Exam 1 • Graded

Total Points

105.5 / 110 pts

Question 1

AVL Tree Insertion 12 / 12 pts

- → + 2 pts Insert 60 as left child of 66
- → 2 pts Checked: 60, 66, 48, 68, 40
 Checking 60 at the beginning and/or 40 at the end are not required.
- → + 2 pts Node 68 is imbalanced and must be rebalanced.
- → + 3 pts Left-right rotation (also OK if they say double rotation) is needed.
- - + 0 pts No credit
 - + 0 pts Flag for cheating if they insert 10 instead

- → + 3 pts check if source == destination and return 1
 - **+ 2 pts** iterate through source correctly (using iterators)
 - + 2 pts iterate through destination correctly (using iterators)
 - + 2 pts check for name match correctly
- → + 3 pts Structure your code to ensure you have the iterator to the chemical in source when you try to move it to dest/targ. Grader: see additional notes.
 - + 3 pts use std::move correctly to invoke std::string's move semantics
- → + 3 pts clean up (erase or swap/pop) after move
- ✓ + 2 pts return correct value
- → + 9 pts Correct use of std::find or std::find_if in place of rubric items 2-5
 - + 6 pts Mostly correct use of std::find or std::find_if in place of rubric items 2-5
 - + 3 pts Somewhat correct use of std::find or std::find_if in place of rubric items 2-5
 - + 0 pts No credit
 - 1 pt Minor but not trivial syntax errors
 - 2 pts Moderate syntax errors
 - **3 pts** Major syntax errors
 - + 0 pts Flag for cheating if they write "targ" instead of "dest"

Question 3

Vector vs List in C++ 6 / 6 pts

- → + 6 pts 2 right examples, including: subscript notation / [] operator; .at(); O(1) advance multiple positions; difference between iterators / iterator arithmetic; comparison of iterators; resize(); capacity(); reserve(); shrink_to_fit()
 - + 3 pts 1 right example
 - + 0 pts 0 right examples

25 / 25 pts

- → + 3 pts O(log n) complexity/operations for insert
- → + 3 pts In this case, each comparison takes O(log n) for findMin
- → + 3 pts So you must multiply the comparisons in T by the complexity of findMin in A1, A2, ..., An
- \checkmark + 3 pts Total O(log n * log n) = O(log² n)
- → 3 pts Improve by tracking min for each AVL tree (this can be included in the complexity of each insert/delete
 without changing the complexity)
- → 4 pts Move semantics are needed because when you insert an element of T, which is an entire AVL tree (an object), you'll probably be moving it. Otherwise, you'll be copying an entire tree every insert, which is O(n).
 - + 2 pts Half credit for move semantics explanation
 - + 0 pts No credit

Question 5

Complexities of Basic Operations

8 / 10 pts

- 2 pts Insert in splay tree (amortized): O(log n)
- 2 pts Access vector (worst): O(1)
- 2 pts Find in sorted linked list (average): O(n)
- 2 pts Delete from AVL tree (worst): O(log n)
- ✓ 2 pts Find in binary search tree (worst): O(n)
 - 0 pts All correct

Question 6

Move Assignment

7.5 / 10 pts

- **+ 5 pts** a) If you don't check for self-assignment, and you delete the target before writing to it, you end up deleting and losing any dynamically allocated data members.
- → + 5 pts b) If you don't delete the target before writing to it, you overwrite any pointers to dynamically allocated memory, losing access to that memory and causing a memory leak.
 - + 2.5 pts Half credit for above answer almost but not completely right
 - + 0 pts No credit
 - + 0 pts Flag

B-Trees 6 / 6 pts

→ + 3 pts B-trees are used when random access times are much greater than sequential access times, typically due to the data not being able to fit completely in memory. Examples include but are not limited to disk I/O or accessing data over a network or at a different physical location.

- + 1.5 pts Half credit for above answer almost but not completely right
- → + 3 pts B-trees "flatten" the tree by keeping an array of pointers to intervals within the ordered data, effectively making it an m-ary tree rather than binary. This reduces the depth of the tree, trading sequential accesses through the array of intervals for random accesses required to follow a "child" pointer.
 - + 1.5 pts Half credit for above answer almost but not completely right
 - + 0 pts No credit

Question 8

Remove Range (Coding)

15 / 15 pts

erase each element in range and move the iterator forward by:

- → + 6 pts by using return value of .erase() most efficient
 - + **4 pts** by using a 2nd iterator so one keeps the place of the element to be erased while the other moves forward (make sure they actually implement this correctly)
 - + 3 pts by repeatedly calling lower_bound again after each erase inefficient
 - + 2 pts by using the return value of .erase() and also incrementing the iterator this will skip values.
 - **+ 0 pts** By trying to increment the iterator after erasing it this won't work.
 - + 0 pts No credit
- - + 0 pts No credit
 - 1 pt Minor but not trivial syntax errors
 - 2 pts Moderate syntax errors
 - 3 pts Major syntax errors

- + 3 pts Θ(n)
- → + 3 pts Θ(n log n)
 - + 3 pts $\Theta(n \sqrt{n})$
- - **+ 3 pts** Θ(n log* n)
 - + 3 pts Other correct answer that is not on the order of any of the above
 - + 0 pts No correct answers

CSCI 335 Exam 1 Fall 2024

Version A

Instructions:

Write your name and EmplID clearly.

When you receive this exam, check to make sure anyone sitting immediately adjacent to you has a different version. If you have the same version as a neighbor, notify a TA.

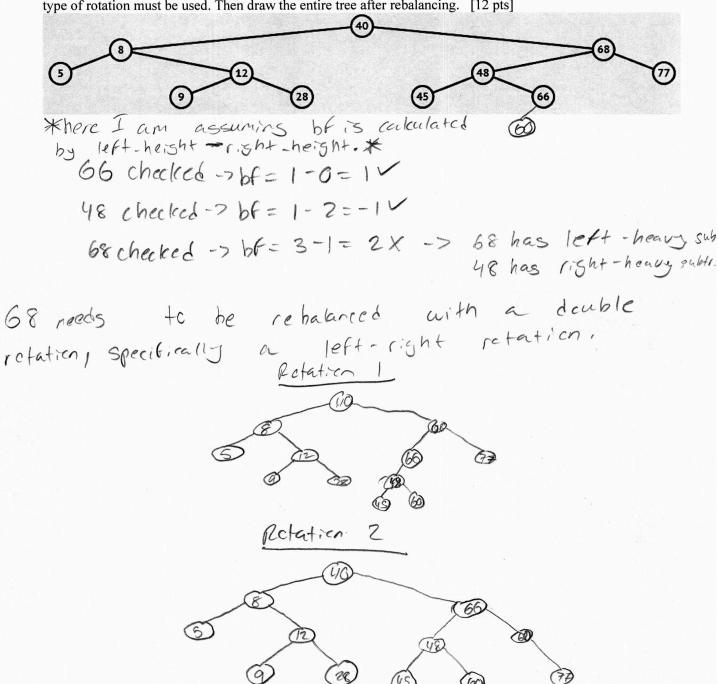
All phones, earbuds, watches, and other electronic devices must be put away in your bag.

If you're found to be in violation of these rules, or are otherwise observed trying to exchange information with another student or read their answers, your name will be taken and your exam will be carefully reviewed for signs of academic dishonesty.

Do not open this exam until instructed to do so.

Note: this exam has a total of 110 points, though the maximum score will be capped at 100.

1) Insert 60 into this AVL tree (add it on the diagram), then rebalance if necessary. List all nodes checked for balance in the order they're checked. If rebalancing is necessary, state which node must be rebalanced and what type of rotation must be used. Then draw the entire tree after rebalancing. [12 pts]



2) Suppose you have two lists of chemicals – for example, an "approved" list and a "banned" list. The lists are implemented as vectors, and the chemicals as strings. You want to write a function that can move a given chemical from one list to the other.

Implement the following function that moves *chemical* from *source* to *dest* using efficient move semantics. If *chemical* is found in *source* and not found in *dest*, it is moved and 1 is returned. Otherwise, nothing is moved and 0 is returned. If *source* and *dest* are the same, 1 is returned. Iterators must be used wherever appropriate. [20 pts]

bool moveChemical (const std::string& chemical, std::vector<std::string> source, std::vector<std::string> dest){

3) List 2 things a C++ Vector or Vector iterator can do that a C++ List or List iterator can't. Your answers must mention some method, syntax, etc. that C++ Vectors use, not just general properties of vectors. [6 pts]

}

A vector iterator is random access while a list iterator is bidirectional. This means your can do iterator arithmetic with vector iterators such as it-3; but only it-i with list iterators. Also, you can see if one vector iterator is growter than another while you can only see if two list iterators are equal or not

4) Suppose you have an AVL tree, T, whose elements are themselves AVL trees, $A_1, A_2, ..., A_n$. The elements of $A_1, A_2, ..., A_n$ are integers, and $A_1, A_2, ..., A_n$ are ordered within T by their own min elements.

What is the big-O complexity of inserting a new element into T? Write out a full complexity analysis. What modification to AVL trees could be made to improve the complexity, and what would the resulting complexity be? Assume efficient move semantics in your answer, but also briefly explain how a lack of move

semantics might affect the algorithm and complexity. [25 pts]

Tostart, overload the AVL comparison operators such that it returns, the correct beel based en the min elements of the AVL trees. The function to get the min element of an AVL will lieep traversing left until the left child is null, in which case 1 it will return the current element. Because we are traversing down a path, werst case time is OC logn). Therefore, comparisons are Oclegn). New, inserting into an AVL tree is nermally alog n), but give comparisons are are oclogn), the overall complexity of inserting to Tis now Octogin). Agood modification would be changing insert & delete of the ALL trees such that there is always a pointer to the minimum element. This would enaline comparisons out and reduce the complexity of inserting to Tto O(lcgn), We have assumed efficient more semantics thus far, but if we didn't have more semantizs, then we would need to deep copy the whole Ath tree when inserting to T. This will add can) to everall complexity making it oclogent n) = ocn).

5) Give the time complexity of each, in big O notation, with a tight bound. Assume it's a single operation (e.g. insert/delete/find 1 element) on a data structure of size n. Find is also known as "lookup" or "search". [10 pts]

Insert in a splay tree (amortized worst case)	OClog n)
Access in a vector (worst case)	0(1)
Find in a sorted linked list (average case)	O.Cn>
Delete from an AVL tree (worst case)	O(legn)
Find in a binary search tree (worst case)	O(logn)

6) When writing a move assignment operator according to best practices, two things you need to do include: a) check to make sure you're not performing a self-assignment, and b) delete the target before writing to it. What happens in each case if you don't perform that action? [10 pts]

If you don't do Cas, then when you delete the target, you won't have anything to curite from lif you are doing self-assignments. If you don't do (b), then when you overwrite the target, the previous memory target pointed to will still be in memory with no real means of being beleted.

7) In 3-5 sentences, explain the type of situation B-trees are used for, and how B-trees are designed to improve performance. [6 pts]

B-trees are designed to limit the amount of fetching the CPV has to do to memory in exchange for an increase in average number of comparisons executed. Since each node has more than one element in it, the height of a B-tree is significantly loss than a regular binary tree, thus limiting the number of betches on everage for find insert, belete jetc. Of course, this means the CPV has to perform more comparisons, but that, ok since comparisons are fast, of tetching is not as faist.

8) Complete the function removeRange so that it efficiently removes all integers with values between x and y from a given set S. It should return the number of elements removed. It should be as efficient as possible.

References for std::set::lower bound and std::set::erase are included below, and you should use those methods in removeRange. You may assume all necessary libraries are included. [15 pts]

// Returns an iterator pointing to the first element in the container which is not considered to go before val // (i.e., either it is equivalent or goes after). Returns set::end if all elements are considered to go before val. iterator lower bound (const value type& val);

// Removes the element at position from the set container. Returns an iterator to the element that follows the // last element removed (or set::end, if the last element was removed). iterator erase (const iterator position);

// removes all values from x to y, inclusive, from S.

// precondition: $x \le y$.

// returns the number of elements removed.

int removeRange (std::set<int>& S, int x, int y){

auto it = S. Icwer-bound (X); int, res = O; while (it ! = S.end() && *i+ L= J) & it = Sierase City

ceturn resi

9) Give an example of two mathematical functions, f(n) and g(n), such that: [6 pts]

- f(n), $g(n) \in o(n^2)$
- $f(n), g(n) \in \Omega(n)$
- $f(n) \notin \Theta(g(n))$

}

neither function contains an exponent.

$$f(n) = n \log \log n$$

 $g(n) = n \log n$