Ali Kuwajerwala

Actively seeking software engineering or research roles at this time.

○ github.com/alik-git □

in linkedin.com/in/alihkw ☐

647-787-3036

⊠ ali.kuwajerwala@mail.utoronto.ca 🖸

□ alihkw.com

EXPERIENCE

Robotics Researcher - UofT (Summer 2020)

NSERC USRA Position

Supervisor: Prof. Florian Shkurti

Result: Backwards Reachability Tutorial ☐ Goal: Safety guarantees for autonomous robots.

 Conducted research on reachability analysis, attempting to efficiently compute the safe exploration sets of autonomous robots using **Python**,
Matlab, and **C++** with **CUDA**.

Software Developer - EPSON (2018-2019) Robotics (Computer Vision / Evaluation Team)

- Developed 3D object detection and pose estimation technologies for commercial bin picking robots.
- Automated evaluation tasks using Python and Bash, substantially increasing (upto 5x) the amount of tasks run each day.
- Evaluated algorithm concepts and analyzed research results to diagnose and fix detection/estimation issues.

Teaching Assistant - UofT (2017-Present)

- Intro to Mobile Robotics (CSC477)
- Data Structures and Analysis (CSC263)
- Intro to Theory of Computation (CSC236)

EDUCATION

University of Toronto (2015 - 2020)

H.B.Sc. Computer Science Specialist

& Mathematics Major

CGPA: 3.63 - Dean's List Scholar

Award(s): NSERC Undergrad Student Research Award, value \$ 4500 for Robotics Research.

- UTM Robotics Club ☐

(Co-Founder / Head of Operations)

- Ongoing Project: Using robot cars to collect garbage on campus.
- UTM MCS Society (VP of Internal Affairs) □



PROJECTS

Feature Visualization for Neural Networks (Jupyter Notebook Tutorial): **○** □

- Built an interactive tutorial demonstrating how Neural Networks build up their understanding of images using **Tensor-Flow**, **DeepDream** and **Lucid**.
- Used as a workshop for the UTM ML Reading Group and the UTM Robotics Club.

Autonomous Driving Through Imitation Learning (Research Project under the UofT Robotics Institute): \bigcirc \square

- Used **PyTorch** and **ROS** to test a range of ML techniques implemented on a RC Car using the MIT Racecar platform.
- Performed adversarial attacks on the network and analysed its effects on performance.

NeoCirkuits (Android App): ♥ □

- Made a math (graph theory) based puzzle game for Android using Java in Android Studio.
- Implemented a fully featured creator tool allowing users to create their own levels.
- Collaborated with Professor Alex Rennet to use NeoCirkuits in the 'Introduction to Combinatorics' course at UofT.

SOFTWARE SKILLS

LANGUAGES Python, C/C++, Java

TECHNOLOGIES PyTorch, ROS, OpenAI

Gym, OpenCV, Android

Studio, CUDA