




Ali BaniAsad


Curriculum Vitae


 Website: alibaniasad1999

 Scholar: Ali BaniAsad

 LinkedIn: alibaniasad1999

 GitHub: alibaniasad1999

 Email: alibaniasad1999@gmail.com

 Phone: (+98) 991-214-7276

EDUCATION

M.S. Aerospace Engineering
Sharif University of Technology

Sep. 2022 – Apr. 2025

B.S. Aerospace Engineering
Sharif University of Technology
Upper-division GPA: 3.72/4.00

Sep. 2017 – May 2022

RESEARCH INTERESTS

- Reinforcement Learning
- Robotics
- Multi-Agent Systems
- Automatic Control
- Game Theory
- Embedded ML

PUBLICATIONS

Journal Papers

- A. Sharifi, **A. BaniAsad**, and S. Mozafari, “Applied an in-motion transfer alignment approach during global positioning system outages utilizing a recurrent neural network algorithm,” *Engineering Applications of Artificial Intelligence*, vol. 157, pp. 111167, 2025, doi: 10.1016/j.engappai.2025.111167.
- **A. BaniAsad**, et al., “Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach,” *ISA Transactions*, vol. 148, pp. 515-527, 2024, doi: 10.1016/j.isatra.2024.03.005.

Conference Papers

- **A. BaniAsad** and H. Nobahari, “Robust DDPG Reinforcement Learning Differential Game Guidance in Low-Thrust, Multi-Body Dynamical Environments,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Project Repo](#) ([Code](#), [Report](#), and [Presentation](#)) on [GitHub](#)).
- M. Amirpour, **A. BaniAsad**, and H. Nobahari, “Reinforcement Learning-Based Controller Design for a Suspended Ball Plant,” in *Proc. of 23rd International Conference of Iranian Aerospace Society*, 2025 ([Proceedings entry](#)) ([Report](#)).
- H. Nobahari, **A. BaniAsad**, and A. Sharifi, “Linear Quadratic Integral Differential Game applied to the Real-time Control of a Quadrotor Experimental setup,” *Proc. of 2022 10th RSI International Conference on Robotics and Mechatronics (ICRoM)*, 2022, pp. 578-583, doi: 10.1109/ICRoM57054.2022.10025263.

Preprints and Under Review

- **A. BaniAsad**, H. Nobahari, “Robustness on Demand: Transformer-Directed Switching in Multi-Agent RL,” (in preparation), 2025.
- R. Pordal, A. Sharifi, and **A. BaniAsad**, “Ellipsoidal Set-Theoretic Design of Robust Safety Filters for Constrained Linear Systems,” arXiv: 2510.22790 [eess.SY], 2025. (preprint)

PROFESSIONAL EXPERIENCE

Work Experience

Robotic Engineer at Fasta Robotics fasta.technology  Oct. 2025 – Present
Autonomous Mobile Robot Development Tehran, Iran


- Developed AI-driven navigation for warehouse AMRs; reduced manual intervention by 40%.
- Deployed embedded ML for obstacle detection, path planning, and collision avoidance.
- Designed multi-robot fleet coordination algorithms optimizing task allocation and traffic flow.
- Fused LiDAR, camera, and IMU data for robust SLAM-based localization and mapping.
- Architected ROS 2 nodes for reliable hardware–software communication across the fleet.
- Validated controllers in Isaac Sim and PyBullet; generated synthetic datasets for training.

Academic Research

Embedded RL Control for Robots  Aug. 2022 – Apr. 2025
Master's Thesis in Sharif University of Technology Tehran, Iran
Supervisors: Nobahari Hadi, PhD

- Designed zero-sum, disturbance-augmented training; policies stable under $10\times$ perturbations.
- Built 15k LOC RL stack (DDPG, TD3, SAC, PPO) in PyTorch/TensorFlow+Gym.
- Optimized neural networks via quantization for resource-constrained hardware.
- Validated robustness on Gymnasium tasks: Ant, Humanoid, HalfCheetah, Walker2d.
- Ported system to C++/Python ROS 2 node for hardware-in-the-loop testing.

Researcher at CNAV Lab    May 2020 – Feb. 2025
Head of Lab (Former) Tehran, Iran
Supervisors: Nobahari Hadi, PhD and Sharifi Alireza, PhD

- Led embedded AI (C) and RL projects for robotic control and navigation.
- Developed LSTM-MLP for GPS-denied INS alignment; $< 0.1\%$ drift vs Kalman-INS. 

Game Theory-Based Control for 3-DoF Platform   Feb. 2021 – Sep. 2023
Bachelor's Thesis — Sharif University of Technology **Best Thesis Award** 
Supervisor: Nobahari Hadi, PhD

- Designed LQI differential-game controller; outperformed ADRC/DOBC in robustness.
- Deployed via MATLAB/Simulink-to-C pipeline for real-time 3-DoF quadcopter control.

TEACHING EXPERIENCE

Section Leader — Stanford University Apr. 2025 – June 2025

- Code in Place (CS106A) [verify](#)
- Mentor 10 international learners in Python.

Teaching Assistant — Sharif University of Technology Sep. 2018 – Present

- Automatic Control (2021 – Present), Control Lab (2022 – Present), Dynamics (2023), Aircraft Design II (Fall 2021), Fundamentals of Programming C/C++ (Fall 2018)




Community Outreach Sep. 2020 – Dec. 2021

- University Entrance-Exam Preparation, [Virgol Charity](#).

AWARDS AND HONORS

- Best Undergraduate Thesis — Iranian Aerospace Society 2023
“Control of a 3-DOF Quadrotor Stand via LQI & Differential Game Theory”
- National M.Sc. Entrance Exam (Aerospace) — Rank 23 / 1 000+ 2022
- National B.Sc. Entrance Exam — Top 0.5 % of 150 000 2017
- [NODET](#) — National Organization for Development of Exceptional Talents 2010–2017

TECHNICAL SKILLS

- **Programming Languages:**
 - C/C++
 - Embedded C
 - MATLAB
 - Python
- **Tools and OS:**
 - Git 
 - ROS
 - Terminal 
 - Linux 
 - Simulink
 - \LaTeX
- **Libraries/Frameworks:**
 - **Machine Learning Libraries:**
PyTorch, TensorFlow, Keras, Scikit-learn, OpenCV, OpenAI Gym, JAX
 - **Data Analysis and Visualization Libraries:**
Matplotlib, NumPy, Pandas, Seaborn, Plotly
 - **Simulation Tools:** Isaac Sim, MuJoCo, PyBullet, Gazebo
- **Languages:** Farsi (Native), English (Full Professional Proficiency)
The TOEFL iBT score is 96 (Reading: 26, Listening: 27, Speaking: 22, Writing: 21)

NOTABLE COURSES

Selected University Courses 2017–2024

- **Programming & Numerics:** Basic C Programming (20/20), Numerical Calculations (20/20)
- **Math & Statistics:** Engineering Mathematics (19.8/20), Probability & Statistics (20/20)
- **Control Systems:** Automatic Control (18.1), Control Lab (18.5/20), Optimal Control (17.5/20)
- **Aerospace Engineering:** Aircraft Design II (18.3/20), Flight Dynamics II (18.3/20)
- **Research:** B.Sc. Thesis (20/20)

Online Courses 2017–2024

- **Robotics Specialization** — Univ. of Pennsylvania (6 courses) [verify](#)
- **Reinforcement Learning Specialization** — Univ. of Alberta (4 courses) [verify](#)
- **AI Engineering Pro-Cert** — IBM (6 courses)
- **Accelerated Computing with CUDA Python** — NVIDIA
- **Neural Networks & Deep Learning** — deeplearning.ai [verify](#)
- **Python Data Structures** — Univ. of Michigan [verify](#)
- **Intro to Embedded Machine Learning** — Edge Impulse [verify](#)
- **Game Theory** — Stanford University [verify](#)