## **DFS: Depth-First Search**

- DFS is another popular search strategy.
- It can do certain things that BFS cannot do. We will discuss some of these algorithms in COMP 271 (so you cannot get rid of DFS after COMP171).
- DFS idea :
  - Whenever we visit a vertex v from another vertex u, we recursively visit a neighbor of v that has not been visited before until all neighbors of v have been visited. Then we backtrack (return) to u.

## **Algorithm**

#### Algorithm DFS(s)

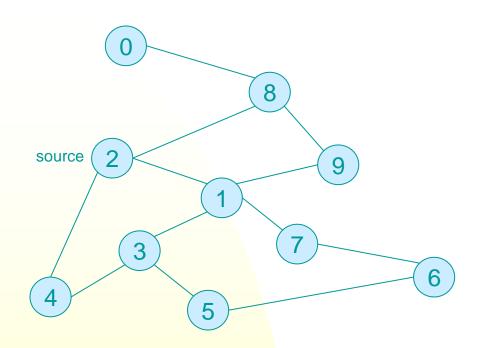
- 1. **for** each vertex v
- 2. **do** flag[v] := false; Flag all vertices as not visited
- 3. RDFS(s);

#### Algorithm RDFS(v)

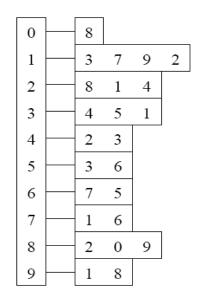
- 1. flag[v] := true;
- 2. **for** each neighbor w of v
- 3. **do if** flag[w] = false
- 4. then RDFS(w);

Visit *v*, and mark *v* as visited.

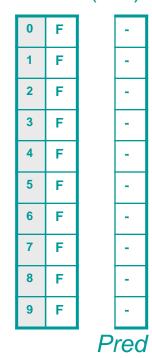
For each unvisited neighbor. make a recursive call *RDFS*(*w*).



#### **Adjacency List**

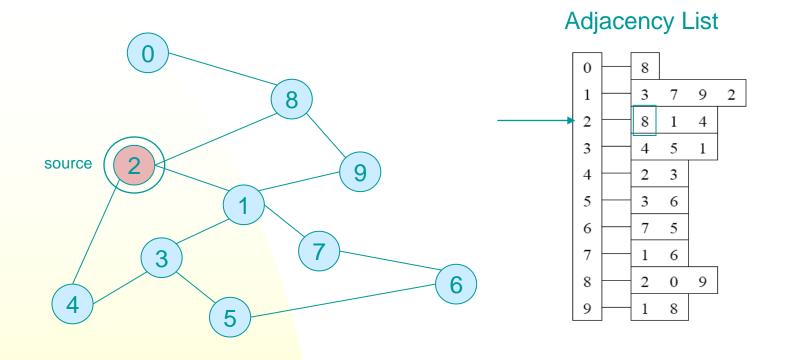


#### Visited Table (T/F)



Initialize visited table (all empty F)

Initialize Pred to -1



#### Visited Table (T/F)

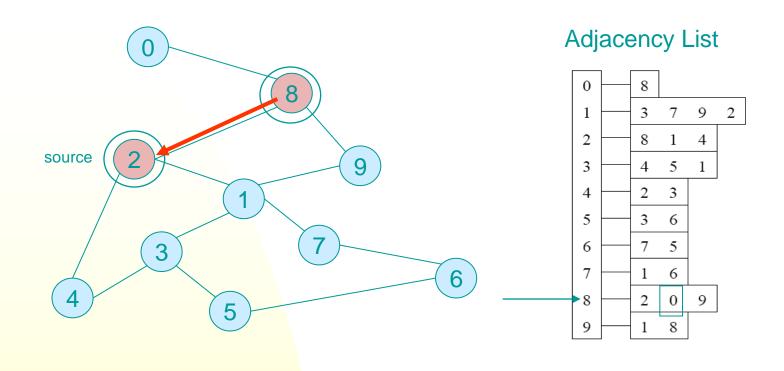
0	F		-
1	F		-
2	Т		-1
3	F		-
4	F		-
5	F		-
6	F		-
7	F		-
8	F		-
9	F		-
		P	rea

Mark 2 as visited

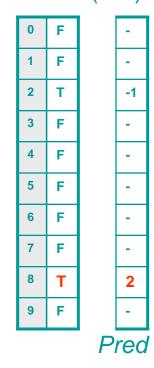
visit sequence= {2}

RDFS(2)

recursive call → RDFS(8)



Visited Table (T/F)

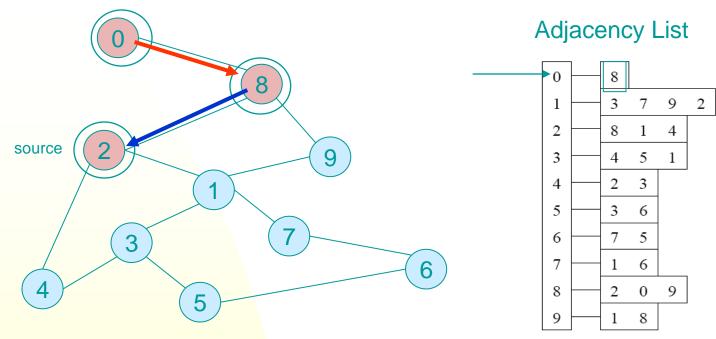


Mark 8 as visited

visit sequence= {2, 8}

Recursive calls

RDFS(2)
RDFS(8)
recursive call→RDFS(0)



visit sequence= {2, 8, 0}

#### Visited Table (T/F)

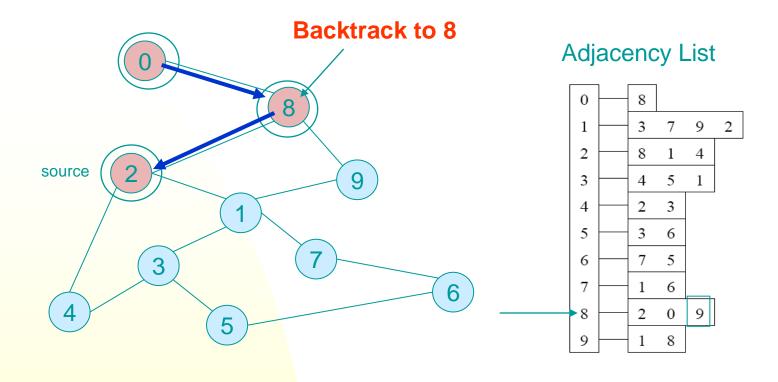
		-	
0	Т		8
1	F		-
2	Т		-1
3	F		-
4	F		-
5	F		-
6	F		-
7	F		-
8	Т		2
9	F		-
		P	rea

Mark 0 as visited

Recursive calls

RDFS(2) RDFS(8)

RDFS(0) -> no unvisited neighbor, return to (backtrack) RDFS(8)



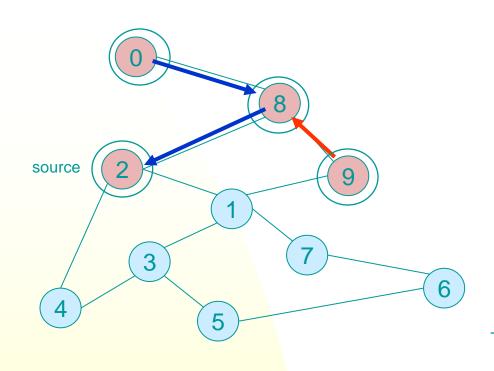
#### Visited Table (T/F)

0	Т		8
1	F		-
2	Т		-1
3	F		-
4	F		-
5	F		-
6	F		-
7	F		-
8	Т		2
9	F		-
		P	rea

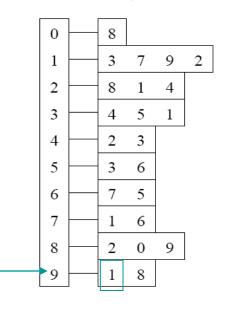
visit sequence= {2, 8, 0}

Recursive calls

RDFS(2)
RDFS(8)
recursive call→RDFS(9)



#### Adjacency List



#### Visited Table (T/F)

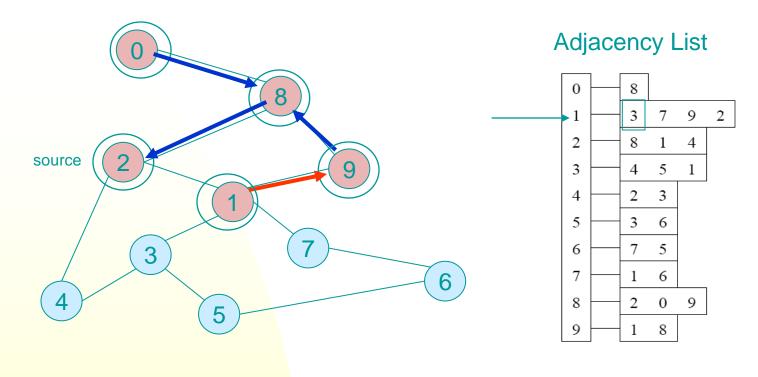
0	Т		8
1	F		-
2	Т		-1
3	F		-
4	F		-
5	F		-
6	F		-
7	F		-
8	Т		2
9	Т		8
		P	reo

Mark 9 as visited

visit sequence = {2, 8, 0, 9}

Recursive calls

RDFS(2)
RDFS(8)
RDFS(9)
recursive call→RDFS(1)



#### Visited Table (T/F)

0	Т		8
1	Т		9
2	Т		-1
3	F		-
4	F		-
5	F		-
6	F		-
7	F		-
8	Т		2
9	Т		8
		P	rea

Mark 1 as visited

visit sequence = {2, 8, 0, 9, 1}

RDFS(2)

Recursive

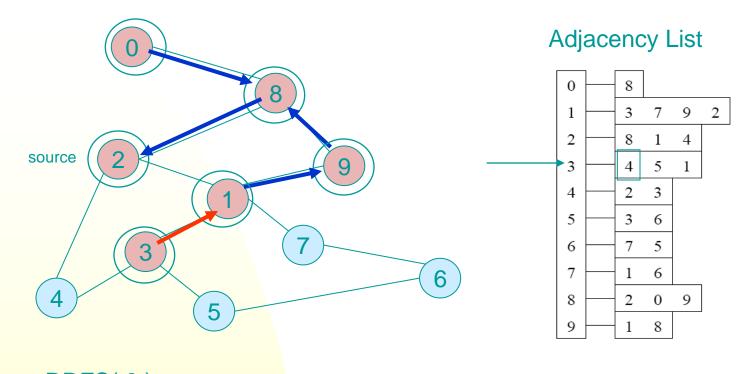
calls

RDFS(8)

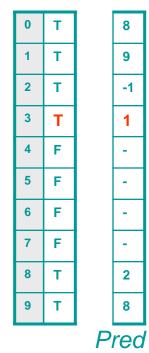
RDFS(9)

RDFS(1)

recursive call→RDFS(3)



Visited Table (T/F)



Mark 3 as visited

RDFS(2) visit sequence= {2, 8, 0, 9, 1, 3}

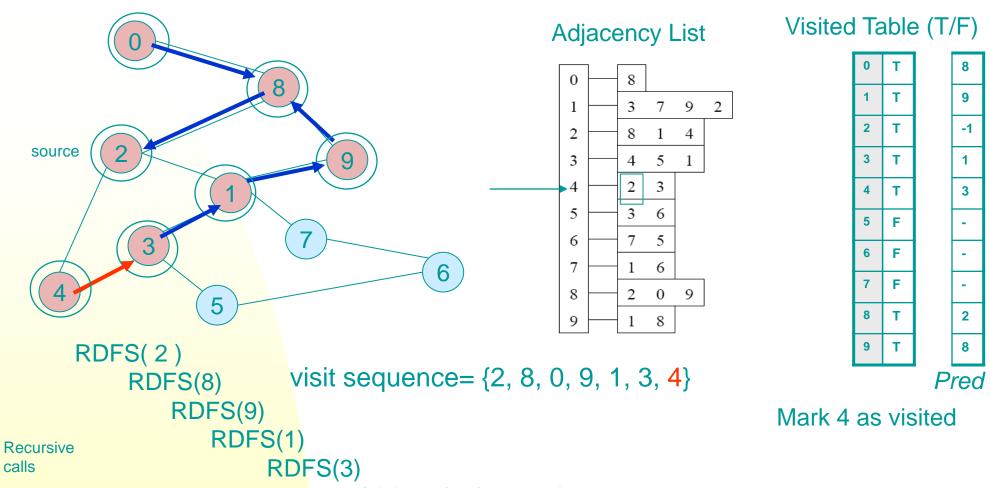
RDFS(1) RDFS(3)

RDFS(9)

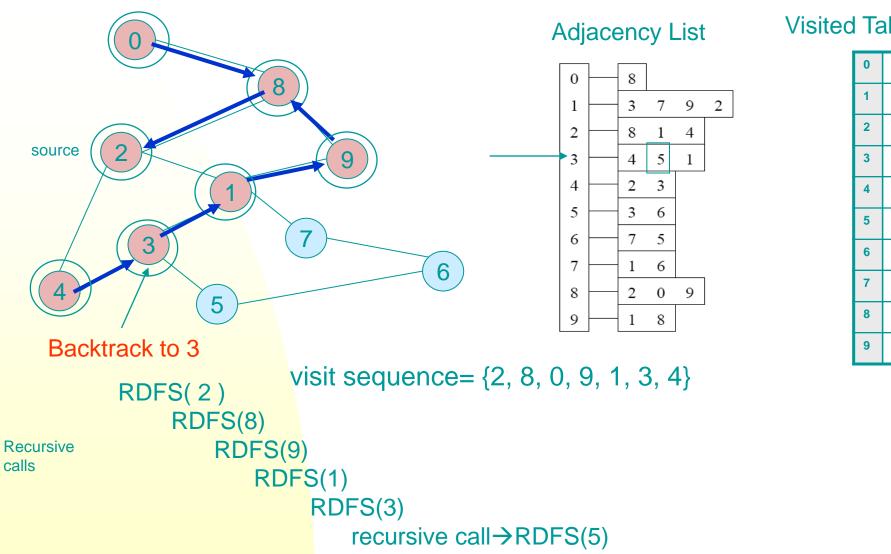
Recursive

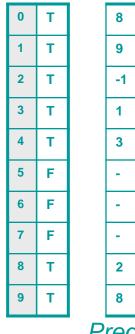
calls

recursive call→RDFS(4)

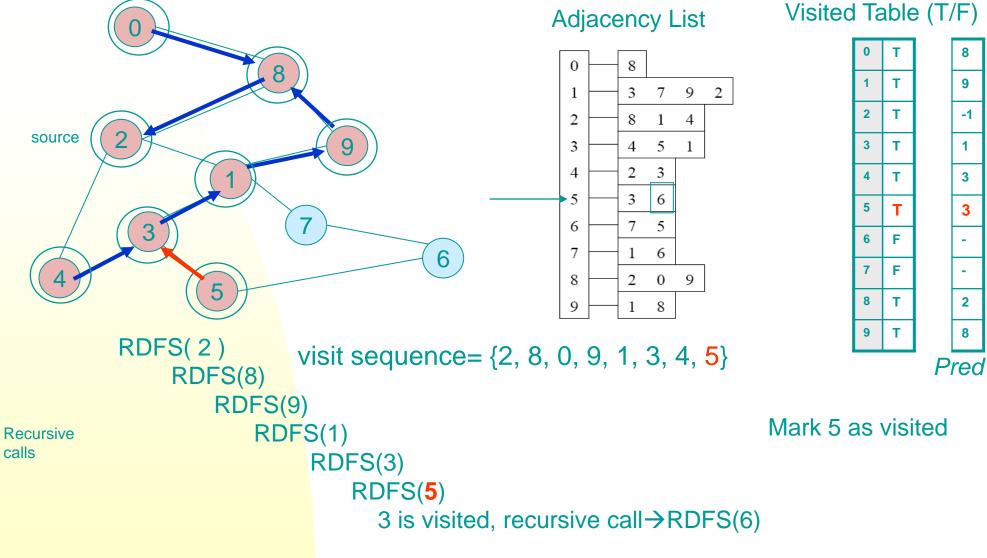


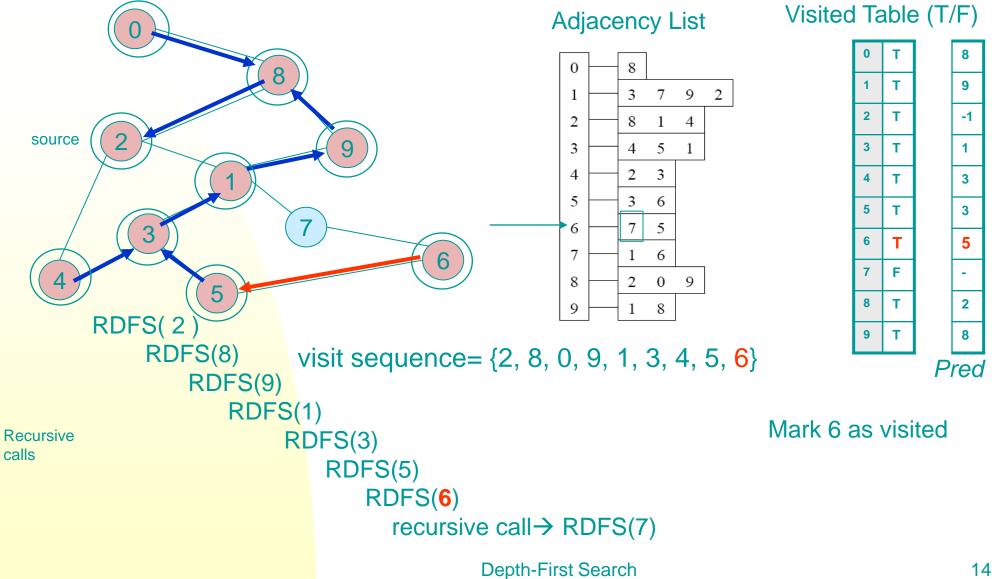
RDFS(4) → STOP all of 4's neighbors have been visited backtrack (return back) to call RDFS(3)

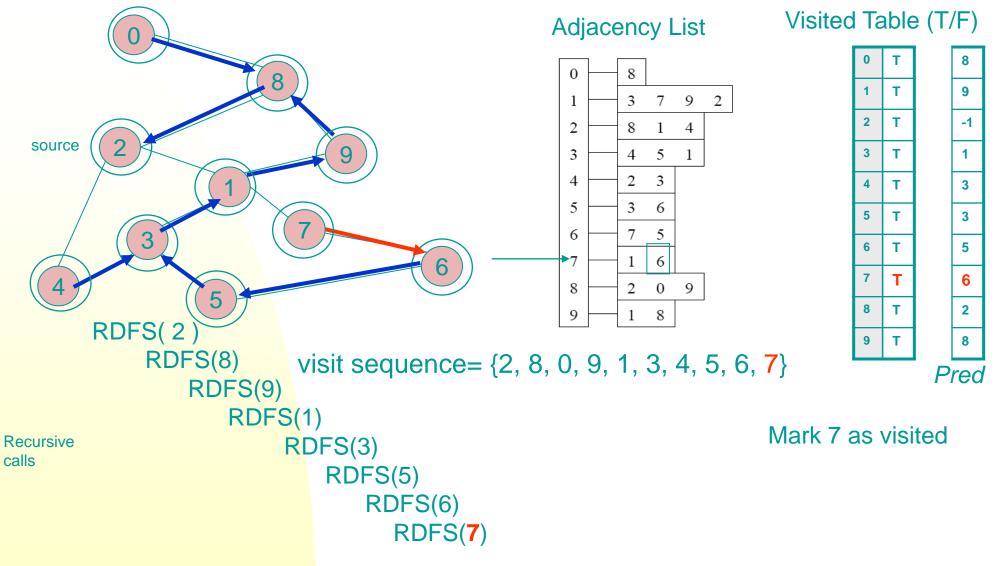


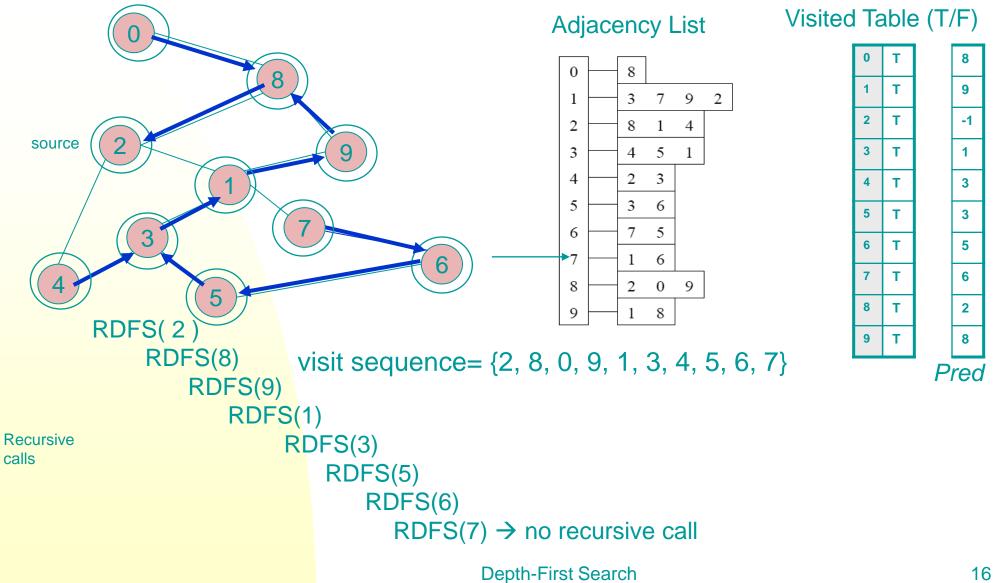


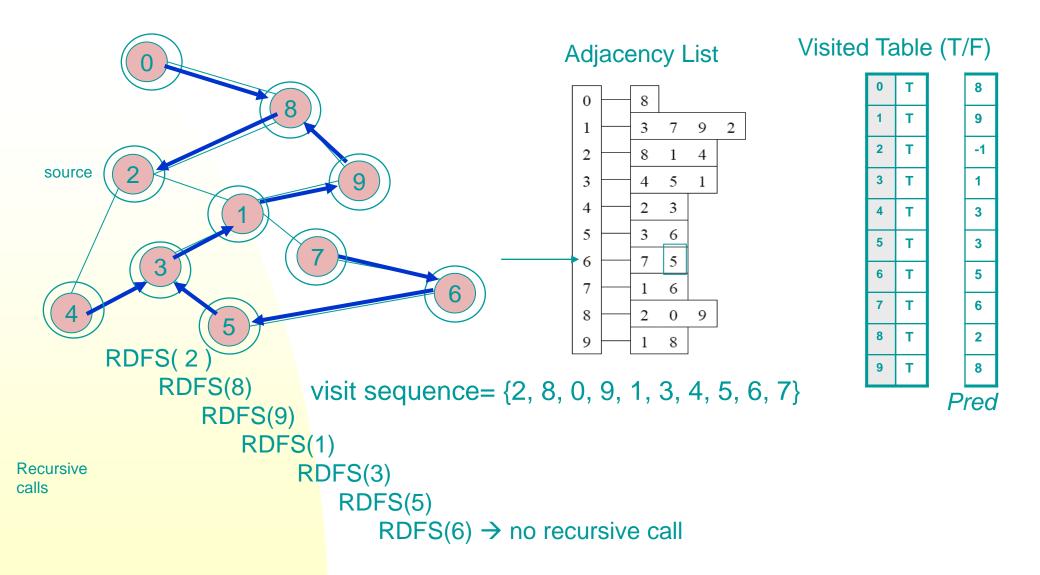
**Pred** 

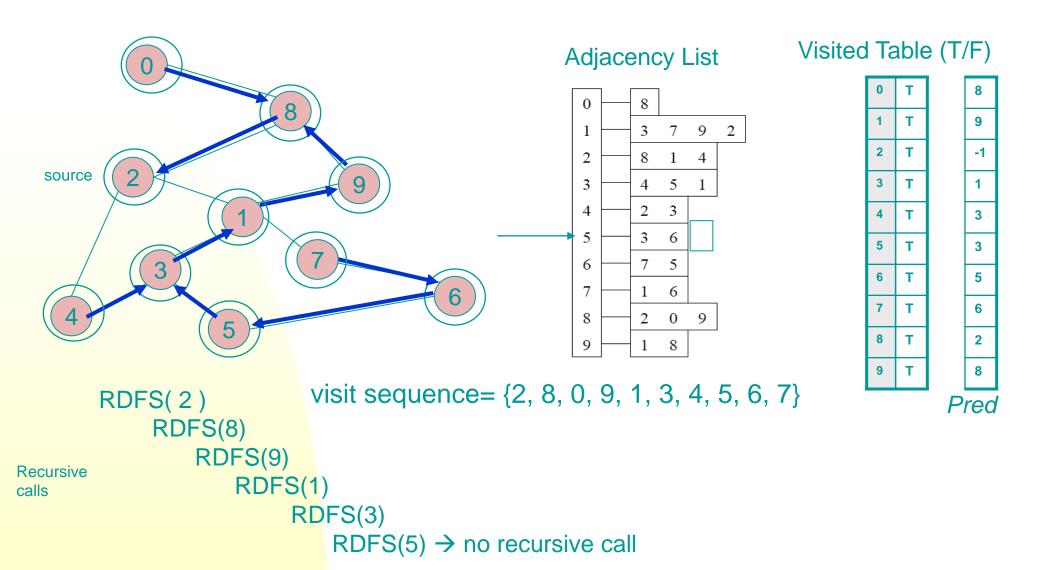


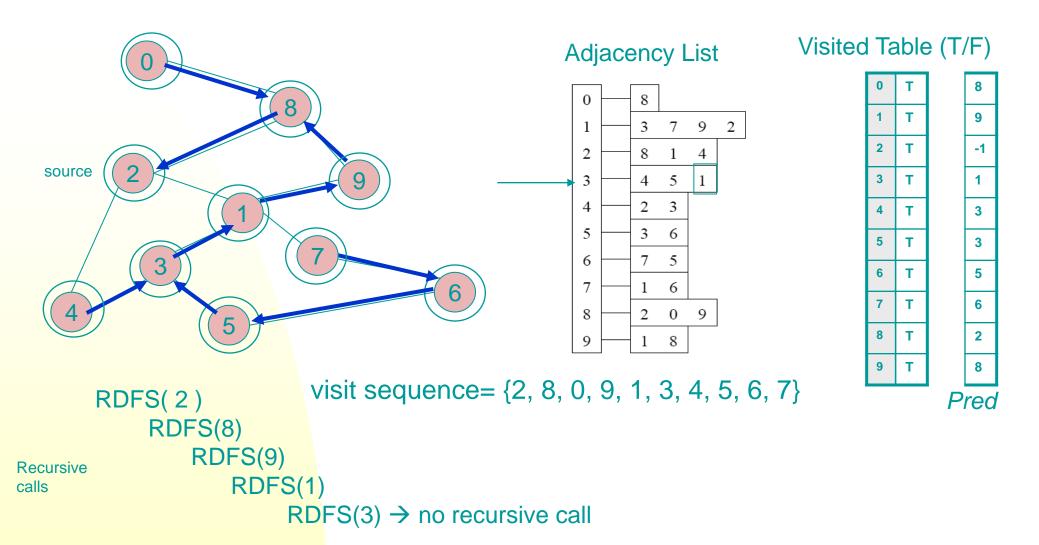


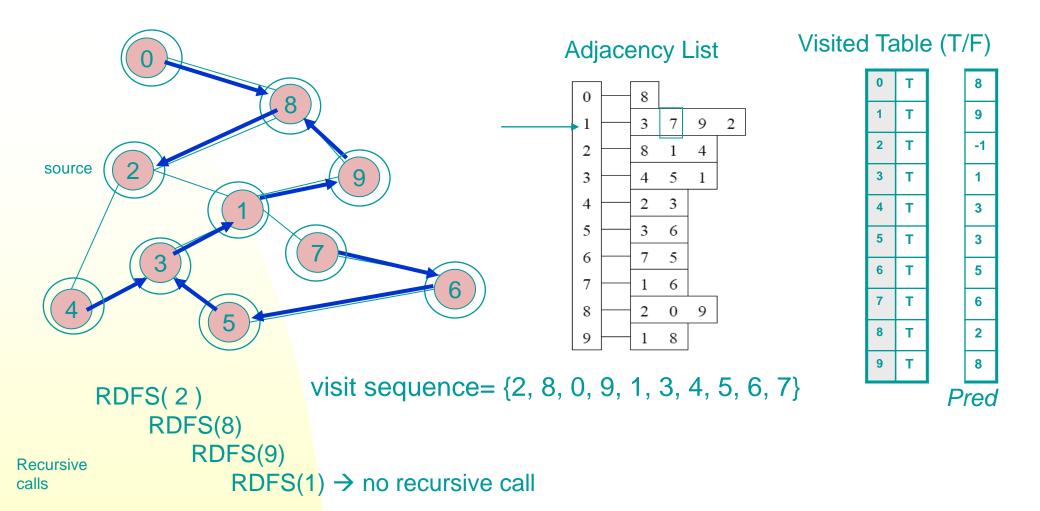


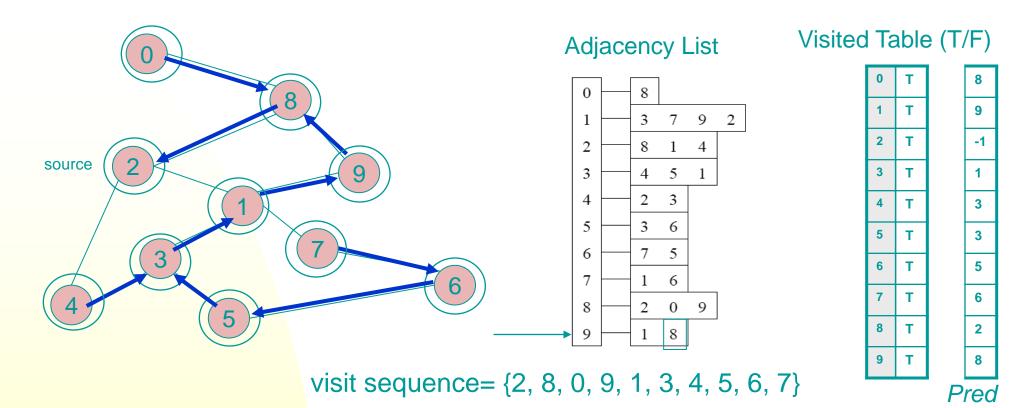








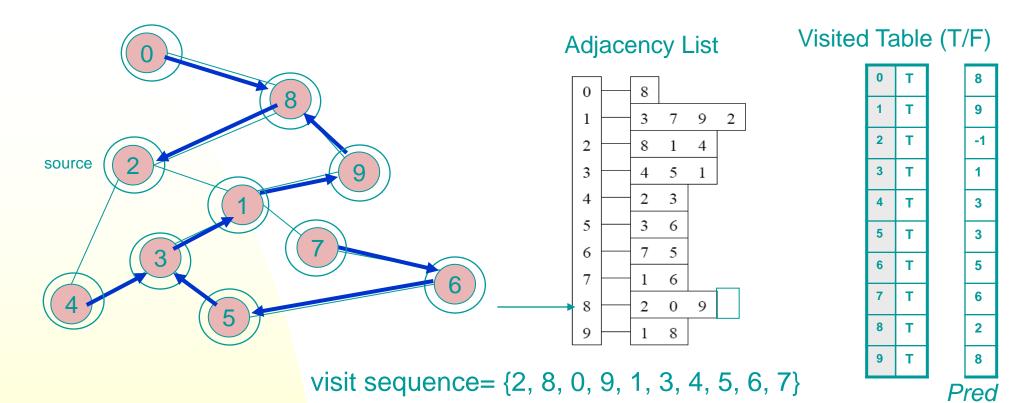




RDFS(2) Recursive calls

RDFS(8)

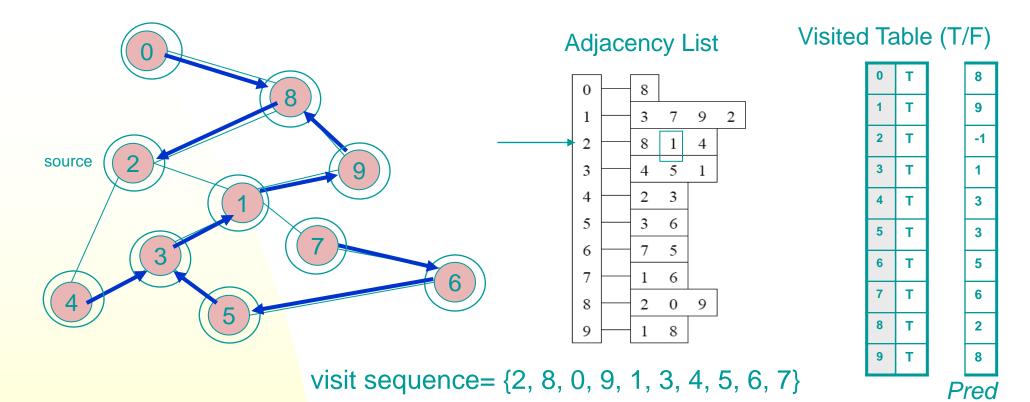
 $RDFS(9) \rightarrow no recursive call$ 



RDFS(2)

Recursive calls

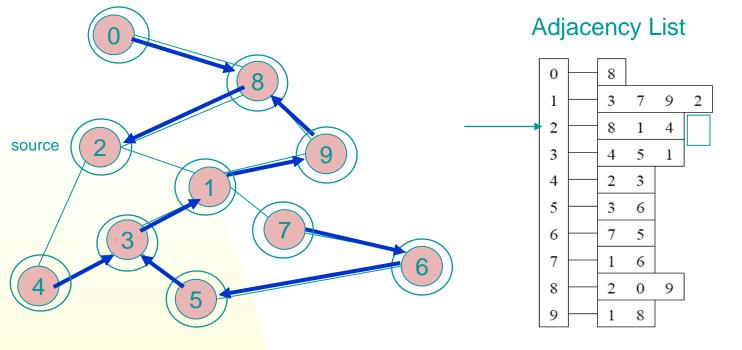
RDFS(8) → no recursive call



RDFS(2) → no recursive call

Recursive calls

#### Recover a path



#### Visited Table (T/F)

0	Т		8
1	Т		9
2	Т		-1
3	Т		1
4	Т		3
5	Т		3
6	Т		5
7	Т		6
8	Т		2
9	Т		8
Prea			

visit sequence= {2, 8, 0, 9, 1, 3, 4, 5, 6, 7}

#### **Algorithm** Path(w)

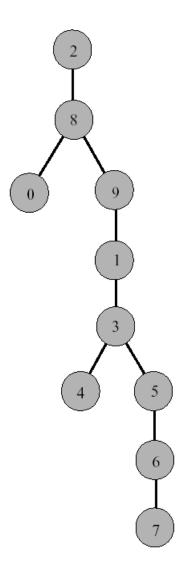
- 1. if  $pred[w] \neq -1$
- 2. then
- 3. Path(pred[w]);
- 4. output w

Try some examples.

- Path(0) ->
- Path(6) ->
- Path(7) ->

#### **DFS Tree**

The edges that we traverse during DFS (or the edges that we backtrack along) form a tree. We usually call the rooted version (rooted at the source) the DFS tree.



#### Running time analysis

The running time analysis is very similar to BFS. Let the graph be represented by an *adjacent list*, and *n* and *m* represent the number of vertices and edges in the graph respectively.

## Running time analysis

- Each (connected) vertex is visited EXACTLY one time → so there are O(n) recursive call.
- For a particular vertex v, (in the recursive call) we need to find all its neighbors. For adjacent list representation, it takes O(degree(v)).
  - Hence, the total number of time for all vertices is

$$\sum_{\text{vertex } v} O(\deg(v)) = O(2m) = O(m)$$

For adjacency list representation, the running time for DFS is

$$O(n) + O(n) + O(2m) = O(n+m)$$

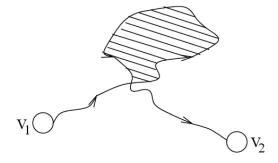
initialization

number of recursive call

find out all the neighbors

## Some applications of BFS/DFS -- Connectivity

- A graph is connected if and only if there exists a path between every pair of distinct vertices.
- If a path is not simple, then it contains cycles. Since any cycle can be bypassed, the non-simple path contains a simple path.



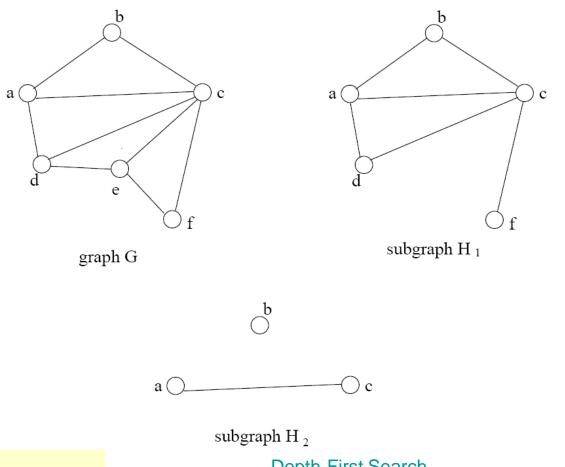
Therefore, a graph is connected if and only if there exists a simple path between every pair of distinct vertices.

## Some applications of BFS/DFS -- Connectivity

- One can use BFS or DFS to decide if a graph is connected. Run BFS or DFS using an arbitrary vertex as the source. At the end, if all vertices have been visited (all flags are marked 'T'), then the graph is connected. Otherwise, the graph is disconnected.
- The running time is O(n+m).

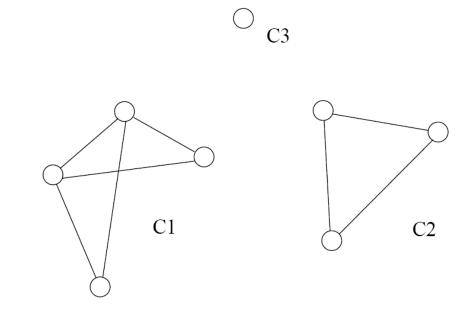
# Some applications of BFS/DFS – Connected Components

A graph  $H(V_H, E_H)$  is a subgraph of  $G(V_G, E_G)$  if and only if  $V_H \subset V_G$  and  $E_H \subset E_G$ .



## Some applications of BFS/DFS – Connected Components

- A connected component is a maximal connected subgraph of a graph.
- The set of connected components is unique for a given graph.



3 components: C1, C2, and C3

#### Some applications of BFS/DFS – Connected Components

**Algorithm** DFSConn(G) **Input:** a graph G **Output:** the connected components **for** each vertex v2. **do** flag[v] := false;———— For each vertex **for** each vertex v3. If not visited **do if** flag[v] = false  $\leftarrow$ 4. 5. then output "A new connected component:"; Call RDFS(v) 6.  $RDFS(v); \longleftarrow$ This will find Algorithm RDFS(v)all connected flag[v] := true;vertices to "v" output v; Basic DFS algorithm. 3. **for** each neighbor w of v**do if** flag[w] = false4. then RDFS(w);

5.

## Some applications of BFS/DFS – Connected Components

#### Running time analysis

Running time for each i connected-component

$$O(n_i + m_i)$$

- Question:
  - Can two connected components have the same edge?
  - Can two connected components have the same vertex?
- It follows

$$\sum_{i} O(n_{i} + m_{i}) = O(\sum_{i} n_{i} + \sum_{i} m_{i}) = O(n + m)$$