

# Ali Demir Mechatronics Engineer



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Pendik/Istanbul



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# Skills —

English (YDS: 86.25)

Matlab - Simulink

OpenCV

TensorFlow

ROS

Python

Machine Learning & Deep Learning

Linux

LabView

Arduino

Embedded C

(\*)[The skill scale is from 0 (Fundamental Awareness) to 6 (Expert).]

References available upon request.

#### summary

He is currently working on different ADAS projects. He is very curious about SOTA deep learning techniques and their applications on different areas, and mostly knows about CNN (convolutional neural network) architectures (in the domain of classification and object detection) and Deep RL (Reinforcement Learning) algorithms. He also knows about main problems can be met during training this networks and SOTA solutions for this problems. He is open to offers from different areas and very eager to learn new things.

### education

Since 2015 M.Sc. Student in Mechatronics Engineering Istanbul Technical University Current GPA: 3.50/4.00, Courses Completed

Thesis in progress and it is focused on Deep Reinforcement Learning

2009 - 2014 B.Sc. in Mechatronics Engineering

Okan University

GPA: 3.35/4.00, Honors Degree

Ranked as 4th Most Successful in his class

Student Representative of Electrics and Electronics Department in University Congress from 2010 to 2012

2012 - 2013 B.Sc. in Mechatronics Engineering

Opole University of Technology

GPA: 3.96/4.00

As an Exchange Student with Erasmus Program

### publications

2017 "Cooperative Adaptive Cruise Control Using Visible Light Communi-

cation", IEEE Signal Processing and Communications Applications

Conference, 2017, Antalya, Turkey.

2016 "Design and Experimental Validation of a Low Cost Autonomous Ve-

hicle Testbed", AAT Conference, 2016, Istanbul, Turkey.

## experience

09/2016 -**Progin Bilisim** 

Development of Computer Vision Aided Lane Departure Warning System (LDWS) for Semi Autonomous Vehicles (Tubitak, Project No: 7151056). (Completed)

Development of Vehicle Platooning System with V2V Communica-

tion (Completed)

Development of Neural Network based E - Horizon System for Com-

mercial Vehicles

2014 - 2016 GDS Muhendislik ARGE

Algorithm Side of Ship Main Engine Systems Simulation Project

(TUBITAK - 1507)

Development of Medical Training Equipment (Ministry of Science, Industry and Technology)

**TOFAS (Fiat - Chrysler Automobiles)** 2014

Development of Production Quality Control System via Image Processina

- Programming and Software Development via LabView
- Reducing Negative Light Effects on the Image Processing

AUTORECON (EU 7th FP Project)

- · As an Assistant Field Engineer
- Industrial Six Axis Robot Programming (Comau C4G and C5G)

#### 2014 Mekar Lab. at Okan University

Studying on Radar Sensors to be used for "Adaptive Cruise Control" systems of cars which also was his Graduation project.