Ali BaniAsad

Tehran, Azadi Ave, P932+FM4, Iran
+98 991-214-7276 alibaniasad1999@yahoo.com linkedin.com/in/alibaniasad1999 github.com/alibaniasad1999

Education

Sharif University of Technology **September 2022 – February 2025 (Expected)**
Master of Science in Aerospace Engineering *Tehran, Iran*

Sharif University of Technology **September 2017 – May 2022**
Bachelor of Science in Aerospace Engineering, GPA: 3.72/4 (17.56/20) last 6 semesters *Tehran, Iran*

Research Interests

- Reinforcement Learning
- Optimal Control
- Artificial Intelligence
- Deep Learning
- Robotics
- Computer Vision
- Automatic Control
- Game Theory

Publications *[Google Scholar profile]*

- **Ali BaniAsad**, Reza Pordal, Alireza Sharifi, Hadi Nobahari. "Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach." *ISA Transactions, Elsevier*, 2024.
- Alireza Sharifi, **Ali BaniAsad**. "Applied an In-Motion Transfer Alignment Approach During Global Positioning System Outages Utilizing a Recurrent Neural Network Algorithm." *Engineering Applications of Artificial Intelligence*, 2024 (Under Review).
- Hadi Nobahari, **Ali BaniAsad**, Alireza Sharifi. "Linear Quadratic Integral Differential Game Applied to the Real-time Control of a Quadrotor Experimental Setup." *ICRoM, IEEE*, 2022.

Research Experience

Researcher at CNAV Lab **May 2020 – Ongoing**
Head of Lab (Current), Researcher (Former) *Tehran, Iran*

- Led projects on **Embedded AI** in C, **Reinforcement Learning (RL)**, and **ROS** for robotic control systems.
- Developed **Multi-Agent** tech and AI navigation, enhancing vehicle **Precision** and **Safety**.

Master's Thesis *[GitHub]* **August 2022 – February 205 (Expected)**
Reinforcement Learning for Robotics in Complex Dynamical Systems *Tehran, Iran*

- Investigated various **Reinforcement Learning** methods and compared their performance to classic control strategies.
- Integrated **ROS** to implement and test **Real-World Robotic** systems, validating performance in practical scenarios.

Bachelor's Thesis *[GitHub]* **February 2021 – September 2023**
Game Theory-Based Control for Three Degrees of Freedom Platform *Tehran, Iran*

- Controlled a 3DoF setup using **Differential Game** theory, employing **Nash Equilibrium** for **Robust** controller.
- Evaluated performance through Simulink simulations and practical **Implementation** on an experimental setup.

Projects

Coordination of Multi-Agent Autonomous Systems | *Embedded C, HIL, Optimization, Simulink* **July 2023**

- Developed a multi-agent model for optimized autonomous coordination under **Real-World Constraints**.
- Implemented and validated the model with Simulink simulations and **HIL** testing using a **Microcontroller**.

Multi-Objective Heuristic Optimization | *OOP, Optimization Algorithms, Python* **February 2023**

- Implemented the REMARK algorithm for **Multi-Objective** optimization with conflicting objectives.
- Utilized heuristic methods to achieve high approximations of the **Pareto Set**, balancing trade-offs between objectives.

Advanced Aircraft Trim Stability Analysis | *Advanced UI, Aircraft Control, Python* **March 2022**

- Developed an advanced UI software, **Optimizing Analysis Processes** and enhancing design precision.

AIAA Regional Jet Design Competition | *Aircraft Design, Computer Modeling, MATLAB, Python* **June 2021**

- Fully designed a regional jet, encompassing **Coding**, **Computer Design**, and **Simulations**.

Awards and Honors

- Iranian Aerospace Society's **Best Undergraduate Thesis** Award.
- Ranked **Top 0.5%** in Nationwide Undergraduate Entrance Exam among more than 150,000 participants, 2017.

Technical Skills

Programming Languages: C/C++, Embedded C, MATLAB, Python
Tools and Platforms: Git, Linux, ROS, Simulink, Terminal, LaTeX
Libraries/Frameworks: Matplotlib, NumPy, Pandas, PyTorch, TensorFlow
Quantitative Skills: Reinforcement Learning, Robotics, Data Structures, Deep Learning, Embedded Machine Learning, Heuristic Optimization, Game Theory