

Ali BaniAsad

Curriculum Vitae

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EDUCATION

M.S. Aerospace Engineering
Sharif University of Technology

Sep. 2022 – Sep. 2025

B.S. Aerospace Engineering
Sharif University of Technology

Sep. 2017 – May 2022

RESEARCH INTERESTS

- Reinforcement Learning
- Robotics
- Multi-Agent Systems
- Automatic Control
- Game Theory
- Embedded ML

PUBLICATIONS

Journal Papers

- A. Sharifi, **A. BaniAsad**, and S. Mozafari, “Applied an in-motion transfer alignment approach during global positioning system outages utilizing a recurrent neural network algorithm,” *Engineering Applications of Artificial Intelligence*, vol. 157, pp. 111167, 2025, doi: 10.1016/j.engappai.2025.111167.
- **A. BaniAsad**, et al., “Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach,” *ISA Transactions*, vol. 148, pp. 515-527, 2024, doi: 10.1016/j.isatra.2024.03.005.

Conference Papers

- **A. BaniAsad** and H. Nobahari, “Robust DDPG Reinforcement Learning Differential Game Guidance in Low-Thrust, Multi-Body Dynamical Environments,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Project Repo \(Code, Report, and Presentation\) on GitHub](#)).
- M. Amirpour, **A. BaniAsad**, and H. Nobahari, “Reinforcement Learning-Based Controller Design for a Suspended Ball Plant,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Report](#)).
- H. Nobahari, **A. BaniAsad**, and A. Sharifi, “Linear Quadratic Integral Differential Game applied to the Real-time Control of a Quadrotor Experimental setup,” *Proc. of 2022 10th RSI International Conference on Robotics and Mechatronics (ICRoM)*, 2022, pp. 578-583, doi: 10.1109/ICRoM57054.2022.10025263.

Preprints and Under Review

- **A. BaniAsad**, H. Nobahari, “Robustness on Demand: Transformer-Directed Switching in Multi-Agent RL,” (in preparation), 2025.
- R. Pordal, A. Sharifi, and **A. BaniAsad**, “Ellipsoidal Set-Theoretic Design of Robust Safety Filters for Constrained Linear Systems,” arXiv: 2510.22790 [eess.SY], 2025. (preprint)

PROFESSIONAL EXPERIENCE

Work Experience

Robotic Engineer at Fasta Robotics [fasta.technology](#)  Oct. 2025 – Present
Autonomous Mobile Robot Development Tehran, Iran

- Developed AI-powered systems for autonomous mobile robots (AMRs) in warehouse and industrial environments.
- Implemented embedded ML algorithms for real-time obstacle detection, path planning, and collision avoidance.
- Designed fleet management algorithms for coordinating multiple AMRs, optimizing task allocation and traffic flow.
- Integrated computer vision and sensor fusion (LiDAR, cameras, IMU) for robust localization and mapping.
- Collaborated on ROS 2-based architecture for seamless communication between robot hardware and control systems.
- Utilized Isaac Sim and PyBullet for physics-based simulation, algorithm validation, and synthetic data generation.

Academic Research

Embedded RL Control for Robots  Aug. 2022 – Apr. 2025
Master's Thesis in Sharif University of Technology Tehran, Iran
Supervisors: Nobahari Hadi, PhD

- Designed zero-sum, disturbance-augmented training that kept policies stable under $10\times$ worst-case perturbations.
- Built 15k LOC RL control stack (DDPG, TD3, SAC, PPO) in PyTorch/TensorFlow+Gym for embedded robots.
- Optimized neural networks through quantization for constrained hardware with limited CPU/memory resources.
- Validated robustness on Gymnasium locomotion tasks—Ant, Humanoid, HalfCheetah, Walker2d.
- Ported system to C++/Python ROS 2 hardware-in-the-loop node for on-board testing.

Researcher at CNAV Lab [in](#)   May 2020 – Feb. 2025
Head of Lab (Current), Researcher (Former) Tehran, Iran
Supervisors: Nobahari Hadi, PhD and Sharifi Alireza, PhD

- Led projects on embedded AI in C, reinforcement learning, and ROS for robotic control systems.
- Designed RL algorithms to enhance robotic navigation, decision-making, and adaptability.
- Robust in-motion transfer alignment method based on multilayer neural network. 
 - Proposed LSTM-MLP using only IMU + SINS data when GPS is unavailable.
 - Cut navigation drift to $< 0.1\%$ of Kalman-INS error during 100s GPS outages.
 - Generalized across ship, ROV, and car datasets, outperforming conventional methods.

Game Theory-Based Control for 3-DoF Platform

Bachelor's Thesis in Sharif University of Technology

Feb. 2021 – Sep. 2023

Supervisors: Nobahari Hadi, PhD

Tehran, Iran

Awarded the Best Undergraduate Thesis

- Modeled a [3-DoF setup](#) in Simulink and identified dynamics for parameter estimation.
- Controlled 3-DoF quadcopter using differential game and Nash equilibrium for robust control.
- Implemented controller through MATLAB/Simulink-to-C pipeline for real-time hardware.
- Benchmarked against ADRC and DOBC, achieving superior disturbance robustness.

Projects

Coordination of Multi-Agent Autonomous Systems

July 2023

Sharif University of Technology

Tehran, Iran

Supervisors: Nobahari Hadi, PhD

- Optimized a multi-agent model for communication delays and obstacle avoidance.
- Implemented and validated with Simulink simulations and HIL testing using embedded C.

Multi-Objective Heuristic Optimization

Feb. 2023

Sharif University of Technology

Tehran, Iran

Supervisors: Nobahari Hadi, PhD

- Implemented [REMARK](#) algorithm for multi-objective optimization with conflicting objectives.
- Utilized heuristic methods to achieve high approximations of the Pareto Set.

Advanced Aircraft Trim Stability Analysis

Mar. 2022

Sharif University of Technology

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Developed advanced user interface software for aircraft stability analysis.
- Provided real-time interactive adjustments for aircraft performance evaluation.

AIAA Regional Jet Design Competition [Poster]

June 2021

Sharif University of Technology

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Led regional jet design, integrating disciplines for performance and industry standards.
- Developed project [report](#) and presentation with design choices and simulation results.
- Applied computer modeling for aerodynamic, structural, and performance analysis.

TEACHING EXPERIENCE

Section Leader — Stanford University

Apr. 2025 – June 2025

- Code in Place (CS106A) [verify](#)
- Mentor 10 international learners in Python.

Teaching Assistant — Sharif University of Technology

Sep. 2018 – Present

- Automatic Control (2021 – Present), Control Lab (2022 – Present), Dynamics (2023), Aircraft Design II (Fall 2021), Fundamentals of Programming C/C++ (Fall 2018)

Community Outreach

Sep. 2020 – Dec. 2021

- University Entrance-Exam Preparation, [Virgol Charity](#).

AWARDS AND HONORS

- Best Undergraduate Thesis — Iranian Aerospace Society 2023
“Control of a 3-DOF Quadrotor Stand via LQI & Differential Game Theory”
- National M.Sc. Entrance Exam (Aerospace) — Rank 23 / 1 000+ 2022
- National B.Sc. Entrance Exam — Top 0.5 % of 150 000 2017
- **NODET** — National Organization for Development of Exceptional Talents 2010–2017

TECHNICAL SKILLS

- **Programming Languages:**

- C/C++
- Embedded C
- MATLAB
- Python

- **Tools and OS:**

- Git 
- ROS
- Terminal 
- Linux 
- Simulink
- L^AT_EX

- **Libraries/Frameworks:**

- **Machine Learning Libraries:**
PyTorch, TensorFlow, Keras, Scikit-learn, OpenCV, OpenAI Gym, JAX
- **Data Analysis and Visualization Libraries:**
Matplotlib, NumPy, Pandas, Seaborn, Plotly
- **Simulation Tools:** Isaac Sim, MuJoCo, PyBullet, Gazebo

- **Languages:** Farsi (Native), English (Full Professional Proficiency)

The TOEFL iBT score is 96 (Reading: 26, Listening: 27, Speaking: 22, Writing: 21)

NOTABLE COURSES

Selected University Courses 2017–2024

- **Programming & Numerics:** Basic C Programming (20/20), Numerical Calculations (20/20)
- **Math & Statistics:** Engineering Mathematics (19.8/20), Probability & Statistics (20/20)
- **Control Systems:** Automatic Control (18.1), Control Lab (18.5/20), Optimal Control (17.5/20)
- **Aerospace Engineering:** Aircraft Design II (18.3/20), Flight Dynamics II (18.3/20)
- **Research:** B.Sc. Thesis (20/20)

Online Courses 2017–2024

- **Robotics Specialization** — Univ. of Pennsylvania (6 courses) [verify](#)
- **Reinforcement Learning Specialization** — Univ. of Alberta (4 courses) [verify](#)
- **AI Engineering Pro-Cert** — IBM (6 courses)
- **Accelerated Computing with CUDA Python** — NVIDIA
- **Neural Networks & Deep Learning** — deeplearning.ai [verify](#)
- **Python Data Structures** — Univ. of Michigan [verify](#)
- **Intro to Embedded Machine Learning** — Edge Impulse [verify](#)
- **Game Theory** — Stanford University [verify](#)