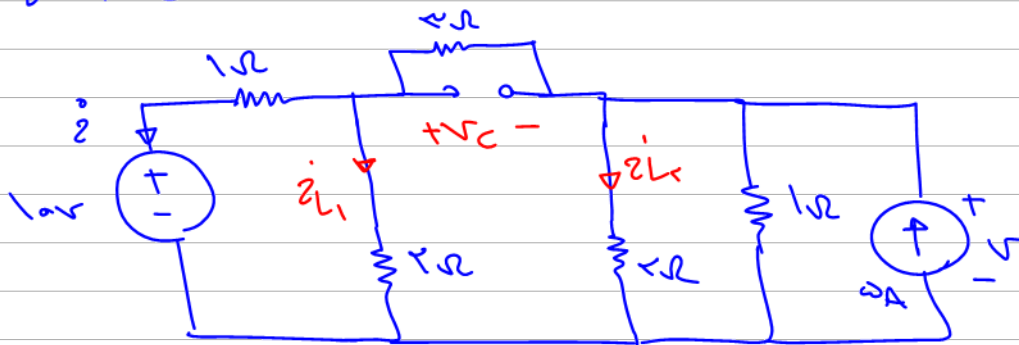
$\Rightarrow V_{L1} = L_1 \frac{di_{L1}}{dt} = \frac{di_{L1}}{dt} = 5 \Rightarrow \frac{di_{L1}}{dt}(0^+) = 5$

$\frac{di_{L2}}{dt}(0^+) = 5$

$i_C = C \frac{dV_C}{dt} \Rightarrow \frac{dV_C}{dt}(0^+) = 5A$

$\Rightarrow \frac{dV}{dt}(0^+) = 0, \frac{di}{dt}(0^+) = 0$

$$t = +\infty$$



$$\Rightarrow \begin{cases} V_{L1} = 0 \rightarrow \frac{di_{L1}}{dt}(\infty) = 0 \\ V_{Lr} = 0 \rightarrow \frac{di_{Lr}}{dt}(\infty) = 0 \\ i_C = 0 \rightarrow \frac{dV_C}{dt}(\infty) = 0 \end{cases}$$

$$\frac{dV}{dt}(\infty) = 0, \frac{di}{dt}(\infty) = 0$$

۱؛ فقط جمع آثار، تقسیم جریان استفاده نمی‌کنیم

$$i_{L1}(\infty) = \frac{[(1||2)+3]||1}{[(1||2)+3]||1+2} 10A + \left(\frac{1||2}{1||2+1||2+3} \right) \left(\frac{1}{1+2} \right) 2A = \frac{120}{29} A$$

$$i_{Lr}(\infty) = \frac{[(1||2)+3]||1}{[(1||2)+3]||1+2} 2A + \left(\frac{1||2}{1||2+1||2+3} \right) \left(\frac{1}{1+2} \right) 10A = \frac{V2}{29} A$$

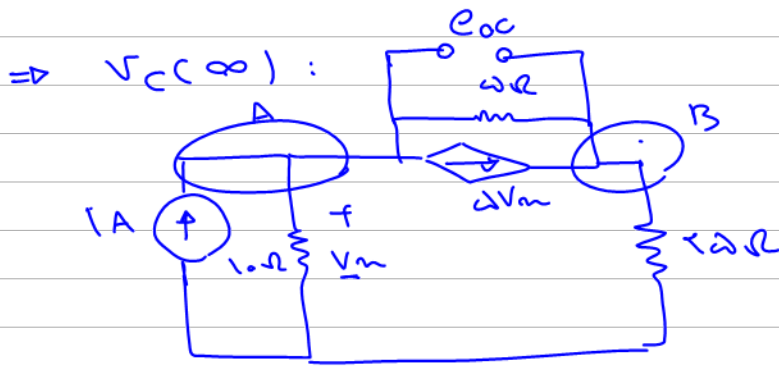
$$V_C(\infty) = 2i_{L1} - 2i_{Lr} = \frac{90}{29}$$

$$\Rightarrow i(\infty) = -i_{L1} - \frac{V_C}{2} = \frac{-120}{29}$$

$$V(\infty) = 1 \times (2 - i_{Lr} + \frac{V_C}{2}) = \frac{120}{29}$$

سؤال ٣

الف

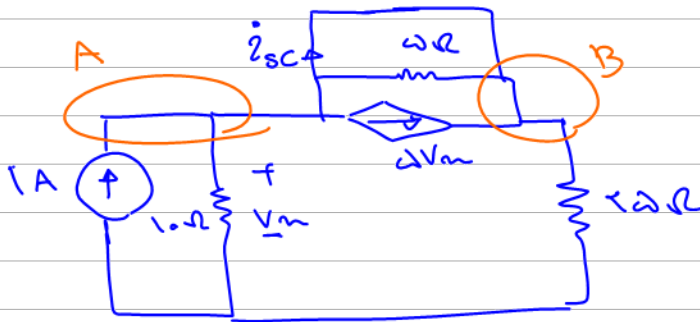


A kcl: $-1 + \frac{V_n}{1} + \Delta V_n + \frac{e_{oc}}{1} = 0 \Rightarrow \Delta V_n + e_{oc} = 1$

B kcl: $\frac{V_n - e_{oc}}{2} - \frac{e_{oc}}{1} - \Delta V_n = 0 \Rightarrow -1.5V_n - 4e_{oc} = 0$

$$\begin{bmatrix} V_n \\ e_{oc} \end{bmatrix} = \begin{bmatrix} \Delta 1 & 1 \\ -1.5 & -4 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} V_n = 1.04 \\ e_{oc} = -1.17A \end{cases}$$

$\tau = R_{eq} C = 1.709 ms$



A kcl: $-1 + \frac{V_n}{1} + i_{sc} + \Delta V_n = 0 \quad \Delta V_n + 1.0 i_{sc} = 1$

B kcl: $-\Delta V_n - i_{sc} + \frac{V_n}{2} = 0 \Rightarrow -1.5V_n - 2i_{sc} = 0$

$$\begin{bmatrix} V_n \\ i_{sc} \end{bmatrix} = \begin{bmatrix} \Delta 1 & 1 \\ -1.5 & -2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1.17 \\ -1.709 \end{bmatrix}$$

$$R_{eq} = \frac{e_{oc}}{i_{sc}} = \frac{-1.17A}{-1.709A} = 0.684 \Omega \quad \tau = 1.709 ms$$

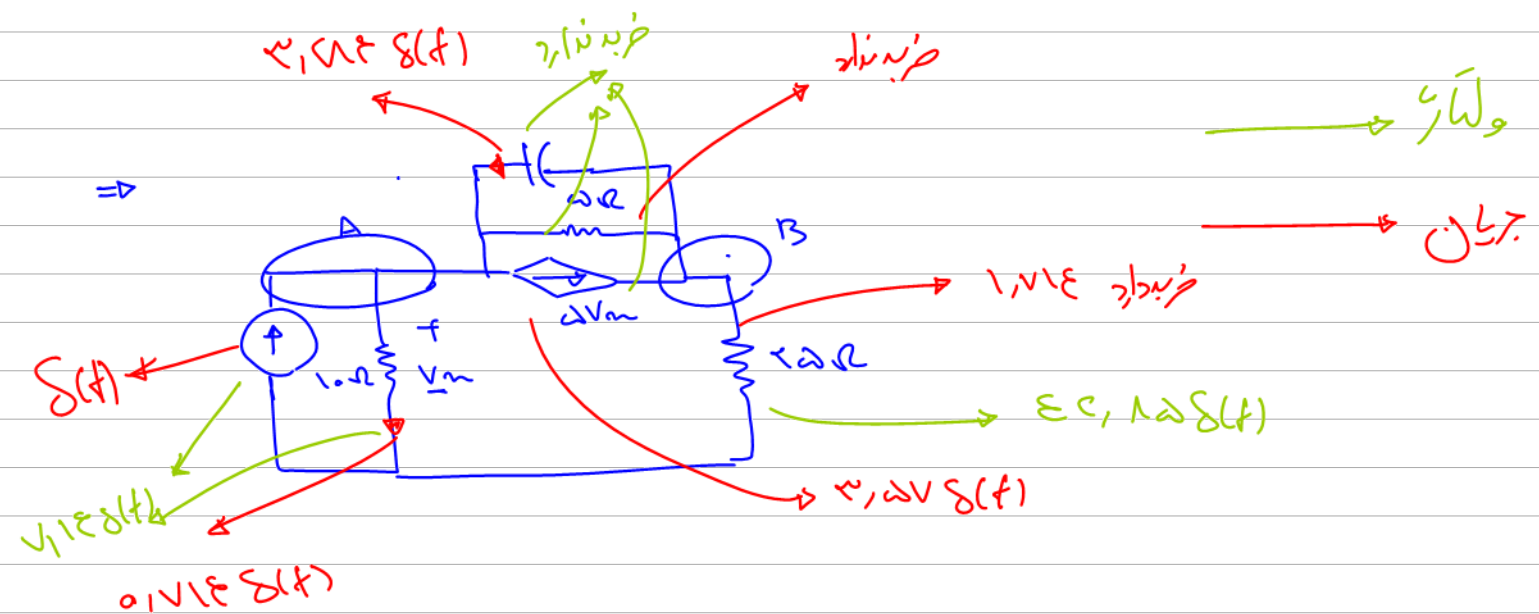
$C = 1mF$

$$y(t) = (y(0^+) - y(\infty))e^{-\frac{t}{\tau}} + y(\infty)$$

$$\rightarrow \begin{cases} V_C(t) = (0 + 1,171) e^{-1,59t} - 1,171 \Rightarrow V_C(t) = 1,171 (e^{-1,59t} - 1) \text{ (V)} \\ V_A(t) = (1,171 - 1,07) e^{-1,59t} + 1,07 \Rightarrow V_A(t) = (0,1 e^{-1,59t} + 1,07) \text{ (V)} \end{cases}$$

پایان $\rightarrow h_{vc}(t) = 1,2 \times (-1,29) e^{-1,29t} u(t) = -1,428 e^{-1,29t} u(t)$

$$h_{V_m}(t) = \overset{-1596}{9_{11}} \times \overset{-1596}{(-1596)} e^{u(t)} + \overset{-1596}{V_{11}} \delta(t) = -210920 e^{u(t)} + V_{11} \delta(t)$$



(مثال ٤)

(الف)

$$\begin{cases} v_c + v = v_s = 0 & (\text{KVL}) \quad \text{I} \\ v + v_c = \frac{1}{\omega} \frac{dv_c}{dt} = 0 & (\text{KCL}) \quad \text{II} \\ i = \frac{v - v_s}{\omega} & \text{III} \end{cases}$$

$$\text{II, III} \rightarrow \frac{\omega}{1\omega} v_c' + \frac{1}{\omega} v_s = v \quad \text{I} \Rightarrow \frac{\omega}{1\omega} \frac{dv_c}{dt} + v_c = \frac{v}{\omega} v_s$$

$$\Rightarrow \frac{dv_c}{dt} + \frac{1\omega}{\omega} v_c = \frac{1\omega}{\omega} v_s$$

$$\text{I} \rightarrow v_c = v_s - v \Rightarrow \frac{dv_s}{dt} - \frac{dv}{dt} + \frac{1\omega}{\omega} v_s - \frac{1\omega}{\omega} v = \frac{1\omega}{\omega} v_s$$

$$\Rightarrow \frac{dv}{dt} + \frac{1\omega}{\omega} v = \frac{dv_s}{dt} + \frac{\omega}{\omega} v_s$$

(ب)

$$v_c: \frac{dv_c}{dt} + \frac{1\omega}{\omega} v_c = \frac{1\omega}{\omega} \quad t > 0, \quad v_c(0^+) = 0$$

$$\Rightarrow v_c = \underbrace{\frac{v}{\omega}}_{\text{دائم}} - \underbrace{\frac{v}{\omega} e^{-\frac{1\omega}{\omega} t}}_{\text{زائل}}, \quad t > 0 \Rightarrow v_c(t) = \frac{v}{\omega} (1 - e^{-\frac{1\omega}{\omega} t}) u(t)$$

$$v: \quad , \quad v_c(0^-) = 0$$

$$t > 0 \Rightarrow \frac{dv}{dt} + \frac{1\omega}{\omega} v = \frac{\omega}{\omega}, \quad v_c(0^+) = ??$$

$$\int_0^{0^+} \rightarrow v_c(0^+) - v_c(0^-) = 1 \Rightarrow v_c(0^+) = 1$$

$$\Rightarrow v(t) = (1 - \frac{\omega}{\omega}) e^{-\frac{1\omega}{\omega} t} + \frac{\omega}{\omega} \Rightarrow v(t) = \underbrace{(\frac{v}{\omega} e^{-\frac{1\omega}{\omega} t})}_{\text{زائل}} + \underbrace{\frac{\omega}{\omega}}_{\text{دائم}} u(t)$$

(ب)

$$v_c: \frac{dv_c}{dt} + \frac{1}{\omega} v_c = \frac{1}{\omega} \delta(t), \quad v_c(0^-) = 0, \quad v_c(0^+) = ??$$

$$\int_{0^-}^{0^+} \rightarrow v_c(0^+) - v_c(0^-) = \frac{1}{\omega} \Rightarrow v_c(0^+) = \frac{1}{\omega}$$

$$t > 0 \quad \frac{dv_c}{dt} + \frac{1}{\omega} v_c = 0 \Rightarrow v_c = \frac{1}{\omega} e^{-\frac{1}{\omega} t} \quad t > 0$$

$$\Rightarrow v_c(t) = \frac{1}{\omega} e^{-\frac{1}{\omega} t} u(t)$$

نذرا

$$\textcircled{3} \rightarrow v = v_s - v_c = \delta(t) - \frac{1}{\omega} e^{-\frac{1}{\omega} t}$$

نذرا

* پاسخ فیزیکی یک سیستم پایدار، قسمت دائمی ندارد.

$$V_C: S(t) = \frac{V}{a}(1 - e^{-\frac{1}{a}t})u(t) \Rightarrow S' = \frac{1}{a}e^{-\frac{1}{a}t}u(t) \quad (ت)$$

$$h(t) = \frac{1}{a}e^{-\frac{1}{a}t}u(t) \Rightarrow h(t) = S'(t)$$

$$V: S(t) = \left(\frac{V}{a}e^{-\frac{1}{a}t} + \frac{r}{a}\right)u(t) \Rightarrow S'(t) = -\frac{1}{a}e^{-\frac{1}{a}t}u(t) + \left(\frac{V}{a} + \frac{r}{a}\right)\delta(t)$$

$$\Rightarrow h(t) = -\frac{1}{a}e^{-\frac{1}{a}t}u(t) + \delta(t) \Rightarrow h(t) = S'(t)$$

← در یک سیستم LTI، پاسخ ضرب برابر با مشتق پاسخ پله است.

$$V_S(t) = \delta[u(t) - u(t-r)] \quad (ت)$$

← از خاصیت LTI بودن مدار استفاده می‌کنیم:

$$\Rightarrow V_C(t) = \delta[S(t) - S(t-r)]$$

$$\Rightarrow V_C(t) = \left[\frac{1}{a}(1 - e^{-\frac{1}{a}t})u(t) - \frac{1}{a}(1 - e^{-\frac{1}{a}(t-r)})u(t-r) \right]$$

$$V(t) = V_S - V_C = \left(\frac{1}{a} + \frac{1}{a}e^{-\frac{1}{a}t}\right)u(t) - \left(\frac{1}{a} + \frac{1}{a}e^{-\frac{1}{a}(t-r)}\right)u(t-r)$$

$$\Rightarrow V(t) =$$

سؤال (۵)

در هر مدار خطی تغییرناپذیر با زمان (LTI) صرف نظر از مرتبه مدار موارد زیر برقرار است:

(۱) پاسخ حالت صفر نسبت به ورودی خطی است. $h(t) = \frac{ds(t)}{dt}$ (۲)

(۲) پاسخ ورودی صفر نسبت به شرایط اولیه خطی است.

$h(t) \rightarrow$ پاسخ ضربه
 $S(t) \rightarrow$ پاسخ پله \Rightarrow
 $z(t) \rightarrow$ پاسخ ورودی صفر

$$\begin{cases} y_1(t) = h(t) + z(t) & t > 0 \\ y_2(t) = S(t) + 2z(t) & t > 0 \end{cases}$$

$$\left. \begin{aligned} y_1 - \frac{y_2}{2} &= h - \frac{S}{2} \\ h &= \frac{ds}{dt} \end{aligned} \right\} \Rightarrow y_1 - \frac{y_2}{2} = s' - \frac{s}{2}$$

$$\Rightarrow -\frac{1}{2} - \frac{e}{2}e^{-t} + \frac{s}{2}e^{-\frac{t}{2}} = \frac{ds}{dt} - \frac{s}{2}, \quad s(0^-) = 0 \Rightarrow s(0^+) = 0$$

$$\Rightarrow s(t) = S_h + S_p$$

$$\begin{cases} S_h = ke^{\frac{t}{2}} \\ S_p = A + Be^{-t} + Ce^{-\frac{t}{2}} \Rightarrow A=1, B=1, C=-2 \end{cases}$$

$$\Rightarrow s(t) = ke^{\frac{t}{2}} + 1 + e^{-t} - 2e^{-\frac{t}{2}}$$

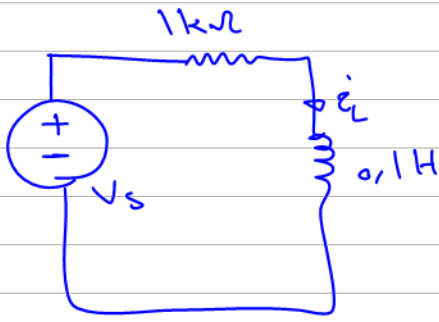
$$s(0^+) = 0 \Rightarrow k + 1 + 1 - 2 = 0 \Rightarrow k = 0$$

$$\Rightarrow s(t) = 1 + e^{-t} - 2e^{-\frac{t}{2}} \Rightarrow h(t) = (-e^{-t} + e^{-\frac{t}{2}})u(t)$$

$$y_1(t) = h(t) + z(t) \Rightarrow z(t) = (-2e^{-t} + e^{-\frac{t}{2}}) \quad t > 0$$

سؤال ٦

الف)



$$\frac{di_L}{dt} + 10^4 i_L = 10 V_s$$

$$V_s = V_0 e^{-10^4 t} \rightarrow i_L = i_h + i_p \quad \left\{ \begin{array}{l} i_h = K e^{-10^4 t} \\ i_p = A t e^{-10^4 t} \end{array} \right.$$

(فرض که پاسخ کامل)

برای پیدا کردن

$$\Rightarrow \frac{d(A t e^{-10^4 t})}{dt} + 10^4 A t e^{-10^4 t} = V_0 e^{-10^4 t}$$

$$A e^{-10^4 t} - 10^4 A t e^{-10^4 t} + 10^4 A t e^{-10^4 t} = A e^{-10^4 t} = V_0 e^{-10^4 t}$$

$$\Rightarrow A = V_0$$

$$\Rightarrow i_L(t) = K e^{-10^4 t} + V_0 t e^{-10^4 t} \quad \left\{ \begin{array}{l} i_L(t) = V_0 (1 - t e^{-10^4 t}) u(t) \\ i_L(0^+) = 0 \end{array} \right.$$

ب)

$$V_s = 1000 \sin(\omega t + 30^\circ)$$

$$i_L(t) = i_h + i_p \rightarrow \left\{ \begin{array}{l} i_h = K e^{-10^4 t} \\ i_p = A \sin(\omega t + \varphi) \end{array} \right.$$

$$A \omega \cos(\omega t + \varphi) - 10^4 A \sin(\omega t + \varphi) = 10^4 \sin(\omega t + 30^\circ)$$

$$\omega = 10^4 \rightarrow 10^4 A (\cos(\omega t + \varphi) - \sin(\omega t + \varphi)) = 10^4 \sin(\omega t + 30^\circ)$$

$$\Rightarrow A [(\cos \varphi - \sin \varphi) \cos \omega t - (\sin \varphi + \cos \varphi) \sin \omega t] = \left[\frac{\sqrt{2}}{2} \cos \omega t - \frac{1}{2} \sin \omega t \right]$$

$$\begin{cases} \cos \varphi = \frac{\sqrt{r}+1}{\sqrt{r}A} \Rightarrow \\ \sin \varphi = \frac{1-\sqrt{r}}{\sqrt{r}A} \end{cases} \Rightarrow \begin{cases} \cos^2 \varphi + \sin^2 \varphi = 1 \Rightarrow A = \frac{\sqrt{r}}{r} \\ \tan \varphi = \frac{1-\sqrt{r}}{1+\sqrt{r}} \Rightarrow \varphi = -12^\circ \end{cases}$$

~ r V

$$\Rightarrow \dot{i}_L(t) = k e^{-10^5 t} + \frac{\sqrt{r}}{r} \sin(10^5 t - 12^\circ)$$

$$\dot{i}_L(0^+) = 0 \Rightarrow k + \frac{\sqrt{r}}{r} \sin(-12^\circ) = 0 \Rightarrow k = \frac{\sqrt{r}}{r} \sin(12^\circ)$$

$$\dot{i}_L(t) = \frac{\sqrt{r}}{r} \sin(12^\circ) e^{-10^5 t} + \frac{\sqrt{r}}{r} \sin(10^5 t - 12^\circ)$$

$$v_s = 1000 \sin(\omega t + \theta), \omega = 10 \text{ kHz}$$



$$\frac{d\dot{i}_L}{dt} + 10^5 \dot{i}_L = v_s \Rightarrow \dot{i}_p = A \sin(\omega t + \varphi)$$

→ $\sin \varphi = \frac{\sin \theta + \cos \theta}{\sqrt{r}A} \Rightarrow \tan \varphi = \frac{1 + \tan \theta}{1 - \tan \theta} = \tan(\theta - \epsilon \omega)$

→ $\cos \varphi = \frac{\cos \theta - \sin \theta}{\sqrt{r}A}$

$$\Rightarrow \varphi = \theta - \epsilon \omega \quad \textcircled{I}$$

$$\Rightarrow \dot{i} = \dot{i}_h + \dot{i}_p = k e^{-\frac{t}{\tau}} + A \sin(\omega t + \varphi) \Rightarrow k = -A \sin(\varphi)$$

$\dot{i}(0^+) = 0$

→ $k=0 \Rightarrow \varphi = k\pi \Rightarrow \theta = k\pi + \frac{\pi}{\epsilon}$

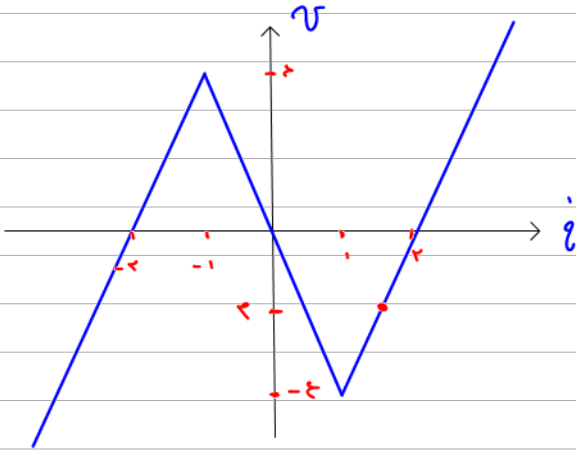
$$\Rightarrow \theta_{\text{new}} = \epsilon \omega \Rightarrow \Delta \theta = 12^\circ$$

$$k = \text{min} \Rightarrow \varphi = k\pi + \frac{\pi}{r} \Rightarrow \theta = k\pi + \frac{\pi}{\epsilon}$$

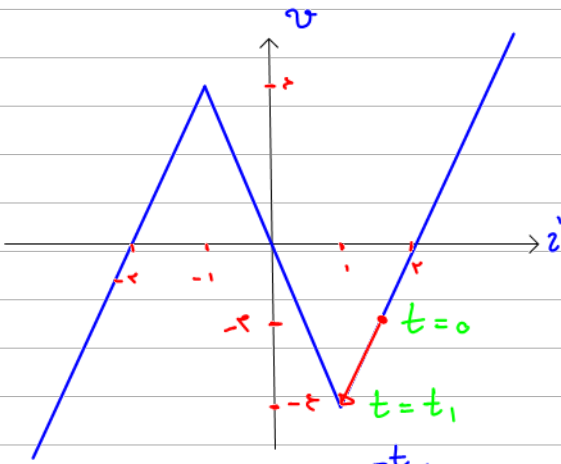
$$\Rightarrow \theta_{\text{new}} = -\epsilon \omega \Rightarrow \Delta \theta = -12^\circ$$

سؤال (۷)

ضابطه ولتاژ خازن را به ازای یک دوره تناوب به دستی آوریم و رسم می کنیم. بین منظور مستخدم داده شده را تقریب تکامل - خطی می زنیم



$$V_C(0^-) = V_C(0^+) = -\tau$$



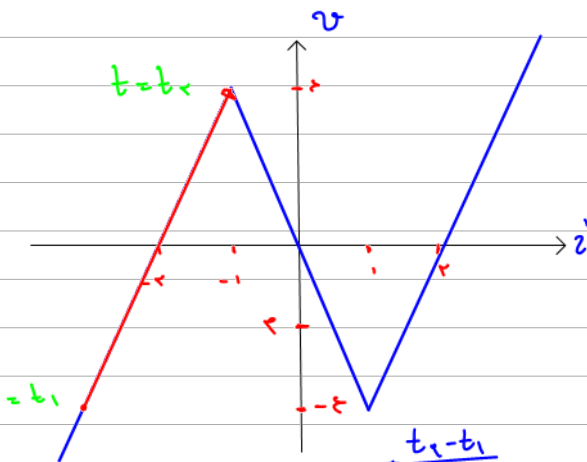
$$\begin{cases} \epsilon \frac{dv}{dt} + i = 0 \\ i = \frac{v}{\epsilon} + \tau \end{cases} \Rightarrow \frac{dv}{dt} + \frac{v}{\epsilon C} = \frac{-\tau}{C}$$

$$\Rightarrow v = k e^{-\frac{t}{\epsilon C}} - \tau \quad \left. \begin{matrix} V_C(0^+) = -\tau \end{matrix} \right\} v = \tau e^{-\frac{t}{\epsilon C}} - \tau$$

$$V_C(t_1) = -\epsilon \Rightarrow \tau e^{-\frac{t_1}{\epsilon C}} - \tau = -\epsilon \Rightarrow e^{-\frac{t_1}{\epsilon C}} = \frac{\tau}{\epsilon} \Rightarrow t_1 = \epsilon C \ln\left(\frac{\tau}{\epsilon}\right)$$

$$\Rightarrow t_1 = \frac{\epsilon \ln\left(\frac{\tau}{\epsilon}\right)}{\ln(9)}$$

$$V_C(t_1^-) = V_C(t_1^+) = -\epsilon$$



$$\begin{cases} \epsilon \frac{dv}{dt} + i = 0 \\ i = \frac{v}{\epsilon} - \tau \end{cases} \Rightarrow \frac{dv}{dt} + \frac{v}{\epsilon C} = \frac{+\tau}{C}$$

$$\Rightarrow v = k e^{-\frac{t-t_1}{\epsilon C}} + \tau \quad \left. \begin{matrix} V_C(t_1^+) = -\epsilon \end{matrix} \right\} v = -\tau e^{-\frac{t-t_1}{\epsilon C}} + \tau$$

$$(t_2) = \epsilon \Rightarrow -\tau e^{-\frac{t_2-t_1}{\epsilon C}} + \tau = \epsilon \Rightarrow e^{-\frac{t_2-t_1}{\epsilon C}} = \frac{+\tau}{\epsilon} \Rightarrow t_2 - t_1 = \epsilon C \ln\left(\frac{\tau}{\epsilon}\right)$$

$$\Rightarrow t_2 = \frac{\epsilon \ln\left(\frac{\tau}{\epsilon}\right)}{\ln(9)}$$

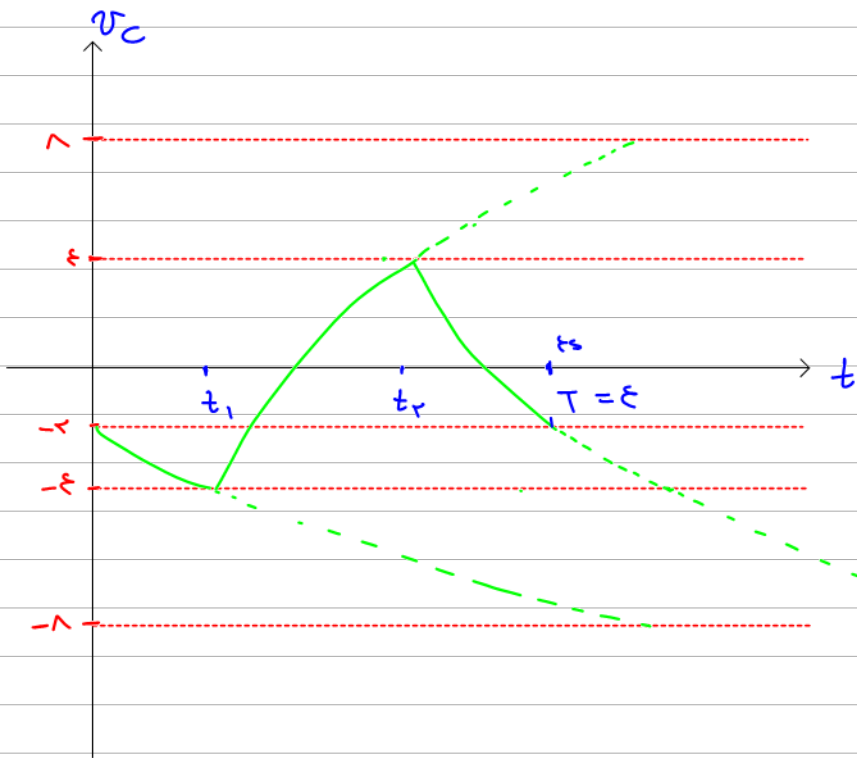
$$V_C(t_r^-) = V_C(t_r^+) = +\mathcal{E}$$

$$\left. \begin{aligned} e^{\frac{dr}{dt} + i} &= 0 \\ i &= \frac{v}{\mathcal{E}} + r \end{aligned} \right\} \frac{dv}{dt} + \frac{v}{\mathcal{E}C} = \frac{-r}{C}$$

$$\Rightarrow v = k e^{-\frac{t-t_r}{\mathcal{E}C}} - \Lambda \quad \left. \begin{aligned} & \\ V_C(t_r^+) &= +\mathcal{E} \end{aligned} \right\} v = \Lambda e^{-\frac{t-t_r}{\mathcal{E}C}} - \Lambda$$

$$v(t_r) = -r \Rightarrow \Lambda e^{-\frac{t_r-t_r}{\mathcal{E}C}} - \Lambda = -r \Rightarrow e^{-\frac{t_r-t_r}{\mathcal{E}C}} = \frac{1}{r} \Rightarrow t_r - t_r = \mathcal{E}C \ln(r)$$

$$t_r = \frac{\mathcal{E} \ln(4)}{\ln(4)} = \mathcal{E} \Rightarrow T = \mathcal{E}s$$



سؤال ۸

تأییدی که $V_{C1} < V_{C2}$ باشد دید خاعوش است.

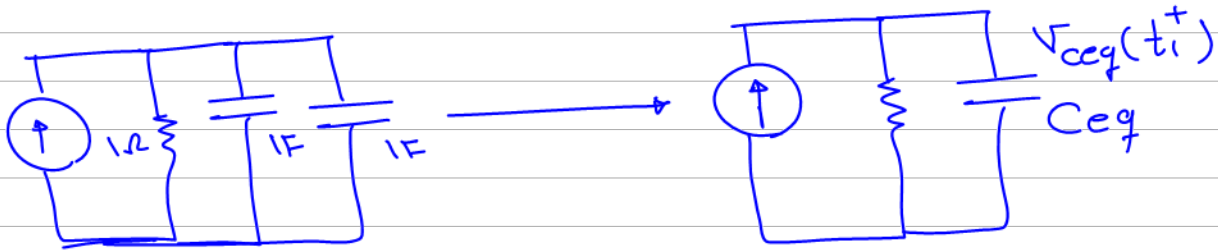
$$\Rightarrow V_{C1} < 1$$

$$V_{C1} = (0 - 2)e^{-t} + 2 = 2(1 - e^{-t})$$

$$V_{C1}(1) = 1 \Rightarrow e^{-t} = \frac{1}{2} \Rightarrow t_1 = \ln(2) \Rightarrow V_{C1} = 2(1 - e^{-t}) \quad 0 < t < t_1$$

$$\Rightarrow V_{C2} = 1 \quad 0 < t < t_1$$

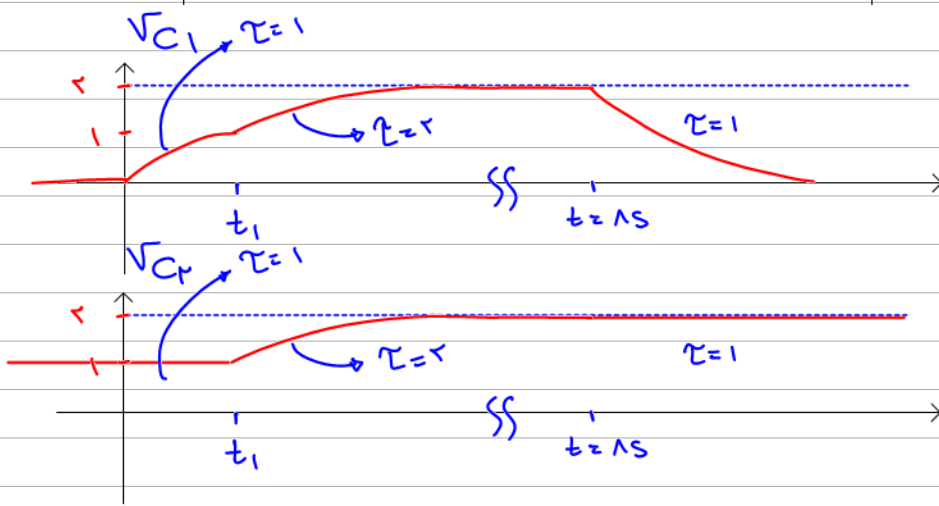
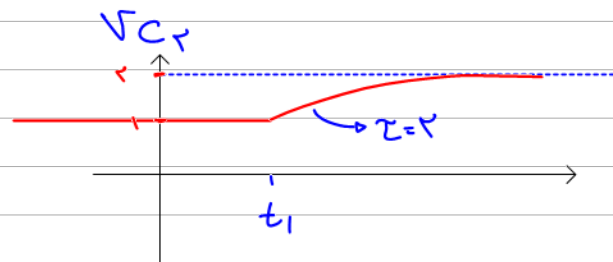
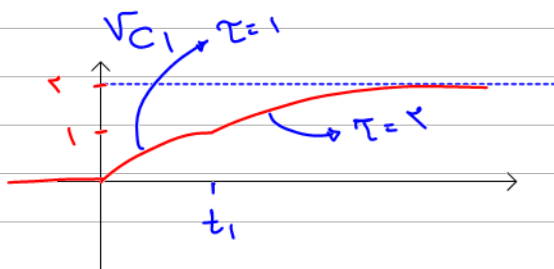
$$t > t_1 \Rightarrow V_{C1} > 1$$



$$C_{eq} = C_1 + C_2 = 2F$$

$$V_{ceq}(t_1^+) = \frac{C_1 V_C(t_1^-) + C_2 V_C(t_1^-)}{C_1 + C_2} = \frac{C_1 + C_2}{C_1 + C_2} = 1$$

$$\Rightarrow V_{C1} = V_{C2} = (1 - 2)e^{-\frac{t}{2}} + 2 = 2 - e^{-\frac{t}{2}}$$



ب

سؤال ٩) * شبکه را به صورت یک مدار معادلتی با مشخصه معادل R_{eq} , e_{oc} , i_{sc} فرض می کنیم



$$S(t) = \frac{1}{\omega_0} (1 - e^{-\frac{t}{\tau}}) u(t)$$

$$\tau = \Delta \Rightarrow RC = \Delta \Rightarrow R_{eq} = \tau, \omega_0$$

$$S(\infty) = e_{oc} = \frac{1}{\omega_0}$$

$$\Rightarrow i_{sc} = \frac{1}{\tau_0} \times \frac{1}{\tau, \omega} = \frac{1}{\omega_0} A$$



$$L = 1H \Rightarrow \tau = \frac{L}{R_{eq}} = \frac{1}{\tau, \omega} = \frac{\tau}{\omega}$$

$$S(\infty) = i_{sc} = \frac{1}{\omega_0} A$$

$$S(0^+) = 0$$

$$\Rightarrow S(t) = (S(0^+) - S(\infty)) e^{-\frac{t}{\tau}} + S(\infty)$$

$$\Rightarrow S(t) = -\frac{1}{\omega_0} e^{-\tau, \omega t} + \frac{1}{\omega_0} = \frac{1}{\omega_0} (1 - e^{-\tau, \omega t})$$

$$\Rightarrow S(t) = \frac{1}{\omega_0} (1 - e^{-\tau, \omega t}) u(t)$$

$$\Rightarrow h(t) = \frac{ds}{dt} = \frac{1}{\tau_0} e^{-\tau, \omega t} u(t) + 0 = \frac{1}{\tau_0} e^{-\tau, \omega t} u(t)$$

(الف)

$$\dot{i}_L(0^-) = \dot{i}_L(0^+) = 0 \Rightarrow \dot{i}_L = r(1 - e^{-t}) \quad 0 < t < 1$$

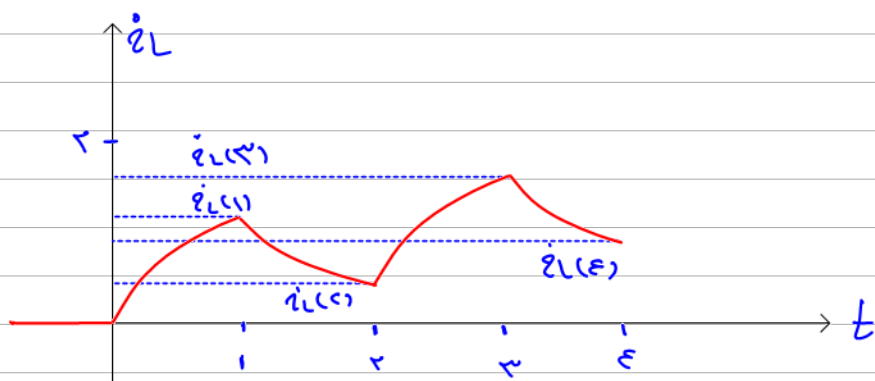
$$\Rightarrow \dot{i}_L(1^-) = r(1 - e^{-1}) \Rightarrow \dot{i}_L(1^+) = \frac{r(e-1)}{e}$$

$$\Rightarrow \dot{i}_L = r(1 - \frac{1}{e})e^{-(t-1)} \quad 1 < t < 2 \Rightarrow \dot{i}_L(2^-) = \dot{i}_L(2^+) = \frac{r(e-1)}{e^2}$$

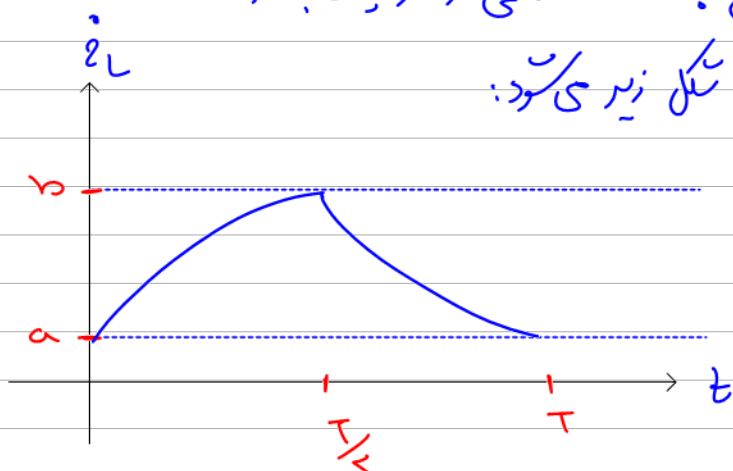
$$\Rightarrow \dot{i}_L = \frac{r(e-1)}{e^2} e^{-(t-2)} + r \quad 2 < t < 3 \Rightarrow \dot{i}_L(3^-) = \dot{i}_L(3^+) = \frac{r(e^2 - e^2 + e - 1)}{e^3}$$

$$\Rightarrow \dot{i}_L = \left(\frac{r - \frac{r}{e}}{e^2} + r \right) e^{-(t-3)} \quad 3 < t < 4 \Rightarrow \dot{i}_L(4^-) = \dot{i}_L(4^+) = \frac{r(e^3 - e^2 + e - 1)}{e^4}$$

$$\Rightarrow \begin{cases} \dot{i}_L(0) = 0 \\ \dot{i}_L(1) = \frac{r(e-1)}{e} \\ \dot{i}_L(2) = \frac{r(e-1)}{e^2} \\ \dot{i}_L(3) = \frac{r(e^2 - e^2 + e - 1)}{e^3} \\ \dot{i}_L(4) = \frac{r(e^3 - e^2 + e - 1)}{e^4} \end{cases}$$



(ب) فرض کنید پس از مدت زمانی طولانی بارخ به حالت دائمی خود رسیده باشد
 نمودار زمانی بارخ در هر دوره تناوب به شکل زیر می شود:



$$\Rightarrow (a - r)e^{-1} + r = b$$

$$(b - a)e^{-1} + 0 = a$$

$$\Rightarrow \begin{cases} a = \frac{r}{e+1} \\ b = \frac{re}{e+1} \end{cases}$$

$$\Rightarrow V_L = V_S - R \dot{q}_L = V_S - \dot{q}_L \Rightarrow$$

