



COM17

```
17:21:59.020 -> Volt= 0.00 || Servo Angle= 0
17:22:00.019 -> Volt= 0.00 || Servo Angle= 0
17:22:01.013 -> Volt= 0.00 || Servo Angle= 0
17:22:02.004 -> Volt= 0.00 || Servo Angle= 0
17:22:03.002 -> Volt= 0.00 || Servo Angle= 0
17:22:04.014 -> Volt= 0.00 || Servo Angle= 0
17:22:05.003 -> Volt= 0.00 || Servo Angle= 0
17:22:05.992 -> Volt= 0.00 || Servo Angle= 0
17:22:07.009 -> Volt= 0.00 || Servo Angle= 0
17:22:07.998 -> Volt= 0.00 || Servo Angle= 0
17:22:08.990 -> Volt= 0.00 || Servo Angle= 0
17:22:09.979 -> Volt= 0.00 || Servo Angle= 0
17:22:11.013 -> Volt= 0.00 || Servo Angle= 0
```

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COM17

```
17:22:18.016 -> Volt= 0.00 || Servo Angle= 0
17:22:18.973 -> Volt= 0.00 || Servo Angle= 0
17:22:20.015 -> Volt= 0.00 || Servo Angle= 0
17:22:20.982 -> Volt= 0.00 || Servo Angle= 0
17:22:21.972 -> Volt= 0.00 || Servo Angle= 0
17:22:22.987 -> Volt= 0.00 || Servo Angle= 0
17:22:23.978 -> Volt= 0.00 || Servo Angle= 0
17:22:25.004 -> Volt= 0.00 || Servo Angle= 0
17:22:25.978 -> Volt= 4.14 || Servo Angle= 144
17:22:27.005 -> Volt= 4.15 || Servo Angle= 144
17:22:27.995 -> Volt= 4.16 || Servo Angle= 144
17:22:28.987 -> Volt= 4.17 || Servo Angle= 144
17:22:29.981 -> Volt= 4.15 || Servo Angle= 144
```

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COM17

```
17:24:39.013 -> Volt= 4.22 || Servo Angle= 144
17:24:40.010 -> Volt= 4.16 || Servo Angle= 144
17:24:41.011 -> Volt= 4.12 || Servo Angle= 144
17:24:42.011 -> Volt= 4.14 || Servo Angle= 144
17:24:43.010 -> Volt= 4.17 || Servo Angle= 144
17:24:43.989 -> Volt= 4.15 || Servo Angle= 144
17:24:44.998 -> Volt= 4.15 || Servo Angle= 144
17:24:45.981 -> Volt= 4.16 || Servo Angle= 144
17:24:46.975 -> Volt= 4.15 || Servo Angle= 144
17:24:48.011 -> Volt= 4.17 || Servo Angle= 144
17:24:48.977 -> Volt= 4.16 || Servo Angle= 144
17:24:49.972 -> Volt= 4.16 || Servo Angle= 144
17:24:51.017 -> Volt= 4.17 || Servo Angle= 144
```

☒ Autoscroll ☒ Show timestamp

COM17

```
19:00:00.836 -> Volt= 4.11 || Servo Angle= 147.96
19:00:01.828 -> Volt= 4.19 || Servo Angle= 150.84
19:00:02.853 -> Volt= 4.26 || Servo Angle= 153.36
19:00:03.830 -> Volt= 4.15 || Servo Angle= 149.40
19:00:04.818 -> Volt= 4.12 || Servo Angle= 148.32
19:00:05.843 -> Volt= 4.16 || Servo Angle= 149.76
19:00:06.815 -> Volt= 4.16 || Servo Angle= 149.76
19:00:07.834 -> Volt= 4.12 || Servo Angle= 148.32
19:00:08.814 -> Volt= 4.18 || Servo Angle= 150.48
19:00:09.845 -> Volt= 4.06 || Servo Angle= 146.16
19:00:10.804 -> Volt= 4.19 || Servo Angle= 150.84
19:00:11.825 -> Volt= 4.14 || Servo Angle= 149.04
19:00:12.809 -> Volt= 4.09 || Servo Angle= 147.24
```

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```
19:04:10.101 -> Volt= 4.79 || Servo Angle= 172.44
19:04:11.087 -> Volt= 4.74 || Servo Angle= 170.64
19:04:12.117 -> Volt= 4.71 || Servo Angle= 169.56
19:04:13.100 -> Volt= 4.86 || Servo Angle= 174.96
19:04:14.085 -> Volt= 4.75 || Servo Angle= 171.00
19:04:15.104 -> Volt= 4.75 || Servo Angle= 171.00
19:04:16.089 -> Volt= 4.72 || Servo Angle= 169.92
19:04:17.108 -> Volt= 4.76 || Servo Angle= 171.36
19:04:18.082 -> Volt= 4.75 || Servo Angle= 171.00
19:04:19.101 -> Volt= 4.75 || Servo Angle= 171.00
19:04:20.085 -> Volt= 4.63 || Servo Angle= 166.68
19:04:21.107 -> Volt= 4.74 || Servo Angle= 170.64
19:04:22.122 -> Volt= 4.72 || Servo Angle= 169.92
```

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