

In this note I will explain the theory behind explicit finite difference method for diffusion

We can write the diffusion equation as follows

$$\frac{\partial F}{\partial t} = D \frac{\partial^2 F}{\partial x^2}$$

$$F(x,t) = \begin{matrix} \text{time} \\ P_m^{(n)} \end{matrix} \quad \begin{matrix} \text{Position} \\ m \end{matrix}$$

$$\frac{\partial F}{\partial t} \approx \frac{F_m^{n+1} - F_m^n}{\Delta t} \quad (\text{Forward in time})$$

$$\frac{\partial^2 F}{\partial x^2} \approx \frac{F_{m-1}^n - 2F_m^n + F_{m+1}^n}{(\Delta x)^2} \quad (\text{Centered in Space})$$

Because of the above approximations, we call this method FTCS (Forward time center space)

By inserting the difference equations into the differential equations we will have

$$\frac{F_m^{n+1} - F_m^n}{\Delta t} = D \frac{F_{m-1}^n - 2F_m^n + F_{m+1}^n}{(\Delta x)^2}$$

$$\Rightarrow F_m^{n+1} = D \frac{\Delta t}{(\Delta x)^2} (F_{m-1}^n - 2F_m^n + F_{m+1}^n) + F_m^n$$

\Rightarrow We can write the above equation in matrix form

Form 8

$$F = \frac{D \Delta t}{(\Delta x)^2} \begin{pmatrix} 1 & 0 & & & & & \\ 1 & -2 & 1 & & & & \\ . & 1 & -2 & 1 & & & \\ . & . & . & . & . & . & \\ . & . & . & . & . & . & \\ . & . & . & 1 & -2 & 1 & 0 \\ . & . & . & . & 1 & -2 & 1 \\ . & . & . & . & . & 0 & 1 \end{pmatrix} \begin{pmatrix} F_0^n \\ F_1^n \\ \vdots \\ F_{m-1}^n \\ F_m^n \\ F_{m+1}^n \\ \vdots \\ F_n^n \\ F_M^n \end{pmatrix} + F^n$$

\hookrightarrow tri-diagonal matrix

Sparse matrix

Stability Analysis (Von Neumann analysis)

let's start with the update rule 8

$$F_j^{n+1} = F_j^n + r (F_{j-1}^n - 2F_j^n + F_{j+1}^n) \quad r = \frac{\Delta t}{\Delta x^2}$$

Now suppose that U_j^n is the values with infinite precision (without round off error due to floating point representation)

and suppose that N_j^n is the solution with round off error ϵ_j^n .

$$\Rightarrow U_j^n = N_j^n + \epsilon_j^n$$

Since both U_j^n and N_j^n satisfy the update rule equation, so will do ϵ_j^n .

$$\Rightarrow \epsilon_j^{n+1} = \epsilon_j^n + r (\epsilon_{j-1}^n - 2\epsilon_j^n + \epsilon_{j+1}^n)$$

The core of Neuman analysis is Fourier transform

Here is the formula for discrete FT

$$F[h] = \sum_{k=0}^{N-1} x[k] \exp\left(\frac{-i2\pi h k}{N}\right) \quad (\text{FT})$$

$$x[n] = \sum_{h=0}^{N-1} F[h] \exp\left(\frac{i2\pi h n}{N}\right) \quad (\text{IFT})$$

let's start with the derived update rule

$$\varepsilon_j^{n+1} = \varepsilon_j^n + r(\varepsilon_{j+1}^n - 2\varepsilon_j^n + \varepsilon_{j-1}^n)$$

let's write the inverse Fourier transfer of ε_j^n

$$\{\varepsilon_{j,n}, n\} = \varepsilon_j^n = \sum_{h=0}^{N-1} E[h,n] \exp\left(\frac{i2\pi h j}{N}\right)$$

Now let's plug in the equation above in the update rule

$$\varepsilon(x,t) = \varepsilon(j,n,t) = \varepsilon_j^n$$

$$\Rightarrow \begin{cases} \mathcal{E}_j^n = \sum_{h=0}^{N-1} E[h,n] \exp\left(\frac{i 2\pi h j}{N}\right) \\ \mathcal{E}_{j\pm 1}^n = \sum_{h=0}^{N-1} E[h,n] \exp\left(\frac{i 2\pi h (j\pm 1)}{N}\right) \\ \mathcal{E}_j^{n+1} = \sum_{h=0}^{N-1} E[h,n+1] \exp\left(\frac{i 2\pi h j}{N}\right) \end{cases}$$

$$E[h,n] \exp\left(\frac{i 2\pi h j}{N}\right) = \square_j^n ; \exp\left(\frac{i 2\pi h}{N}\right) = e^{ih}$$

Plug in the
update rule

$$\begin{aligned} \sum_h \square_j^{n+1} &= \sum_h \square_j^n + r \left(\sum_h \square_j^n e^{ih} - 2 \sum_h \square_j^n + \sum_h \square_j^n e^{-ih} \right) \\ &= \sum_h \square_j^n + r \left(\sum_h \square_j^n (e^{ih} - 2 + e^{-ih}) \right) \end{aligned}$$

$$\Rightarrow \square_j^{n+1} = \square_j^n + r \left(\square_j^n (e^{-ih} - 2 + e^{ih}) \right)$$

$$\Rightarrow \frac{\square_j^{n+1}}{\square_j^n} = 1 + r \left(e^{-ih} - 2 + e^{ih} \right) = \frac{E[h,n+1]}{E[h,n]}$$

We call $\frac{E[h,n+1]}{E[h,n]}$ amplification factor (G)

$$\Rightarrow G = 1 + r \left(e^{-i\gamma} - 2 + e^{i\gamma} \right) = 1 - 4r \left(\frac{e^{-i\gamma/2} + e^{i\gamma/2}}{2i} \right)^2$$

$$= 1 - 4r \sin^2 \left(\frac{\gamma}{2} \right)$$

$$\Rightarrow |G| \leq 1 \Rightarrow \left| 1 - 4r \sin^2 \left(\frac{\gamma}{2} \right) \right| < 1$$

$$\Rightarrow 4r \sin^2 \left(\frac{\gamma}{2} \right) < 2$$

$$\Rightarrow \left\{ r < \frac{1}{2} \right\} \Rightarrow \left\{ \frac{D \Delta t}{\Delta x^2} < \frac{1}{2} \right\}$$