

>>> On Dinur's Proof of the PCP Theorem  
>>> COMP 531: Advanced Theory of Computation

Names: Aly Ibrahim<sup>†</sup>, Justin Li<sup>‡</sup>, Harley Wiltzer<sup>§</sup>  
Institute: McGill University  
Date: May 2, 2020

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<sup>†</sup>aly.ibrahim@mail.mcgill.ca

<sup>‡</sup>juan.y.li@mail.mcgill.ca

<sup>§</sup>harley.wiltzer@mail.mcgill.ca

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## >>> Theorem Statement

### Definition (Non-Deterministic Polynomial (NP))

$\exists$  deterministic polynomial-time verifier for an NP problem  $S$  that takes an input instance  $x$  and a polynomial-size proof  $t$   
That:

- \* Completeness: Accepts  $(x \in S)$
- \* Soundness: Rejects  $(x \notin S)$

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### Definition (Probabilistically Checkable Proof (PCP))

$\text{PCP}[r(n), q(n)]$  is the class of languages provable with a PCP system which uses  $O(r(n))$  bits of randomness, queries  $O(q(n))$  bits in the proof, and has completeness 1, soundness  $1/2$ .

## >>> Theorem Statement

Theorem (PCP Theorem)

$$\text{NP} \subseteq \text{PCP}[\log n, 1]$$

## BACKGROUND

>>> Background

- \* Hardness of Approximation
- \* Constraints
- \* Constraint Graphs
- \* Expander Graphs

>>> Hardness of Approximation

EFFICIENT

EXACT

HARD



## >>> Hardness of Approximation

P Complexity Class

EFFICIENT

EXACT

HARD

## >>> Hardness of Approximation

### Fixed Parameter Algorithms

EFFICIENT

EXACT

HARD

## >>> Hardness of Approximation

### Fixed Parameter Algorithms

EFFICIENT

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Imagine  $A$  solves an NP graph problem in  $O(V \cdot 2^E)$  time

Although inefficient, if graph is sparse, it is useful

## >>> Hardness of Approximation

### Approximation Algorithms

EFFICIENT

EXACT

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## >>> Hardness of Approximation

### Definition ( $\alpha$ -Approximation)

Given a combinatorial optimization maximization problem  $x$  with an optimal solution  $\text{OPT}$ , we say an algorithm  $A$  is an  $\alpha$ -approximation algorithm with  $(0 < \alpha \leq 1)$ , if  $A$  is guaranteed to return a solution with value  $\geq \alpha \cdot \text{OPT}$ .

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A maximization combinatorial optimization problem is said to have a PTAS if it has a  $(1-\epsilon)$ -approximation algorithm for every constant  $\epsilon > 0$ .

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### Definition (Hardness assuming $P \neq NP$ )

When a combinatorial optimization problem has no PTAS

## >>> Hardness of Approximation

### Definition (Combinatorial Optimization to Decision)

Example: GAP-E3SAT <sub>$c,s$</sub>  ( $0 < s \leq c \leq 1$ )

Given an estimate-3SAT (E3SAT) formula on  $m$  clauses, output:

- \* YES ( $\text{OPT} \geq c \cdot m$ )
- \* NO ( $\text{OPT} < s \cdot m$ )
- \* Anything o.w.



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$\text{PCP-theorem} \iff \exists \text{ universal constant } s < 1 \text{ s.t. } \text{GAP-E3SAT}_{1,s} \text{ is NP-hard.}$

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choose random clause, check if it satisfies.

If  $x \in \text{GAP-E3SAT}_{1,s}$  then all clauses satisfy

If  $x \notin \text{GAP-E3SAT}_{1,s}$  then at most  $s$  clauses satisfy

## >>> Constraint Graphs

### Definition

$G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  is called a constraint graph, if

1.  $(V, E)$  is an undirected graph.
2.  $V$  is the set of variables that assumes values over alphabet  $\Sigma$ .
3. Each edge  $e \in E$ , defines a constraint  $c(e) \subseteq \Sigma \times \Sigma$ , and  $\mathcal{C} = \{c(e)\}_{e \in E}$ . A constraint  $c(e)$  is said to be satisfied by  $(a, b)$  iff  $(a, b) \in c(e)$ .

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An assignment is a mapping  $\sigma : V \rightarrow \Sigma$ .

$$\text{UNSAT}_{\sigma}(G) = \Pr_{(u,v) \in E} [\sigma(u), \sigma(v)) \notin c(e)], \quad \text{UNSAT}(G) = \min_{\sigma} \text{UNSAT}_{\sigma}(G).$$



## >>> Expander Graphs

### Definition

Let  $G = (V, E)$  be a  $d$ -regular graph. Let  $E(S, \bar{S}) = |(S \times \bar{S}) \cap E| = |\{(u, v) \in E \mid u \in S \text{ and } v \in \bar{S}\}|$  equal the number of edges from a subset  $S \subseteq V$  to its complement. The edge expansion of  $G$  is defined as

$$h(G) = \min_{S: |S| \leq \frac{|V|}{2}} \frac{E(S, \bar{S})}{|S|}.$$

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### Definition ( $h(G) \propto (d - \lambda)$ )

The spectral gap  $(d - \lambda)$  of  $G$ 's adjacency matrix corresponds to its edge expansion  $h(G)$ . Good expanders have large  $h(G)$ .

## >>> Expander Graphs

### Lemma

*There exists  $d_0 \in \mathbb{N}$  and  $h_0 > 0$ , such that there is a polynomial-time constructible family  $\{X_n\}_{n \in \mathbb{N}}$  of  $d_0$ -regular graphs  $X_n$  on  $n$  vertices with  $h(X_n) \geq h_0$ .*

## PROOF SKETCH

# PCP-Theorem

>>> Proof Sketch

GAP-E3SAT<sub>1,s</sub>



PCP-Theorem

## >>> Proof Sketch



## >>> Proof Sketch





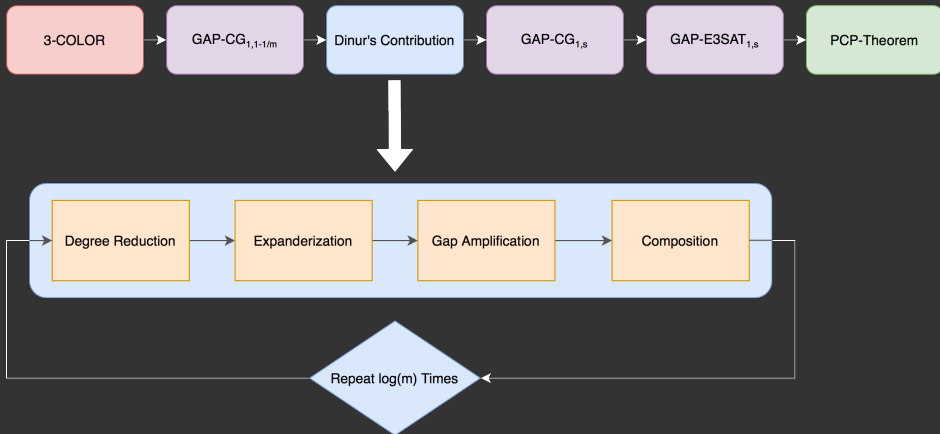
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# >>> Dinur's Contribution

Post-Stage Property	Init	Pre	Gap Amp (t)	Comp
$ V $	$ V_0 $	$\leq 2 E_0 $	$==$	$O(d V_0 )$
$ E $	$ E_0 $	$O( E_0 )$	$O(d^t E_0 )$	$O(d^t E_0 )$
$ \Sigma $	$\tilde{\Sigma}$	$\Sigma_0$	$\Sigma_0^{d^t}$	$\Sigma_0$
$\deg(G)$	const	$O(d V )$	?	-
Regular?	$\times$	$\checkmark$	$\times$	$\times$
Good Expander?	$\times$	$\checkmark$	$\times$	$\times$
$\lambda(G)$	-	$\lambda$	?	-
NO case $\text{gap}(G)$	gap	$\downarrow$	$O(t \cdot \text{gap})$	$\downarrow$

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### Lemma (Preprocessing Lemma)

*There exist constants  $0 < \lambda < d$  and  $\beta_1 > 0$  such that any constraint graph  $G$  can be transformed into a constraint graph  $G'$ , denoted  $G' = \text{prep}(G)$ , such that*

- \*  $G'$  is  $d$ -regular with self-loops, and  $\lambda(G') \leq \lambda \leq d$ .*
- \*  $G'$  has the same alphabet as  $G$ , and  $\text{size}(G') = \mathcal{O}(\text{size}(G))$ .*
- \*  $\beta_1 \cdot \text{UNSAT}(G) \leq \text{UNSAT}(G') \leq \text{UNSAT}(G)$ .*

### Lemma (Amplification Lemma)

*Let  $0 < \lambda < d$ , and  $|\Sigma|$  be constants. There exists a constant  $\beta_2 = \beta_2(\lambda, d, |\Sigma|) > 0$ , such that for every  $t \in \mathbb{N}$  and for every  $d$ -regular constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  with a self-loop on each vertex and  $\lambda(G) \leq \lambda$ ,*

$$\text{UNSAT}(G^t) \geq \beta_2 \cdot t \cdot \min \left( \text{UNSAT}(G), \frac{1}{t} \right).$$

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### Lemma (Composition Lemma)

Assume the existence of an assignment tester  $\mathcal{P}$ , with constant rejection probability  $\epsilon > 0$ , and alphabet  $\Sigma_0, |\Sigma_0| = \mathcal{O}(1)$ . There exists  $\beta_3 > 0$  that depends only on  $\mathcal{P}$ , such that given any constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$ , one can compute, in linear time, the constraint graph  $G' = G \circ \mathcal{P}$ , such that  $\text{size}(G') = c(\mathcal{P}, |\Sigma|) \cdot \text{size}(G)$ , and

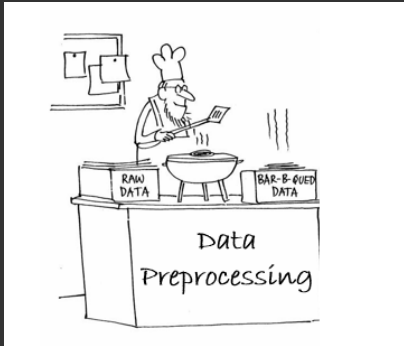
$$\beta_3 \cdot \text{UNSAT}(G) \leq \text{UNSAT}(G') \leq \text{UNSAT}(G).$$



# PRE-PROCESSING

## Degree Reduction + Expanderization

## >>> Preprocessing



- \* Start with a NP-complete problem
- \* Encode it into constraint graphs
- \* Transform constraint graph into expander graphs that are easier to work with
- \* Keep track of the change in gap during transformations

## >>> Preprocessing

Two transformations:

### 1. Degree reduction

- \* Blow up number of vertices
- \* Transform into a constant degree graph

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- \* Superimpose a constant degree expander graph
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- \* Blow up number of vertices
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### 2. Expanderize

- \* Superimpose a constant degree expander graph
- \* Add self-loops to each vertex

These two steps can be captured by the following:

$$G' = \text{prep}_2(\text{prep}_1(G)).$$

## >>> Preprocessing lemma

### Lemma

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>>>  $\text{Prep}_1$

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Let  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  be a constraint graph. The constraint graph  $\text{prep}_1(G) = \langle (V', E'), \Sigma, \mathcal{C}' \rangle$  is defined as follow:

- \* For each vertex  $v \in V$ ,  $[v] = \{(v, e) | e \in E \text{ is incident on } v\}$ .

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- \* Connect all vertices in  $[v]$  to form a  $d_0$ -regular graph  $X_v$  with expansion at least  $h_0$ . We denote  $E_1 = \cup_{v \in V} E(X_v)$ .

$$E_2 = \{ \{(v, e), (v', e)\} \mid e = \{v, v'\} \in E \}.$$

Finally,  $E' = E_1 \cup E_2$ .



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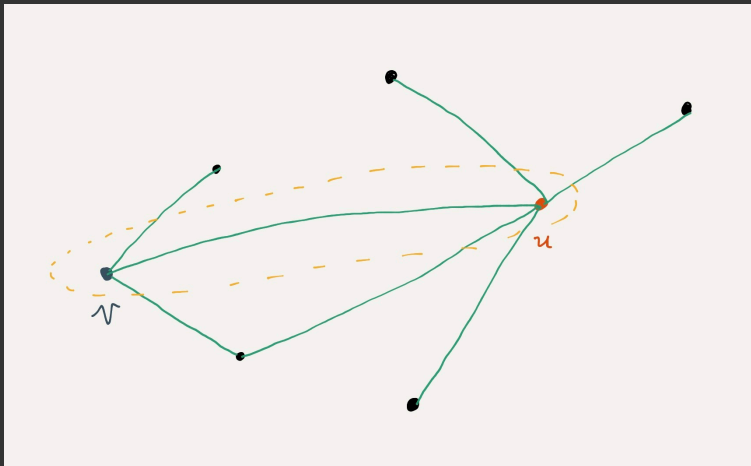
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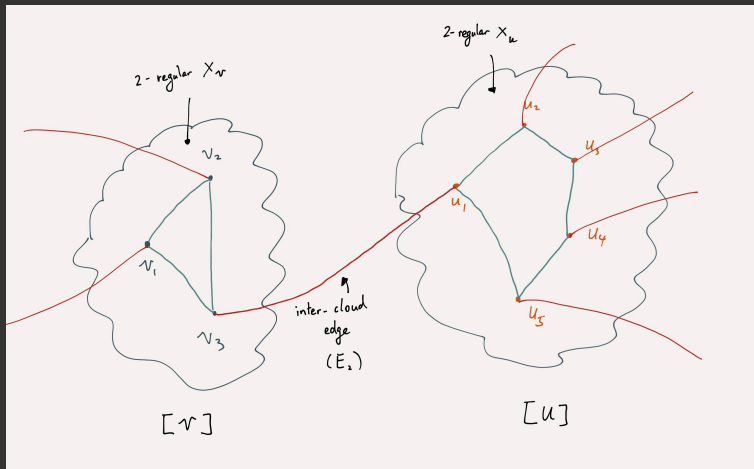
$$E_2 = \{\{(v, e), (v', e)\} \mid e = \{v, v'\} \in E\}.$$

Finally,  $E' = E_1 \cup E_2$ .

- \* Add equality constraint for each new edge.

>>> Prep<sub>1</sub>





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The above transformation gives rise to a constraint graph such that  $|V'| < 2|E|$ , and

$$c \cdot \text{UNSAT}(G) \leq \text{UNSAT}(G') \leq \text{UNSAT}(G).$$

and moreover, for any assignment  $\sigma' : V' \rightarrow \Sigma$  let  $\sigma : V \rightarrow \Sigma$  be defined according to the plurality value,

$$\forall v \in V, \sigma(v) \triangleq \arg \max_{a \in \Sigma} \left\{ \Pr_{(v,e) \in [v]} [\sigma'(v,e) = a] \right\}.$$

Then,  $c \cdot \text{UNSAT}_\sigma(G) \leq \text{UNSAT}(G')$ .

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Proof preliminaries:

- \*  $|E'| \leq d|E|, d = d_0 + 1$
- \*  $\sigma(v)$  is the most popular assigned value in cloud  $v$ .

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- \*  $\sigma(v)$  is the most popular assigned value in cloud  $v$ .
- \* Let  $\sigma' : V' \rightarrow \Sigma$  be the best assignment for  $G'$ .
- \*  $F \subseteq E$  is the set of edges that reject  $\sigma$ .
- \*  $F' \subseteq E'$  is the set of edges that reject  $\sigma'$ .
- \*  $S = \bigcup_{v \in V} \{(v, e) \in [v] \mid \sigma'(v, e) \neq \sigma(v)\}$

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- \*  $S = \bigcup_{v \in V} \{(v, e) \in [v] \mid \sigma'(v, e) \neq \sigma(v)\}$
- \* Key observation: an edge  $e = \{v, v'\} \subseteq F$ , the corresponding inter-cloud edge  $\{(v, e), (v', e)\} \in E'$  is either in  $F'$  or has an end point in  $S$ .
- \*  $\implies |F'| + |s| \geq |F| = \alpha \cdot |E|$ .
- \*  $\alpha = \text{UNSAT}_\sigma(G) = \frac{|F|}{|E|}, \text{UNSAT}_{\sigma'}(G') = \frac{|F'|}{|E'|}$

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- \*  $\implies |F'| + |s| \geq |F| = \alpha \cdot |E|$ .
- \*  $\alpha = \text{UNSAT}_\sigma(G) = \frac{|F|}{|E|}, \text{UNSAT}_{\sigma'}(G') = \frac{|F'|}{|E'|}$
- \* if  $\text{gap} = 0, \text{gap}' = 0$
- \* otherwise, We look at the following two cases:
  1.  $|F'| \geq \frac{\alpha}{2}|E|$ .
  2.  $|F'| < \frac{\alpha}{2}|E|, \implies |S| \geq \frac{\alpha}{2}|E|$ .



>>>  $\text{Prep}_1$

$$|F'| \geq \frac{\alpha}{2}|E|:$$

$$\implies \alpha' = \frac{|F'|}{|E'|} \geq \frac{\frac{\alpha}{2}|E|}{d|E|} = \frac{\alpha}{2d}$$

$$\implies \text{UNSAT}_{\sigma'}(G') \geq \frac{\text{UNSAT}_{\sigma}(G)}{2d}$$

>>> Prep<sub>1</sub>

$|S| \geq \frac{\alpha}{2}|E|$ :

- \* Let  $S^v$  denote the set of vertices in  $[v]$  that  $\sigma'$  disagrees with  $\sigma$ .
- \*  $S_a^v = \{(v, e) \in S^u | \sigma'(v, e) = a\}$
- \*  $\implies |S_a^v| \leq \frac{|[v]|}{2}$
- \* from expander property,  $E(S_a^v, [v] \setminus S_a^v) \geq h_0 \cdot |S_a^v|$
- \* but these are precisely the edges that connect two vertices with a majority value and minority value, meaning it violates the equality constraint for edges within a cloud!

>>> Prep<sub>1</sub>

This means we have at least the following amount of edges that belongs to  $F'$ :

$$\begin{aligned}\sum_{v \in V} \sum_{a \in \Sigma} \frac{h_0}{2} |s_a^v| &= \frac{h_0}{2} \sum_{v \in V} \sum_a |s_a^v| \\ &= \frac{h_0}{2} \sum_{v \in V} s^v \\ &= \frac{h_0}{2} |S| \\ &\geq \frac{h_0}{2} \frac{\alpha}{2} |E| \quad (\text{from case 2}) \\ &= \frac{\alpha h_0}{4} |E|\end{aligned}$$

$$\Rightarrow \text{UNSAT}_{\sigma'}(G') = \frac{|F'|}{|E'|} \geq \frac{\frac{\alpha h_0}{4} |E|}{|E'|} \geq \frac{\frac{\alpha h_0}{4} |E|}{d|E|} = \frac{h_0}{4d} \alpha = \frac{h_0}{4d} \text{UNSAT}_{\sigma}(G).$$

>>>  $\text{Prep}_2$

### Definition

Let  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  be a constraint graph. The constraint graph  $\text{prep}_2(G) = \langle (V, E'), \Sigma, \mathcal{C}' \rangle$  as follows.

- \* Vertices remain the same.
- \* Let  $X$  be a  $d'_o$ -regular graph on  $V$  and edge set  $E_1$  such that  $\lambda(X) < \lambda_0 < d'_o$  (expander graph). Let  $E_2 = \{\{v, v\} \mid v \in V\}$  (self-loops).  $E' = E \cup E_1 \cup E_2$ .
- \* For constraints, we just add null constraints (always satisfied) for each new edge.

>>>  $\text{Prep}_2$

The above transformation leads to the following lemma:

### Lemma

*There exists global constants  $d'_0 > \lambda_0 > 0$  such that for any  $d$ -regular constraint graph  $G$ , the constrain graph  $G' = \text{prep}_2(G)$  has the following properties:*

- \*  $G'$  is  $(d + d_0 + 1)$ -regular expander with self-loop on every vertex, and  $\lambda(G') \leq d + d + \lambda_0 + 1 < \deg(G')$ ,*
- \*  $\text{size}(G') = \mathcal{O}(\text{size}(G))$ ,*
- \* For every*  
$$\sigma : V \rightarrow \Sigma, \frac{d}{d+d'_0+1} \cdot \text{UNSAT}_\sigma(G) \leq \text{UNSAT}_\sigma(G') \leq \text{UNSAT}_\sigma(G).$$

>>> Prep<sub>2</sub>

- \* The degree of each vertex is increased by  $d'_0 + 1$ .
- \*  $|E'|$  is gone up by at most  $c' \leq (d + d'_0 + 1)/d$
- \* constant size increase.

>>> Prep<sub>2</sub>

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- \*  $|E'|$  is gone up by at most  $c' \leq (d + d'_0 + 1)/d$
- \* constant size increase.
- \* Fix an assignment  $\sigma : V \rightarrow \Sigma$ ,
- \*

$$\begin{aligned}\text{UNSAT}_\sigma(G') &= \frac{\# \text{ edges violated by } \sigma}{|E'|} \\ &\geq \frac{|E| \cdot \text{UNSAT}_\sigma(G)}{c' \cdot |E|} \\ &= \frac{d}{d + d'_0 + 1} \cdot \text{UNSAT}_\sigma(G)\end{aligned}$$

## >>> Preprocessing Lemma

Finally, combining the previous two transformation, we have:

$$G' = \text{prep}_2(\text{prep}_1(G))$$

with the following gap:

$$\text{UNSAT}(\text{Prep}_1(G)) \leq c \cdot \text{UNSAT}(G),$$

and

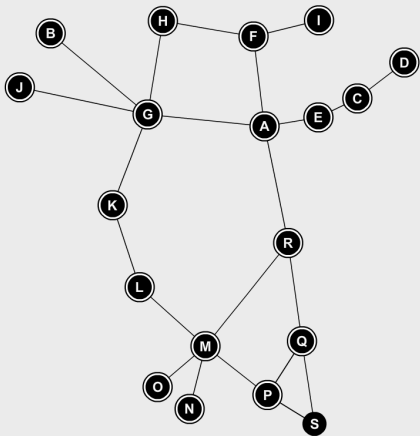
$$\begin{aligned} \text{UNSAT}(\text{Prep}_2(\text{Prep}_1(G))) &\leq \frac{d}{d + d'_0 + 1} \cdot c \cdot \text{UNSAT}(G) \\ \Rightarrow \beta_1 &= \frac{cd}{d + d'_0 + 1} \end{aligned}$$



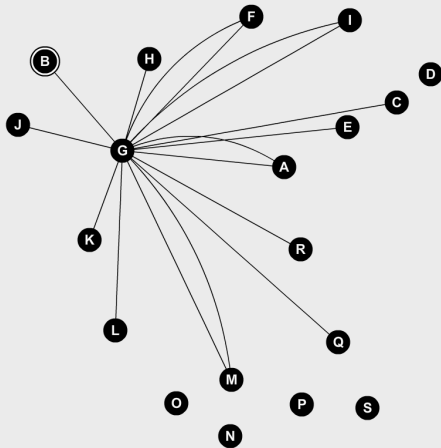
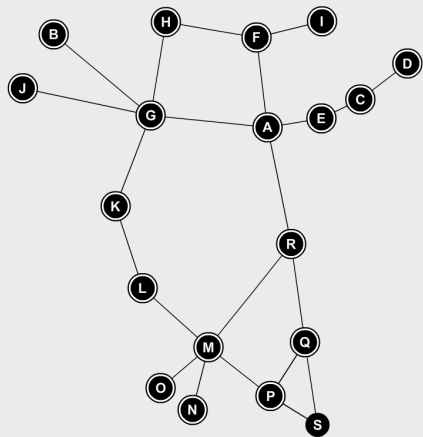


## GAP AMPLIFICATION

```
>>> Idea
```



>>> Idea



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INPUT:  $(G, \mathcal{C})$  a  $d$ -regular constraint  $(n, d, \lambda)$ -expander.

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RECALL:  $F \subseteq E$  is the set of edges failing  $\mathcal{C}$

AFTERMATH:

- \* Polynomial increase in graph size.

- \*  $\text{GAP}'$  increases 
$$\begin{cases} 0 & \text{If } \text{GAP} = 0 \\ \geq \frac{t}{O(1)} \times \min(\text{GAP}, \frac{1}{t}) & \text{Else} \end{cases}$$

- \* Alphabet blows up  $\Sigma' = \Sigma^{d^t}$ .

- \*  $\lambda'$  and  $d'$  decrease in value (ignore).



## Definition

An ``One or More Random Walk'' (OM) in a regular graph  $G = (V, E)$ :

1. Picks a random vertex  $a \in V$  to start at
2. Takes a step along a random edge of current vertex
3. Decides to stop with probability  $1/t$ . Otherwise step 2
4. Names the final vertex  $b$ .

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### Definition

A ``Zero or More Random Walk'' (ZoM) in a regular graph  $G = (V, E)$ , starting from a vertex  $v$ :

1. Stop with probability  $1/t$
2. Take a step along a random edge of current vertex
3. Go to step 1

>>> Graph Powering  $G' = G^{(t)}$

\*  $V' = V$

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- \*  $\sigma(v) \doteq \text{maxarg}_{a \in \Sigma} \{ \mathbb{P}[\text{ZoM } v \rightarrow w \text{ s.t. } \sigma'(w)_v = a \mid \text{stops} \leq t \text{ steps}] \}$



>>> How do we generate Edges?

Perform the following Random Process/Verifier

1. Perform a One or More Random Walk (OoM)
2. Denote the start vertex by  $a$  and the end vertex by  $b$
3. For each  $u \rightarrow v$  in path from  $a$  to  $b$ 
  - \* Reject if  $\text{dist}_G(u, a) \leq t$   
and  $\text{dist}_G(v, b) \leq t$   
and  $(\sigma'(a)_u, \sigma'(b)_v) \notin \mathcal{C}(u, v)$
  - \* Accept o.w.

>>> How do we generate Edges?

BAD SIDE EFFECTS:

- \*  $|E'| = \Omega(|E|^2)$
- \* produce a *probability distribution over all possible edges* making the resulting graph a weighted constraint graph with possible parallel edges

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BAD SIDE EFFECTS:

- \*  $|E'| = \Omega(|E|^2)$
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FIX:

- \* throws away any  $(a \rightarrow b) \in E'$  if  $\text{dist}_G(a, b) > 10 \log(|\Sigma|)t \doteq B$ .
  - \* Why can we throw these edges? Verifier always Accepts them.
  - \* Effect? reduce graph size and  $\text{gap} \uparrow \approx \frac{|F'|}{|E'|\downarrow}$
- \* replace each weighted edge with multiple parallel edges appropriately
  - \* Effect? back to an unweighted constraint graph

## Definition (Faulty Step)

Within the verifier's OoM random walk, we say a particular step  $u \rightarrow v$  is faulty if:

1.  $(u \rightarrow v) \in F$  (recall  $F \subseteq E$  is the edges failing  $\mathcal{C}$ )
2.  $\text{dist}_G(u \rightarrow a) \leq t$  and  $\sigma'(a)_u = \sigma(u)$
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### Definition (# Faulty Steps)

Let  $N$  be the r.v. counting the number of faulty steps. If  $N > 0$ , the verifier rejects

$\mathbb{P}[N > 0]$  is large  $\implies$  GAP' large

### Definition (Faulty\* Step)

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Let  $L$  be a r.v. denoting the number of steps the  $a \rightarrow b$  walk.

We need to show that  $\text{GAP}' \geq \frac{t}{O(1)} \cdot \frac{|F|}{|E|}$

### Lemma

For any non-negative r.v.  $N$ ,  $\mathbb{P}[N > 0] \geq \frac{\mathbb{E}[N]^2}{\mathbb{E}[N^2]}$

### Proof.

Using Cauchy-Schwarz

$$\mathbb{E}[N] = \mathbb{E}[N \cdot \mathbb{1}[N > 0]] \leq \sqrt{\mathbb{E}[N^2]} \sqrt{\mathbb{E}[\mathbb{1}[N > 0]]^2} = \sqrt{\mathbb{E}[N^2]} \sqrt{\mathbb{P}[N > 0]}$$

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**Lemma**

$$\mathbb{E}[N] \geq \frac{t}{4|\Sigma|^2} \cdot \frac{|F|}{|E|}$$

**Lemma**

$$\mathbb{E}[N^*] \geq \frac{t}{8|\Sigma|^2} \cdot \frac{|F|}{|E|}$$

**Lemma**

$$\mathbb{E}[N^{*2}] \leq O(1) \cdot t \cdot \frac{|F|}{|E|}$$

## Lemma

Let  $(u, v)$  be a fixed edge in the regular graph  $G = (V, E)$ . Do a DoM in  $G$ , conditioned on making exactly  $k$   $u \rightarrow v$  steps. Then:

- \* The distribution on the final vertex  $b$  is the same as if we did a ZoM starting from  $v$ .
- \* The distribution on the initial vertex  $a$  is same as if we did an ZoM starting from  $u$ .
- \*  $a$  and  $b$  are independent.

### Lemma

$$\mathbb{E}[N] \geq \frac{t}{4|\Sigma|^2} \cdot \frac{|F|}{|E|}$$

### Proof.

$$\mathbb{E}[N_{u \rightarrow v}] = \sum_{k \geq 1} \mathbb{E}[N_{u \rightarrow v} \mid \text{exactly } k \text{ } u \rightarrow v \text{ steps}] \quad (1)$$

$$\times \mathbb{P}[\text{exactly } k \text{ } u \rightarrow v \text{ steps}] \quad (2)$$

$$= \sum_{k \geq 1} k \cdot \mathbb{P}[u \rightarrow v \text{ is faulty} \mid \text{exactly } k \text{ } u \rightarrow v \text{ steps}] \quad (3)$$

$$\times \mathbb{P}[\text{exactly } k \text{ } u \rightarrow v \text{ steps}] \quad (4)$$

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$$\mathbb{P}[u \rightarrow v \text{ is faulty} \mid \text{exactly } k \text{ } u \rightarrow v \text{ steps}] \tag{5}$$

$$= \left( \mathbb{P}[\text{dist}_G(w \rightarrow a) \leq t \text{ and } \sigma'(w)_u = \sigma(u)] \right)^2 \tag{6}$$

Lemma

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Proof.

Using  $\mathbb{E}[N] \geq \frac{t}{4|\Sigma|^2} \cdot \frac{|F|}{|E|}$

### Lemma

*Let  $G$  be an  $(n, d, \lambda)$ -expander and  $F \subset E(G) = E$ , then the probability that a random walk, starting in the zero<sup>th</sup> step from a random edge in  $F$ , passes through  $F$  on its  $t^{\text{th}}$  step, is bounded by*

$$\frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^{t-1}$$

ENGLISH: Vertices from a Random Walk in an Expander are as if picked Independently from  $V$ .



### Lemma

$$\mathbb{E}[N^{*2}] \leq O(1) \cdot t \cdot \frac{|F|}{|E|}$$

### Proof.

$$\text{Let } N_F = \sum_{i=1}^{\infty} \mathbb{1}[i^{\text{th}} \text{ step in } F] = \sum_{i=1}^{\infty} \zeta_i.$$

$$\mathbb{E}[N^{*2}] \leq \mathbb{E}[N_F^2] = \sum_{i,j=1}^{\infty} \mathbb{E}[\zeta_i \cdot \zeta_j] \leq 2 \sum_{i=1}^{\infty} \mathbb{P}[\zeta_i = 1] \cdot \sum_{j \geq i} \mathbb{P}[\zeta_j = 1 \mid \zeta_i = 1] \quad (7)$$

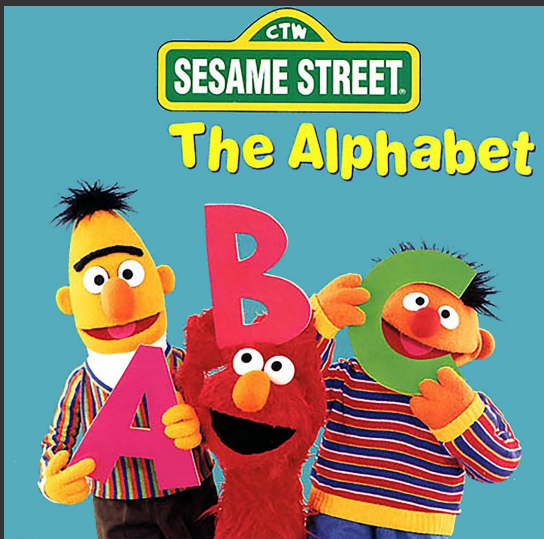
$$\mathbb{P}[\zeta_j = 1 \mid \zeta_i = 1] \quad (8)$$

$$= \mathbb{P}[\text{the walk is } j-i \text{ steps more}] \quad (9)$$

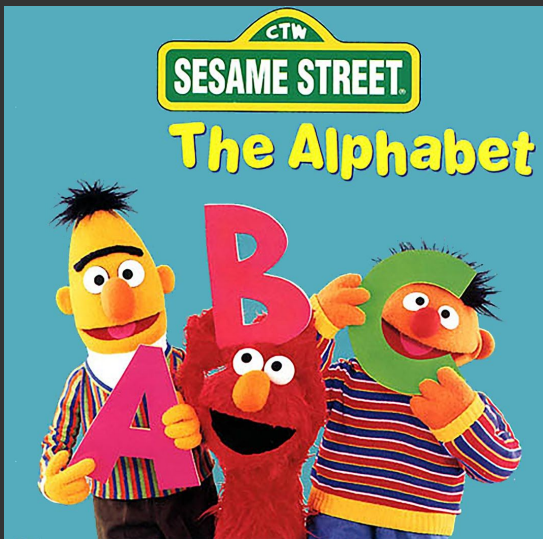
$$\times \mathbb{P}[\text{a walk from random vertex } \in F \text{ takes } (j-i)^{\text{th}} \text{ step in } F] \quad (10)$$

$$\leq (1 - 1/t)^{j-i} \left( \frac{|F|}{|E|} + \left( \frac{\lambda}{d} \right)^{j-i-1} \right) \quad (11)$$

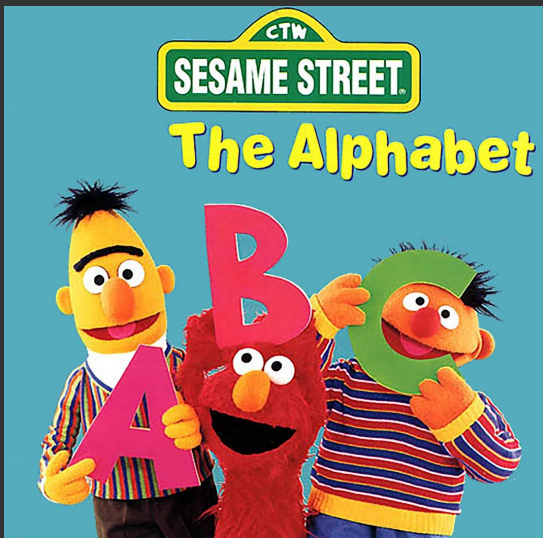
## ALPHABET REDUCTION / COMPOSITION



- \* The amplification step does a great job of increasing the gap



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- \* ... at the cost of blowing up the assignment alphabet superexponentially



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- \* ... at the cost of blowing up the assignment alphabet superexponentially
- \* We must construct a method of constraining the assignment alphabet. This is called the Alphabet Reduction/Composition step.

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- \* Due to the recursive nature of the overall gap amplification procedure, individual constraints are aggregated iteratively with an alphabet reduction step after each iteration
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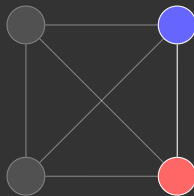
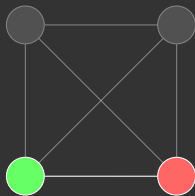
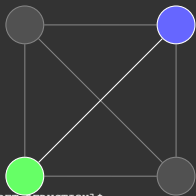
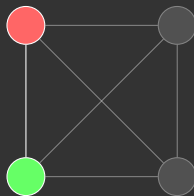
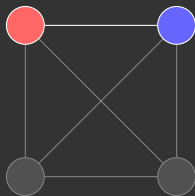
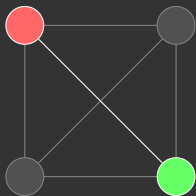


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- \* Due to the recursive nature of the overall gap amplification procedure, individual constraints are aggregated iteratively with an alphabet reduction step after each iteration
- \* We can therefore condition on the satisfiability of constraints in previous iterations to encode the satisfiability of the next constraints in a fixed alphabet. However, we must maintain two guarantees:
  1. Completeness: If the constraint graph originally had an unsat value of 0, the alphabet reduction step must output a constraint graph with unsat value 0.
  2. Soundness: If the constraint graph was not originally satisfiable and had gap  $g$ , the constraint graph output by the alphabet reduction step has gap  $\epsilon g$  for some  $\epsilon > 0$ .

## >>> Assignment Tester: It's not so simple

- \* Unfortunately, these guarantees are not enough.
- \* The issue: the satisfiability of constraints individually *does not* imply the satisfiability of constraints simultaneously.



## >>> Assignment Tester: The definition

### Definition (Assignment Tester)

An *Assignment Tester* with alphabet  $\Sigma_0$  and rejection probability  $\epsilon > 0$  is an algorithm  $\mathcal{P}$  whose input is a circuit  $\Phi$  over Boolean variables  $X$ , and whose output is a constraint graph  $G = \langle (V, E), \Sigma_0, \mathcal{C} \rangle$  such that  $V \supset X$ , and such that the following hold. Let  $V' \triangleq V \setminus X$  and let  $a : X \rightarrow \{0, 1\}$  be an assignment.

- \* **Completeness:** If  $a \in \text{SAT}(\Phi)$ , there exists  $b : V' \rightarrow \Sigma_0$  such that  $\text{UNSAT}_{a \cup b}(G) = 0$ .
- \* **Soundness:** If  $a \notin \text{SAT}(\Phi)$ , then for all  $b : V' \rightarrow \Sigma_0$ ,  $\text{UNSAT}_{a \cup b}(G) \geq \epsilon r_d(a, \text{SAT}(\Phi))$ .

where  $r_d : \{0, 1\}^n \times \{0, 1\}^n \rightarrow \mathbf{R}_{\geq 0} : (x, y) \mapsto \frac{1}{n} d_{\text{Hamming}}(x, y)$ , and  $d_{\text{Hamming}}$  denotes the Hamming distance, which trivially satisfies the properties of a metric.

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- \* **Good news:** Assignment Testers exist
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- \* **Best news:** *It's not so bad.* We know that the alphabet size of the constraint graph at the beginning of each alphabet reduction step is either some initial arbitrary alphabet  $\Sigma$  or the fixed size "target" alphabet  $\Sigma_0$ . But,  $|\Sigma|, |\Sigma_0| \in O(1)$ ! Therefore, the size of the constraint graph constructed for each constraint is some function  $c(\mathcal{P}, |\Sigma|)$ , where  $\mathcal{P}$  is the assignment tester. Note, neither  $\mathcal{P}$  or  $|\Sigma|$  depend on the size of the graph!

## >>> Composition: Preliminaries

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- \* Before we begin, we state a few definitions concerning error-correcting codes:

### Definition (Linear Dimension)

An error correcting code  $\text{Enc} : \Sigma \rightarrow \{0,1\}^\ell$  is said to have *linear dimension* if  $\ell \in O(\log_2 |\Sigma|)$ .

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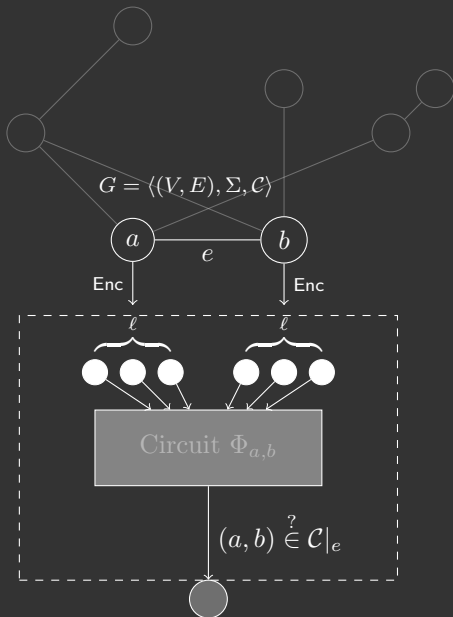
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### Definition (Relative Distance)

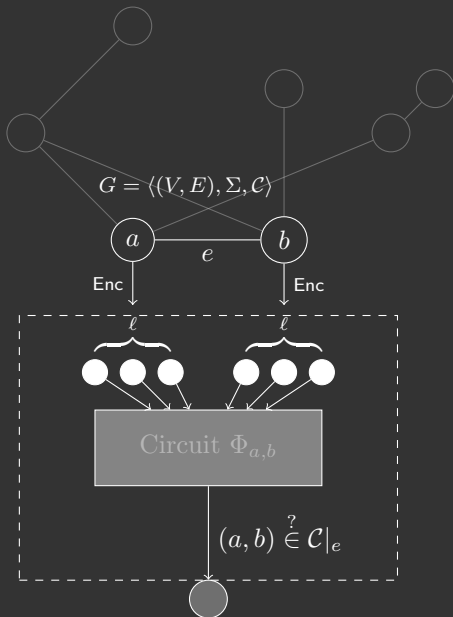
An error correcting code  $\text{Enc} : \Sigma \rightarrow \{0,1\}^\ell$  is said to have *relative distance*  $\rho$  if for every  $a_1, a_2 \in \Sigma$  with  $a_1 \neq a_2$ ,  $d_{\text{Hamming}}(\text{Enc}(a_1), \text{Enc}(a_2)) \geq \rho\ell$  (or equivalently,  $d_r(\text{Enc}(a_1), \text{Enc}(a_2)) \geq \rho$ ).

## >>> Composition: Step 1 -- Robustization



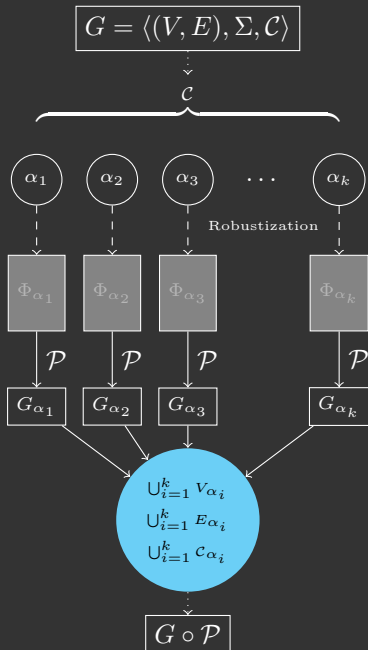
- \* Input: Constraint graph  $G$
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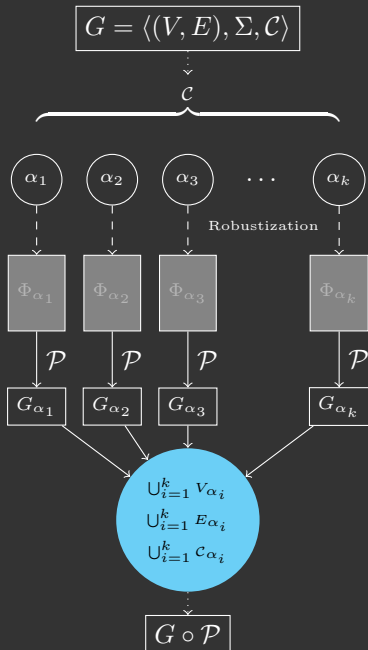
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  1. Linear dimension,  $\ell$
  2. Relative distance  $\rho > 0$
- \* Output: For each constraint in  $\mathcal{C}$ , a circuit on  $2\ell \in O(1)$  variables as shown on the left.

## >>> Composition: Step 2 -- Constraint graph composition



- \* Input: Boolean circuits  $\Phi_{\alpha_i}$  for each constraint  $\alpha_i \in \mathcal{C}$ , produced by the robustization
- \* Given an Assignment Tester  $\mathcal{P}$

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- \* Input: Boolean circuits  $\Phi_{\alpha_i}$  for each constraint  $\alpha_i \in \mathcal{C}$ , produced by the robustization
- \* Given an Assignment Tester  $\mathcal{P}$
- \* Output: The  $\Sigma_0$ -alphabet constraint graph encoding the original input constraint graph, written  $G \circ \mathcal{P}$

## >>> Alphabet Reduction Lemma

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There exists  $\beta_3 \in O(1) > 0$  such that

- \*  $\beta_3 \text{UNSAT}(G) \leq \text{UNSAT}(G \circ \mathcal{P}) \leq \text{UNSAT}(G)$
- \*  $G \circ \mathcal{P}$  can be computed in  $O(|G|)$  time, and  $|G \circ \mathcal{P}| \in O(|G|)$

## >>> Alphabet Reduction Lemma: Proof of complexity

- \* Each circuit  $\Phi_{\alpha_i}$  is over  $2^\ell$  nodes. Therefore, the circuits are simulated in  $2^{O(2^\ell)}$  time.
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- \* Likewise, union linearly-many constraint graphs (since  $|G \circ \mathcal{P}| \in O(|G|)$ ), so the overall time complexity is  $O(|G|)$ .

## >>> Alphabet Reduction Lemma: Proof of inequality (RHS)

We will now prove that  $\text{UNSAT}(G \circ \mathcal{P}) \leq \text{UNSAT}(G)$ .

- \* Let  $\sigma: V \rightarrow \Sigma$  be an optimal assignment for  $G$ , such that  $\text{UNSAT}_\sigma(G) = \text{UNSAT}(G)$
- \* We define an assignment  $\sigma': V' \rightarrow \Sigma_0$  on the variables of  $G \circ \mathcal{P}$  such that  $\sigma'([v]) = \text{Enc}(\sigma(v)) \in \{0,1\}^\ell$ .

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So, we have shown that

$$\text{UNSAT}(G') = \min_{\tilde{\sigma}'} \text{UNSAT}_{\tilde{\sigma}'}(G') \leq \text{UNSAT}_{\sigma'}(G') \leq \text{UNSAT}_\sigma(G) = \text{UNSAT}(G)$$

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It remains to show that  $\beta_3 \text{UNSAT}(G) \leq \text{UNSAT}(G \circ \mathcal{P})$  for some  $\beta_3 > 0$ .

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- \* However, since  $\text{Enc}$  has relative distance  $\rho > 0$ , we must change up to a fraction  $\rho/2$  of the bits in  $[v]$  or  $[w]$  (if not both) to satisfy  $c((v, w))$ .
  - \*  $\implies d_r(\sigma'|_{[v] \cup [w]}, \text{SAT}(\tilde{c}(e))) \geq \frac{1}{2} \rho = \frac{\rho}{4}$

## >>> Alphabet Reduction Lemma: Proof of inequality (LHS) Pt. 2

Recall that  $\mathcal{P}$  satisfies the soundness probability, with rejection probability  $\epsilon$ .

$$\begin{aligned}\text{UNSAT}(G') &= \text{UNSAT}_{\sigma'}(G') \\ &= \frac{1}{|E|} \sum_{e \in E} \text{UNSAT}_{\sigma'|_{V_e}}(G_e)\end{aligned}$$

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By Soundness



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THANK YOU FOR LISTENING! WE HOPE IT WAS FUN

HAPPY TO ANSWER ANY QUESTIONS