Ali BaniAsad

Curriculum Vitae

Contact Information

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EDUCATION

M.S. Aerospace Engineering Sharif University of Technology Sep. 2022 – Nov 2024 (Expected)

B.S. Aerospace Engineering Sharif University of Technology

Sep. 2017 – May 2022

RESEARCH INTERESTS

- Robotics
 - Reinforcement Learning
 - * Multi-Agent Systems
 - * Optimal Control in RL
 - * Policy Optimization
 - Computer Vision
 - * Object Detection
 - * Sensor Fusion
 - * Image Segmentation
 - * 3D Reconstruction
- Artificial Intelligence
 - Machine Learning

- Artificial Neural Networks
- Deep Learning
- Natural Language Processing
- Control Systems
 - Optimal Control
 - Automatic Control
 - Robust Control
- Game Theory
 - Differential Game
 - Multi-Agent Game
 - Cooperative Game Theory
 - Non-Cooperative Game Theory

PUBLICATIONS

Journal Papers

• Ali BaniAsad, Alireza Sharifi, Reza Pordal, Hadi Nobahhari. "Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach." *ISA Transactions, Elsevier*, 2024.

- Alireza Sharifi, **Ali BaniAsad**. "Robust In-Motion Transfer Alignment of Low-Grade Inertial Navigation Systems with Recurrent Neural Networks in the Event of Reference Malfunction." *IEEE*, 2024 (Active)
- Ali BaniAsad, Hadi Nobahhari. "Robust Differential Game Reinforcement Learning with Soft Actor-Critic for Guidance in Low-Thrust Multi-Body Environments." AIAA, 2024 (Active)
- Ali BaniAsad, Alireza Sharifi. "Enhancing AHRS Results with Deep Learning LSTM Networks for Real-Time Attitude Estimation in GNSS-Denied Environments." Engineering Applications of Artificial Intelligence, 2024 (Active)

Conference Papers

 Hadi Nobahhari, Ali BaniAsad, Alireza Sharifi. "Linear Quadratic Integral Differential Game Applied to the Real-time Control of a Quadrotor Experimental Setup." ICRoM, IEEE, 2022.

RESEARCH EXPERIENCE

Researcher at CNAV Lab in 🗘 🔼

May 2020 – Ongoing Tehran, Iran

Head of Lab (Current), Researcher (Former) Supervisors: Hadi Nobahari, PhD and Alireza Sharifi, PhD

• Led projects focusing on the integration of embedded AI using C programming for the development of advanced robotic control systems, enhancing overall system efficiency and performance.

- Designed and implemented reinforcement learning (RL) algorithms to optimize robotic navigation and decision-making processes, significantly improving adaptability in dynamic environments.
- Developed advanced quadrotor technology with AI-driven navigation systems, including INS-AI and AHRS AI, resulting in enhanced precision, safety, and operational reliability during complex missions.
- Collaborated with interdisciplinary teams to integrate Robot Operating System (ROS) frameworks, streamlining development processes and ensuring effective communication across project stakeholders.
- Conducted rigorous testing and validation of AI navigation systems, utilizing realworld simulations to ensure robustness and reliability under various operational conditions.

Robust Reinforcement Learning Guidance August 2022 – November 2024

Master's Thesis in Sharif University of Technology

Supervisors: Hadi Nobahari, PhD

• Investigated various reinforcement learning methods, comparing their performance to classic control strategies to identify advantages and limitations.

- Integrated Robot Operating System (ROS) to implement and test real-world robotic systems, validating performance in practical scenarios.
- Utilized differential game theory to develop robust and safe reinforcement learning algorithms, enhancing decision-making and trajectory planning in complex environments.
- Developed safety protocols and mechanisms to ensure reliable operation of robotic systems in uncertain conditions, focusing on minimizing risk during navigation and task execution.
- Conducted simulations to evaluate the robustness of the proposed methods, demonstrating their effectiveness in maintaining safety while optimizing performance under dynamic constraints.

Game Theory-Based Control for a UAV February 2021 – September 2023 Bachelor's Thesis in Sharif University of Technology

Supervisors: Hadi Nobahari, PhD

- Developed a robust control system for a quadcopter using differential game theory, employing Nash equilibrium to optimize controller performance under uncertainty.
- Evaluated system performance through extensive Simulink simulations, ensuring the theoretical models translated effectively to real-world applications.
- Implemented and tested the control strategy on a three-degree-of-freedom setup, demonstrating the efficacy of the game-theoretic approach in practical scenarios.
- Conducted a series of experiments to assess the quadcopter's stability and responsiveness, refining the control algorithms based on performance feedback.

Optimized Flocking of Autonomous Drones 🗘

July 2023

Project in Sharif University of Technology Supervisors: Hadi Nobahari, PhD Tehran, Iran

- Developed a UAV swarm model optimizing flocking behavior under real-world constraints, utilizing Embedded C for control algorithms and addressing challenges such as communication delays and environmental obstacles.
- Implemented and validated the model with Simulink simulations and Hardware-inthe-Loop (HIL) testing using a microcontroller, ensuring robustness and reliability in practical applications.
- Employed optimization techniques to enhance swarm performance, focusing on coordination and obstacle avoidance strategies.

Multi-Objective Heuristic Optimization © Project in Sharif University of Technology

February 2023

Tehran, Iran

Supervisors: Hadi Nobahari, PhD

• Implemented the REMARK algorithm for multi-objective optimization with conflicting objectives, allowing for the effective evaluation of trade-offs.

• Utilized heuristic methods to achieve high approximations of the Pareto set, balancing multiple objectives for optimal decision-making.

Advanced Aircraft Trim Stability Analysis with DATCOM 🗘

March 2022

Project in Sharif University of Technology

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Developed an advanced user interface (UI) for DATCOM software, streamlining the analysis workflow for aircraft trim stability assessments and enhancing user experience through intuitive design.
- Integrated features such as real-time data visualization and interactive parameter adjustments, allowing for more accurate and efficient evaluations of aircraft performance under various flight conditions.
- Conducted thorough testing and validation of the UI to ensure reliability and precision in output, significantly improving the design process for engineers and researchers.

AIAA Regional Jet Design Competition (7)

June 2021

Project in Sharif University of Technology Supervisors: Afshin Banazadeh, PhD

Tehran, Iran

- Led the comprehensive design of a regional jet, integrating various engineering disciplines to ensure optimal performance and compliance with industry standards.
- Utilized MATLAB and Python for complex computer modeling, including aerodynamic analysis, structural assessments, and performance simulations.
- Developed a detailed project report and presentation, showcasing design choices and simulation results, which facilitated a successful team presentation at the competition.
- Collaborated with a multidisciplinary team to refine design concepts, ensuring effective communication and integration of ideas throughout the project lifecycle.

TEACHING EXPERIENCE

Teaching Assistant

• Fundamentals of Programming (C/C++) September 2018 – December 2018 Department of Computer Engineering, Sharif University of Technology Instructor: Ms. Marjan Nikbin

• Automatic Control September 2021 – Present Department of Aerospace Engineering, Sharif University of Technology Instructors: Hadi Nobahari, PhD and Alireza Sharifi, PhD

• Control Lab September 2021 – Present Department of Aerospace Engineering, Sharif University of Technology Instructors: Hadi Nobahari, PhD and Alireza Sharifi, PhD

• Aircraft Design II September 2021 – December 2021 Department of Aerospace Engineering, Sharif University of Technology Instructors: Afshin Banazadeh PhD Dynamics September 2021 – December 2023
 Department of Aerospace Engineering, Sharif University of Technology
 Instructors: Alireza Sharifi, PhD

 Introduction to Aerospace Engineering September 2021 – December 2023
 Department of Aerospace Engineering, Sharif University of Technology

AWARDS AND HONORS

Ranked 23 2017

Ranked 23 among more than 6,000 participants in the Nationwide University Entrance Exam for Aerospace Engineering.

Iranian Aerospace Society's Best Undergraduate Thesis Award 2022

Awarded for the exceptional undergraduate thesis titled "Control of a 3DOF Quadrotor Stand using a Linear-Quadratic-Integral Controller based on Differential Game Theory".

Ranked Top 0.5%

Ranked Top 0.5% among 150,000 participants of Iran's Undergraduate University Entrance Exam

TECHNICAL SKILLS

• Programming Languages

Instructors: Alireza Sharifi, PhD

- C/C++ - Embedded C - MATLAB - Python

• Tools and Platforms

- Libraries/Frameworks:
 - Machine Learning Libraries:

Data Analysis and Visualization Libraries:

- Simulation Tools:

* Gazebo	* MuJoCo
• Robotics Skills	
- Machine Learning	
* Deep Learning * Artificial Neural Networks * Recurrent Neural Networks * Embedded Machine Learning	 * Reinforcement Learning * Heuristic Optimization * Convex Optimization * Image Processing
Control Systems* Optimal Control * Auto	matic Control * Robust Control
- Game Theory	
* Differential Game* Multi-Agent Systems	* Cooperative Game* Non-Cooperative Game
• Languages	
 Farsi (Native) English (Full Professional Proficience The TOEFL iBT score is 96 (Reading: 21) 	ey) ng: 26, Listening: 27, Speaking: 22, Writ-
NOTABLE C	OURSES
University Courses Sharif University of Technology, Tehran, Iran	2017 - 2024

• Programming and Computational Methods:

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• Mathematics and Statistics:

- Basic Programming of C (20)

- Engineering Mathematics (19.8) - Probability and Statistics (20)

- Numerical Calculations (20)

• Control Systems:

- Automatic Control (18.1) - Optimal Control (17.5)

- Control Lab (18.5)

• Aerospace Engineering:

- Aircraft Design II (18.3)
- Flight Dynamics II (18.3)

- Research and Projects:
 - Bachelor Thesis (20)

Online Courses 2017 – 2024

• Robotics:

Provided by University of Pennsylvania, Courser

verify certificate

- Aerial Robotics - Perception

- Computational Motion Planning - Estimation and Learning

- Mobility - Capstone

• Reinforcement Learning:

Provided by University of Alberta, Coursera

verify certificate

- Fundamentals of Reinforcement Learning
- Sample-based Learning Methods
- Prediction and Control with Function Approximation
- A Complete Reinforcement Learning System

• IBM AI Engineering:

Provided by IBM, Coursera

- Machine Learning with Python
- Introduction to Deep Learning and Neural Networks with Keras
- Building Deep Learning Models with TensorFlow
- Introduction to Neural Networks and PyTorch
- Introduction to Computer Vision and Image Processing
- AI Capstone Project with Deep Learning

• Neural Networks and Deep Learning:

Provided by deeplearning.ai, Coursera verify certificate

• Python Data Structures:

Provided by University of Michigan, Coursera verify certificate

• Introduction to Embedded Machine Learning:

Provided by Edge Impulse, Coursera verify certificate

• Game Theory:

Provided by Stanford University, Coursera verify certificate

HOBBIES

• Violin 🎵

• Classical Music •

• Reading

• Coding •

• Swimming 鑑

• Hiking **A**

• Traveling +

• Photography •

• Chess ir

REFERENCES

• Sharifi, Alireza, PhD

Assistant Professor of Aerospace Engineering, Sharif University of Technology Dr. Sharifi Supervised my work in the CNAV Lab for over three years, during which we collaborated on multiple projects. I served as both a researcher and a teaching assistant during this time.

Faculty Page at Sharif University
 ■ ar.sharifi@sharif.edu

- **S** Google Scholar Profile - **J** (+98)-21-6616-8115

• Nobahari, Hadi, PhD

Professor of Aerospace Engineering, Sharif University of Technology I have worked with Dr. Nobahari for over four years, including on both my master's and bachelor's theses.

- **♦** Faculty Page at Sharif University - ► nobahari@sharif.edu

- **Շ** Google Scholar Profile - **J** (+98)-21-6616-4040

• Banazadeh, Afshin, PhD

Professor of Aerospace Engineering, Sharif University of Technology

I have taken several courses with Dr. Banazadeh, achieving excellent results. I

developed a fully designed regional jet and created a GUI to facilitate and automate the design process. Additionally, I served as a teaching assistant for the "Airplane Design II" course for one year.

- **⊕** Faculty Page at Sharif University - **►** banazadeh@sharif.edu

- **Շ** Google Scholar Profile - **J** (+98)-21-6616-8108