Hands-on tutorial on Linear Programming and Integer Linear Programming modeling

Introduction to AMPL and GMPL

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Overview

AMPL

Introduction to AMPL Example

GMPL/GLPK
Introduction to GMPL/GLPK
Example

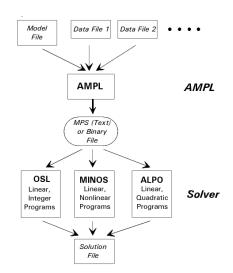
Conclusion and References

Introduction to



- Algebraic Modeling Programming Language AMPL assists in formulating the optimization problem at interest within a mathematical formalism. It allows to:
 - use computers to design, experiment, refine and apply mathematical programming models without coding;
 - solve instances without designing algorithms nor crack hard mathematical problems.
- AMPL purpose: translating an optimization problem into a different form understandable by a generic solver.

The strategic place of AMPL

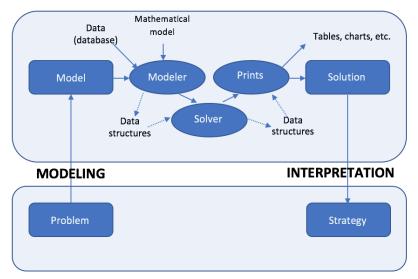


What is a solver?

- Software that finds a solution to a mathematical problem that receives as input.
- Together with the solution, it returns also some information related to the mathematical model that describes the problem.
- Solvers can be useful to optimize different class of mathematical programming problems:
 - Linear Programming problems (LP);
 - Mixed-Integer Linear Programming (MILP);
 - Mixed-Integer Quadratic Programming (MIQP);
 - Constraint Programming (CP);
 - Quadratic Programming (QP);
 - Quadratically Constrained Programming (QCP);
 - Mixed-Integer Quadratically Constrained Programming (MIQCP);
 - Nonlinear Programming (NLP).



From the problem to the strategy



Advantages of AMPL

- AMPL was designed and implemented in 1985 by Robert Fourer, David M. Gay and Brian Kernighan.
- Modeling languages can help to make mathematical programming more economical and reliable.
- **Familiarity** with algebraic modeling languages (based on the use of traditional mathematic notation).
- Application to several class of problems.
- Support to different solvers.
- Naturalness of its syntax and generality of its set and indexing expressions.

Example - The Diet Problem

A diet prescribes that, to respect minimum daily necessities, specific amounts of *calories*, *proteins* and *calcium* have to be introduced in the body. This diet is composed of five basic foods (*bread*, *milk*, *eggs*, *meat*, *sweets*), while basic amounts are 2000 calories, 50 g. of proteins and 700 mg of calcium.

The following values are derived from dietetic tables, indicating how many calories (in cal.) proteins (in g.), calcium (in mg.) every portion of each food provides:

	Bread	Milk	Eggs	Meat	Sweets
Calories	150	120	160	230	450
Proteins	4	8	15	14	4
Calcium	2	285	54	80	22

Instead the following tables represents the costs and the maximum daily number of portions, for each item of every food:

	Bread	Milk	Eggs	Meat	Sweets
Cost	3	2	3	19	15
Max portions	4	7	2	3	2

Determine a minimum cost diet that satisfy every prescription.

Formulation

Let's start assigning a variable to every portion of each food:
 X1, X2, X3, X4, X5

• The objective function corresponds to the sum of the costs of every food: $min 3x_1 + 2x_2 + 3x_3 + 19x_4 + 15x_5$

Daily minimum necessities:

• Calories: $150x_1 + 120x_2 + 160x_3 + 230x_4 + 450x_5 \ge 2000$

• Proteins: $4x_1 + 8x_2 + 15x_3 + 14x_4 + 4x_5 \ge 50$

• Calcium: $2x_1 + 285x_2 + 54x_3 + 80x_4 + 22x_5 \ge 700$

Maximum number of portions:

• Bread: $0 \le x_1 \le 4$

• Milk: $0 \le x_2 \le 7$

• Eggs: $0 \le x_3 \le 2$

• Meat: $0 \le x_4 \le 3$

• Sweets: $0 \le x_5 \le 2$

What you must know to start

- Every AMPL project is composed of at least two files:
 - the model, where you describe the problem; the extension of this file is .mod.
 - the data, where you specify the problem instance, i.e. the values to be used for parameters, sets and variables defined in the model; the extension of this file is .dat.
- Note: it is a smart move to keep always separated the model and the data: doing so, the model can be use again on several instances of data, without even modify a character!
- The AMPL process can be represented in six simple steps:
 - 1. Launch AMPL
 - 2. Load the model (.mod)
 - 3. Load the data (.dat)
 - 4. Specify the solver to use
 - 5. Solve the model
 - 6. Display solution and results



Something to know about AMPL syntax

- AMPL is case-sensitive
- Every instruction ends with;
- Before every definition, there must be a declaration
- The length of a row is maximum 255 characters (other characters will be simply ignored)
- Main keywords used: set, param, var, minimize/maximize, subject to / s.t.

The model file: diet.mod

```
diet.mod ~
# SETS DEFINITION
set M; # set of substances
set N: # set of foods
# PARAMETERS DEFINITION
param amount portion (M.N): # amounts of substances for every portion of each food
param cost{N}; # cost of every portion of each food
param max portions{N}: # maximum daily number of portions for each food
param minimum_amount{M}; # minimum amounts of substances to reach daily
# VARIABLES DEFINITION
var x\{N\}>=0; # number of portions for each food
# OBJECTIVE FUNCTION
minimize total cost: sum{i in N} cost[i] * x[i]:
# CONSTRAINTS DEFINITION
subject to daily_necessities{i in M}: sum{j in N} amount_portion[i,j] * x[j] >= minimum_amount[i];
subject to max_number{i in N}: x[i] <= max_portions[i];</pre>
```

- As you can see, there are no numbers specified in this file: this will let you keep separated the model from several instances of the problem

 Flexibility and modularity: to solve a new instance of the problem, you will not have to re-define the model everytime; only the data file will change.
- Declaration in the .mod file, definition in the .dat file



AMPL

Sets

```
# SETS DEFINITION
set M; # set of substances
set N; # set of foods
```

- Sets define the domain of the problem
- A set is a group of elements that are instances of the same kind of entity; it can be:
 - unordered: set a:
 - numerical: set a := 1 .. 10 **by** 2;
 - ordered: set a ordered:
 - circular: set a circular;
- Operations on sets: union, diff, inter, symdiff, card, within
- If a set A is ordered, there are also these ones: first(A), last(A), next(i,A,j), prev(i,A,j), next(i,A), prev(i,A), ord0(i,A), member(i,A)
- You can use the keyword cross if it is the cartesian product of other two sets: set a := X cross Y: 4 D > 4 P > 4 E > 4 E > 9 Q P

Parameters

PARAMETERS DEFINITION
param amount_portion(M,N); # amounts of substances for every portion of each food
param cost(N); # cost of every portion of each food
param max_portions(N); # maximum daily number of portions for each food
param minimum_amount(M); # minimum amounts of substances to reach daily

- Parameters are problem values
- A parameter can be:
 - a single scalar: param b;
 - a collection of values indexed by a set: param a {j in P};
 - param cost{N} indicates that there is a cost value associated to each item of the set N
- Every information given in the problem represents a parameter.
- Parameters and other numerical values are the building blocks of expressions that make up a model's objective and constraints.



Variables

VARIABLES DEFINITION
var x{N}>=0; # number of portions for each food

- Variables are quantities that describe the problem solution and they are determined by the solver
- Syntactically, their declarations are the same as parameters and they can be:
 - simple: var x;
 - a collection of unknown quantities indexed by a set: $var x\{N\}$;
 - $var x\{N\} \ge 0$ indicates that there is a variable for every item of the set N and each one must be nonnegative

The objective function and the constraints

```
# OBJECTIVE FUNCTION
minimize total_cost: sum{i in N} cost[i] * x[i];
```

- The function to be optimized
- According to the requirements, the goal may be to minimize or maximize a certain value

```
# CONSTRAINTS DEFINITION|
subject to daily_necessities{i in M}: sum{j in N} amount_portion[i,j] * x[j] >= minimum_amount[i];
subject to max_number{i in N}: x[i] <= max_portions[i];</pre>
```

- The objective function is followed by the list of constraints to satisfy during the resolution of the problem
- Constraints are introduced by the keywords subject to
- Also the objective function and constraints must have names.



The data file

```
diet.dat ~
# SETS POPULATION
set M := CALORIES PROTEINS CALCIUM;
set N := BREAD MILK EGGS MEAT SWEETS;
# PARAMETERS POPULATION
param amount portion : BREAD MILK EGGS MEAT SWEETS :=
CALORIES 150 120 160 230 450
PROTEINS 4 8 15 14 4
CALCIUM 2 285 54 80 22;
param cost :=
BREAD 3
MILK 2
EGGS 3
MEAT 19
SWEETS 15;
param max_portions :=
BREAD 4
MILK 7
EGGS 2
MEAT 3
SWEETS 2;
param minimum amount :=
CALORIES 2000
PROTEINS 50
CALCIUM 700:
```

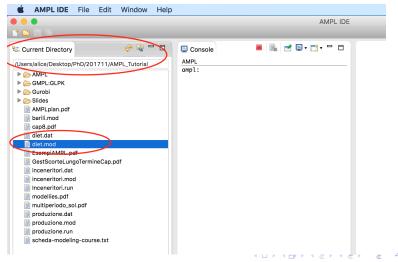
Definition of sets and parameters

The symbol used for definition is :=

```
diet.dat ~
 SETS POPULATION
set M := CALORIES PROTEINS CALCIUM;
set N := BREAD MILK EGGS MEAT SWEETS:
# PARAMETERS POPULATION
param amount_portion : BREAD MILK EGGS MEAT SWEETS :=
CALORIES 150 120 160 230 450
PROTEINS 4 8 15 14 4
CALCIUM 2 285 54 80 22;
param cost :=
                                     param amount portion{M,N}
BREAD 3
MILK 2
               param cost{N}
EGGS 3
MEAT 19
SWEETS 15:
param max_portions :=
BREAD 4
MILK 7
                      param max_portions{N}
EGGS 2
MFAT 3
SWEETS 2:
param minimum_amount :=
CALORIES 2000
PROTEINS 50
                        param minimum amount{M}
CALCIUM 700:
```

How to solve the problem

1. Launch the AMPL IDE and go to the directory where you have the files:



- 2. Load the model: **model diet.mod**;
- 3. Load the data: data diet.dat;
- 4. Choose the solver: option solver cplex;
- 5. Solve the problem: solve;
- 6. Look at the results: display x;

```
Console

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ΔΜΡΙ
ampl: model diet.mod;
ampl: data diet.dat;
ampl: option solver cplex:
ampl: solve:
CPLEX 12.7.1.0: optimal solution; objective 40
1 dual simplex iterations (0 in phase I)
ampl: display x;
x [*] :=
 BREAD 4
  EGGS 2
  MEAT 0
  MTIK 7
SWEETS 0.533333
ampl: display total_cost;
total\_cost = 40
```

The optimal solution is given by 4 portions of bread, 2 of eggs, 0 of meat, 7 of milk and 0.533 of sweets; the objective function is equal to 40.

AMPL-Gurobi

- Another way: solving the problem using AMPL and calling Gurobi as solver.
- We can use again the .mod and .dat files because they do not need edits.
- The only thing to be changed is the solver and its options:
 - option solver gurobi;
 - option gurobi_options 'presolve 2'; to tell Gurobi to be "aggressive" (default value -1; 0 disabled; 1 "conservative").
 - option gurobi_options \$gurobi_options 'mipgap 0.01'; to set the MIP gap (the solver will terminate when the gap between the lower and upper objective bound is less than MIPGap times the absolute value of the upper bound).

Here is the code:

```
Console
AMPL
ampl: model diet.mod;
ampl: data diet.dat:
ampl: option solver aurobi:
ampl: option aurobi_options 'presolve 2':
ampl: option gurobi_options $gurobi_options 'mipgap 0.01';
ampl: solve;
Gurobi 7.5.0: presolve 2
mipgap 0.01
Gurobi 7.5.0: optimal solution; objective 40
1 simplex iterations
ampl: display x:
x [*] :=
 BREAD 4
  EGGS 2
  MEAT 0
  MILK 7
SWEETS 0.533333
ampl: display total_cost;
total\_cost = 40
```

Introduction to GLPK



- GLPK (i.e., GNU Linear Programming Kit) is a software package developed in ANSI C by Andrew Makhorin (Department for Applied Informatics, Moscow Aviation Institute) for solving large-scale LP and MIP problems.
- Part of the GNU Project, actually it is a library.
- The package contains several components:
 - For LP problems: revised simplex method and primal-dual interior point method;
 - For IP problems: Branch-and-bound method and cut routines;
 - Others: translator for GNU MathProg modeling language;
 API; stand-alone LP/MIP solver glpsol



glpsol and GMPL

- Since GLPK is a library, it needs a client software where can be run exploiting GLPK APIs → The default client is the glpsol solver (GNU Linear Program Solver).
- glpsol can take GMPL model and data as inputs and it finds a solution as output.
- GMPL (i.e., GNU Math Programming Language) is a modeling language intended for describing linear mathematical programming models:
 - Like in AMPL, the model is described through model objects such as sets, parameters, variables, constraints and objectives;
 - The model description is composed of two parts:
 - the model section
 - the data section
 - GMPL syntax is basically the same as AMPL.



The Diet Problem with GMPL and glpsol

 You can use just one .mod file containing both model and data section, divided by the keyword data; or you can divide, as before, model and instance in two separate files, as you like.

```
diet-ampl.mod ~
V* THE DIET PROBLEM */
set M:
/* substances */
set N:
/* foods */
param minimum amount{M}:
/* minimum amounts of substances to reach daily */
param amount portion{M,N};
/* amounts of substances for every portion of each food */
param cost{N}:
/* cost of every portion of each food */
param max portions{N}:
/* maximum daily number of portions for each food */
var x{n in N} >= 0;
/* number of portions for each food */
s.t. daily_necessities{i in M}: sum{j in N} amount_portion[i,j] * x[j] >= minimum_amount[i];
s.t. max number{i in N}: x[i] <= max portions[i];</pre>
/* constraints */
minimize total cost: sum{i in N} cost[i] * x[i]:
/* total cost (euro) */
```

The last instruction is end;



How to solve the problem with glpsol

- Open a new terminal window, go to the folder where you have your diet-gmpl.mod file
- 2. Type **glpsol -model diet-gmpl.mod -output diet-gmpl.sol** to solve the problem and write the results on a .sol file

```
AMPL_Tutorial — -bash — 99×31
Last login: Fri Nov 10 17:52:31 on ttys000
MBP-di-Alice:~ alice$ cd Desktop/PhD/201711/AMPL_Tutorial/
MBP-di-Alice: AMPL_Tutorial alice$ glpsol --model diet-gmpl.mod --output diet-gmpl.sol
GLPSOL: GLPK LP/MIP Solver, v4.63
Parameter(s) specified in the command line:
--model diet-gmpl.mod --output diet-gmpl.sol
Reading model section from diet-gmpl.mod...
Reading data section from diet-gmpl.mod...
59 lines were read
Generating daily necessities...
Generating max number...
Generating total cost...
Model has been successfully generated
GLPK Simplex Optimizer, v4.63
9 rows, 5 columns, 25 non-zeros
Preprocessing...
3 rows, 5 columns, 15 non-zeros
A: min|aij| = 2.000e+00 max|aij| = 4.500e+02 ratio = 2.250e+02
GM: min[aij] = 2.737e-01 max[aij] = 3.653e+00 ratio = 1.335e+01
EQ: min|aij| = 7.493e-02 max|aij| = 1.000e+00 ratio = 1.335e+01
Constructing initial basis...
Size of triangular part is 3
      0: obi = 0.000000000e+00 inf =
                                        4.355e+02 (3)
      5: obi = 8.967677733e+01 inf = 0.000e+00 (0)
      9: obi = 4.000000000e+01 inf = 0.000e+00 (0)
OPTIMAL LP SOLUTION FOUND
Time used: 0.0 secs
Memory used: 0.1 Mb (126378 bytes)
Writing basic solution to 'diet-gmpl.sol'...
MBP-di-Alice: AMPL_Tutorial alice$
```

The output file

• Obviously, as before, the optimal solution found is 40.

•	•			die	et-gmpl.s	sol ~			
Proble Rows: Column Non-ze Status Object	9 s: 5 ros: 25 : OPTIMAL		- 40 (MINimum)						
No.	Row name	St	Activity	Lower	bound	Upper bo	und	Marginal	
	daily_necess	NL	2000		2000			0.0333333	
2	daily_necess	ities B	[PROTEINS] 104.133		50				
3	daily_necess	ities			700				
4	max_number[E	READ]			700				
	max_number[M	NU	4				4	-2	
,	max_number [i	NU	7				7	-2	
6	max_number[E		2				2	2 22222	
7	max_number[N	NU IEAT1	2				2	-2.33333	
	_	В	. 0				3		
8	max_number[S	WEETS B	0.533333				2		
9	total_cost	В	40				2		
No.	Column name	St	Activity	Lower	bound	Upper bo	und	Marginal	
1	x[BREAD]	В	4		0				
	x[MILK]	В	7		0				
	x[EGGS]	В	2		0				
	x[MEAT]	NL	0		0			11.3333	
5	x [SWEETS]	В	0.533333		0				

Conclusion

- We talked about some possible ways of solving problems exploiting solvers and mathematical programming languages.
- We learned the basics of AMPL and GMPL through an example.
- And now, what's next? More problems to solve!

References



AMPL

http://ampl.com



AMPL: A Modeling Language for Mathematical Programming R. Fourer, D.M. Gay, B. Kernighan http://ampl.com/resources/the-ampl-book/



Short guide about AMPL for Operations Research classes (Italian) M. Bruglieri, R. Cordone, L. Liberti, http://profs.sci.univr.it/~rrizzi/classes/modeling-intro/AMPL/manualeampl.pdf



Operations Research - AMPL (Italian)
D. Macaluso, M. Pennacchi, G. Stangoni
https://www.slideshare.net/macdario/ricerca-operativa-ampl



Slides about AMPL (Italian) F. Rinaldi

http://www.math.unipd.it/~rinaldi/teaching/IntroM.pdf and http://www.math.unipd.it/~rinaldi/teaching/Sintassi_Esempi.pdf





GLPK

https://en.wikibooks.org/wiki/GLPK



GLPK/GMPL

https://en.wikibooks.org/wiki/GLPK/GMPL_(MathProg)



Modeling Language GNU MathProg

A. Makhorin

https://www.cs.unb.ca/~bremner/docs/glpk/gmpl.pdf



Operations Research with GNU Linear Programming Kit

T. Sottinen

http://lipas.uwasa.fi/~tsottine/lecture_notes/or.pdf



The GNU Linear Programming Kit (GLPK): Resources, Tutorials etc.

S. Pokutta

https://spokutta.wordpress.com/the-gnu-linear-programming-kit-glpk/



To exercise online with AMPL:

http://ampl.com/cgi-bin/ampl/amplcgi



To exercise online with several solvers and languages:

https://neos-server.org/neos/solvers/

