Collision Prevention in Distributed 6TiSCH Networks

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Using 6top Transaction Avoid Table Cell Buffer

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Simulator Results

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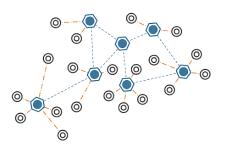
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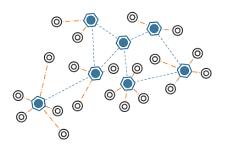
IoT & Wireless Sensor Networks

Network technologies and IoT.



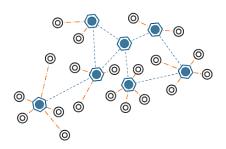
IoT & Wireless Sensor Networks

- Network technologies and IoT.
- WSN: standardization of IoT nodes communication.



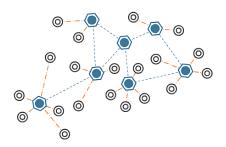
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IoT & Wireless Sensor Networks

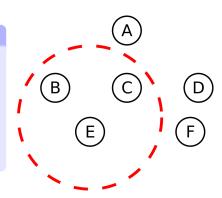
- Network technologies and IoT.
- ▶ WSN: standardization of IoT nodes communication.
- ▶ Low power consumption, low cost.
- ▶ IEEE802.15.4 one of the main standards of WSN.



IEEE802.15.4

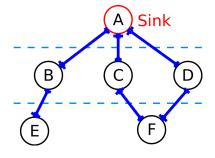
Converge Cast Structure

► Nodes radio ranges defines the neighborhood.



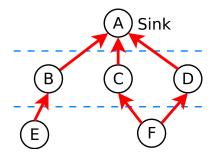
Converge Cast Structure

- ► Nodes radio ranges defines the neighborhood.
- Sink is selected.



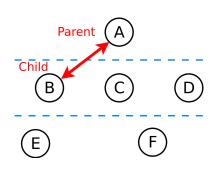
Converge Cast Structure

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Converge Cast Structure

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- Sink is selected.
- Packets are forwarded toward the sink.
- Communication pairs.



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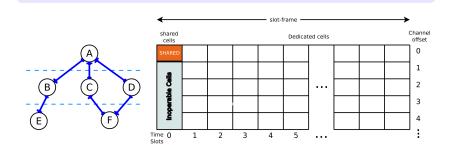
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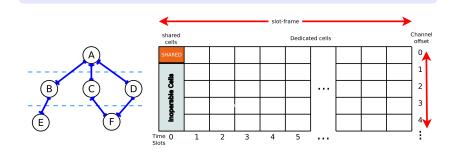
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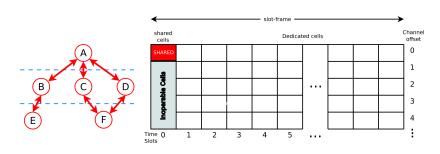
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- ► TSCH is an extension of the MAC layer of IEEE802.15.4.



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- ► Time/Frequency multiplexing of the bandwidth.

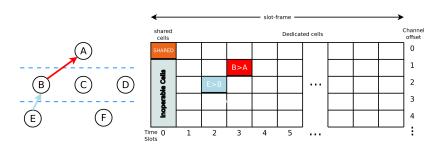


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- ► Shared cells/Dedicated cells..



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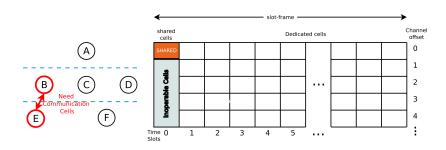
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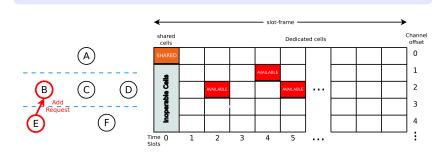
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- Time/Frequency multiplexing of the bandwidth.
- ► Shared cells/Dedicated cells..
- ▶ 6TiSCH operation sublayer 6top will manage the TSCH.

Cell Reservation Process

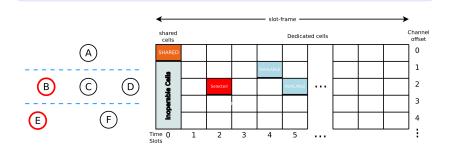
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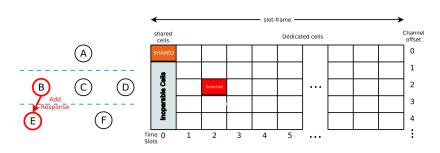
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- 2. Child node sends an Add request.



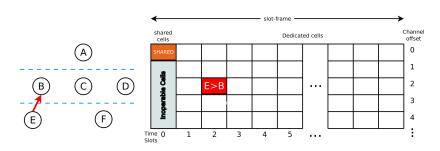
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- 3. Scheduling function decides which cells to be selected.
- 4. Parent node replies with an Add response.
- 5. Cell is added and communication start.



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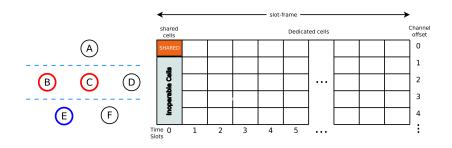
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Summary and Contributions

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Collision in Dedicated Cells

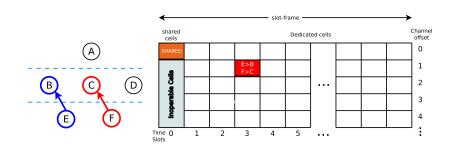
- Collision free Dedicated Cells?
- Neighbor nodes can select the same communication cell.



Project challenges & Objectives

Collision in Dedicated Cells

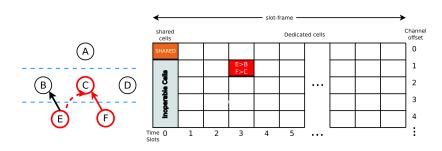
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Project challenges & Objectives

Collision in Dedicated Cells

- Collision free Dedicated Cells?
- Neighbor nodes can select the same communication cell.
- Collision at the reception Node.



Project Objectives

Reducing the collisions in TSCH dedicated cells.

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- Creating a flexible mechanism, compatible with all scheduling functions

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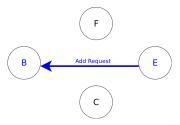
Using 6top Transaction

Why?

- Submitted in the shared slot.
- ► Contains the reserved cells.

How?

▶ The child node Sends an Add Request.



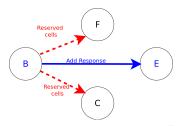
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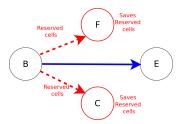
Using 6top Transaction

Why?

- Submitted in the shared slot.
- Contains the reserved cells.

How?

- The child node Sends an Add Request.
- ▶ The parent replies with the selected cells.
- ► The Neighbor nodes collects the reserved cells and save them.



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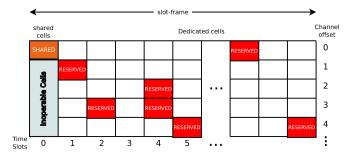
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Avoid Table structure and functioning

Avoid Table

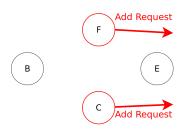
► The cells reserved by neighbors will be saved by a structure similar to TSCH table.



Avoid Table structure and functioning

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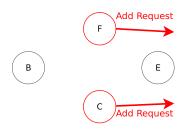
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- Scheduling function will avoid selecting cells found in this structure.



Avoid Table structure and functioning

Avoid Table

- ► The cells reserved by neighbors will be saved by a structure similar to TSCH table.
- Scheduling function will avoid selecting cells found in this structure.
- 6top will manage this table.



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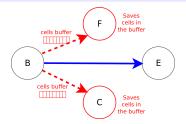
Cell Buffer

Why?

- Some of the 6top Transaction are lost.
- ▶ Number of the neighbors will not receive the reserved cells.

How?

Creating a cell buffer that will contain k reserved cells for each node.



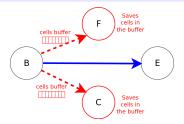
Cell Buffer

Why?

- Some of the 6top Transaction are lost.
- Number of the neighbors will not receive the reserved cells.

How?

- Creating a cell buffer that will contain k reserved cells for each node.
- Transmitting the cell buffer each time a cell is reserved.



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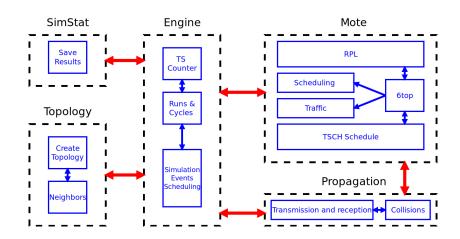
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Simulator Architecture



Simulation Parameters

Parameter	Value
Number of Motes	100
Number of cycles per run	1000
Number of runs per simulation	1000
Timeslot duration	10 <i>ms</i>
Slotframe length	101
Number of channels	16
Area	1Km $ imes 1$ Km
Topology constraint	\geq 3 neighbors with PDR 50 $\%$
Radio sensitivity	$-97~\mathrm{dBm}$
Radio range	100m
Traffic	1 packet/node each 10 cycles

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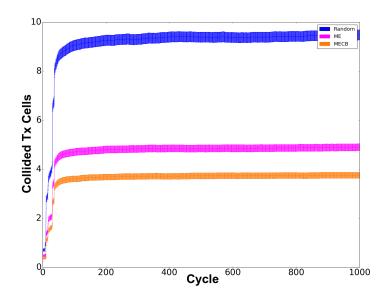
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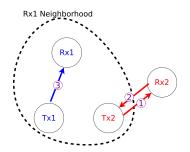
Collision reasons

▶ The lost 6top transactions.

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Collision reasons

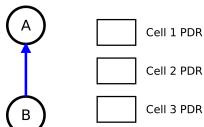
- ▶ The lost 6top transactions.
- Special Case That Induce Collisions.



Collision in Dedicated Cells

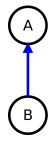
 Housekeeping approach and cell relocation.

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- ► Tx housekeeping.



Collision in Dedicated Cells

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0.8 Cell 1 PDR

0.8 Cell 2 PDR

Cell 2 FDF

0.8 Cell 3 PDR

Collision in Dedicated Cells

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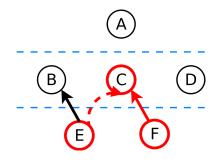


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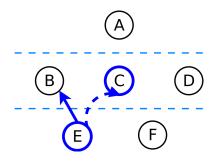
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0.3 Cell 3 PDR

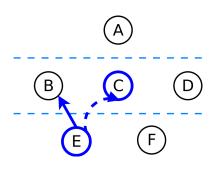
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- Tx housekeeping.
- Rx housekeeping.



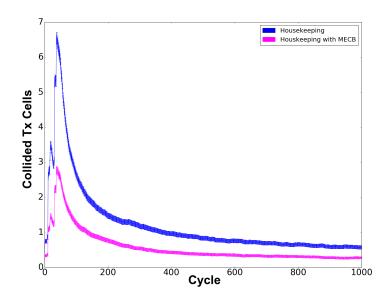
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- Housekeeping approach and cell relocation.
- Tx housekeeping.
- Rx housekeeping.
- Dealing with collisions after they occur. Good idea ?

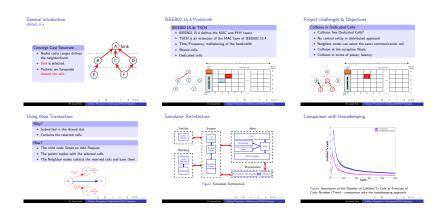


Comparison with Housekeeping



Summary

- Our implementation introduce no overhead in the network.
- ► The implementation achieved 60% reduction in the number of collided Tx cells and 70% reduction of the Collided Packets.
- ► The Combination of Our approach and Housekeeping accomplish an almost collision free dedicated cells.
- Outlook
 - Our goal is to reach a place were we have collision free network, using more complex methods.
 - Our prespective in this project was work on 6top, but our next steps is to study the effects of traffic in the protocols performances.



Thanks for your attention! Questions?