

Ali BaniAsad

Curriculum Vitae

Contact Information

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EDUCATION

M.S. Aerospace Engineering
Sharif University of Technology

Sep. 2022 – Nov 2024 (Expected)

B.S. Aerospace Engineering
Sharif University of Technology

Sep. 2017 – May 2022

RESEARCH INTERNSHIPS

- **Robotics**

- **Reinforcement Learning**

- * Multi-Agent Systems
 - * Optimal Control in RL
 - * Policy Optimization

- **Computer Vision**

- * Object Detection
 - * Sensor Fusion
 - * Image Segmentation
 - * 3D Reconstruction

- **Artificial Intelligence**

- Machine Learning

- Artificial Neural Networks
 - Deep Learning
 - Natural Language Processing

- **Control Systems**

- Optimal Control
 - Automatic Control
 - Robust Control

- **Game Theory**

- Differential Game
 - Multi-Agent Game
 - Cooperative Game Theory
 - Non-Cooperative Game Theory

PUBLICATIONS

Journal Papers

- **Ali BaniAsad**, Alireza Sharifi, Reza Pordal, Hadi Nobahhari. "Attitude Control of a 3-DoF Quadrotor Platform Using a Linear Quadratic Integral Differential Game Approach." *ISA Transactions*, [Elsevier](#), 2024.

- Alireza Sharifi, **Ali BaniAsad**. "Robust In-Motion Transfer Alignment of Low-Grade Inertial Navigation Systems with Recurrent Neural Networks in the Event of Reference Malfunction." *IEEE*, 2024 (Active)
- **Ali BaniAsad**, Hadi Nobahhari. "Robust Differential Game Reinforcement Learning with Soft Actor-Critic for Guidance in Low-Thrust Multi-Body Environments." *AIAA*, 2024 (Active)
- **Ali BaniAsad**, Alireza Sharifi. "Enhancing AHRS Results with Deep Learning LSTM Networks for Real-Time Attitude Estimation in GNSS-Denied Environments." *Engineering Applications of Artificial Intelligence*, 2024 (Active)

Conference Papers

- Hadi Nobahhari, **Ali BaniAsad**, Alireza Sharifi. "Linear Quadratic Integral Differential Game Applied to the Real-time Control of a Quadrotor Experimental Setup." *ICRoM*, [IEEE](#), 2022.

RESEARCH EXPERIENCE

Researcher at [CNAV Lab](#) [in](#) [🔗](#) [📺](#)

Head of Lab (Current), Researcher (Former)

Supervisors: Hadi Nobahari, PhD and Alireza Sharifi, PhD

May 2020 – Ongoing

Tehran, Iran

- Led projects focusing on the integration of embedded AI using C programming for the development of advanced robotic control systems, enhancing overall system efficiency and performance.
- Designed and implemented reinforcement learning (RL) algorithms to optimize robotic navigation and decision-making processes, significantly improving adaptability in dynamic environments.
- Developed advanced quadrotor technology with AI-driven navigation systems, including INS-AI and AHRS AI, resulting in enhanced precision, safety, and operational reliability during complex missions.
- Collaborated with interdisciplinary teams to integrate Robot Operating System (ROS) frameworks, streamlining development processes and ensuring effective communication across project stakeholders.
- Conducted rigorous testing and validation of AI navigation systems, utilizing real-world simulations to ensure robustness and reliability under various operational conditions.

Robust Reinforcement Learning Guidance [🔗](#)

Master's Thesis in Sharif University of Technology

Supervisors: Hadi Nobahari, PhD

August 2022 – November 2024

Tehran, Iran

- Investigated various reinforcement learning methods, comparing their performance to classic control strategies to identify advantages and limitations.
- Integrated Robot Operating System (ROS) to implement and test real-world robotic systems, validating performance in practical scenarios.
- Utilized differential game theory to develop robust and safe reinforcement learning algorithms, enhancing decision-making and trajectory planning in complex environments.
- Developed safety protocols and mechanisms to ensure reliable operation of robotic systems in uncertain conditions, focusing on minimizing risk during navigation and task execution.
- Conducted simulations to evaluate the robustness of the proposed methods, demonstrating their effectiveness in maintaining safety while optimizing performance under dynamic constraints.

Game Theory-Based Control for a UAV   February 2021 – September 2023
Bachelor's Thesis in Sharif University of Technology Tehran, Iran
 Supervisors: Hadi Nobahari, PhD

- Developed a robust control system for a quadcopter using differential game theory, employing Nash equilibrium to optimize controller performance under uncertainty.
- Evaluated system performance through extensive Simulink simulations, ensuring the theoretical models translated effectively to real-world applications.
- Implemented and tested the control strategy on a three-degree-of-freedom setup, demonstrating the efficacy of the game-theoretic approach in practical scenarios.
- Conducted a series of experiments to assess the quadcopter's stability and responsiveness, refining the control algorithms based on performance feedback.

Optimized Flocking of Autonomous Drones  July 2023
Project in Sharif University of Technology Tehran, Iran
 Supervisors: Hadi Nobahari, PhD

- Developed a UAV swarm model optimizing flocking behavior under real-world constraints, utilizing Embedded C for control algorithms and addressing challenges such as communication delays and environmental obstacles.
- Implemented and validated the model with Simulink simulations and Hardware-in-the-Loop (HIL) testing using a microcontroller, ensuring robustness and reliability in practical applications.
- Employed optimization techniques to enhance swarm performance, focusing on coordination and obstacle avoidance strategies.

Multi-Objective Heuristic Optimization  February 2023
Project in Sharif University of Technology Tehran, Iran
 Supervisors: Hadi Nobahari, PhD

- Implemented the REMARK algorithm for multi-objective optimization with conflicting objectives, allowing for the effective evaluation of trade-offs.

- Utilized heuristic methods to achieve high approximations of the Pareto set, balancing multiple objectives for optimal decision-making.

Advanced Aircraft Trim Stability Analysis with DATCOM

March 2022

Project in Sharif University of Technology

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Developed an advanced user interface (UI) for DATCOM software, streamlining the analysis workflow for aircraft trim stability assessments and enhancing user experience through intuitive design.
- Integrated features such as real-time data visualization and interactive parameter adjustments, allowing for more accurate and efficient evaluations of aircraft performance under various flight conditions.
- Conducted thorough testing and validation of the UI to ensure reliability and precision in output, significantly improving the design process for engineers and researchers.

AIAA Regional Jet Design Competition

June 2021

Project in Sharif University of Technology

Tehran, Iran

Supervisors: Afshin Banazadeh, PhD

- Led the comprehensive design of a regional jet, integrating various engineering disciplines to ensure optimal performance and compliance with industry standards.
- Utilized MATLAB and Python for complex computer modeling, including aerodynamic analysis, structural assessments, and performance simulations.
- Developed a detailed project report and presentation, showcasing design choices and simulation results, which facilitated a successful team presentation at the competition.
- Collaborated with a multidisciplinary team to refine design concepts, ensuring effective communication and integration of ideas throughout the project lifecycle.

TEACHING EXPERIENCE

Teaching Assistant



- **Fundamentals of Programming (C/C++)** September 2018 – December 2018
Department of Computer Engineering, Sharif University of Technology
Instructor: [Ms. Marjan Nikbin](#)
- **Automatic Control** September 2021 – Present
Department of Aerospace Engineering, Sharif University of Technology
Instructors: [Hadi Nobahari](#), PhD and [Alireza Sharifi](#), PhD

- **Control Lab** September 2021 – Present
Department of Aerospace Engineering, Sharif University of Technology
 Instructors: Hadi Nobahari, PhD and Alireza Sharifi, PhD
- **Aircraft Design II** September 2021 – December 2021
Department of Aerospace Engineering, Sharif University of Technology
 Instructors: Afshin Banazadeh PhD
- **Dynamics** September 2021 – December 2023
Department of Aerospace Engineering, Sharif University of Technology
 Instructors: Alireza Sharifi, PhD
- **Introduction to Aerospace Engineering** September 2021 – December 2023
Department of Aerospace Engineering, Sharif University of Technology
 Instructors: Alireza Sharifi, PhD

AWARDS AND HONORS

- Ranked 23** among more than 6,000 participants in the Nationwide University 2017
- Iranian Aerospace Society’s Best Undergraduate Thesis Award** 2022
 Awarded for the exceptional undergraduate thesis titled ”Control of a 3DOF Quadcopter Stand using a Linear-Quadratic-Integral Controller based on Differential Game Theory”.
- Ranked Top 0.5%** 2017
 Ranked Top 0.5% among 150,000 participants of Iran’s Undergraduate University Entrance Exam
- Admittance in the entrance exam of NODET high school.** 2013

TECHNICAL SKILLS

- **Programming Languages**
 - C/C++
 - Embedded C
 - MATLAB
 - Python 🐍
- **Tools and Platforms**
 - Git 
 - ROS
 - Terminal >_
 - Linux 
 - Simulink
 - L^AT_EX
- **Libraries/Frameworks:**
 - Machine Learning Libraries:

- * PyTorch C and Python
- * TensorFlow C and Python
- * Keras
- * Scikit-learn
- * OpenAI Gym
- * JAX
- **Data Analysis and Visualization Libraries:**
 - * Matplotlib
 - * NumPy
 - * Pandas
 - * OpenCV
- **Simulation Tools:**
 - * Gazebo
 - * MuJoCo
- **Robotics Skills**
 - Machine Learning
 - * Deep Learning
 - * Artificial Neural Networks
 - * Recurrent Neural Networks
 - * Embedded Machine Learning
 - * Reinforcement Learning
 - * Heuristic Optimization
 - * Convex Optimization
 - * Image Processing
 - Control Systems
 - * Optimal Control
 - * Automatic Control
 - * Robust Control
 - Game Theory
 - * Differential Game
 - * Multi-Agent Systems
 - * Cooperative Game
 - * Non-Cooperative Game
- **Languages**
 - Farsi (Native)
 - English (Full Professional Proficiency)
The TOEFL iBT score is 96 (Reading: 26, Listening: 27, Speaking: 22, Writing: 21)

NOTABLE COURSES

University Courses

Sharif University of Technology, Tehran, Iran

2017 – 2024

- **Programming and Computational Methods:**

- Basic Programming of C (20)
- Numerical Calculations (20)
- **Mathematics and Statistics:**
 - Engineering Mathematics (19.8)
 - Probability and Statistics (20)
- **Control Systems:**
 - Automatic Control (18.1)
 - Optimal Control (17.5)
 - Control Lab (18.5)
- **Aerospace Engineering:**
 - Aircraft Design II (18.3)
 - Flight Dynamics II (18.3)
- **Research and Projects:**
 - Bachelor Thesis (20)

Online Courses

2017 – 2024

- **Robotics:**
Provided by University of Pennsylvania, Coursera [verify certificate](#)
 - Aerial Robotics
 - Perception
 - Computational Motion Planning
 - Estimation and Learning
 - Mobility
 - Capstone
- **Reinforcement Learning:**
Provided by University of Alberta, Coursera [verify certificate](#)
 - Fundamentals of Reinforcement Learning
 - Sample-based Learning Methods
 - Prediction and Control with Function Approximation
 - A Complete Reinforcement Learning System
- **IBM AI Engineering:**
Provided by IBM, Coursera
 - Machine Learning with Python
 - Introduction to Deep Learning and Neural Networks with Keras
 - Building Deep Learning Models with TensorFlow
 - Introduction to Neural Networks and PyTorch
 - Introduction to Computer Vision and Image Processing
 - AI Capstone Project with Deep Learning
- **Neural Networks and Deep Learning:**
Provided by deeplearning.ai, Coursera [verify certificate](#)

- **Python Data Structures:**

Provided by University of Michigan, Coursera

[verify certificate](#)

- **Introduction to Embedded Machine Learning:**

Provided by Edge Impulse, Coursera

[verify certificate](#)

- **Game Theory:**

Provided by Stanford University, Coursera

[verify certificate](#)

HOBBIES

- Violin 🎻

- Classical Music (e.g., Vivaldi, Vitali) 🎧

- Reading (e.g., The Selfish Gene, Sapiens) 📖

- Coding (including new technologies, check, and funny projects) 💻

- Swimming 🏊

- Traveling ✈️

- Chess ♟️

- Hiking 🏔️

- Photography 📷

- Table Tennis 🏓

REFERENCES

- **Sharifi, Alireza, PhD**

Assistant Professor of Aerospace Engineering, Sharif University of Technology

Dr. Sharifi Supervised my work in the [CNAV Lab](#) for over three years, during which we collaborated on multiple projects. I served as both a researcher and a teaching assistant during this time.

– 🌐 [Faculty Page at Sharif University](#)

– ✉️ ar.sharifi@sharif.edu

– 🎓 [Google Scholar Profile](#)

– ☎️ (+98)-21-6616-8115

- **Nobahari, Hadi, PhD**

Professor of Aerospace Engineering, Sharif University of Technology

I have worked with Dr. Nobahari for over four years, including on both my master's and bachelor's theses.

– 🌐 [Faculty Page at Sharif University](#)

– ✉️ nobahari@sharif.edu

– 🎓 [Google Scholar Profile](#)

– ☎️ (+98)-21-6616-4040

- **Banazadeh, Afshin, PhD**

Professor of Aerospace Engineering, Sharif University of Technology

I have taken several courses with Dr. Banazadeh, achieving excellent results. I developed a fully designed regional jet and created a GUI to facilitate and automate the design process. Additionally, I served as a teaching assistant for the "Airplane Design II" course for one year.

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