image_classification

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Project created during the Deep Learning Specialization course on www.coursera.org

1 Classification of hand gestures with resNet

```
[1]: import numpy as np
  import h5py
```

1.1 Data preparation

```
[2]: # Load the dataset
     def load_dataset():
         train_dataset = h5py.File('./data/train_signs.h5', "r")
         train_set_x_orig = np.array(train_dataset["train_set_x"][:])
         train_set_y_orig = np.array(train_dataset["train_set_y"][:])
         test_dataset = h5py.File('./data/test_signs.h5', "r")
         test_set_x_orig = np.array(test_dataset["test_set_x"][:])
         test_set_y_orig = np.array(test_dataset["test_set_y"][:])
         classes = np.array(test_dataset["list_classes"][:])
         train_set_y_orig = train_set_y_orig.reshape((1, train_set_y_orig.shape[0]))
         test_set_y_orig = test_set_y_orig.reshape((1, test_set_y_orig.shape[0]))
         return train_set_x_orig, train_set_y_orig, test_set_x_orig, test_set_y_orig,_u
[3]: X_train_orig, Y_train_orig, X_test_orig, Y_test_orig, classes = load_dataset()
      # Normalize data
     X_train = X_train_orig/255.
     X_{\text{test}} = X_{\text{test_orig}}/255.
      # Convert training and test labels to one-hot encoded matrices
     Y_train = np.eye(6)[Y_train_orig.reshape(-1)]
```

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Y_test = np.eye(6)[Y_test_orig.reshape(-1)]
```

1.2 Model architecture

```
[4]: from keras import layers
     from keras.layers import Input, Add, Dense, Activation, ZeroPadding2D, u
      →BatchNormalization, Flatten, Conv2D, AveragePooling2D, MaxPooling2D
     from keras.models import Model, load_model
     from keras.preprocessing import image
     from keras.initializers import glorot_uniform
     Using TensorFlow backend.
[5]: # Create ResNet identity block
     def identity_block(X, f, filters, stage, block):
          # Defining name basis
         conv_name_base = 'res' + str(stage) + block + '_branch'
         bn_name_base = 'bn' + str(stage) + block + '_branch'
          # Retrieve filters size
         F1, F2, F3 = filters
         # Build identity block
         X_shortcut = X
         X = Conv2D(filters = F1, kernel\_size = (1, 1), strides = (1, 1), padding = (1, 1)
       →'valid', name = conv_name_base + '2a', kernel_initializer =
      →glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis = 3, name = bn_name_base + '2a')(X)
         X = Activation('relu')(X)
         X = Conv2D(filters=F2, kernel_size=(f, f), strides=(1, 1), padding='same',_
       →name=conv_name_base + '2b', kernel_initializer=glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis=3, name=bn_name_base + '2b')(X)
         X = Activation('relu')(X)
         X = Conv2D(filters=F3, kernel_size=(1,1), strides=(1,1), padding='valid',__
       →name=conv_name_base + '2c', kernel_initializer=glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis=3, name=bn_name_base + '2c')(X)
         X = Add()([X, X_shortcut])
         X = Activation('relu')(X)
         return X
```

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[6]: # Create ResNet convolutional block
     def convolutional_block(X, f, filters, stage, block, s = 2):
         # Define name basis
         conv_name_base = 'res' + str(stage) + block + '_branch'
         bn_name_base = 'bn' + str(stage) + block + '_branch'
         # Retrieve filters size
         F1, F2, F3 = filters
         # Build convolutional block
         X_{shortcut} = X
         X = Conv2D(F1, (1, 1), strides = (s,s), padding='valid', name = (s,s)
      →conv_name_base + '2a', kernel_initializer = glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis = 3, name = bn_name_base + '2a')(X)
         X = Activation('relu')(X)
         X = Conv2D(F2, (f, f), strides=(1,1), padding='same', name=conv_name_base +
      →'2b', kernel_initializer=glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis=3, name=bn_name_base + '2b')(X)
         X = Activation('relu')(X)
         X = Conv2D(F3, (1,1), strides=(1,1), padding='valid', name=conv_name_base +
      →'2c', kernel_initializer=glorot_uniform(seed=0))(X)
         X = BatchNormalization(axis=3, name=bn_name_base + '2c')(X)
         X_shortcut = Conv2D(F3, (1,1), strides=(s,s), padding='valid',_
      →name=conv_name_base + '1',
      →kernel_initializer=glorot_uniform(seed=0))(X_shortcut)
         X_shortcut = BatchNormalization(axis=3, name=bn_name_base +'1')(X_shortcut)
         X = Add()([X_shortcut, X])
         X = Activation('relu')(X)
         return X
[7]: # Build ResNet model
     def ResNet50(input_shape = (64, 64, 3), classes = 6):
         X_input = Input(input_shape)
          X = ZeroPadding2D((3, 3))(X_input)
```

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⇒= glorot_uniform(seed=0))(X)
        X = BatchNormalization(axis = 3, name = 'bn_conv1')(X)
        X = Activation('relu')(X)
        X = MaxPooling2D((3, 3), strides=(2, 2))(X)
        X = convolutional\_block(X, f = 3, filters = [64, 64, 256], stage = 2, 
     \rightarrowblock='a', s = 1)
        X = identity_block(X, 3, [64, 64, 256], stage=2, block='b')
        X = identity_block(X, 3, [64, 64, 256], stage=2, block='c')
        X = convolutional_block(X, f=3, filters=[128, 128, 512], stage=3, block='a', |
     \hookrightarrows=2)
        X = identity_block(X, f=3, filters=[128, 128, 512], stage=3, block='b')
        X = identity_block(X, f=3, filters=[128, 128, 512], stage=3, block='c')
        X = identity_block(X, f=3, filters=[128, 128, 512], stage=3, block='d')
        X = convolutional_block(X, f=3, filters=[256, 256, 1024], stage=4, block='a')
        X = identity_block(X, f=3, filters=[256, 256, 1024], stage=4, block='b')
        X = identity_block(X, f=3, filters=[256, 256, 1024], stage=4, block='c')
        X = identity_block(X, f=3, filters=[256, 256, 1024], stage=4, block='d')
        X = identity_block(X, f=3, filters=[256, 256, 1024], stage=4, block='e')
        X = identity_block(X, f=3, filters=[256, 256, 1024], stage=4, block='f')
        X = convolutional_block(X, f=3, filters=[512, 512, 2048], stage=5, block='a')
        X = identity_block(X, f=3, filters=[512, 512, 2048], stage=5, block='b')
        X = identity_block(X, f=3, filters=[512, 512, 2048], stage=5, block='c')
        X = AveragePooling2D(pool_size=(2,2), name='avg_pool')(X)
        X = Flatten()(X)
        X = Dense(classes, activation='softmax', name='fc' + str(classes),
     →kernel_initializer = glorot_uniform(seed=0))(X)
        model = Model(inputs = X_input, outputs = X, name='ResNet50')
        return model
[8]: model = ResNet50(input_shape = (64, 64, 3), classes = 6)
     1.3 Training and testing
[9]: # Compile the model
     model.compile(optimizer='adam', loss='categorical_crossentropy',_
      →metrics=['accuracy'])
```

 $X = Conv2D(64, (7, 7), strides = (2, 2), name = 'conv1', kernel_initializer_{local}$

```
[10]: # Train the model
     model.fit(X_train, Y_train, epochs = 2, batch_size = 32)
     Epoch 1/2
     1080/1080 [============ ] - 71s 66ms/step - loss: 1.7110 -
     accuracy: 0.4750
     Epoch 2/2
     accuracy: 0.7972
[10]: <keras.callbacks.dallbacks.History at 0x654621be0>
 [11]: # Evaluate the model on the test set
      preds = model.evaluate(X_test, Y_test)
      print ("Loss = " + str(preds[0]))
      print ("Test Accuracy = " + str(preds[1]))
       120/120 [========= ] - 2s 16ms/step
      Loss = 3.9948134740193684
      Test Accuracy = 0.1666666716337204
      1.4 Testing on pretrained model
  [12]: # Load pretrained model (found here: https://github.com/kotestyle/
        \rightarrow deep-learning-coursera)
       model = load_model('./models/ResNet50.h5')
       /Applications/anaconda3/lib/python3.6/site-packages/keras/engine/saving.py:384:
       UserWarning: Error in loading the saved optimizer state. As a result, your model
       is starting with a freshly initialized optimizer.
         warnings.warn('Error in loading the saved optimizer '
  [13]: # Evaluate pretrained model on the test set
        preds = model.evaluate(X_test, Y_test)
        print ("Loss = " + str(preds[0]))
        print ("Test Accuracy = " + str(preds[1]))
        120/120 [=========] - 2s 21ms/step
        Loss = 0.5301785508791605
        Test Accuracy = 0.8666666746139526
   [14]: from matplotlib.pyplot import imshow
         import scipy.misc
        from PIL import Image
        %matplotlib inline
```

```
[15]: def inference(path):
    # Load the image
    my_image = Image.open(path)
    imshow(my_image)

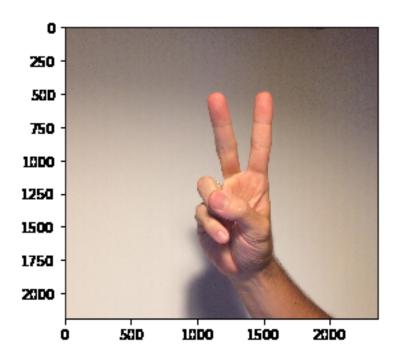
# Preprocess the image to coincide with model input size
    img = image.load_img(path, target_size=(64, 64))
    x = image.img_to_array(img)
    x = np.expand_dims(x, axis=0)
    x = x / 255.0

# Predict the class
    predictions = model.predict(x)

print('\nPredicted class: ', np.argmax(predictions))

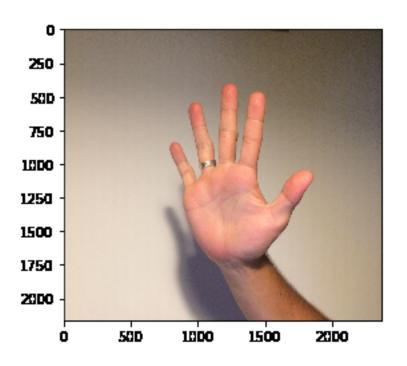
[16]: inference('./test/2.jpg')
```

Predicted class: 2



[17]: inference('./test/5.jpg')

Predicted class: 5



[]: