

Deep learning

1.1. From neural networks to deep learning

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Many applications require the automatic extraction of “refined” information from raw signal (e.g. image recognition, automatic speech processing, natural language processing, robotic control, geometry reconstruction).



(ImageNet)

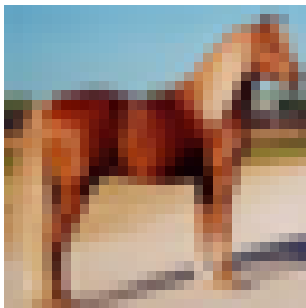
Our brain is so good at interpreting visual information that the “semantic gap” is hard to assess intuitively.

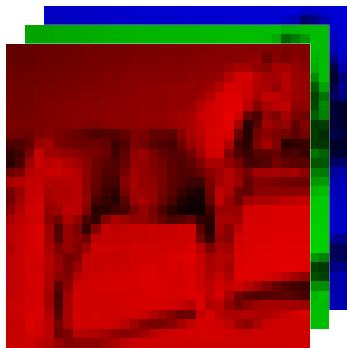
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This:



is a horse





```

>>> from torchvision.datasets import CIFAR10
>>> cifar = CIFAR10('./data/cifar10/', train=True, download=True)
Files already downloaded and verified
>>> x = torch.from_numpy(cifar.data)[43].permute(2, 0, 1)
>>> x[:, :4, :8]
tensor([[[ 99,  98, 100, 103, 105, 107, 108, 110],
         [100, 100, 102, 105, 107, 109, 110, 112],
         [104, 104, 106, 109, 111, 112, 114, 116],
         [109, 109, 111, 113, 116, 117, 118, 120]],

        [[166, 165, 167, 169, 171, 172, 173, 175],
         [166, 164, 167, 169, 169, 171, 172, 174],
         [169, 167, 170, 171, 171, 173, 174, 176],
         [170, 169, 172, 173, 175, 176, 177, 178]],

        [[198, 196, 199, 200, 200, 202, 203, 204],
         [195, 194, 197, 197, 197, 199, 200, 201],
         [197, 195, 198, 198, 198, 199, 201, 202],
         [197, 196, 199, 198, 198, 199, 200, 201]]], dtype=torch.uint8)

```

Extracting semantic automatically requires models of extreme complexity, which cannot be designed by hand.

Techniques used in practice consist of

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Deep learning encompasses software technologies to scale-up to billions of model parameters and as many training examples.

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Classical ML methods combine a “learnable” model from statistics (e.g. “linear regression”) with prior knowledge in pre-processing.

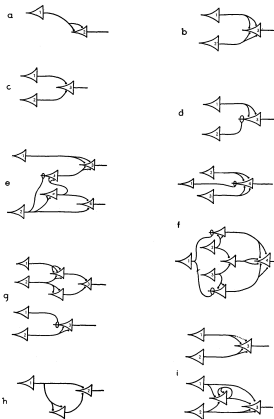
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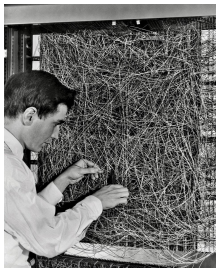
“Artificial neural networks” pre-dated these approaches, and do not follow this dichotomy. They consist of “deep” stacks of parametrized processing.

From artificial neural networks to “Deep Learning”

Networks of “Threshold Logic Unit”



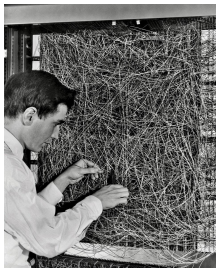
(McCulloch and Pitts, 1943)



Frank Rosenblatt working on the Mark I perceptron (1956)

1949 – Donald Hebb proposes the Hebbian Learning principle (Hebb, 1949).

1951 – Marvin Minsky creates the first ANN (Hebbian learning, 40 neurons).

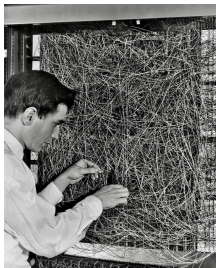


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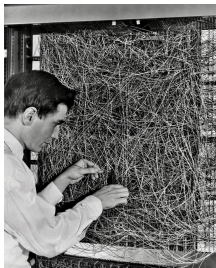
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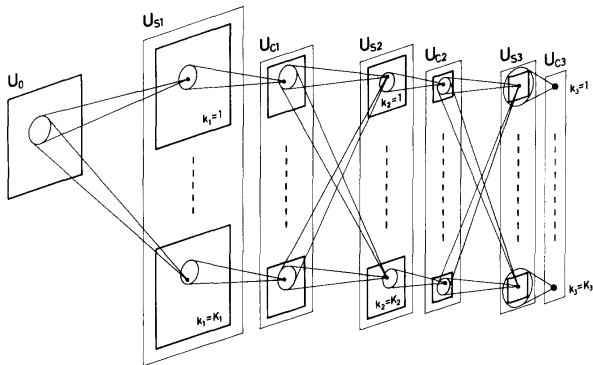
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- 1959 – David H. Hubel and Torsten Wiesel demonstrate orientation selectivity and columnar organization in the cat's visual cortex (Hubel and Wiesel, 1962).



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- 1982 – Paul Werbos proposes back-propagation for ANNs (Werbos, 1981).

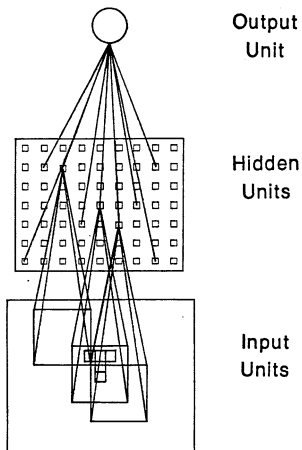
Neocognitron



(Fukushima, 1980)

This model follows Hubel and Wiesel's results.

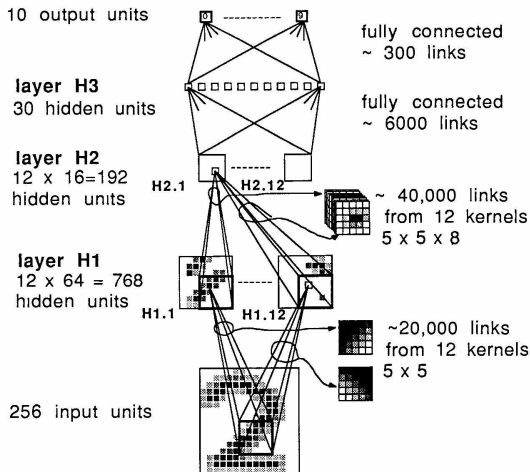
Network for the T-C problem



Trained with back-prop.

(Rumelhart et al., 1988)

LeNet family



(LeCun et al., 1989)

ImageNet Large Scale Visual Recognition Challenge.

Started 2010, 1 million images, 1000 categories

Hatchet


A small ax with a short handle used with one hand (usually to chop wood)

849
pictures

Numbers in brackets: (the number of synsets in the subtree)

- ImageNet 2011 Fall Release (321)
 - plant, flora, plant life (4486)
 - geological formation, formation
 - natural object (1112)
 - sport, athletics (176)
 - artifact, artefact (10504)
 - instrumentality, instrumenta
 - device (2760)
 - implement (726)
 - tool (347)
 - abrader, abradant
 - bender (0)
 - clincher (0)
 - comb (1)
 - cutting implement (1)
 - bit (12)
 - blade (2)
 - cutter, cutlery, c
 - bolt cutter (0)
 - cigar cutter (
 - die (0)
 - edge tool (92
 - adz, adze
 - ax, axe (1
 - broad

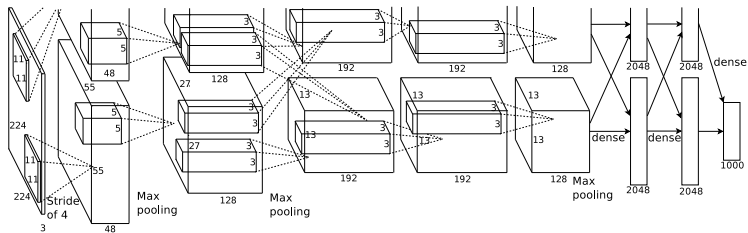
Tree map Visualization Images of the Synset Downloads



The grid displays 24 images of hatchets and axes. The images show the tools in various contexts: some are being used to chop wood, some are lying on surfaces, some are hanging on walls, and some are shown in close-up. The images are arranged in a 4x6 grid.

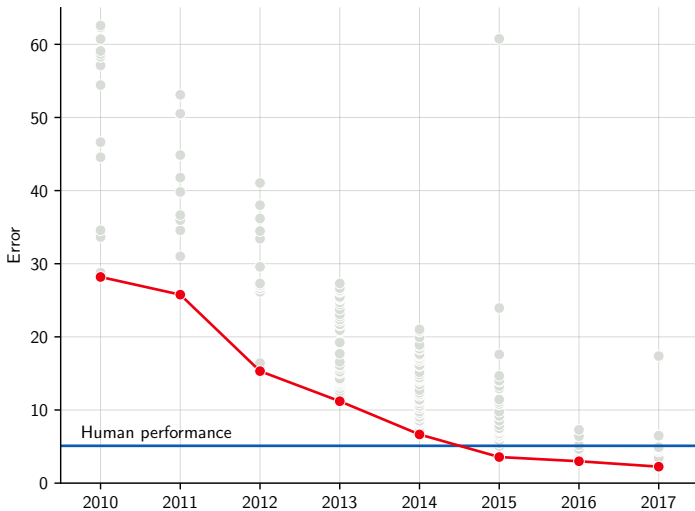
(<http://image-net.org/challenges/LSVRC/2014/browse-synsets>)

AlexNet



(Krizhevsky et al., 2012)

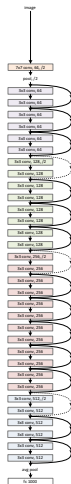
Top-5 error rate on ImageNet



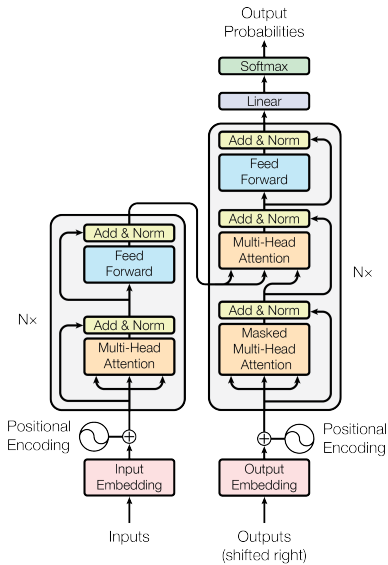
(Gershgorn, 2017)



GoogleNet (Szegedy et al., 2015)



ResNet (He et al., 2015)



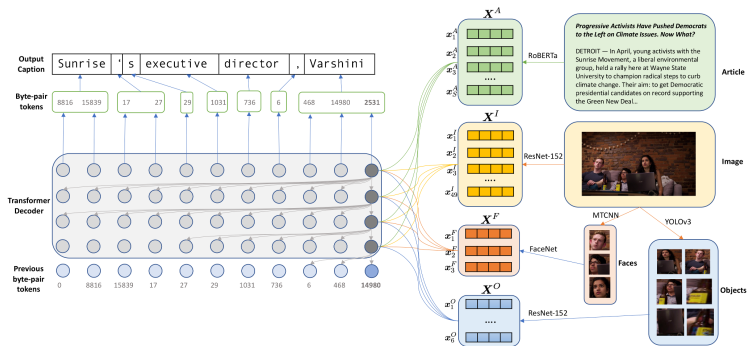
(Vaswani et al., 2017)

Deep learning is built on a natural generalization of a neural network: **a graph of tensor operators**, taking advantage of

- the chain rule (aka “back-propagation”),
- stochastic gradient descent,
- convolutions,
- parallel operations on GPUs.

This does not differ much from networks from the 90s.

This generalization allows to design complex networks of operators dealing with images, sound, text, sequences, etc. and to train them end-to-end.



(Tran et al., 2020)

The end

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