

# Ali BaniAsad

## Curriculum Vitae

Website: alibaniasad1999

Scholar: Ali BaniAsad

LinkedIn: alibaniasad1999

GitHub: alibaniasad1999

Email: alibaniasad1999@gmail.com

Phone: (+98) 991-214-7276

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## EDUCATION

M.S. Aerospace Engineering  
*Sharif University of Technology*

Sep. 2022 – Sep. 2025

B.S. Aerospace Engineering  
*Sharif University of Technology*

Sep. 2017 – May 2022

## RESEARCH INTERESTS

- Reinforcement Learning
- Robotics
- Multi-Agent Systems
- Automatic Control
- Game Theory
- Embedded ML

## PUBLICATIONS

### Journal Papers

- A. Sharifi, **A. BaniAsad**, and S. Mozafari, “Applied an in-motion transfer alignment approach during global positioning system outages utilizing a recurrent neural network algorithm,” *Engineering Applications of Artificial Intelligence*, vol. 157, pp. 111167, 2025, doi: 10.1016/j.engappai.2025.111167.
- **A. BaniAsad**, et al., “Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach,” *ISA Transactions*, vol. 148, pp. 515-527, 2024, doi: 10.1016/j.isatra.2024.03.005.

### Conference Papers

- **A. BaniAsad** and H. Nobahari, “Robust DDPG Reinforcement Learning Differential Game Guidance in Low-Thrust, Multi-Body Dynamical Environments,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Project Repo \(Code, Report, and Presentation\) on GitHub](#)).
- M. Amirpour, **A. BaniAsad**, and H. Nobahari, “Reinforcement Learning-Based Controller Design for a Suspended Ball Plant,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Report](#)).
- H. Nobahari, **A. BaniAsad**, and A. Sharifi, “Linear Quadratic Integral Differential Game applied to the Real-time Control of a Quadrotor Experimental setup,” *Proc. of 2022 10th RSI International Conference on Robotics and Mechatronics (ICRoM)*, 2022, pp. 578-583, doi: 10.1109/ICRoM57054.2022.10025263.

### Preprints and Under Review

- **A. BaniAsad**, H. Nobahari, “Robustness on Demand: Transformer-Directed Switching in Multi-Agent RL,” (in preparation), 2025.
- R. Pordal, A. Sharifi, and **A. BaniAsad**, “Ellipsoidal Set-Theoretic Design of Robust Safety Filters for Constrained Linear Systems,” arXiv: 2510.22790 [eess.SY], 2025. (preprint)

## PROFESSIONAL EXPERIENCE

### Work Experience

**Robotic Engineer at Fasta Robotics** [fasta.tech](https://fasta.tech)  Oct. 2025 – Present  
*Autonomous Mobile Robot Development* Tehran, Iran


- Developed AI-powered systems for autonomous mobile robots (AMRs) in warehouse and industrial environments.
- Implemented embedded ML algorithms for real-time obstacle detection, path planning, and collision avoidance.
- Designed fleet management algorithms for coordinating multiple AMRs, optimizing task allocation and traffic flow.
- Integrated computer vision and sensor fusion (LiDAR, cameras, IMU) for robust localization and mapping.
- Collaborated on ROS 2-based architecture for seamless communication between robot hardware and control systems.
- Utilized Isaac Sim and PyBullet for physics-based simulation, algorithm validation, and synthetic data generation.

### Academic Research

**Embedded RL Control for Robots**  Aug. 2022 – Apr. 2025  
*Master's Thesis in Sharif University of Technology* Tehran, Iran  
Supervisors: Nobahari Hadi, PhD

- Designed zero-sum, disturbance-augmented training that kept policies stable under  $10\times$  worst-case perturbations.
- Built 15k LOC RL control stack (DDPG, TD3, SAC, PPO) in PyTorch/TensorFlow+Gym for embedded robots.
- Optimized neural networks through quantization for constrained hardware with limited CPU/memory resources.
- Validated robustness on Gymnasium locomotion tasks—Ant, Humanoid, HalfCheetah, Walker2d.
- Ported system to C++/Python ROS 2 hardware-in-the-loop node for on-board testing.

**Researcher at CNAV Lab**    May 2020 – Feb. 2025  
*Head of Lab (Current), Researcher (Former)* Tehran, Iran  
Supervisors: Nobahari Hadi, PhD and Sharifi Alireza, PhD

- Led projects on embedded AI in C, reinforcement learning, and ROS for robotic control systems.
- Designed RL algorithms to enhance robotic navigation, decision-making, and adaptability.
- Robust in-motion transfer alignment method based on multilayer neural network. 
  - Proposed LSTM-MLP using only IMU + SINS data when GPS is unavailable.
  - Cut navigation drift to  $< 0.1\%$  of Kalman-INS error during 100s GPS outages.
  - Generalized across ship, ROV, and car datasets, outperforming conventional methods.


## Game Theory-Based Control for 3-DoF Platform

Feb. 2021 – Sep. 2023

*Bachelor's Thesis in Sharif University of Technology*

Tehran, Iran

Supervisors: Nobahari Hadi, PhD

*Awarded the Best Undergraduate Thesis *

- Modeled a [3-DoF setup](#) in Simulink and identified dynamics for parameter estimation.
- Controlled 3-DoF quadcopter using differential game and Nash equilibrium for robust control.
- Implemented controller through MATLAB/Simulink-to-C pipeline for real-time hardware.
- Benchmarked against ADRC and DOBC, achieving superior disturbance robustness.

## Projects

### Coordination of Multi-Agent Autonomous Systems

July 2023

*Sharif University of Technology*

Tehran, Iran

Supervisors: Nobahari Hadi, PhD

- Optimized a multi-agent model for communication delays and obstacle avoidance.
- Implemented and validated with Simulink simulations and HIL testing using embedded C.

### Multi-Objective Heuristic Optimization

Feb. 2023

*Sharif University of Technology*

Tehran, Iran

Supervisors: Nobahari Hadi, PhD

- Implemented [REMARK](#) algorithm for multi-objective optimization with conflicting objectives.
- Utilized heuristic methods to achieve high approximations of the Pareto Set.

### Advanced Aircraft Trim Stability Analysis

Mar. 2022

*Sharif University of Technology*

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Developed advanced user interface software for aircraft stability analysis.
- Provided real-time interactive adjustments for aircraft performance evaluation.

### AIAA Regional Jet Design Competition [\[Poster\]](#)

June 2021

*Sharif University of Technology*

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Led regional jet design, integrating disciplines for performance and industry standards.
- Developed project [report](#) and presentation with design choices and simulation results.
- Applied computer modeling for aerodynamic, structural, and performance analysis.

## TEACHING EXPERIENCE

### Section Leader — Stanford University

Apr. 2025 – June 2025

- Code in Place (CS106A) [verify](#)
- Mentor 10 international learners in Python.

### Teaching Assistant — Sharif University of Technology

Sep. 2018 – Present

- Automatic Control (2021 – Present), Control Lab (2022 – Present), Dynamics (2023), Aircraft Design II (Fall 2021), Fundamentals of Programming C/C++ (Fall 2018)

### Community Outreach




Sep. 2020 – Dec. 2021

- University Entrance-Exam Preparation, [Virgol Charity](#).

## AWARDS AND HONORS

- Best Undergraduate Thesis — Iranian Aerospace Society 2023  
“Control of a 3-DOF Quadrotor Stand via LQI & Differential Game Theory”
- National M.Sc. Entrance Exam (Aerospace) — Rank 23 / 1 000+ 2022
- National B.Sc. Entrance Exam — Top 0.5 % of 150 000 2017
- [NODET](#) — National Organization for Development of Exceptional Talents 2010–2017

## TECHNICAL SKILLS

- **Programming Languages:**
  - C/C++
  - Embedded C
  - MATLAB
  - Python
- **Tools and OS:**
  - Git 
  - ROS
  - Terminal 
  - Linux 
  - Simulink
  - $\text{\LaTeX}$
- **Libraries/Frameworks:**
  - **Machine Learning Libraries:**  
PyTorch, TensorFlow, Keras, Scikit-learn, OpenCV, OpenAI Gym, JAX
  - **Data Analysis and Visualization Libraries:**  
Matplotlib, NumPy, Pandas, Seaborn, Plotly
  - **Simulation Tools:** Isaac Sim, MuJoCo, PyBullet, Gazebo
- **Languages:** Farsi (Native), English (Full Professional Proficiency)  
The TOEFL iBT score is 96 (Reading: 26, Listening: 27, Speaking: 22, Writing: 21)

## NOTABLE COURSES

Selected University Courses 2017–2024

- **Programming & Numerics:** Basic C Programming (20/20), Numerical Calculations (20/20)
- **Math & Statistics:** Engineering Mathematics (19.8/20), Probability & Statistics (20/20)
- **Control Systems:** Automatic Control (18.1), Control Lab (18.5/20), Optimal Control (17.5/20)
- **Aerospace Engineering:** Aircraft Design II (18.3/20), Flight Dynamics II (18.3/20)
- **Research:** B.Sc. Thesis (20/20)

Online Courses 2017–2024

- **Robotics Specialization** — Univ. of Pennsylvania (6 courses) [verify](#)
- **Reinforcement Learning Specialization** — Univ. of Alberta (4 courses) [verify](#)
- **AI Engineering Pro-Cert** — IBM (6 courses)
- **Accelerated Computing with CUDA Python** — NVIDIA
- **Neural Networks & Deep Learning** — deeplearning.ai [verify](#)
- **Python Data Structures** — Univ. of Michigan [verify](#)
- **Intro to Embedded Machine Learning** — Edge Impulse [verify](#)
- **Game Theory** — Stanford University [verify](#)