

# ALI BANIASAD

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## Education

**Sharif University of Technology** September 2022 – February 2025 (Expected)  
*Master of Science in Aerospace Engineering* Tehran, Iran

**Sharif University of Technology** September 2017 – May 2022  
*Bachelor of Science in Aerospace Engineering, GPA: 3.72/4 (17.56/20) last 6 semesters* Tehran, Iran

## Research Interests

- Reinforcement Learning
- Artificial Intelligence
- Robotics
- Automatic Control
- Optimal Control
- Deep Learning
- Computer Vision
- Game Theory

## Publications [\[Google Scholar profile\]](#)

- **Ali BaniAsad**, Reza Pordal, Alireza Sharifi, Hadi Nobahari. "Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach." *ISA Transactions*, [Elsevier](#), 2024.
- Alireza Sharifi, **Ali BaniAsad**. "Applied an In-Motion Transfer Alignment Approach During Global Positioning System Outages Utilizing a Recurrent Neural Network Algorithm." *Engineering Applications of Artificial Intelligence*, 2025 ([Under Review](#)).
- Hadi Nobahari, **Ali BaniAsad**, Alireza Sharifi. "Linear Quadratic Integral Differential Game Applied to the Real-time Control of a Quadrotor Experimental Setup." *ICRoM*, [IEEE](#), 2022.

## Research Experience

**Researcher at CNAV Lab** [in](#) [G](#) [Y](#) May 2020 – Ongoing  
*Researcher* Tehran, Iran

- Led projects on **Embedded AI** in C, **Reinforcement Learning (RL)**, and **ROS** for robotic control systems.
- Developed **Multi-Agent** tech and AI navigation, enhancing vehicle **Precision** and **Safety**.

**Master's Thesis** [\[GitHub\]](#) [G](#) August 2022 – February 205 (Expected)  
*Reinforcement Learning for Robotics in Complex Dynamical Systems* Tehran, Iran

- Investigated various **Reinforcement Learning** methods and compared their performance to classic control strategies.
- Integrated **ROS** to implement and test **Real-World Robotic** systems, validating performance in practical scenarios.

**Bachelor's Thesis** [\[GitHub\]](#) [G](#) February 2021 – September 2023  
*Game Theory-Based Control for Three Degrees of Freedom Platform* Tehran, Iran

- Controlled a **3DoF setup** using **Differential Game** theory, employing **Nash Equilibrium** for **Robust** controller.
- Evaluated performance through Simulink simulations and practical **Implementation** on an experimental setup.

## Projects

**Coordination of Multi-Agent Autonomous Systems** | *Embedded C, HIL, Optimization, Simulink* July 2023

- Developed a multi-agent model for optimized autonomous coordination under **Real-World Constraints**.
- Implemented and validated the model with Simulink simulations and **HIL** testing using a **Microcontroller**.

**Multi-Objective Heuristic Optimization** | *OOP, Optimization Algorithms, Python* February 2023

- Implemented the **REMARK** algorithm for **Multi-Objective** optimization with conflicting objectives.
- Utilized heuristic methods to achieve high approximations of the **Pareto Set**, balancing trade-offs between objectives.

**Advanced Aircraft Trim Stability Analysis** | *Advanced UI, Aircraft Control, Python* March 2022

- Developed an advanced UI software, **Optimizing Analysis Processes** and enhancing design precision.

**AIAA Regional Jet Design Competition** | *Aircraft Design, Computer Modeling, MATLAB, Python* June 2021

- Fully designed a regional jet, encompassing **Coding**, **Computer Design**, and **Simulations**.

## Awards and Honors

- Iranian Aerospace Society's **Best Undergraduate Thesis** Award.
- Ranked **Top 0.5%** in Nationwide Undergraduate Entrance Exam among more than 150,000 participants, 2017.

## Technical Skills

**Programming Languages:** C/C++, Embedded C, MATLAB, Python [P](#)

**Tools and Platforms:** Git [D](#), Linux [A](#), ROS, Simulink, **>\_Terminal**, **L<sup>A</sup>T<sub>E</sub>X**

**Libraries/Frameworks:** Matplotlib, NumPy, Pandas, PyTorch, TensorFlow

**Quantitative Skills:** Reinforcement Learning, Robotics, Data Structures, Deep Learning, Embedded Machine Learning, Heuristic Optimization, Game Theory