Guide of Tool Chain Installation and Use

ver 1.0.0

Release History

ver 1.0.0	2019/03/16	First version content

1 ARM CROSS COMPILE TOOL CHAIN INSTALLATION

This SDK provides the arm-hisiv300-linux cross compile toolchain. The installation steps are as follows:

1.1 Tool Chain Decompression

The arm cross compile toolchain and its installer are located in directory ***tools/arm_toolchain***, enter this directory and decompress it. The commands are as follows:

cd tools/arm_toolchain/

tar –xvf arm-hisi300-linux.tar.bz2

1.2 Tool Chain Installation

Enter the folder ***arm-hisi300-linux/*** after it's decompression and use the script to install the toolchain. The commands are as follows:

chmod +x cross.v300.install

sudo ./ cross.v300.install

1.3 Environment Variables Settings

If your computer is 64-bit, you need to install 32-bit compiler compatibility packages:

sudo aptitude install lib32z1

sudo aptitude install lib32stdc++6-4.8-dbg

Import the path of the tool chain into environment variable, the path can be viewed as follows:

cd /opt/hisi-linux/x86-arm/arm-hisiv300-linux/target/bin

pwd

Add the following statement at the end of the file ***bashrc***:

vi ~/.bashrc

export PATH=/opt/hisi-linux/x86-arm/arm-hisiv300-linux/target/bin:$PATH

Ensure that environmental variable settings take effect:

source ~/.bashrc

1.4 Tool Chain Installation Test

Execute the following commands to view the version of the toolchain:

arm-hisiv300-linux-gcc –v

If "***gcc version 4.8.3 20131202 (prerelease) (Hisilicon_v300)***" appears at the tail of the version description, the toolchain installation is successful.

2 MODEL CONVERSION TOOL INSTALLATION

2.1 Tool Chain Decompression

The model conversion tool and its installer are located in directory ***tools/mv_toolchain***, enter this directory and decompress it. The commands are as follows:

cd tools/mv_toolchain/

tar –xvf model_conversion.tar.gz

2.2 Configuration File Description

Enter the folder after decompression and the development environment requirements document is as follows:

—— ***install-ncsdk.sh***

#script to install all packeges and libs on your system, including caffe-ssd cpu version and tensorflow.

—— ***uninstall-ncsdk.sh*** # Uninstall

—— ***ncsdk.conf*** # ncsdk config file.

—— ***requirments.txt*** # python3 dependencies.

—— ***requirments_apt.txt*** # ubuntu system dependencies.

2.3 Tool chain Installation

Use the script to install the toolchain. The commands are as follows:

sudo ./ install-ncsdk.sh

The installation log will be written into ***setup-logs***.

2.4 Tool Chain Installation Test

Execute the following commands to view the version of the toolchain:

mvNCCompile -v

If "***mvNCCompile v02.00, Copyright @ Movidius Ltd 2016***" appears at the head of the version description, the toolchain installation is successful. Use "***-h***" command to see the help message:

mvNCCompile –h

3 INSTRUCTIONS FOR THE USE OF TOOL CHAINS

3.1 Arm Compile Steps

Developers need to use arm cross-compiler tool chain to compile their own projects, generate executable files and run it on the embedded board. In this SDK sample program, ***Makefile*** shows how to use arm cross compiler to generate executable files.

For example, enter folder ***examples/detect/***, use "***make***" to compile and link, you will see the compile steps like follows:

" arm-hisiv300-linux-g++ -c xxx.c –o xxx.o

arm-hisiv300-linux-g++ -o xxx xxx.o –lpthread ../../libs/SIM_CAM_lib.a "

xxx.c is user-developed programs, ***xxx.o*** is object-file, ***xxx*** is the final executable file.

3.2 Model Conversion steps

Developers need to use ***mvNCCompile*** tool chain to generate a model file which can be read and run on Movidius. This model file could be named as ***"graph"*** and it contains the structure and weight information of the neural network model trained by developers.

The often-used usage and parameters of ***mvNCCompile*** are as follows:

-h	# Show help
-w WEIGHTS	# Model weight (Caffe only), *.caffemodel*
-in INPUTNODE	# Name of input node, default: Caffe: *data*, TF: *input*
-on OUTPUTNODE	# Name of output node, default: Caffe: Last layer, TF:
-o OUTFILE	# Output path of SimCam graph
-s NSHAVES	# Number of Movidius Shave, recommend 6, default 1

For example, enter folder ***examples/convert/***, use script ***compile.sh*** to compile, you will see the compile steps like follows:

“ mvNCCompile xxx.prototxt -w yyy.caffemodel -o graph -s 6 ”

xxx.prototxt is the structure file of network, ***yyy.caffemodel*** is the weight file of network.

Document ***“Train_Model.pdf”*** describes how to modify and generate these two files.

Document ***“SIMCAM_API.pdf”*** describes how to read and run ***graph*** on borad.

In folder ***examples/models/,*** we provide other models for different recognition. ***Labelmap.prototxt*** describes the classifications of the model.