Ali BaniAsad
Curriculum Vitae

Contact Information
Email: alibaniasad1999@yahoo.com
Phone: (+98) 991-214-7276
LinkedIn: alibaniasad1999
GitHub: alibaniasad1999

EDUCATION

M.S. Aerospace Engineering — Sep. 2022 – Nov 2024 (Expected)
Sharif University of Technology

B.S. Aerospace Engineering — Sep. 2017 – May 2022
Sharif University of Technology

RESEARCH INTERESTS

- **Robotics**
  - **Reinforcement Learning**
    - Multi-Agent Systems
    - Optimal Control in RL
    - Policy Optimization
  - **Computer Vision**
    - Object Detection
    - Sensor Fusion
    - Image Segmentation
    - 3D Reconstruction
- **Artificial Intelligence**
  - Machine Learning
  - Artificial Neural Networks
  - Deep Learning
  - Natural Language Processing
- **Control Systems**
  - Optimal Control
  - Automatic Control
  - Robust Control
- **Game Theory**
  - Differential Game
  - Multi-Agent Game
  - Cooperative Game Theory
  - Non-Cooperative Game Theory

PUBLICATIONS

Journal Papers

- **Ali BaniAsad**, Alireza Sharifi, Reza Pordal, Hadi Nobahhari. "Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach." *ISA Transactions, Elsevier*, 2024.
- Alireza Sharifi, **Ali BaniAsad**. "Robust In-Motion Transfer Alignment of Low-Grade Inertial Navigation Systems with Recurrent Neural Networks in the Event of Reference Malfunction." *IEEE*, 2024 (Active)

- **Ali BaniAsad**, Hadi Nobahhari. "Robust Differential Game Reinforcement Learning with Soft Actor-Critic for Guidance in Low-Thrust Multi-Body Environments." *AIAA*, 2024 (Active)
- **Ali BaniAsad**, Alireza Sharifi. "Enhancing AHRS Results with Deep Learning LSTM Networks for Real-Time Attitude Estimation in GNSS-Denied Environments." *Engineering Applications of Artificial Intelligence*, 2024 (Active)

Conference Papers

- Hadi Nobahhari, **Ali BaniAsad**, Alireza Sharifi. "Linear Quadratic Integral Differential Game Applied to the Real-time Control of a Quadrotor Experimental Setup." *ICRoM, IEEE*, 2022.

RESEARCH EXPERIENCE

Researcher at CNAV Lab May 2020 – Ongoing
Head of Lab (Current), Researcher (Former) Tehran, Iran
Supervisors: Hadi Nobahari, PhD and Alireza Sharifi, PhD

- Led projects on integrating **embedded AI** with C programming to develop advanced robotic control systems, enhancing system efficiency and performance.
- Designed and implemented **reinforcement learning (RL)** algorithms to optimize robotic decision-making in environments with disturbances and nonlinearity.
- Integrated **ROS** frameworks with **HIL** and **swarm flight**, enabling seamless communication between robotic components.
- Tested and validated **AI decision-making** and navigation systems through real-world simulations, ensuring robustness under diverse conditions.

Robust Reinforcement Learning Guidance August 2022 – November 2024
Master's Thesis in Sharif University of Technology Tehran, Iran
Supervisors: Hadi Nobahari, PhD

- Investigated various reinforcement learning methods, comparing their performance to classic control strategies to identify advantages and limitations.
- Integrated Robot Operating System (ROS) to implement and test real-world robotic systems, validating performance in practical scenarios.
- Utilized differential game theory to develop robust and safe reinforcement learning algorithms, enhancing decision-making planning in complex environments.
- Conducted simulations to evaluate method safety, demonstrating their effectiveness in maintaining safety and optimizing performance under dynamic constraints.

Game Theory-Based Control for a UAV February 2021 – September 2023
Bachelor's Thesis in Sharif University of Technology Tehran, Iran
Supervisors: Hadi Nobahari, PhD

- Developed a robust control system for a quadcopter using differential game theory, employing Nash equilibrium to optimize controller performance under uncertainty.

- Evaluated system performance through extensive Simulink simulations, ensuring the theoretical models translated effectively to real-world applications.
- Implemented and tested the control strategy on a three-degree-of-freedom setup, demonstrating the efficacy of the game-theoretic approach in practical scenarios.
- Conducted a series of experiments to assess the quadcopter's stability and responsiveness, refining the control algorithms based on performance feedback.

Optimized Flocking of Autonomous Drones July 2023
Project in Sharif University of Technology Tehran, Iran
Supervisors: Hadi Nobahari, PhD

- Developed a UAV swarm model optimizing flocking behavior, using Embedded C for control and addressing communication delays and obstacles.
- Implemented and validated the model with Simulink simulations and HIL testing using a microcontroller, ensuring robustness in practical applications.
- Employed optimization techniques to enhance swarm performance, focusing on coordination and obstacle avoidance strategies.

Multi-Objective Heuristic Optimization February 2023
Project in Sharif University of Technology Tehran, Iran
Supervisors: Hadi Nobahari, PhD

- Implemented the REMARK algorithm for multi-objective optimization with conflicting objectives, allowing for the effective evaluation of trade-offs.
- Utilized heuristic methods to achieve high approximations of the Pareto set, balancing multiple objectives for optimal decision-making.

Advanced Aircraft Trim Stability Analysis with DATCOM March 2022
Project in Sharif University of Technology
Tehran, Iran
Supervisors: Afshin Banazadeh, PhD

- Developed an advanced UI for DATCOM software, streamlining aircraft trim stability analysis and enhancing user experience.
- Integrated real-time data visualization and interactive parameter adjustments for precise aircraft performance evaluations under various flight conditions.
- Tested and validated the UI to ensure reliability and precision, improving the design process for engineers and researchers.

AIAA Regional Jet Design Competition June 2021
Project in Sharif University of Technology Tehran, Iran
Supervisors: Afshin Banazadeh, PhD

- Led the comprehensive design of a regional jet, integrating various engineering disciplines to ensure optimal performance and compliance with industry standards.
- Utilized MATLAB and Python for complex computer modeling, including aerodynamic analysis, structural assessments, and performance simulations.
- Developed a detailed project report and presentation, showcasing design choices and simulation results.

- Collaborated with a multidisciplinary team to refine design concepts, ensuring effective communication and integration of ideas throughout the project lifecycle.

TEACHING EXPERIENCE

Teaching Assistant

- **Fundamentals of Programming (C/C++)** September 2018 – December 2018
  Department of Computer Engineering, Sharif University of Technology
  Instructor: Ms. Marjan Nikbin
- **Automatic Control** September 2021 – Present
  Department of Aerospace Engineering, Sharif University of Technology
  Instructors: Hadi Nobahari, PhD and Alireza Sharifi, PhD
- **Control Lab** September 2021 – Present
  Department of Aerospace Engineering, Sharif University of Technology
  Instructors: Hadi Nobahari, PhD and Alireza Sharifi, PhD
- **Aircraft Design II** September 2021 – December 2021
  Department of Aerospace Engineering, Sharif University of Technology
  Instructors: Afshin Banazadeh PhD
- **Dynamics** September 2021 – December 2023
  Department of Aerospace Engineering, Sharif University of Technology
  Instructors: Alireza Sharifi, PhD
- **Introduction to Aerospace Engineering** September 2021 – December 2023
  Department of Aerospace Engineering, Sharif University of Technology
  Instructors: Alireza Sharifi, PhD

AWARDS AND HONORS

Ranked 23 2017

Ranked 23 among more than 6,000 participants in the Nationwide University Entrance Exam for Aerospace Engineering.

Iranian Aerospace Society's Best Undergraduate Thesis Award 2022

Awarded for the exceptional undergraduate thesis titled "Control of a 3DOF Quadrotor Stand using a Linear-Quadratic-Integral Controller based on Differential Game Theory".

Ranked Top 0.5% 2017

Ranked Top 0.5% among 150,000 participants of Iran's Undergraduate University Entrance Exam

TECHNICAL SKILLS

- **Programming Languages**

  - C/C++ – Embedded C – MATLAB – Python
- **Tools and Platforms**
  - Git – ROS – Terminal
  - Linux – Simulink – LaTeX
- **Libraries/Frameworks:**
  - **Machine Learning:**
    - PyTorch
    - TensorFlow
    - Keras
    - Scikit-learn
    - OpenAI Gym
    - JAX
  - **Data Analysis and Visualization:**
    - Matplotlib
    - NumPy
    - Pandas
    - OpenCV
  - **Simulation:**
    - Gazebo
    - MuJoCo
- **Robotics Skills**
  - Machine Learning
    - Deep Learning
    - Embedded Machine Learning
    - Reinforcement Learning
    - Image Processing
  - Control Systems
    - Optimal Control
    - Automatic Control
    - Robust Control
  - Game Theory
    - Differential Game
    - Multi-Agent Systems
    - Cooperative Game
    - Non-Cooperative Game
- **Optimization**
  - Heuristic Optimization
  - Convex Optimization
  - Multi-Objective Optimization
  - Stochastic Optimization
- **Languages**
  - Farsi (Native)
  - English (Full Professional Proficiency)
    The TOEFL iBT score is 96 (Reading: 26, Listening: 27, Speaking: 22, Writing: 21)

NOTABLE COURSES

University Courses 2017 – 2024
Sharif University of Technology, Tehran, Iran

- **Programming and Computational Methods:**

- Basic Programming of C (20)
- Numerical Calculations (20)

- **Mathematics and Statistics:**
  - Engineering Mathematics (19.8)
  - Probability and Statistics (20)
- **Control Systems:**
  - Automatic Control (18.1)
  - Optimal Control (17.5)
  - Control Lab (18.5)
- **Aerospace Engineering:**
  - Aircraft Design II (18.3)
  - Flight Dynamics II (18.3)
- **Research and Projects:**
  - Bachelor Thesis (20)

Online Courses 2017 – 2024

- **Robotics:** verify certificate
  Provided by University of Pennsylvania, Coursera
  - Aerial Robotics
  - Computational Motion Planning
  - Mobility
  - Perception
  - Estimation and Learning
  - Capstone
- **Reinforcement Learning:** verify certificate
  Provided by University of Alberta, Coursera
  - Fundamentals of Reinforcement Learning
  - Sample-based Learning Methods
  - Prediction and Control with Function Approximation
  - A Complete Reinforcement Learning System
- **IBM AI Engineering:**
  Provided by IBM, Coursera
  - Machine Learning with Python
  - Introduction to Deep Learning and Neural Networks with Keras
  - Building Deep Learning Models with TensorFlow
  - Introduction to Neural Networks and PyTorch
  - Introduction to Computer Vision and Image Processing
  - AI Capstone Project with Deep Learning
- **Neural Networks and Deep Learning:** verify certificate
  Provided by deeplearning.ai, Coursera
- **Python Data Structures:** verify certificate
  Provided by University of Michigan, Coursera
- **Introduction to Embedded Machine Learning:** verify certificate
  Provided by Edge Impulse, Coursera
- **Game Theory:** verify certificate
  Provided by Stanford University, Coursera

HOBBIES

- Violin
- Classical Music (e.g., Vivaldi, Vitali)
- Reading (e.g., The Selfish Gene, Sapiens)
- Coding (including new technologies and funny projects)
- Swimming
- Traveling
- Chess
- Hiking
- Photography
- Table Tennis

REFERENCES

- **Sharifi, Alireza, PhD**
  Assistant Professor of Aerospace Engineering, Sharif University of Technology
  Dr. Sharifi Supervised my work in the CNAV Lab for over three years, during which we collaborated on multiple projects. I served as both a researcher and a teaching assistant during this time.
  - Faculty Page at Sharif University
  - ar.sharifi@sharif.edu
  - Google Scholar Profile
  - (+98)-21-6616-8115

- **Nobahari, Hadi, PhD**
  Professor of Aerospace Engineering, Sharif University of Technology
  I have worked with Dr. Hadi Nobahari for over four years, including on both my master's and bachelor's theses. Additionally, I served as a teaching assistant under his supervision, supporting course instruction and enhancing my understanding of the field.
  - Faculty Page at Sharif University
  - nobahari@sharif.edu
  - Google Scholar Profile
  - (+98)-21-6616-4040

- **Banazadeh, Afshin, PhD**
  Professor of Aerospace Engineering, Sharif University of Technology
  I have taken several courses with Dr. Banazadeh, achieving excellent results. I developed a fully designed regional jet and created a GUI to facilitate and automate the design process. Additionally, I served as a teaching assistant for the "Airplane Design II" course for one year.
  - Faculty Page at Sharif University
  - banazadeh@sharif.edu
  - Google Scholar Profile
  - (+98)-21-6616-8108