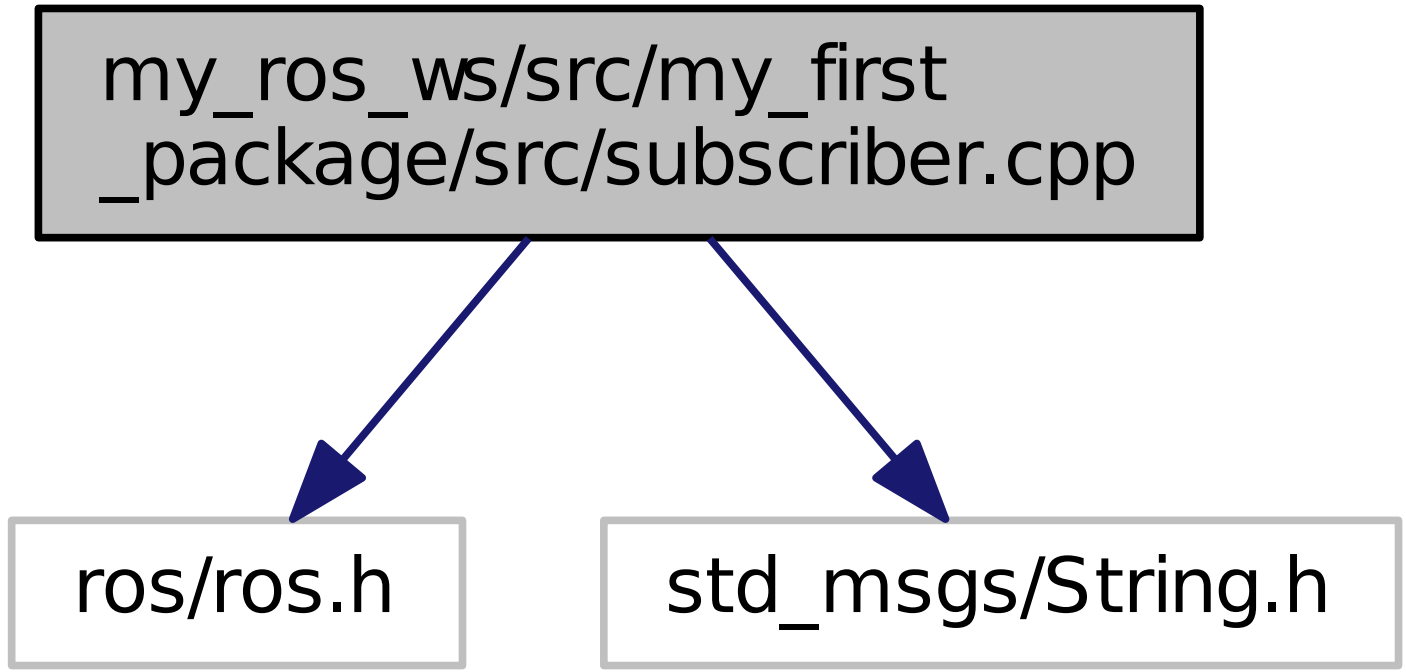
my_ros_ws/src/my_first
_package/src/subscriber.cpp
ros/ros.h
std_msgs/String.h