人工智能 LAB1 实验报告

一、实验目标

实现 BFS,A*算法,完成吃豆人寻找食物的静态搜索。实现 minimax 算法和 alpha-beta 剪枝,完成吃豆人与对手的动态博弈并减少搜索空间。

二、实验环境和工具

实验环境: Ubuntu 16.04 Python3.6.5

实验工具: PyCharm

三、实验内容和过程

(1) BFS

考虑到 BFS 即广度优先搜索,区别于 DFS 深度优先搜索,BFS 需要维护一个存储形式,使得状态先于子状态被遍历,容易想到是一个队列,故只需要把 DFS 的栈 Stack 改为队列 Queue 即可。代码如下:

```
def myBreadthFirstSearch(problem):
   visited = {}
   frontier = util.Queue()
   frontier.push((problem.getStartState(), None))
   while not frontier.isEmpty():
       state, prev_state = frontier.pop()
       if problem.isGoalState(state):
          solution = [state]
          while prev_state != None:
              solution.append(prev_state)
              prev_state = visited[prev_state]
          return solution[::-1]
       if state not in visited:
          visited[state] = prev_state
          for next_state, step_cost in problem.getChildren(state):
              frontier.push((next_state, state))
   return []
```

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(2) A*

A*算法需要依照最小的启发值选择搜索子状态,是一种高级的广度优先搜索,容易想到用优先队列存储状态空间,按照启发值选择搜索状态。代码如下: (其中 f_state 是开始状态到当前状态的实际值)

```
def myAStarSearch(problem, heuristic):
   visited = {}
   frontier = util.PriorityQueue()
   frontier.push((problem.getStartState(), None, 0),
heuristic(problem.getStartState()))
   while not frontier.isEmpty():
       state, prev_state, f_state = frontier.pop()
       if problem.isGoalState(state):
          solution = [state]
          while prev_state != None:
              solution.append(prev_state)
              prev_state = visited[prev_state]
          return solution[::-1]
       if state not in visited:
           visited[state] = prev_state
           for next_state, step_cost in problem.getChildren(state):
              frontier.push((next_state, state, f_state+step_cost),
f_state+step_cost+heuristic(next_state))
   return []
```

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(3) Minimax

考虑预估步数为 depth,写一个递归函数 minimax(state,depth),每次从对手转移执行权到吃豆人时,把 depth-1 送入下次递归,如果是吃豆人执行操作,就求相对于吃豆人的状态最大值,反之求相对于吃豆人的状态最小值,把对应状态作为本次操作的子状态。代码如下:

```
def minimax(self, state, depth):
    if state.isTerminated() or depth == 0:
        return None, state.evaluateScore()

    best_state, best_score = None, -float('inf') if state.isMe() else float('inf')

    for child in state.getChildren():
        if child.isMe():
            _, score = self.minimax(child, depth - 1)
        else:
            _, score = self.minimax(child, depth)

    if state.isMe() and score > best_score:
        best_score = score
        best_state = child
    elif not state.isMe() and score < best_score:
        best_score = score
        best_score = score
        best_state = child

return best_state, best_score</pre>
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(4) minimax 的 alpha-beta 剪枝

在 minimax 算法上做剪枝,记录对手执行不同操作时的最大状态值 alpha,如果在某次轮到吃豆人执行造作时,不管执行何种操作,获得状态值永远小于 alpha,那么这个状态下的搜索子空间的状态值不可能比 alpha 大,对最终结果没有影响,故可以剪枝。beta 同理,代码如下:

```
def alphabeta(self, state, depth, alpha, beta):
    if state.isTerminated() or depth == 0:
        return None, state.evaluateScore()

    best_state, best_score = None, -float('inf') if state.isMe() else float('inf')

    for child in state.getChildren():

        if child.isMe():
            _, score = self.alphabeta(child, depth - 1, alpha, beta)
        else:
            _, score = self.alphabeta(child, depth, alpha, beta)

    if state.isMe():
        if score > beta:
            return child, score
        if score > alpha:
            alpha = score
        if score > best_score:
```

```
best_score = score
    best_state = child

else:
    if score < alpha:
        return child, score
    if score < beta:
        beta = score
    if score < best_score:
        best_score = score
        best_state = child

return best_state, best_score

def getNextState(self, state):
    best_state, _ = self.alphabeta(state, self.depth, -float('inf'), float('inf'))
    return best_state</pre>
```

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