

Monte Carlo Solution to Coulomb Collisions

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- ① Problem Introduction
- ② Algorithms
 - TAKIZUKA and ABE's Algorithm
 - NANBU's Algorithm
- ③ Testcases and *My* Results
 - TRUBNIKOV Test
 - DIRAC Initial Distribution
 - Disorder Induced Heating of a Cold Sphere
- ④ Problems and Comparison Differences
 - Deviation from [6] for TRUBNIKOV's Test
 - Cold Sphere \gg DEBYE-Length
 - Field Solver Scaling Issue

Outline

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Simulate Relaxation Behaviour of a Charged Particle Cloud

Particle characteristics:

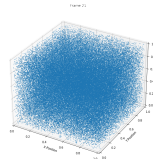
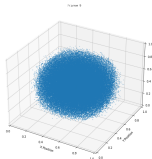
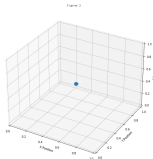
- Equal mass and charge
- No "physical radius"
- Focus on COULOMB interactions

Collision implementation:

- Direct-Simulation-Monte-Carlo (DSMC) approach

Flexibility of the algorithm:

- Mass and charge saved individually per particle
- Suitable for mixed plasmas (e.g. ion-electron interactions)



Landau-Fokker-Planck

Both algorithms converge to the LANDAU-FOKKER-PLANCK equation.

- BOLTZMANN equation [4, p. 1] (total force field F^μ):

$$\frac{\partial f_a}{\partial t} + v^\mu \frac{\partial f_a}{\partial x^\mu} + \frac{F^\mu}{m} \frac{\partial f_a}{\partial v^\mu} = \left(\frac{\delta f_a}{\delta t} \right)_c$$

- LORENTZ force and binary collisions give LANDAU form [6]:

$$\left(\frac{\delta f_a}{\delta t} \right)_c = - \sum_b \frac{\partial}{\partial v_j} \frac{e_a^2 e_b^2 \ln \Lambda}{8\pi \epsilon_0^2 m_a} \int dv' \left[\frac{\delta_{jk}}{u} - \frac{u_j u_k}{u^3} \right] \left[\frac{f_a}{m_b} \frac{\partial f_b(v')}{\partial v'_k} - \frac{f_b}{m_a} \frac{\partial f_a(v')}{\partial v_k} \right]$$

- COULOMB-logarithm $\ln \Lambda$ and DEBYE-length λ_D :

$$\ln \Lambda = \ln \left(\frac{\lambda_D}{b_0} \right), \quad \lambda_D = \sqrt{\frac{\epsilon_0 k_B T}{n q^2}}, \quad b_0 = \frac{|q_1 q_2|}{2\pi \epsilon_0 k_B^3 m_{12} T}$$

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General Algorithm Simulation Step

Assume a ParticleContainer instance f (particle distribution).

-
- 1: Select Δt
 - 2: $E \leftarrow \text{runFieldSolver}(f)$
 - 3: $\text{pairs} \leftarrow \text{selectCollisionPairs}(f)$
 - 4: **for** Every Particle Pair (i, j) **do**
 - 5: $\Delta v \leftarrow \text{getCollisionUpdate}(i, j)$
 - 6: $v_{i,j} \leftarrow v_{i,j} \pm \frac{\Delta v}{2}$
 - 7: **end for**
 - 8: $v \leftarrow v + \frac{\Delta t}{2} \cdot \frac{e}{m} \cdot \frac{E}{\epsilon_0}$ // Kick 1
 - 9: $x \leftarrow x + v \cdot \Delta t$ // Drift
 - 10: $v \leftarrow v + \frac{\Delta t}{2} \cdot \frac{e}{m} \cdot \frac{E}{\epsilon_0}$ // Kick 2
 - 11: $\text{particleNodeDistributionUpdate}()$
-

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TAKIZUKA and ABE (1977) [6, p. 4310]

Particles i and j , number density n , $\mathbf{u} = \mathbf{v}_i - \mathbf{v}_j$, reduced mass m_{ij} ,

$u_{\perp} = \sqrt{u_x^2 + u_y^2}$. Get velocity update $\Delta \mathbf{v}$:

- Variance for $\delta = \tan\left(\frac{\Theta}{2}\right)$ (Θ scattering angle):

$$\langle \delta^2 \rangle = \frac{e_i^2 e_j^2 n \ln \Lambda}{8\pi \epsilon_0^2 m_{ij}^2 u^3} \cdot \Delta t,$$

sample θ normally distributed around mean 0, calculate Θ .

- Sample the azimuthal scattering angle Φ uniformly in $[0, 2\pi]$.
- Calculate velocity update (conserves *kinetic* energy):

$$\Delta \mathbf{v} = \begin{pmatrix} \frac{u_x u_z}{u_{\perp}} \sin \Theta \cos \Phi - \frac{u_y u}{u_{\perp}} \sin \Theta \sin \Phi \\ \frac{u_y u_z}{u_{\perp}} \sin \Theta \cos \Phi - \frac{u_x u}{u_{\perp}} \sin \Theta \sin \Phi \\ -u_{\perp} \sin \Theta \cos \Phi \end{pmatrix} - \mathbf{u}(1 - \cos \Theta).$$

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NANBU (1997) [3, p. 4644]

- Calculate $s \sim \frac{\Delta t}{t_{\text{relaxation}}}$ and solve (look-up table) for A :

$$s = \frac{\ln \Lambda}{4\pi} \left(\frac{2e^2}{\epsilon_0 m} \right)^2 \frac{n \Delta t}{u^3}, \quad \coth A - A^{-1} = e^{-s}.$$

- $U_{1,2} \in [0, 1]$ uniformly sampled, scattering angle Θ , azimuthal Φ :

$$\cos \Theta = \frac{\ln(e^{-A} + 2U_1 \sinh A)}{A}, \quad \sin \Theta = \sqrt{1 - \cos^2 \Theta}, \quad \Phi = 2\pi U_2.$$

- Calculate the velocity update (careful, here is a different convention in use: $u_{\perp}^2 = u_y^2 + u_z^2$):

$$\Delta \mathbf{v} = \mathbf{u}(1 - \cos \Theta) - \frac{\sin \Theta}{u_{\perp}^2} \begin{pmatrix} -u_{\perp}^2 \cos \Phi \\ u_y u_x \cos \Phi + u u_z \sin \Phi \\ u_z u_x \cos \Phi - u u_y \sin \Phi \end{pmatrix}.$$

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TRUBNIKOV Test

Initial conditions:

- Sample positions uniformly, sample velocities according to:

$$f_0(\mathbf{v}) = \left(\frac{m}{2\pi}\right)^{\frac{3}{2}} \frac{1}{\sqrt{T_{\parallel} T_{\perp}}} \exp\left(-\frac{m}{2} \left(\frac{v_{\parallel}^2}{T_{\parallel}^2} + \frac{v_{\perp}^2}{T_{\perp}^2}\right)\right), \quad T = \frac{T_{\parallel}}{3} + \frac{2T_{\perp}}{3}.$$

- Energy conservation $\frac{dT}{dt} = 0$, analytical solution ($\Delta T = T_{\perp} - T_{\parallel}$):

$$\Delta T(t) = \Delta T \cdot e^{-\frac{t}{\tau}}, \quad \tau = \frac{5}{8} \sqrt{2\pi} \tau_0, \quad \tau_0 = \frac{\sqrt{m}}{\pi \sqrt{2} e^4} \frac{T^{\frac{3}{2}}}{n \ln \Lambda}$$

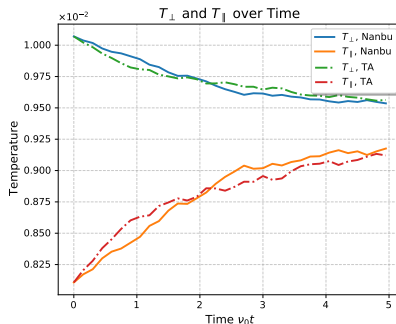
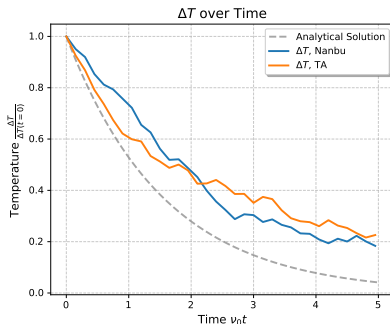
- Numerical temperature (ignore constants):

$$T_i = \frac{1}{N} \sum_{i=1}^N v_i^2, \quad T_{\parallel} = T_x, \quad T_{\perp} = \frac{T_y + T_z}{2}.$$

- No self-consistent field (no influence for uniform distribution).

Simple Example with One Realization

Anisotropic Temperature Evolution, $N = 20000$, $\nu_0 \Delta t = 0.15$



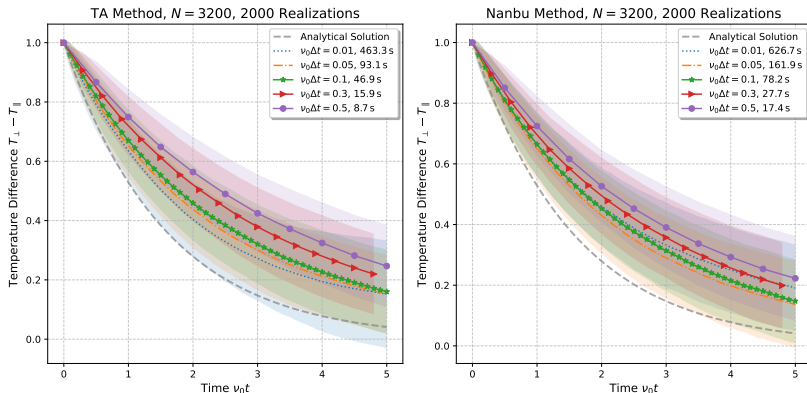
Gives the expected behaviour.

Problem

Line is slightly above the analytical solution!

Accuracy Behaviour: Time vs. Step Sizes

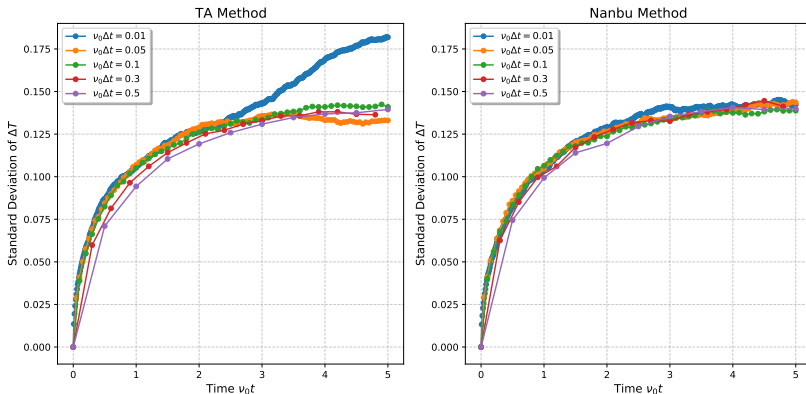
Time Step Size Analysis



Note: Converges with smaller time step sizes. NANBU is *very slightly* better for a given $\nu_0 \Delta t$, but needs significantly longer.

Precision Behaviour: Time vs. Step Sizes

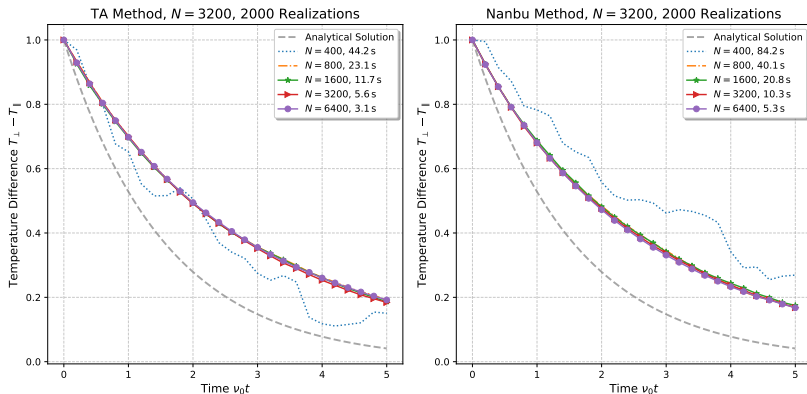
ΔT Standard Deviation Comparison in $\nu_0 \Delta t$



Note: Standard deviation does not grow once the plasma is relaxed.
Time step size has no influence.

Accuracy Behaviour: Time vs. Numbers of Particles

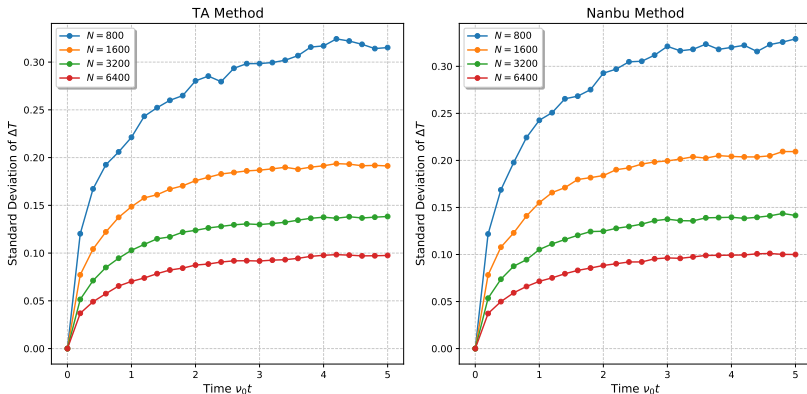
Particle Number Analysis



Note: Uses $\nu_0 \Delta t = 0.2$. Does not change accuracy, only affects precision (next two slide).

Precision Behaviour: Time vs. Numbers of Particles

ΔT Standard Deviation Comparison in N



Note: Uses $\nu_0 \Delta t = 0.2$. More particles improve precision. NANBU is *very slightly* above TA.

Outline

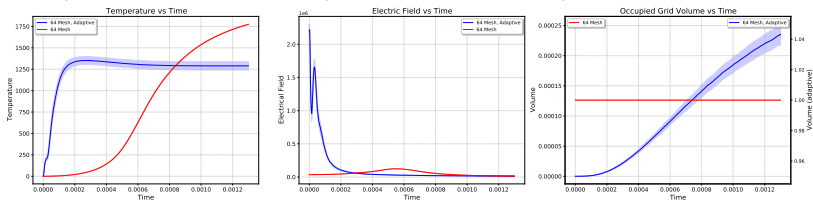
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DIRAC Initial Distribution

Initial conditions:

- Initialize all velocities to 0.
- Sample positions uniformly in a cube of length d_x centered in the middle of the domain.
- Activate self-consistent electric field.

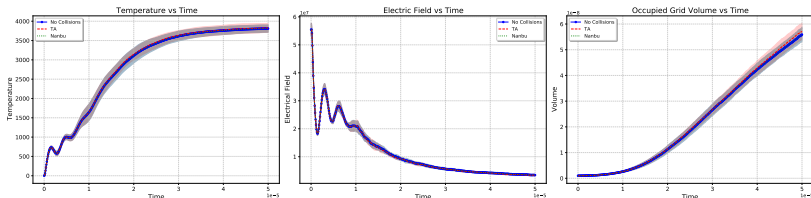
Example $d_x = 0.005L$, 1000 particles, 500 timesteps and 10 realizations:



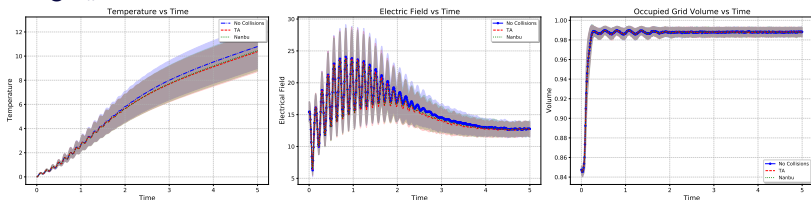
Note: No adaptive grid means all particles are within one cell, delayed and damped initial “surge” of the electrical field.

Influence of Collisions

$d_x = 0.001$, $N = 1000$, 64 adaptive grid, 500 timesteps, 10 realizations:



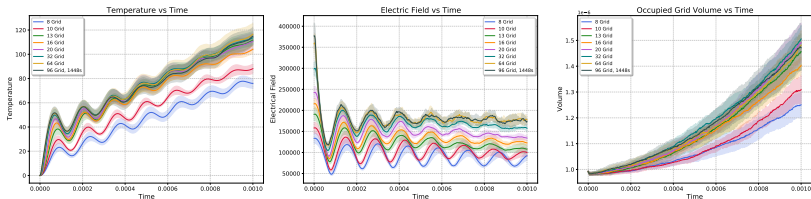
Using $d_x = 0.95$ instead:



Note: Collisions important close to equilibrium/at big timesteps. Drastic change in $|\Delta \mathbf{v}|$ over time: small window where collisions matter.

Influence of Mesh Grid Size

Using $d_x = 0.01$, $N = 500$, 400 timesteps over 10 realizations with the adaptive grid:

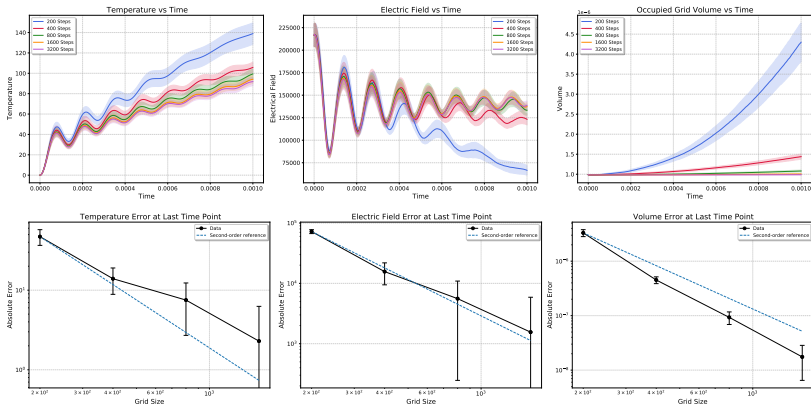


Note:

- Diminishing return within standard deviation after grid size 16 (since the potential is almost uniform).
- Field increases slightly with mesh size (faster space expansion and temperature increase).
- Slight upwards trend in temperature: potential energy is converted to kinetic energy.

Influence of (Time) Step Size

$d_x = 0.01$, $N = 500$, 16 grid size over 100 realizations and relative error:



Note: Roughly second order convergence, which is expected from a Leap-frog step.

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Disorder Induced Heating of a Cold Sphere

Initial conditions according to [2, p. 595]:

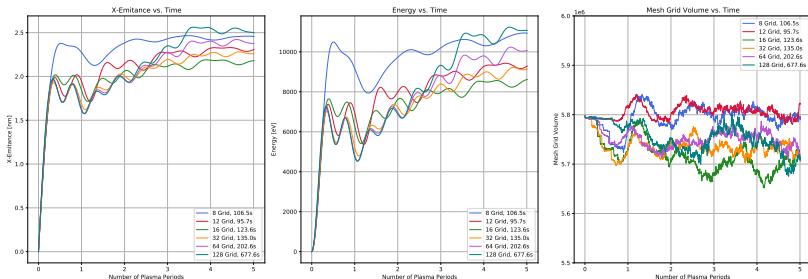
- $L = 100 \mu\text{m}$, $N = 156055$, $n_0 = 6.67 \cdot 10^{18} \text{ m}^{-3}$.
- Positions uniformly in sphere of radius $R = 17.74 \mu\text{m}$.
- Velocities initially at 0.
- Linear focusing force: apply equal and opposite radial electrical force (not accumulative, so fast particles will escape after some steps).
- Additionally: reflect particles on the sphere "shell".
- Analyze the x -emittance:

$$\varepsilon_{x,\text{rms}} = \sqrt{\langle x^2 \rangle \langle v^2 \rangle - (xv)^2}.$$

- Expect oscillation period of $\tau = 4.3 \cdot 10^{-11} \text{ s}$ and a final x -emittance value of $\varepsilon_{x,n}^{\text{eq}} = 0.491 \text{ nm}$.

Mesh-Grid Size Comparison

x emittance (left) for different (adaptive) grid sizes and 1 realization:



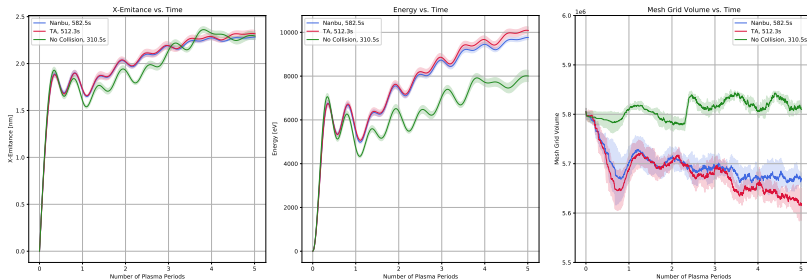
- The confinement works well (right plot).
- Dominant frequencies from FFT on the 64 grid emittance:

$$2.16 \cdot 10^{-11} \text{ s}, \quad 6.49 \cdot 10^{-11} \text{ s}, \quad 3.24 \cdot 10^{-11} \text{ s}.$$

- Diminishing returns at small grids due to homogeneity of particles.
- Missing “smoothness” correlates with spikes in mesh grid volume.

Collision Algorithm Comparison

Using different collision algorithms and 5 realizations each:



- As in [2, p. 595]: no collisions mean lower emittance.
- Collisions significant shortly in the beginning (as before).
- No significant difference between TA and Nambu.
- Overshoots expected emittance value (as before).

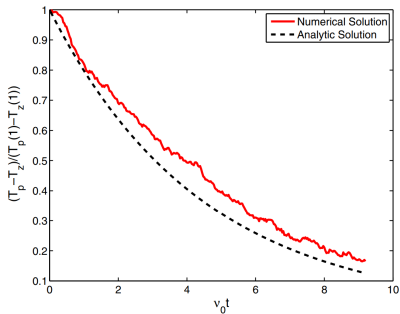
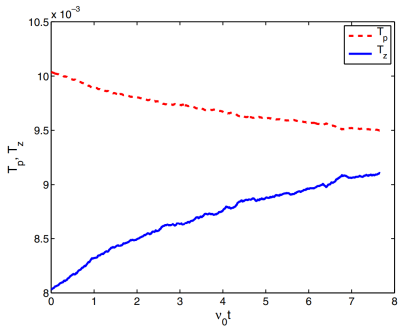
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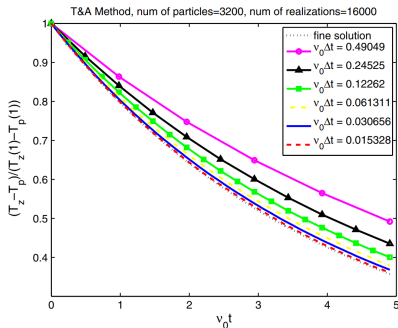
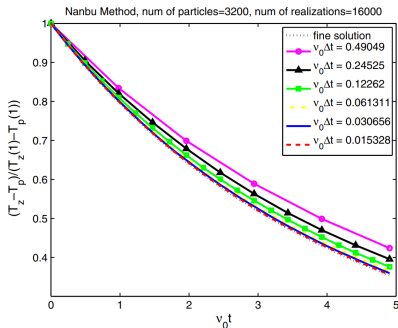
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Trubnikov "Reference" Solution: Test Run



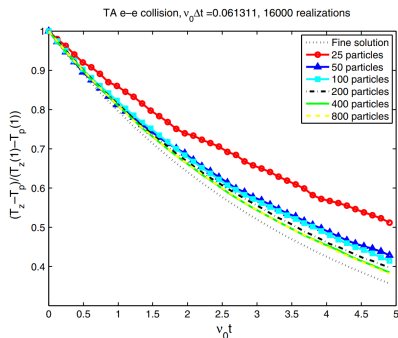
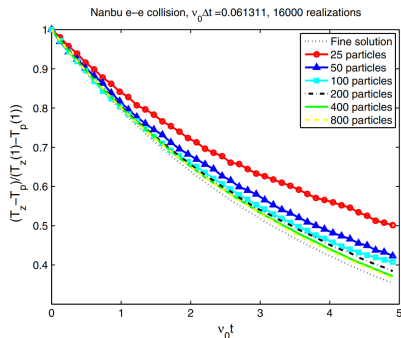
Note: similar behaviour, but simulation slightly above analytical solution.

Trubnikov "Reference" Solution: Time Step Size



- [6] does not use the analytical solution \rightarrow same convergence discrepancy.
- No explanation: uses a fine solution without providing any details.
- NANBU has slightly better accuracy (does not mention computation time).

Trubnikov “Reference” Solution: Number of Particles



- Paper notes convergence in N .
- Does not mention the analytical solution and uses a fine solution.
- Looking at the first graph, their analytical solution is also significantly lower.
- [6] never mentioned their domain size, n or $\ln \Lambda$, λ_D calculation.

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Insignificance of Collisions During Cold Sphere Heating

The program has to options:

- Calculate λ_D , compute collisions in a grid of size $\frac{L}{\lambda_D}$.
- Compute collisions per usual grid cell.

Problem ($k_B T_{\text{eq}} \approx 1.96 \text{ meV}$):

$$\lambda_D = \sqrt{\frac{\varepsilon_0 k_B T}{n q^2}} \approx 0.13 \mu\text{m}.$$

- Gives on average 0.06 particles per cell.
- Confirms marginal significance of collisions in this context.

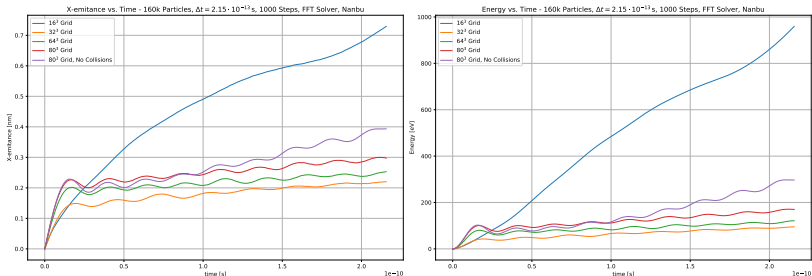
Therefore: here obtained result makes sense!

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Adaptive Grid Sizing: Scaling Problem

Same simulation, no adaptive grid and different grid sizes:



- Oscillations are way more regular.
- Is way closer to the expected equilibrium (0.491 nm).
- Oscillation period seems unchanged.

Adaptive Grid Sizing: Implementation

- Inside `advance()`, calculate self-consistent field using:

```
1 if (this->computeSelfField_m) {  
2     if (this->adjust_field_dims) adjustFieldMeshDimensions();  
3     this->par2grid();  
4     this->fsolver_m->runSolver();  
5     this->grid2par();  
6     if (this->adjust_field_dims) resetBoundaries();  
7 }
```

- Adjust grid dimensions, such that every particle is barely in it.
- After solving and interpolating onto the particles, the boundaries are resetted to the value before.

Adaptive Grid Sizing: Adjust Dimensions

```
1 void adjustFieldMeshDimensions() {
2     std::shared_ptr<ParticleContainer_t> pc = this->pcontainer_m;
3     auto *mesh = &this->fcontainer_m->getMesh();
4     auto *FL    = &this->fcontainer_m->getFL();
5
6     // Calculate the maximum and minimum of all particle coordinates using Kokkos
7     view_type* R      = &(pc->R.getView());
8     MinMaxReducer<Dim> minMax;
9     findMinMax(R, minMax);
10    Vector_t<double, Dim> maxR = minMax.max_val, minR = minMax.min_val;
11
12    // Now figure out componentwise global min/max values
13    Vector_t<double, Dim> globalMaxR, globalMinR;
14    for (size_t i = 0; i < Dim; i++) {
15        ippl::Comm->reduce(&maxR[i], &globalMaxR[i], 1, std::greater<double>());
16        ippl::Comm->reduce(&minR[i], &globalMinR[i], 1, std::less<double>());
17    }
18
19    // Calculate new mesh spacing
20    Vector_t<double, Dim> hr = (globalMaxR-globalMinR) / mesh->getGridsize();
21
22    // set the origin and mesh spacing of the mesh via
23    mesh->setMeshSpacing(hr);
24    mesh->setOrigin(globalMinR);
25
26    this->rmin_m = globalMinR;
27    this->origin_m = globalMinR;
28    this->rmax_m = globalMaxR;
29    this->hr_m = hr;
30
31    extLayoutUpdate(FL, mesh);
32    pc->update();
33 }
```

Adaptive Grid Sizing: Extended Layout Update

```
1 void extLayoutUpdate(ippl::FieldLayout<Dim>* fl, ippl::UniformCartesian<T, Dim>* mesh) {  
2     std::shared_ptr<ParticleContainer_t> pc = this->pcontainer_m;  
3     std::shared_ptr<FieldContainer_t> fc    = this->fcontainer_m;  
4  
5     Field_t<Dim>* rho_m    = &(fc->getRho());  
6     VField_t<T, Dim>* E_m  = &(fc->getE());  
7  
8     rho_m->updateLayout(*fl);  
9     E_m->updateLayout(*fl);  
10    pc->getLayout().updateLayout(*fl, *mesh);  
11  
12    std::get<FFTSolver_t<T, Dim>>(this->fsolver_m->getSolver()).setRhs(*rho_m);  
13 }
```

- Does a few (technically redundant) updates.
- Additional updateLayout do not make a difference.

Adaptive Grid Sizing: Reset Boundaries

Calculating the electrical field:

```
1 void resetBoundaries() {
2     this->origin_m = 0.0;
3     this->rmin_m = this->origin_m;
4     if (this->initial_distr == "sphere") {
5         this->rmax_m = 506.84;
6     } else {
7         this->rmax_m = 1.0;
8     }
9     this->hr_m = this->rmax_m / this->nr_m;
10
11     std::shared_ptr<ParticleContainer_t> pc = this->pcontainer_m;
12     auto *FL = &this->fcontainer_m->getFL();
13     auto *mesh = &this->fcontainer_m->getMesh();
14
15     // set the origin and mesh spacing of the mesh via
16     mesh->setMeshSpacing(this->hr_m);
17     mesh->setOrigin(this->rmin_m);
18 }
```

- Manually reset rmin, rmax and recalculate hr.
- Update the mesh container.

References

- [1] Giacomo Dimarco, Russell Caflisch, and Lorenzo Pareschi. Direct simulation Monte Carlo schemes for Coulomb interactions in plasmas. 2010. arXiv: 1010.0108. URL: <https://arxiv.org/abs/1010.0108>.
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