

Monday

• ASSIGNMENTS PAGE

• Quiz prep. #1 posted → for **FRI QUIZ**

• TUTORIALS start this week

• matlab warm-up worksheets posted → due **MON 14 JAN**

• submission via **math-gps** grading server

• access as Canvas quiz (auto-grades)

• **SPECIAL MATLAB HELP SESSIONS**

[math west] LAB:
$$\begin{array}{r} W \quad 15^{30} - 17^{00} \\ R \quad 10^{30} - 12^{00} \end{array}$$

• plus **COMPUTATIONAL OFFICE HOURS** (FRI + MON)

▼ What is the MACM 316 E-policy?

To minimize classroom distractions from electronic devices, the math department standard E-policy will be applied:

1. All course members are expected to **respect the audio & visual environment of their classmates**.
2. **No electronic devices** may be in use (ie **zero tolerance**) in the designated e-free zone (for B9200, this is **all seats except for the last two rows**) --- except by those students who have a contract for specific educational purposes. Unauthorized use of photographic/recording/transmission technology will be considered a violation of privacy and intellectual property.
3. Students who are permitted the use of electronic devices have agreed to **use them in a manner that minimizes the distraction to others**. Violation of this agreement invalidates permission. E-contracts are to be arranged using the Canvas survey tool.

Use of electronic devices in the classroom are limited to students who have filled out the E-contract ([link](#)). You must bring a copy of this E-contract to lecture each time you use your device --- you may keep a snapshot of your completed contract on your device, instead of paper copy.

In tutorials & office hours, E-contracts are not required for electronics running Matlab, or for coursework-related materials. Other uses of electronic devices are prohibited.

LAST DAY

- introduction to floating-point numerical computing
- **finite-precision**: truncation to 16-digits, rounding
- **finite-discretizations**: discrete **SAMPLING** of continuous functions
 - also numerically-approximated calculus operations
- **finite-operations**: controlled stopping of convergent iterative algorithms
- **THREE KEY QUESTIONS** of **COMPUTATIONAL LINEAR ALGEBRA + CALCULUS**
 - **ACCURACY**: error from exact calc \rightarrow lin alg
 - **EFFICIENCY**: cost in time/memory/cpu vs problem size
 - **ROBUSTNESS**: reliability across range of inputs

MATLAB DEMOS

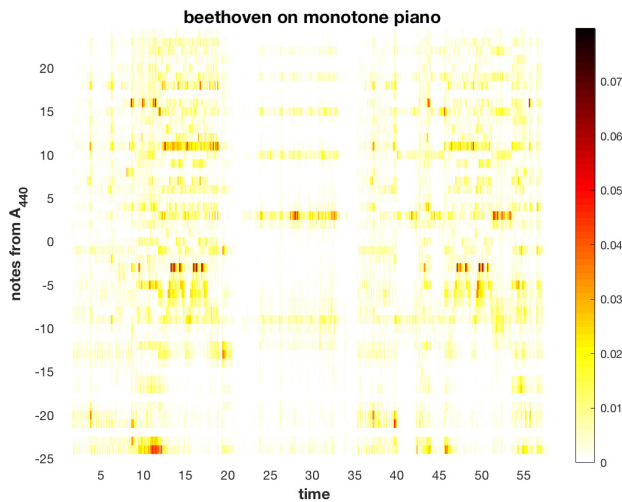
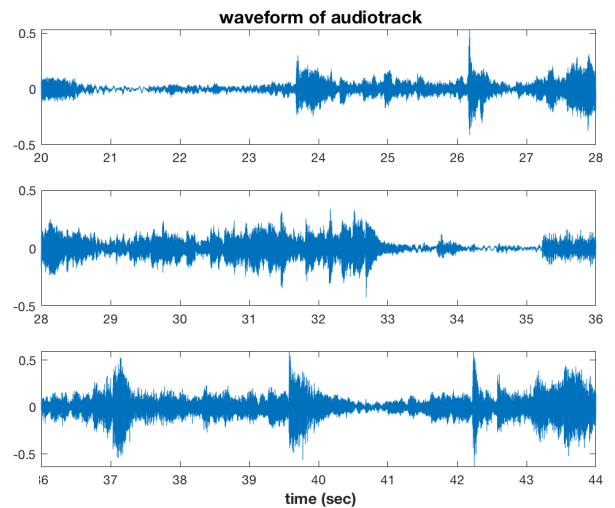
- in-class examples + warm-up for computing reports
- "killer" app \rightarrow special application examples

- 1) what \rightarrow are involved?
- 2) what are the numerical?
- 3) how do the results illuminate upon the?

FIRST SEMO

- analysis of piano music

44.1 kHz digital
audio track



SPECTROGRAM

60 sec = 11 pts

time intervals =

frequencies =

of notes =

- underlying algorithm:

()

SOLVING LINEAR SYSTEMS (BF, ch 6)

- Gaussian elimination (GE) for a 2×2 system

$$\begin{array}{l} ax + by = f_1 \\ cx + dy = f_2 \end{array} \quad \text{row operation} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{add} \rightarrow \begin{pmatrix} - & - \end{pmatrix} y = \begin{pmatrix} - & - \end{pmatrix}$$

$$\underline{-(ax + by)} = \underline{--f_2}$$

- solve for y :

$$y = \frac{f_2 - \frac{c}{a} f_1}{d - \frac{c}{a} b} = \frac{-}{-}$$

rule's

and

$$x = \begin{pmatrix} - & - \end{pmatrix}$$

- in summary, solution of y by $\begin{pmatrix} - & - \end{pmatrix}$ $\{+, -, \times, /\}$
- " of x by $\begin{pmatrix} - & - \end{pmatrix}$ $\left(\begin{array}{l} \text{1-var solve} \\ \text{using} \end{array} \right)$

DISCUSSION

- the GE solution for y involves $by = -$
 - \rightarrow GE algorithm when $\det =$
- but a theorem of lin alg says solution
 - ONLY when \det
 - \rightarrow GE theory when \det $\left(\begin{array}{l} \# \text{ of solutions} \\ \text{or} \end{array} \right)$

2) the GE solution for x involves

• what happens for $a =$? $y = \frac{by}{x} = \frac{1}{-} \left(- \right)$ } ok since b, c

→ GE as a formula or algorithm is formulated

2') GE does NOT lead to a algorithm - can equations + order of eliminating variables (choices for GE)

→ requires choices/decisions to avoid

... and we have addressed **finite-prec** arithmetic

3) formulas may not give results under **finite-prec** arithmetic
→ an issue for "scientific method" + reproducibility

4) how do we test for $\det =$ case ?

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

has the unique solution $(1, 1)$ - it is -

MATLAB + SOLVING $N \times N$ LINEAR SYSTEMS.

- there are many numerical approaches for solving

$$[A] \vec{x} = \vec{b}$$

- Matlab's simplest is "backslash"

$$\vec{x} = [A] \backslash \vec{b}$$

↳ a highly-evolved GE routine

- WHY alternative approaches?

- : what if $[A]$ is a $\begin{pmatrix} & \\ & \end{pmatrix}$ matrix?

- : some mathematical problems involve large matrices for which GE works

- matrices: solved by algorithms \rightarrow than GE

- solves: many different \rightarrow for same $[A]$

- WHY NOT use matrix \rightarrow ? (or Cramer's rule?)

$$\vec{x} = [A]^{-1} \vec{b}$$

↳

(A) in Matlab has extra overhead

\rightarrow numer meth. for solving linear systems do produce the inverse matrix as an

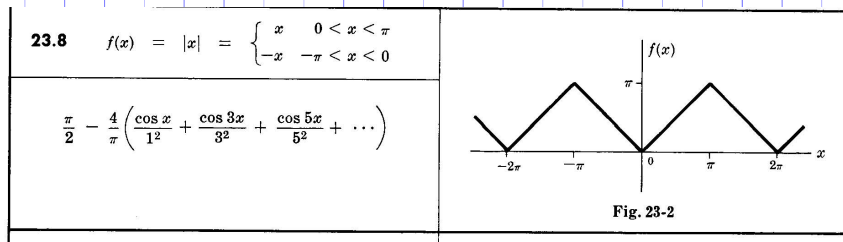
'SIZE MATTERS' SEMO

- a Fourier theorem: every 2π -periodic function $y(t)$ can be uniquely expressed as a trigonometric series

$$y(t) = \underbrace{\sum_{j=0}^{\infty} a_j \cos jt}_{\text{even symmetric part}} + \underbrace{\sum_{j=1}^{\infty} b_j \sin jt}_{\text{odd symmetric part}}$$

where a_j & b_j are Fourier coefficients of $y(t)$
(plus some convergence fine print)

• SAWTOOTH EXAMPLE



- NUMERICAL QUESTION: given N points $(t_j, y(t_j))$ for $0 \leq t \leq \pi$
find an N -term cosine series that satisfies these values.

• a matrix set of equations

$$\begin{bmatrix}
 1 & \dots & \cos kt_1 & \dots & \cos(N-1)t_1 \\
 \vdots & & \vdots & & \vdots \\
 1 & \dots & \cos kt_j & \dots & \cos(N-1)t_j \\
 \vdots & & \vdots & & \vdots \\
 1 & \dots & \cos kt_N & \dots & \cos(N-1)t_N
 \end{bmatrix}
 \begin{bmatrix}
 a_0 \\
 \vdots \\
 a_k \\
 \vdots \\
 a_{N-1}
 \end{bmatrix}
 =
 \begin{bmatrix}
 y_0 \\
 \vdots \\
 y_j \\
 \vdots \\
 y_{N-1}
 \end{bmatrix}$$

\uparrow $k=0$ ac \uparrow $k=N-1$ ac \uparrow N Fourier coeffs \uparrow N values $y_j = y(t_j)$

• Matlab linear algebra $[M] = [\cos kt_j]_{\substack{j=1 \rightarrow N \\ k=1 \rightarrow N}}$ $\substack{\text{rows} \\ \text{cols}}$

$$\vec{b} = \begin{pmatrix} y_0 \\ \vdots \\ y_{N-1} \end{pmatrix}$$

and $\vec{a} = [M] \setminus \vec{b}$

• numerical experiment

1) choose N values $t_j, j=1 \rightarrow N$

a) uniformly-spaced

b) random.

2) solve for \vec{a}

3) check residual error: $[M]\vec{a} - \vec{b}$ (zero for perfect world)



muraki

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