1 Special Orthogonal Polynomials

Orthogonal polynomials are a class of polynomials that arise in various areas particularly in approximation theory, numerical analysis, and interpolation. They are defined by their orthogonality with respect to a weight function over a specific interval. Special orthogonal polynomials, such as Legendre, Chebyshev (Type 1 and Type 2), Laguerre, and Hermite polynomials, are widely used for approximating functions and solving interpolation problems.

1.1 GENERAL POLYNOMIAL DEGREE N

A general polynomial of degree n is given by:

$$S_n^*(x) = a_0^* + a_1^*x + a_2^*x^2 + \dots + a_n^*x^n$$

```
def general(degree, x):
    return x**degree
```

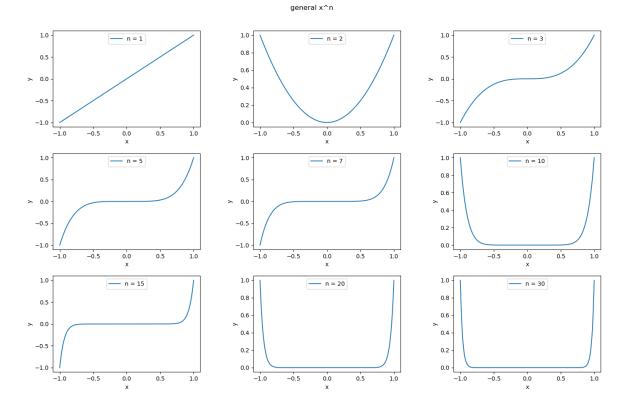


Figure 1: General polynomial $S_n^*(x)$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) = 1$ on [-1, 1] is defined as:

$$\langle f, g \rangle = \int_{-1}^{1} f(x)g(x) dx.$$

For monomials x^i and x^j , the inner product is:

$$\langle x^i, x^j \rangle = \int_{-1}^1 x^i x^j \, dx.$$

The Hilbert matrix H is constructed using the inner products of the monomials:

$$H_{ij} = \langle x^i, x^j \rangle = \int_{-1}^1 x^{i+j} dx.$$

For $i, j = 0, 1, 2, \dots, n$, the entries of H are:

$$H_{ij} = \begin{cases} \frac{2}{i+j+1} & \text{if } i+j \text{ is even,} \\ 0 & \text{if } i+j \text{ is odd.} \end{cases}$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the monomials:

$$d_i = \langle f, x^i \rangle = \int_{-1}^1 e^x x^i \, dx.$$

```
import numpy as np
  import matplotlib.pyplot as plt
  import pandas as pd
  from scipy.integrate import quad
  degree_ = 3
6
  lower_bound = 0
   upper_bound = 1
9
   def fungsi_awal(x):
10
       return np.exp(x)
11
12
   def nama_fungsi_awal():
13
       return "e^x"
14
15
   def inner_product_left(i, j, p, poly_type):
16
       integrand = lambda x: p(i, x) * p(j, x) * weight_function(
17
          poly_type, x)
       result, _ = quad(integrand, lower_bound, upper_bound)
18
       return result
19
20
   def inner_product_right(i, p, f, poly_type):
21
       integrand = lambda x: f(x) * p(i, x) * weight_function(poly_type,
22
           x)
       result, _ = quad(integrand, lower_bound, upper_bound)
23
       return result
24
25
   def weight_function(poly_type, x):
26
       if poly_type == "chebyshev_1":
27
           return 1 / np.sqrt(1 - x**2 + 1e-12)
28
       elif poly_type == "chebyshev_2":
29
           return np.sqrt(1 - x**2 + 1e-12)
30
       elif poly_type == "laguerre":
31
           return np.exp(-x)
32
       elif poly_type == "hermite":
33
           return np.exp(-x**2)
34
       else:
35
           return 1
36
37
   def approximated_function(a, x, p, degree):
38
       n = 0
39
       for i in range(degree + 1):
40
           n = n + a[i] * p(i, x)
41
       return n
42
43
  def calling_function(degree, origin_function, function_approximation,
44
       poly_type):
```

```
A = np.zeros((degree + 1, degree + 1))
       Y = np.zeros(degree + 1)
46
47
       for i in range(degree + 1):
48
           for j in range(degree + 1):
49
               A[i, j] = inner_product_left(i, j, function_approximation
50
                  , poly_type)
           Y[i] = inner_product_right(i, function_approximation,
51
              origin_function, poly_type)
52
       a = np.linalg.solve(A, Y)
53
       x = np.linspace(lower_bound, upper_bound, 100)
54
       y_appx_solver = approximated_function(a, x,
55
          function_approximation, degree)
       hilbert_matrix_df = pd.DataFrame(A)
       solution_df = pd.DataFrame(a, columns=['Coefficient'])
57
       solution_df.index = [f'a{i}' for i in range(len(solution_df))]
58
       print(f"Hilbert Matrix (A) of {function_approximation.__name__}\n
59
          {hilbert_matrix_df}\n")
       print(f"Solution of {function_approximation.__name__} degree {
60
          degree \ \n \ solution_df \ \n")
       plt.plot(x, y_appx_solver, label=function_approximation.__name__
61
          + f" degree {degree}")
62
  calling_function(degree_, fungsi_awal, x_power_i, "general")
```

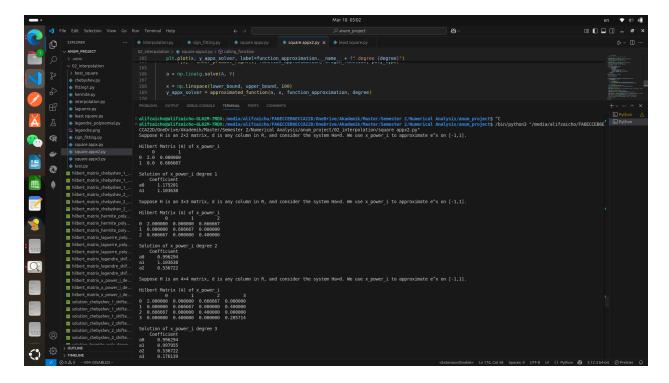


Figure 2: Hilbert Matrix and Solution from general polynomials

2x2 Hilbert Matrix (H) of x_power_i

$$H = \begin{bmatrix} 2.0 & 0.000000 \\ 0.0 & 0.666667 \end{bmatrix}$$

Solution of x_power_i Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 1.175201 \\ 1.103638 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of x_power_i

$$H = \begin{bmatrix} 2.000000 & 0.000000 & 0.666667 \\ 0.000000 & 0.666667 & 0.000000 \\ 0.666667 & 0.000000 & 0.400000 \end{bmatrix}$$

Solution of x_power_i Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 0.996294 \\ 1.103638 \\ 0.536722 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of x_power_i

$$H = \begin{bmatrix} 2.000000 & 0.000000 & 0.666667 & 0.000000 \\ 0.000000 & 0.666667 & 0.000000 & 0.400000 \\ 0.666667 & 0.000000 & 0.400000 & 0.000000 \\ 0.000000 & 0.400000 & 0.000000 & 0.285714 \end{bmatrix}$$

Solution of x_power_i Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 0.996294 \\ 0.997952 \\ 0.536722 \\ 0.176139 \end{bmatrix}$$

```
insert_degrees = [1, 2, 3]
2
  plt.figure(1)
  for i in insert_degrees:
4
      calling_function(i, fungsi_awal, x_power_i, "general")
  dotted_line = np.linspace(lower_bound, upper_bound, 10)
  plt.scatter(dotted_line, fungsi_awal(dotted_line), label=f'Original
     Function {nama_fungsi_awal()}')
  plt.title(f'Approximation of {nama_fungsi_awal()} using {x_power_i.
     __name__} polynomial')
  plt.xlabel('x')
  plt.ylabel('y')
10
  plt.legend()
11
  plt.show()
```



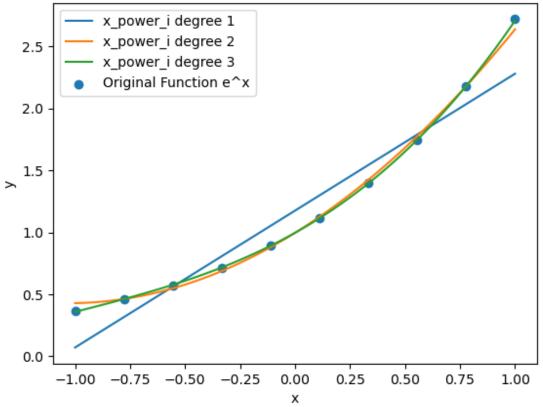


Figure 3: Approximation of e^x using $S_n^*(x)$

1.2 LEGENDRE POLYNOMIALS

Legendre polynomials $P_n(x)$ are orthogonal with respect to the weight function w(x) = 1 on the interval [-1, 1].

$$\int_{-1}^{1} P_m(x) P_n(x) dx = 0 \quad \text{for} \quad m \neq n$$

The polynomials are normalized such that $P_n(1) = 1$. Recurrence Relation:

$$(n+1)P_{n+1}(x) = (2n+1)xP_n(x) - nP_{n-1}(x)$$

```
def legendre_poly(degree, x):
    if degree == 0:
        return np.ones_like(x)
    elif degree == 1:
        return x
else:
```

```
Pn_previous = np.ones_like(x)
7
           Pn\_current = x
8
9
           for i in range(1, degree):
               Pn_new = ((2 * i + 1) * x * Pn_current - i * Pn_previous)
10
                   /(i + 1)
               Pn_previous = Pn_current
11
               Pn_current = Pn_new
12
           return Pn_current
13
14
   def legendre_shifted(degree, x):
15
       t = (2 * x - (lower_bound + upper_bound)) / (upper_bound -
16
          lower_bound)
       return legendre_poly(degree, t)
17
```

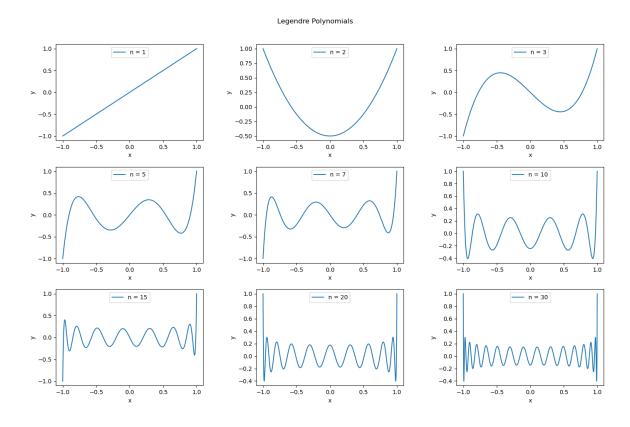


Figure 4: Legendre Polynomials

Suppose the approximation of $f(x) = e^x$ using Legendre polynomials of degree not greater than 3 is given by:

$$f(x) \approx a_0 P_0(x) + a_1 P_1(x) + a_2 P_2(x) + a_3 P_3(x),$$

where $P_0(x), P_1(x), P_2(x), P_3(x)$ are the first four Legendre polynomials:

$$P_0(x) = 1,$$

$$P_1(x) = x,$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1),$$

$$P_3(x) = \frac{1}{2}(5x^3 - 3x).$$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) = 1$ on [-1, 1] is defined as:

$$\langle f, g \rangle = \int_{-1}^{1} f(x)g(x) dx.$$

For Legendre polynomials, the inner product of $P_m(x)$ and $P_n(x)$ is:

$$\langle P_m, P_n \rangle = \int_{-1}^1 P_m(x) P_n(x) dx,$$

The Hilbert matrix H is constructed using the inner products of the Legendre polynomials:

$$H_{ij} = \langle P_i, P_j \rangle = \int_{-1}^1 P_i(x) P_j(x) dx.$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the Legendre polynomials:

$$d_i = \langle f, P_i \rangle = \int_{-1}^1 e^x P_i(x) dx.$$

```
for i in insert_degrees:
calling_function(i, fungsi_awal, legendre_shifted, "legendre")
```

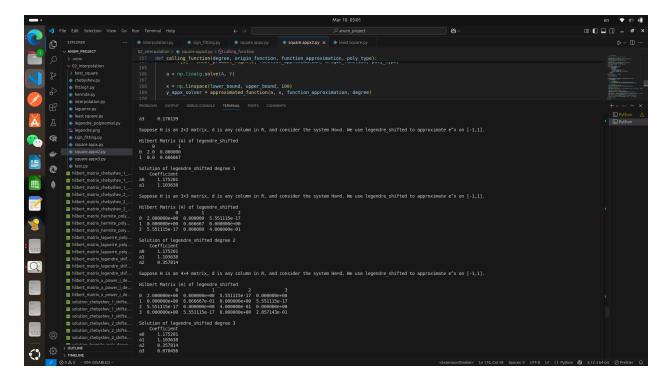


Figure 5: Hilbert Matrix and Solution from legendre polynomials

2x2 Hilbert Matrix (H) of legendre_shifted

$$H = \begin{bmatrix} 2.0 & 0.000000 \\ 0.0 & 0.666667 \end{bmatrix}$$

Solution of legendre_shifted Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 1.175201 \\ 1.103638 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of legendre_shifted

$$H = \begin{bmatrix} 2.000000 & 0.000000 & 5.551115e - 17 \\ 0.000000 & 0.666667 & 0.000000 \\ 5.551115e - 17 & 0.000000 & 0.400000 \end{bmatrix}$$

Solution of legendre_shifted Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 1.175201 \\ 1.103638 \\ 0.357814 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of legendre_shifted

$$H = \begin{bmatrix} 2.000000 & 0.000000 & 5.551115e - 17 & 0.000000 \\ 0.000000 & 0.666667 & 0.000000 & 5.551115e - 17 \\ 5.551115e - 17 & 0.000000 & 0.400000 & 0.000000 \\ 0.000000 & 5.551115e - 17 & 0.000000 & 0.285714 \end{bmatrix}$$

Solution of legendre_shifted Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 1.175201 \\ 1.103638 \\ 0.357814 \\ 0.070456 \end{bmatrix}$$

```
plt.figure(2)
for i in insert_degrees:
    calling_function(i, fungsi_awal, legendre_shifted, "legendre")

dotted_line = np.linspace(lower_bound, upper_bound, 10)

plt.scatter(dotted_line, fungsi_awal(dotted_line), label=f'Original
    Function {nama_fungsi_awal()}')

plt.title(f'Approximation of {nama_fungsi_awal()} using {
    legendre_shifted.__name__} polynomial')

plt.xlabel('x')

plt.ylabel('y')

plt.legend()

plt.show()
```

Approximation of e^x using legendre shifted polynomial

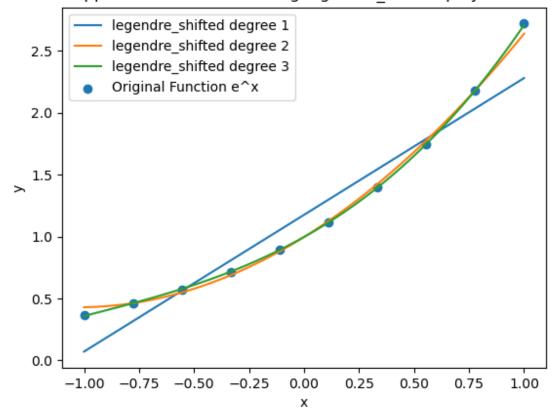


Figure 6: Approximation of e^x using legendre polynomials

1.3 Chebyshev Polynomials

1.3.1 Chebyshev 1

Orthogonality:

$$\int_{-1}^{1} \frac{T_m(x)T_n(x)}{\sqrt{1-x^2}} \, dx = 0 \quad \text{for} \quad m \neq n$$

Recurrence Relation:

$$T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$$

```
def chebyshev_1_poly(degree, x):
2
       if degree == 0:
3
           return np.ones_like(x)
4
       elif degree == 1:
5
           return x
6
       else:
7
           T_previous = np.ones_like(x)
8
           T_current = x
9
           for i in range(1, degree):
                T_new = 2*x*T_current-T_previous
11
                T_{previous} = T_{current}
12
                T_{current} = T_{new}
13
           return T_current
14
15
   def chebyshev_1_shifted(degree, x):
16
       t = (2*x-(lower_bound+upper_bound))/(upper_bound-lower_bound)
17
       return chebyshev_1_poly(degree, t)
18
19
   fig, axs = plt.subplots(n_rows, n_cols, figsize=(15, 15))
20
   fig.suptitle('Chebyshev_1 Polynomials')
21
   for i, ax in enumerate(axs.flat):
22
       if i < len(degrees_polynomial):</pre>
23
           y = chebyshev_1_poly(degrees_polynomial[i],x)
24
           ax.plot(x, y, label=f'n = {degrees_polynomial[i]}')
           # ax.set_title(f'Degree {degrees_polynomial[i]}')
26
           ax.set(xlabel='x', ylabel='y')
27
           ax.legend(loc="upper center")
28
       else:
29
           ax.axis('off')
30
  plt.tight_layout(pad=4.0)
```

1.0 --- n = 1 0.5 0.5 0.0 > 0.0 -0.5 0.0 > 0.0 > 0.0 -0.5 -0.5 -0.5 > 0.0 0.0 -0.5 -0.5 -0.5

Chebyshev_1 Polynomials

Figure 7: Chebyshev polynomials type 1

Suppose the approximation of $f(x) = e^x$ using Chebyshev type 1 polynomials of degree not greater than 3 is given by:

$$f(x) \approx a_0 T_0(x) + a_1 T_1(x) + a_2 T_2(x) + a_3 T_3(x),$$

where $T_0(x), T_1(x), T_2(x), T_3(x)$ are the first four Chebyshev type 1 polynomials:

$$T_0(x) = 1,$$

 $T_1(x) = x,$
 $T_2(x) = 2x^2 - 1,$
 $T_3(x) = 4x^3 - 3x.$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) = \frac{1}{\sqrt{1-x^2}}$ on [-1,1] is defined as:

$$\langle f, g \rangle = \int_{-1}^{1} f(x)g(x) \frac{1}{\sqrt{1-x^2}} dx.$$

For Chebyshev polynomials of the first kind, the inner product of $T_m(x)$ and $T_n(x)$ is:

$$\langle T_m, T_n \rangle = \int_{-1}^1 T_m(x) T_n(x) \frac{1}{\sqrt{1 - x^2}} dx.$$

The Hilbert matrix H is constructed using the inner products of the Chebyshev polynomials:

$$H_{ij} = \langle T_i, T_j \rangle = \int_{-1}^1 T_i(x) T_j(x) \frac{1}{\sqrt{1 - x^2}} dx.$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the Chebyshev polynomials:

$$d_i = \langle f, T_i \rangle = \int_{-1}^1 e^x T_i(x) \frac{1}{\sqrt{1 - x^2}} dx.$$

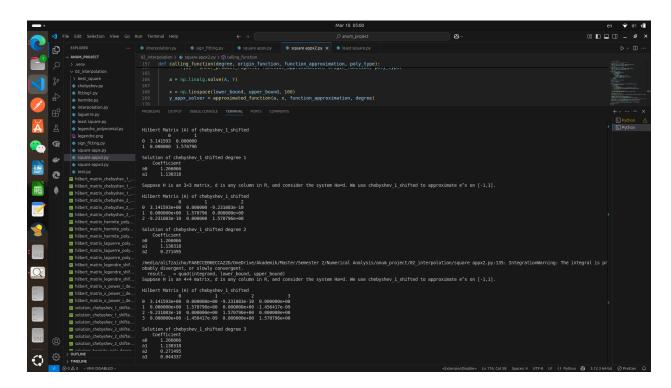


Figure 8: Hilbert Matrix and Solution from chebyshev type 1 polynomials

2x2 Hilbert Matrix (H) of chebyshev_1_shifted

$$H = \begin{bmatrix} 3.141593 & 0.000000 \\ 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_1_shifted Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 1.266066 \\ 1.139318 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of chebyshev_1_shifted

$$H = \begin{bmatrix} 3.141593 & 0.000000 & -9.231803e - 10 \\ 0.000000 & 1.570796 & 0.000000 \\ -9.231803e - 10 & 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_1_shifted Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 1.266066 \\ 1.139318 \\ 0.274495 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of chebyshev_1_shifted

$$H = \begin{bmatrix} 3.141593 & 0.000000 & -9.231803e - 10 & 0.000000 \\ 0.000000 & 1.570796 & 0.000000 & -1.456417e - 09 \\ -9.231803e - 10 & 0.000000 & 1.570796 & 0.000000 \\ 0.000000 & -1.456417e - 09 & 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_1_shifted Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 1.266066 \\ 1.139318 \\ 0.274495 \\ 0.644337 \end{bmatrix}$$



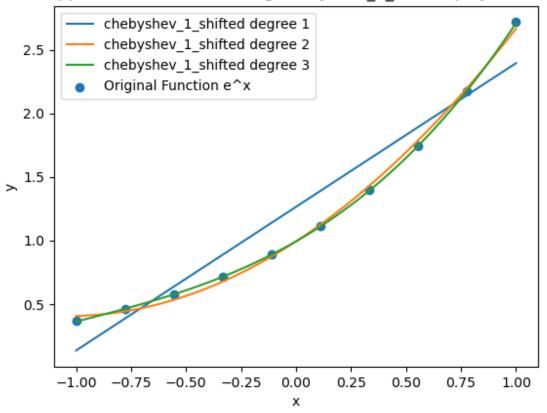


Figure 9: Approximation of e^x using chebyshev type 1 polynomials

1.3.2 Chebyshev 2

Orthogonality:

$$\int_{-1}^{1} U_m(x)U_n(x)\sqrt{1-x^2} dx = 0 \quad \text{for} \quad m \neq n$$

Recurrence Relation:

$$U_{n+1}(x) = 2xU_n(x) - U_{n-1}(x)$$

```
def chebyshev_2_poly(degree, x):
      if degree == 0:
2
          return np.ones_like(x)
3
      elif degree == 1:
4
          return 2 * x
5
      else:
6
          U_previous = np.ones_like(x)
          U_current = 2 * x
          for i in range(1, degree):
9
               U_new = 2 * x * U_current - U_previous
```

```
U_previous = U_current
U_current = U_new
return U_current

def chebyshev_2_shifted(degree, x):
t = (2 * x - (lower_bound + upper_bound)) / (upper_bound - lower_bound)
return chebyshev_2_poly(degree, t)
```

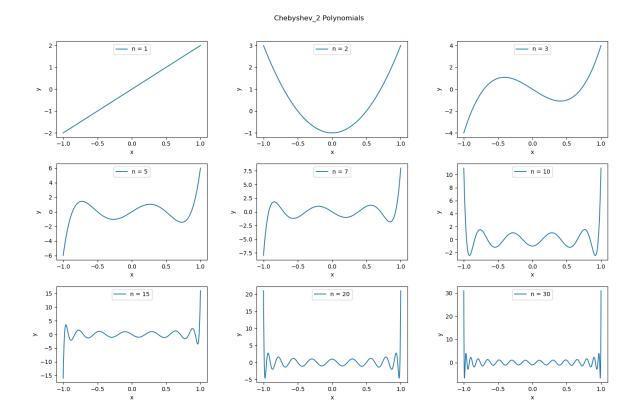


Figure 10: Chebyshev polynomials type 2

Suppose the approximation of $f(x) = e^x$ using Chebyshev type 2 polynomials of degree not greater than 3 is given by:

$$f(x) \approx a_0 U_0(x) + a_1 U_1(x) + a_2 U_2(x) + a_3 U_3(x),$$

where $U_0(x), U_1(x), U_2(x), U_3(x)$ are the first four Chebyshev type 2 polynomials:

$$U_0(x) = 1,$$

 $U_1(x) = 2x,$
 $U_2(x) = 4x^2 - 1,$
 $U_3(x) = 8x^3 - 4x.$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) = \sqrt{1-x^2}$ on [-1,1] is defined as:

$$\langle f, g \rangle = \int_{-1}^{1} f(x)g(x)\sqrt{1 - x^2} \, dx.$$

For Chebyshev polynomials of the second kind, the inner product of $U_m(x)$ and $U_n(x)$ is:

$$\langle U_m, U_n \rangle = \int_{-1}^1 U_m(x) U_n(x) \sqrt{1 - x^2} \, dx.$$

The Hilbert matrix H is constructed using the inner products of the Chebyshev polynomials:

$$H_{ij} = \langle U_i, U_j \rangle = \int_{-1}^{1} U_i(x) U_j(x) \sqrt{1 - x^2} \, dx.$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the Chebyshev polynomials:

$$d_i = \langle f, U_i \rangle = \int_{-1}^1 e^x U_i(x) \sqrt{1 - x^2} \, dx.$$

```
for i in insert_degrees:
calling_function(i, fungsi_awal, chebyshev_2_shifted, "
chebyshev_2")
```

Figure 11: Hilbert Matrix and Solution from chebyshev type 2 polynomials

2x2 Hilbert Matrix (H) of chebyshev_2_shifted

$$H = \begin{bmatrix} 1.570796 & 0.000000 \\ 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_2_shifted Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 1.130318 \\ 0.542991 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of chebyshev_2_shifted

$$H = \begin{bmatrix} 1.570796 & 0.000000 & 1.564876e - 12 \\ 0.000000 & 1.570796 & 0.000000 \\ 1.564876e - 12 & 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_2_shifted Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 1.130318 \\ 0.542991 \\ 0.133011 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of chebyshev_2_shifted

$$H = \begin{bmatrix} 1.570796 & 0.000000 & 1.564876e - 12 & 0.000000 \\ 0.000000 & 1.570796 & 0.000000 & 3.129615e - 12 \\ 1.564876e - 12 & 0.000000 & 1.570796 & 0.000000 \\ 0.000000 & 3.129615e - 12 & 0.000000 & 1.570796 \end{bmatrix}$$

Solution of chebyshev_2_shifted Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 1.130318 \\ 0.542991 \\ 0.133011 \\ 0.021897 \end{bmatrix}$$



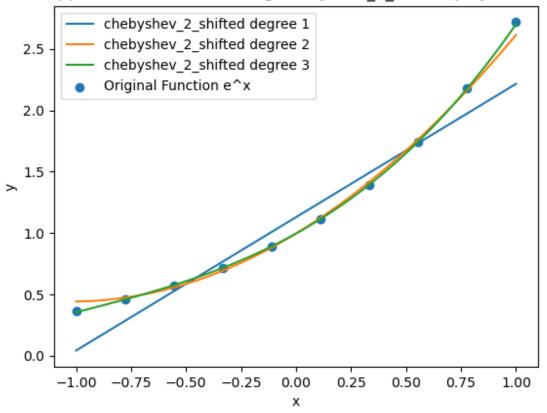


Figure 12: Approximation of e^x using chebyshev type 2 polynomials

1.4 LAGUERRE POLYNOMIALS

Definition:

$$\int_0^\infty L_m(x)L_n(x)e^{-x} dx = 0 \quad \text{for} \quad m \neq n$$

Recurrence Relation:

$$(n+1)L_{n+1}(x) = (2n+1-x)L_n(x) - nL_{n-1}(x)$$

```
def laguerre_poly(degree, x):
    if degree == 0:
        return np.ones_like(x)

elif degree == 1:
        return 1 - x

else:
        L_previous = np.ones_like(x)

        L_current = 1 - x

for i in range(1, degree):
```

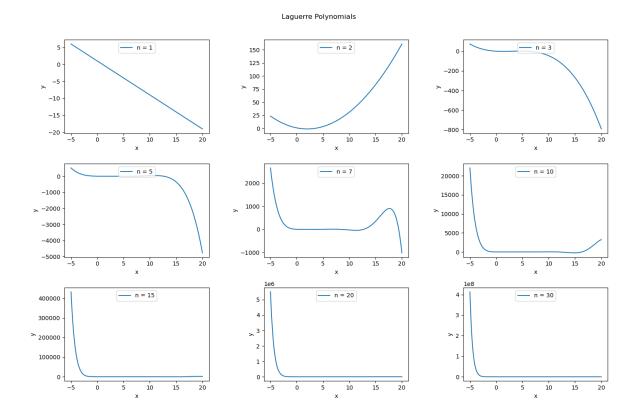


Figure 13: Laguerre polynomials

Suppose the approximation of $f(x) = e^x$ using Laguerre polynomials of degree not greater than 3 is given by:

$$f(x) \approx a_0 L_0(x) + a_1 L_1(x) + a_2 L_2(x) + a_3 L_3(x),$$

where $L_0(x), L_1(x), L_2(x), L_3(x)$ are the first four Laguerre polynomials:

$$L_0(x) = 1,$$

$$L_1(x) = -x + 1,$$

$$L_2(x) = \frac{1}{2}(x^2 - 4x + 2),$$

$$L_3(x) = \frac{1}{6}(-x^3 + 9x^2 - 18x + 6).$$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) =$

 e^{-x} on [0,1] is defined as:

$$\langle f, g \rangle = \int_0^1 f(x)g(x)e^{-x} dx.$$

For Laguerre polynomials, the inner product of $L_m(x)$ and $L_n(x)$ is:

$$\langle L_m, L_n \rangle = \int_0^1 L_m(x) L_n(x) e^{-x} dx.$$

The Hilbert matrix H is constructed using the inner products of the Laguerre polynomials:

$$H_{ij} = \langle L_i, L_j \rangle = \int_0^1 L_i(x) L_j(x) e^{-x} dx.$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the Laguerre polynomials:

$$d_i = \langle f, L_i \rangle = \int_0^1 e^x L_i(x) e^{-x} dx = \int_0^1 L_i(x) dx.$$

```
for i in insert_degrees:
calling_function(i, fungsi_awal, laguerre_poly, "laguerre")
```

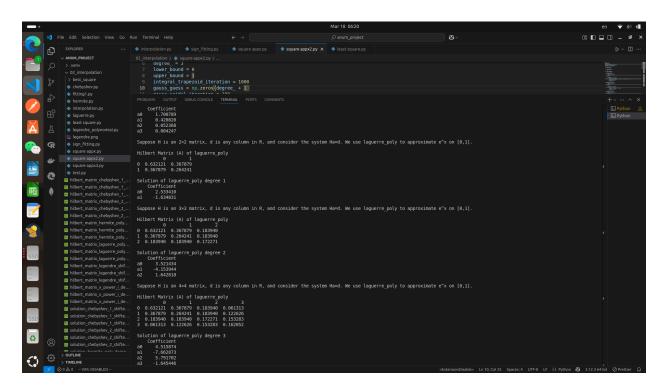


Figure 14: Hilbert Matrix and Solution from laguerre polynomials

2x2 Hilbert Matrix (H) of laguerre_poly

$$H = \begin{bmatrix} 0.632121 & 0.367879 \\ 0.367879 & 0.264241 \end{bmatrix}$$

Solution of laguerre_poly Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 2.533410 \\ -1.634831 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of laguerre_poly

$$H = \begin{bmatrix} 0.632121 & 0.367879 & 0.183940 \\ 0.367879 & 0.264241 & 0.183940 \\ 0.183940 & 0.183940 & 0.139292 \end{bmatrix}$$

Solution of laguerre_poly Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 3.521434 \\ -4.153944 \\ 1.642818 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of laguerre_poly

$$H = \begin{bmatrix} 0.632121 & 0.367879 & 0.183940 & 0.061313 \\ 0.367879 & 0.264241 & 0.183940 & 0.122626 \\ 0.183940 & 0.183940 & 0.139292 & 0.061313 \\ 0.061313 & 0.122626 & 0.061313 & 0.030653 \end{bmatrix}$$

Solution of laguerre_poly Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 4.515874 \\ -7.662873 \\ 5.791702 \\ -1.645446 \end{bmatrix}$$

```
plt.figure(5)
for i in insert_degrees:
    calling_function(i, fungsi_awal, laguerre_poly, "laguerre")

dotted_line = np.linspace(lower_bound, upper_bound, 10)

plt.scatter(dotted_line, fungsi_awal(dotted_line), label=f'Original
    Function {nama_fungsi_awal()}')

plt.title(f'Approximation of {nama_fungsi_awal()} using {
    laguerre_poly.__name__} polynomial')

plt.xlabel('x')

plt.ylabel('y')

plt.legend()

plt.show()
```

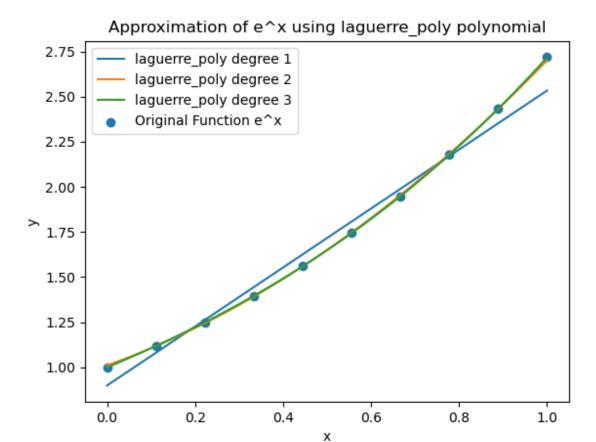


Figure 15: Approximation of e^x using leguerre polynomials

1.5 HERMITE POLYNOMIALS

Definition:

$$\int_{-\infty}^{\infty} H_m(x)H_n(x)e^{-x^2} dx = 0 \quad \text{for} \quad m \neq n$$

Recurrence Relation:

$$H_{n+1}(x) = 2xH_n(x) - 2nH_{n-1}(x)$$

```
def hermite_poly(degree, x):
    if degree == 0:
        return np.ones_like(x)

elif degree == 1:
        return 2 * x

else:
        H_previous = np.ones_like(x)

        H_current = 2 * x

for i in range(1, degree):
        H_new = 2 * x * H_current - 2 * i * H_previous
```

```
H_previous = H_current
H_current = H_new
return H_current
```

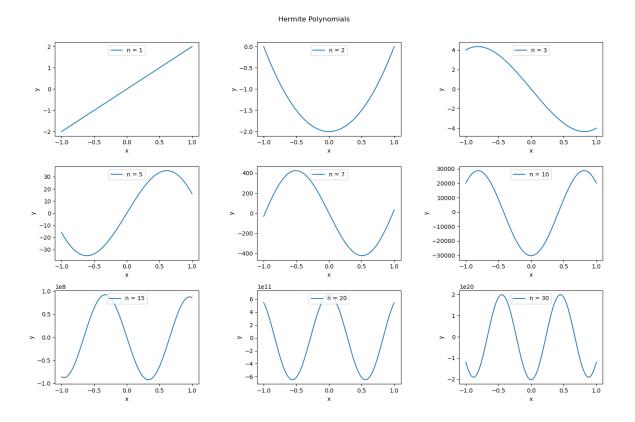


Figure 16: Hermite Polynomials

Suppose the approximation of $f(x) = e^x$ using Hermite polynomials of degree not greater than 3 is given by:

$$f(x) \approx a_0 H_0(x) + a_1 H_1(x) + a_2 H_2(x) + a_3 H_3(x),$$

where $H_0(x)$, $H_1(x)$, $H_2(x)$, $H_3(x)$ are the first four Legendre polynomials:

$$H_0(x) = 1,$$

 $H_1(x) = 2x,$
 $H_2(x) = 4x^2 - 2,$
 $H_3(x) = 8x^3 - 12x.$

The inner product of two functions f(x) and g(x) with respect to the weight function $\rho(x) = e^{-x^2}$ on [-1,1] is defined as:

$$\langle f, g \rangle = \int_{-1}^{1} f(x)g(x)e^{-x^2} dx.$$

For Hermite polynomials, the inner product of $H_m(x)$ and $H_n(x)$ is:

$$\langle H_m, H_n \rangle = \int_{-1}^1 H_m(x) H_n(x) e^{-x^2} dx.$$

The Hilbert matrix H is constructed using the inner products of the Hermite polynomials:

$$H_{ij} = \langle H_i, H_j \rangle = \int_{-1}^{1} H_i(x) H_j(x) e^{-x^2} dx.$$

The vector **d** is computed using the inner products of $f(x) = e^x$ with the Hermite polynomials:

$$d_i = \langle f, H_i \rangle = \int_{-1}^1 e^x H_i(x) e^{-x^2} dx = \int_{-1}^1 e^x H_i(x) e^{-x^2} dx.$$

for i in insert_degrees:
calling_function(i, fungsi_awal, hermite_poly, "hermite")

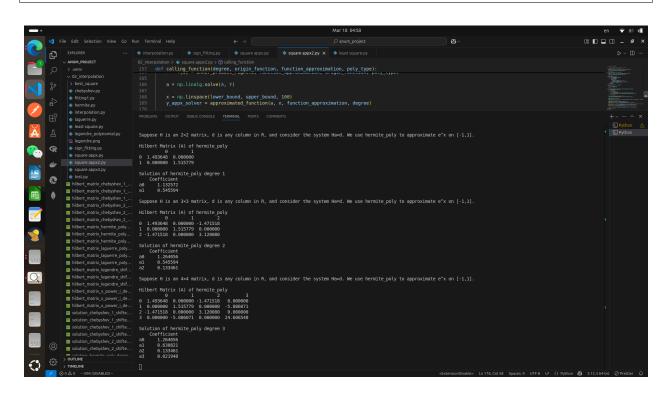


Figure 17: Hilbert Matrix and Solution from hermite polynomials

Hilbert Matrices and Solutions for Hermite Polynomial Approximation. 2x2 Hilbert Matrix (H) of hermite_poly

$$H = \begin{bmatrix} 1.493648 & 0.000000 \\ 0.000000 & 1.515779 \end{bmatrix}$$

Solution of hermite_poly Degree 1

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \end{bmatrix} = \begin{bmatrix} 1.132572 \\ 0.545594 \end{bmatrix}$$

3x3 Hilbert Matrix (H) of hermite_poly

$$H = \begin{bmatrix} 1.493648 & 0.000000 & -1.471518 \\ 0.000000 & 1.515779 & 0.000000 \\ -1.471518 & 0.000000 & 3.120080 \end{bmatrix}$$

Solution of hermite_poly Degree 2

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \end{bmatrix} = \begin{bmatrix} 1.264056 \\ 0.545594 \\ 0.133461 \end{bmatrix}$$

4x4 Hilbert Matrix (H) of hermite_poly

$$H = \begin{bmatrix} 1.493648 & 0.000000 & -1.471518 & 0.000000 \\ 0.000000 & 1.515779 & 0.000000 & -5.886071 \\ -1.471518 & 0.000000 & 3.120080 & 0.000000 \\ 0.000000 & -5.886071 & 0.000000 & 24.606548 \end{bmatrix}$$

Solution of hermite_poly Degree 3

$$\mathbf{a} = \begin{bmatrix} a_0^* \\ a_1^* \\ a_2^* \\ a_3^* \end{bmatrix} = \begin{bmatrix} 1.264056 \\ 0.630821 \\ 0.133461 \\ 0.021948 \end{bmatrix}$$

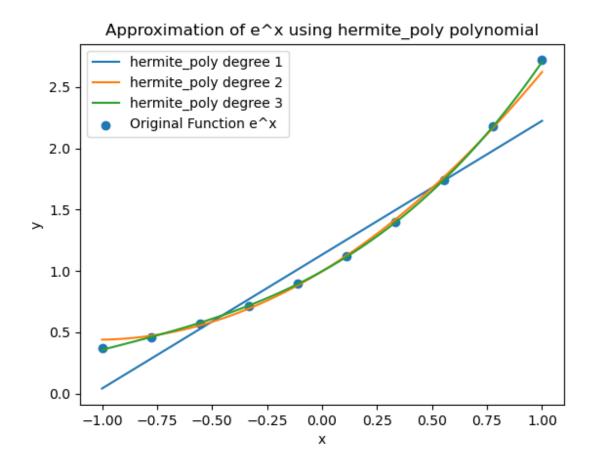


Figure 18: Approximation of e^x using hermite polynomials