

|Size | estimation induction heating home appliances based artificial neural networks recipient

|Estimation | induction heating home appliances based artificial neural networks recipient size

|Induction | heating home appliances based artificial neural networks recipient size estimation

|Heating | home appliances based artificial neural networks recipient size estimation induction

|Home | appliances based artificial neural networks recipient size estimation induction heating

|Appliances | based artificial neural networks recipient size estimation induction heating home

|Based | artificial neural networks recipient size estimation induction heating home appliances

|Artificial | neural networks recipient size estimation induction heating home appliances based

|Neural | networks recipient size estimation induction heating home appliances based artificial

|Networks | recipient size estimation induction heating home appliances based artificial neural

|Recipient | size estimation induction heating home appliances based artificial neural networks

|LumpedCircuit | model switched reluctance motors exhibiting core losses nonlinear

|Model | switched reluctance motors exhibiting core losses nonlinear lumped-circuit

|Switched | reluctance motors exhibiting core losses nonlinear lumpedcircuit model

|Reluctance | motors exhibiting core losses nonlinear lumpedcircuit model switched

|Motors | exhibiting core losses nonlinear lumpedcircuit model switched reluctance

|Exhibiting | core losses nonlinear lumpedcircuit model switched reluctance motors

|Core | losses nonlinear lumpedcircuit model switched reluctance motors exhibiting

|Losses | nonlinear lumpedcircuit model switched reluctance motors exhibiting core

|Nonlinear | lumpedcircuit model switched reluctance motors exhibiting core losses

|Machine | learning induction cooking applications

|Learning | induction cooking applications machine

|Induction | cooking applications machine learning

|Cooking | applications machine learning induction

|Applications | machine learning induction cooking

|Relevant | datasources smart city environment discovery

|DataSources | smart city environment discovery relevant

|Smart | city environment discovery relevant datasources

|City | environment discovery relevant datasources smart

|Environment | discovery relevant datasources smart city

|Discovery | relevant datasources smart city environment

|Search | network rssibased target localization unknown environments associative

|Network | rssibased target localization unknown environments associative search

|RSSIBased | target localization unknown environments associative search network

|Target | localization unknown environments associative search network rssi-based

|Localization | unknown environments associative search network rssibased target

|Unknown | environments associative search network rssibased target localization

|Environments | associative search network rssibased target localization unknown

|Associative | search network rssibased target localization unknown environments

|Intelligence | quality life assessment ambient

|Quality | life assessment ambient intelligence

|Life | assessment ambient intelligence quality

|Assessment | ambient intelligence quality life

|Ambient | intelligence quality life assessment

|Coordinada | de un nuevo grado en ingeniera electronica y automtica implementacin

|De | un nuevo grado en ingeniera electronica y automtica implementacin coordinada

|Un | nuevo grado en ingeniera electronica y automtica implementacin coordinada de

|Nuevo | grado en ingeniera electronica y automtica implementacin coordinada de un

|Grado | en ingeniera electronica y automtica implementacin coordinada de un nuevo

|En | ingeniera electronica y automtica implementacin coordinada de un nuevo grado

|Ingeniera | electronica y automtica implementacin coordinada de un nuevo grado en

|Electronica | y automtica implementacin coordinada de un nuevo grado en ingeniera

|Y | automatica implementacin coordinada de un nuevo grado en ingeniera electronica

|Automatica | implementacin coordinada de un nuevo grado en ingeniera electronica y

|Implementacin | coordinada de un nuevo grado en ingeniera electronica y automatica

|Determination | torquecurrent position characteristics switched reluctance motor high number poles experimental

|Torquecurrent | position characteristics switched reluctance motor high number poles experimental determination

|Position | characteristics switched reluctance motor high number poles experimental determination torquecurrent

|Characteristics | switched reluctance motor high number poles experimental determination torquecurrent position

|Switched | reluctance motor high number poles experimental determination torquecurrent position characteristics

|Reluctance | motor high number poles experimental determination torquecurrent position characteristics switched

|Motor | high number poles experimental determination torquecurrent position characteristics switched reluctance

|High | number poles experimental determination torquecurrent position characteristics switched reluctance motor

|Number | poles experimental determination torquecurrent position characteristics switched reluctance motor high

|Poles | experimental determination torquecurrent position characteristics switched reluctance motor high number

|Experimental | determination torquecurrent position characteristics switched reluctance motor high number poles

|Memoria | del profesor toms polln santamara (19492009) en

|Del | profesor toms polln santamara (19492009) en memoria

|Profesor | toms polln santamara (19492009) en memoria del
 |Toms | polln santamara (19492009) en memoria del profesor
 |Polln | santamara (19492009) en memoria del profesor toms
 |Santamara | (19492009) en memoria del profesor toms polln
 |(19492009) | en memoria del profesor toms polln santamara
 |En | memoria del profesor toms polln santamara (19492009)
 |Trajectory | planner multiple uavs realistic scenarios evolutionary
 |Planner | multiple uavs realistic scenarios evolutionary trajectory
 |Multiple | uavs realistic scenarios evolutionary trajectory planner
 |UAVs | realistic scenarios evolutionary trajectory planner multiple
 |Realistic | scenarios evolutionary trajectory planner multiple uavs
 |Scenarios | evolutionary trajectory planner multiple uavs realistic
 |Evolutionary | trajectory planner multiple uavs realistic scenarios
 |Congreso | de tecnologas aplicadas la enseanza de la electrnic aae 2008 viii
 |De | tecnologas aplicadas la enseanza de la electrnic aae 2008 viii congreso
 |Tecnologas | aplicadas la enseanza de la electrnic aae 2008 viii congreso de
 |Aplicadas | la enseanza de la electrnic aae 2008 viii congreso de tecnolo-
 gas
 |La | enseanza de la electrnic aae 2008 viii congreso de tecnologas aplicadas
 |Enseanza | de la electrnic aae 2008 viii congreso de tecnologas aplicadas la
 |De | la electrnic aae 2008 viii congreso de tecnologas aplicadas la enseanza
 |La | electrnic aae 2008 viii congreso de tecnologas aplicadas la enseanza de
 |Electrnic | aae 2008 viii congreso de tecnologas aplicadas la enseanza de la
 |TAEE | 2008 viii congreso de tecnologas aplicadas la enseanza de la electr-

nica

|2008 | viii congreso de tecnologas aplicadas la enseanza de la electrnica taee

|VIII | congreso de tecnologas aplicadas la enseanza de la electrnica taee 2008

|Intelligence | tools next generation quality service management computational

|Tools | next generation quality service management computational intelligence

|Next | generation quality service management computational intelligence tools

|Generation | quality service management computational intelligence tools next

|Quality | service management computational intelligence tools next generation

|Service | management computational intelligence tools next generation qual-
ity

|Management | computational intelligence tools next generation quality service

|Computational | intelligence tools next generation quality service management

|Life | evaluation elderly disabled people using selforganizing maps quality

|Evaluation | elderly disabled people using selforganizing maps quality life

|Elderly | disabled people using selforganizing maps quality life evaluation

|Disabled | people using selforganizing maps quality life evaluation elderly

|People | using selforganizing maps quality life evaluation elderly disabled

|Using | selforganizing maps quality life evaluation elderly disabled people

|SelfOrganizing | maps quality life evaluation elderly disabled people using

|Maps | quality life evaluation elderly disabled people using selforganizing

|Quality | life evaluation elderly disabled people using selforganizing maps

|Radiotherapy | portal images using wavelets denoising

|Portal | images using wavelets denoising radiotherapy

|Images | using wavelets denoising radiotherapy portal

|Using | wavelets denoising radiotherapy portal images
|Wavelets | denoising radiotherapy portal images using
|Denoising | radiotherapy portal images using wavelets
|Path | planner uavs realistic environments evolutionary
|Planner | uavs realistic environments evolutionary path
|UAVs | realistic environments evolutionary path planner
|Realistic | environments evolutionary path planner uavs
|Environments | evolutionary path planner uavs realistic
|Evolutionary | path planner uavs realistic environments
|Classification | fuzzy growing hierarchical som supervised
|Fuzzy | growing hierarchical som supervised classification
|Growing | hierarchical som supervised classification fuzzy
|Hierarchical | som supervised classification fuzzy growing
|SOM | supervised classification fuzzy growing hierarchical
|Supervised | classification fuzzy growing hierarchical som
|Networks | qos network management neural
|QoS | network management neural networks
|Network | management neural networks qos
|Management | neural networks qos network
|Neural | networks qos network management
|Maps | embedded processor selection selforganizing
|Embedded | processor selection selforganizing maps
|Processor | selection selforganizing maps embedded

|Selection | selforganizing maps embedded processor

|Selforganizing | maps embedded processor selection

|Ships | models seakeeping improvement studies using flaps tfoil fast

|Models | seakeeping improvement studies using flaps tfoil fast ships

|Seakeeping | improvement studies using flaps tfoil fast ships models

|Improvement | studies using flaps tfoil fast ships models seakeeping

|Studies | using flaps tfoil fast ships models seakeeping improvement

|Using | flaps tfoil fast ships models seakeeping improvement studies

|Flaps | tfoil fast ships models seakeeping improvement studies using

|Tfoil | fast ships models seakeeping improvement studies using flaps

|Fast | ships models seakeeping improvement studies using flaps tfoil

|Implementation | voice command recognition system humanmachine interface
embedded systems microcontroller

|Voice | command recognition system humanmachine interface embedded sys-
tems microcontroller implementation

|Command | recognition system humanmachine interface embedded systems mi-
crocontroller implementation voice

|Recognition | system humanmachine interface embedded systems microcon-
troller implementation voice command

|System | humanmachine interface embedded systems microcontroller imple-
mentation voice command recognition

|Humanmachine | interface embedded systems microcontroller implementation
voice command recognition system

|Interface | embedded systems microcontroller implementation voice command
recognition system humanmachine

|Embedded | systems microcontroller implementation voice command recogni-
tion system humanmachine interface

|Systems | microcontroller implementation voice command recognition system
humanmachine interface embedded

|Microcontroller | implementation voice command recognition system human-
machine interface embedded systems

|Sensing | adaptive analog circuits smart

|Adaptive | analog circuits smart sensing

|Analog | circuits smart sensing adaptive

|Circuits | smart sensing adaptive analog

|Smart | sensing adaptive analog circuits

|Optimization | transport oil pipelines networks multiobjective

|Transport | oil pipelines networks multiobjective optimization

|Oil | pipelines networks multiobjective optimization transport

|Pipelines | networks multiobjective optimization transport oil

|Networks | multiobjective optimization transport oil pipelines

|Multiobjective | optimization transport oil pipelines networks

|Nonideal | mixed analogdigital multipliers electronic processing circuits based
neural networks applying

|Mixed | analogdigital multipliers electronic processing circuits based neural
networks applying nonideal

|Analogdigital | multipliers electronic processing circuits based neural networks
applying nonideal mixed

|Multipliers | electronic processing circuits based neural networks applying non-
ideal mixed analogdigital

|Electronic | processing circuits based neural networks applying nonideal mixed
analogdigital multipliers

|Processing | circuits based neural networks applying nonideal mixed analogdig-
ital multipliers electronic

|Circuits | based neural networks applying nonideal mixed analogdigital multipliers electronic processing

|Based | neural networks applying nonideal mixed analogdigital multipliers electronic processing circuits

|Neural | networks applying nonideal mixed analogdigital multipliers electronic processing circuits based

|Networks | applying nonideal mixed analogdigital multipliers electronic processing circuits based neural

|Applying | nonideal mixed analogdigital multipliers electronic processing circuits based neural networks

|Recognition | system human activities automatic

|System | human activities automatic recognition

|Human | activities automatic recognition system

|Activities | automatic recognition system human

|Automatic | recognition system human activities

|Analysis | threephase powerfactor corrector composed three singlephase modules coupling

|Threephase | powerfactor corrector composed three singlephase modules coupling analysis

|Powerfactor | corrector composed three singlephase modules coupling analysis threephase

|Corrector | composed three singlephase modules coupling analysis threephase powerfactor

|Composed | three singlephase modules coupling analysis threephase powerfactor corrector

|Three | singlephase modules coupling analysis threephase powerfactor corrector composed

|Singlephase | modules coupling analysis threephase powerfactor corrector composed three

|Modules | coupling analysis threephase powerfactor corrector composed three singlephase

|Coupling | analysis threephase powerfactor corrector composed three single-phase modules

|Voice | interface using commercially available neural chip manmachine

|Interface | using commercially available neural chip manmachine voice

|Using | commercially available neural chip manmachine voice interface

|Commercially | available neural chip manmachine voice interface using

|Available | neural chip manmachine voice interface using commercially

|Neural | chip manmachine voice interface using commercially available

|Chip | manmachine voice interface using commercially available neural

|ManMachine | voice interface using commercially available neural chip

|Model | based neural networks thermocouple

|Based | neural networks thermocouple model

|Neural | networks thermocouple model based

|Networks | thermocouple model based neural

|Thermocouple | model based neural networks

|Method | sensor linearization based neural networks general

|Sensor | linearization based neural networks general method

|Linearization | based neural networks general method sensor

|Based | neural networks general method sensor linearization

|Neural | networks general method sensor linearization based

|Networks | general method sensor linearization based neural

|General | method sensor linearization based neural networks

|Preservation | sofm euclidean versus manhattan distance comparison topology

|SOFM | euclidean versus manhattan distance comparison topology preservation

|Euclidean | versus manhattan distance comparison topology preservation sofm

|Versus | manhattan distance comparison topology preservation sofm euclidean

|Manhattan | distance comparison topology preservation sofm euclidean versus

|Distance | comparison topology preservation sofm euclidean versus manhattan

|Comparison | topology preservation sofm euclidean versus manhattan distance

|Topology | preservation sofm euclidean versus manhattan distance comparison

|Product | neuron hardware implementation competitive networks dot

|Neuron | hardware implementation competitive networks dot product

|Hardware | implementation competitive networks dot product neuron

|Implementation | competitive networks dot product neuron hardware

|Competitive | networks dot product neuron hardware implementation

|Networks | dot product neuron hardware implementation competitive

|Dot | product neuron hardware implementation competitive networks