# ISTANBUL TECHNICAL UNIVERSITY COMPUTER ENGINEERING DEPARTMENT

### BLG 458E Functional Programming

Homework 1

Ali Emre Kaya 150210097 kayaemr21@itu.edu.tr

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#### 1 Hilbert Curve

Hilbert Curve is a continuous fractal space-filling curve described by David Hilbert.

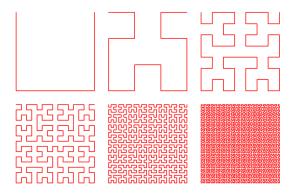


Figure 1: Hilbert curver order 1 to 6 [1]

Hilbert curve is a curve that grows by repeating itself recursively. It is used in different fields such as computer science, image and video rendering. The reason for using it in image and video rendering fields is its ability to preserve the locality of the data.

Let's say you have a one-dimensional array, numbers between 0 and 1 with only 1 digit after the decimal point.

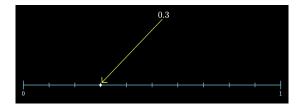


Figure 2: 1d array [2]

You can represent this array using a Hilbert curve as follows.

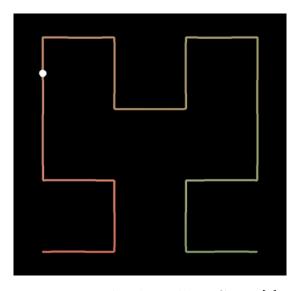


Figure 3: 2nd order Hilbert Curve [2]

If you add numbers with 2 digits after the decimal point to this array in a sequential manner (it can also be thought of as expanding an audio), you will see that there is a minimal change in the places of the old values in the 2D grid.

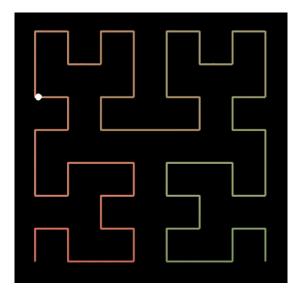


Figure 4: 3th order Hilbert Curve [2]

#### 2 Code

My Hilber curve generation code follows the steps below recursively.

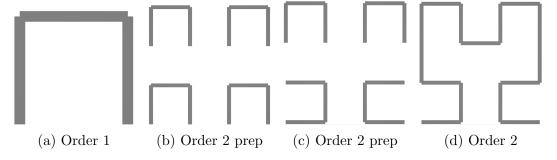


Figure 5: Passing order 1 to order 2

For example, to create a hilber curve in step 2, the program first comes to the Order 1 level and takes the default Lines 5a.

The function that appears here as scaleLine adjusts the thickness and length of the Line according to given number. The reason I used this here was that I could not see it clearly in high orders due to the thinness of the bars. If you were

going to calculate an order higher than 5, increasing the value of 1 here would make it easier for you to see.

The content of the scaleLine function is:

```
93 scaleLine :: Float -> Line -> Line
94 scaleLine factor ((x1,y1),(x2,y2),w) = ((x1*factor, y1*
factor), (x2*factor, y2*factor), w*factor)
```

After keeping the base lines it received as *prev*, it continues to work to calculate the 2nd order.

Here, first of all, the scale Line function appears in the figures again, the reason for using this function here is to reduce the size of the Lines in order to create four new Order 1 copies.

```
174 scale = 1 / (2^(fromIntegral n - 1))
175
176 scaled = map (scaleLine scale) prev
```

The reduced Order 1 is kept in the scaled array.

The reason for using fromIntegral is to convert the Integer n to Float since I want a decimal number. The reason I use map is that since scaleLine only takes one Line, I cannot give all the Lines to the function at once. I solve this by using map and adding the Lines in prev to the function one by one.

Then I create 4 different Order 1s using scaled Lines.

If we examine lines 182, 185, 188 and 189 above, we will notice that 4 different small Order 1s are created using the scaled array. These 4 Order 1s are created at the same index, I use the translateLine function to move them to the correct positions.

```
97 translateLine :: (Float, Float) -> Line -> Line
98 translateLine (dx, dy) ((x1,y1),(x2,y2),w) = ((x1+dx, y1+dy), (x2+dx, y2+dy), w)
```

The translateLine function takes a Float tuple and a Line, shifts the Line according to the data in the tuple, and returns the new Line. In this way, I get the view in the figure 5b.

After this process, I need to rotate the left copy clockwise and the right copy counterclockwise. To do this, I use the rotateLineArray90CW and rotateLineArray90CCW functions.

These functions take a tuple with two Floats as the center of rotation and a Line (I will explain how to find the center in the next code snippet). The rotateLineArray90CW function takes all the Lines one by one and rotates them. While doing this, the function creates a different function inside itself (rotateLine), the newly created function applies the rotation process by calling another function (rotate) defined in the same function for the start and end points of the bar, the details of the process are available on this page [3].

Finding the origin of the lines is not a very difficult application, I just take the farthest corners and their average gives the origin.

The function rotates all Lines one by one, selects the max and min of x and y coordinates from them, then takes the average and returns it as a tuple. concatMap is used to put the start and end points of all points into a single list, fst and snd are used to separate the pair, fst takes the first element while snd takes the second, so I can reach all x indexes with fst and all y indexes with snd.

After doing these rotation operations, I have the image in 5c. After this step, all I have to do is connect the separate pieces to each other in an orderly manner.

```
132 createConnector :: [Line] -> [Line] -> [Line] -> [Line] ->
       [Line]
133 createConnector lines1 lines2 lines3 lines4 =
           -- Bottom Left
           points1 = concatMap (\((x1, y1), (x2, y2), _) ->
136
      [(x1, y1), (x2, y2)]) lines1
           ymax1 = maximum (map snd points1)
           xmin1 = minimum (map fst points1)
138
           -- Top Left
           points2 = concatMap (((x1, y1), (x2, y2), _) \rightarrow
141
      [(x1, y1), (x2, y2)]) lines2
           xmin2 = minimum (map fst points2)
           ymin2 = minimum (map snd points2)
143
           xmax2 = maximum (map fst points2)
145
           -- Top Right
           points3 = concatMap (((x1, y1), (x2, y2), _) \rightarrow
147
      [(x1, y1), (x2, y2)]) lines3
           ymin3 = minimum (map snd points3)
148
           xmin3 = minimum (map fst points3)
149
           xmax3 = maximum (map fst points3)
           -- Bottom Right
           points4 = concatMap (\((x1, y1), (x2, y2), _) ->
      [(x1, y1), (x2, y2)]) lines4
           xmax4 = maximum (map fst points4)
           ymax4 = maximum (map snd points4)
           (_, _, _) = head lines1
       in
158
           [((xmin2, ymin2), (xmin2, ymax1), w), ((xmax2,
      ymin2), (xmin3, ymin3), w), ((xmax3, ymin3), (xmax4,
      ymax4), w)]
```

I do the connecting process with the createConnector function. This function simply finds the vertices that need to be connected and connects these vertices with a string of the required length. With this connections, finally I achieve to take figure 5d.

Below are some Hilbert Curve Orders that I created with my own code and visualized using some web sites (viewstl, 3dviewer).

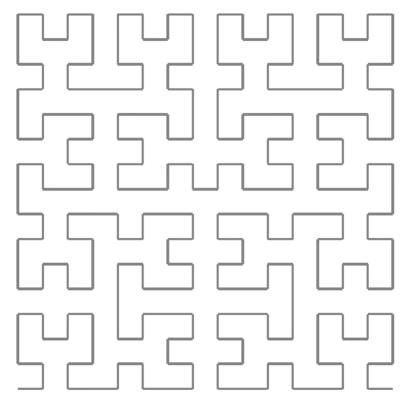


Figure 6: Hilbert Curve Order 4

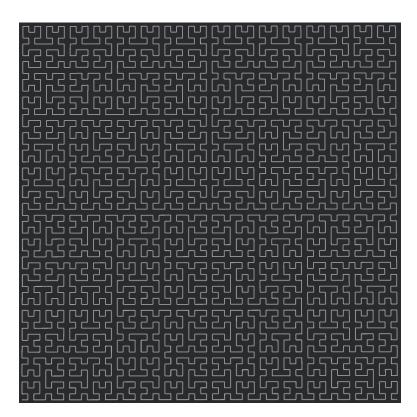


Figure 7: Hilbert Curve Order 6

#### REFERENCES

- [1] Nick Berry. Hilbert curves, 2013. Accessed: 2025-04-11.
- [2] Grant Sanderson. Hilbert's curve: Is infinite math useful? <a href="https://www.youtube.com/watch?v=3s7h2MHQtxc">https://www.youtube.com/watch?v=3s7h2MHQtxc</a>, 2017. 3Blue1Brown, YouTube. Accessed: April 11, 2025.
- [3] Maison et Math. 90 degree rotation around a point that is not the origin. https://maisonetmath.com/transformations/video/571-90-degree-rotation-around-a-point-that-is-not-the-origin, 2017. Accessed: April 11, 2025.