

WEDNESDAY

- TUTORIALS this week
- QUIZ on Friday

LAST DAY

- LU factorization is the mathematical formula representing a GE algorithm
- Matlab's lu command uses partial pivoting

$$[L][U] = [A]$$

- structure of $[L]$: s on u - diag
- LU allows linear solve by 2 $+ O(n)$ flops.

$$[L]\vec{b} = [P]\vec{b} + [U]\vec{x} = \vec{b}$$

- applications of LU: multiple solves, pre-computing α det
- special matrices & non-GE linear solves
 - DIAGONALLY-DOMINANT matrix: robust, no-piv GE
 - CHOLESKY factorization
 - SPARSE & tridiagonal matrices.

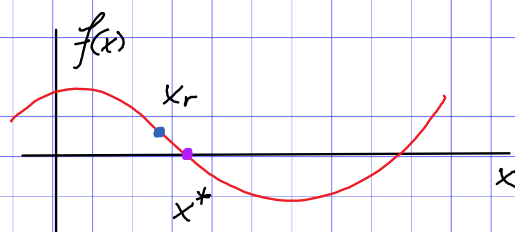
SOLUTION of NONLINEAR EQUATIONS (ch 2)

- ——— function of one or more variables with an

we want

to find x^*

with $f(x^*) = 0$,



involves

$$x_r \rightarrow x^* \quad f(x_r) =$$

→ when x_r is to ,
 $f(x_r)$ is to

- additional advantages from functions

REVISIT NEWTON'S METHOD from COLC 1.

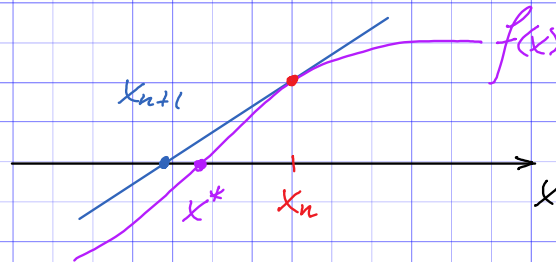
- for $f(x)$ near

$$\text{lin approx of } f(x) = \quad + \quad () (-)$$

graph is

to $f(x)$

- IEA for Newton's meth.



- if x_n is a for x^* , then x_{n+1} is a potentially

since $(x_{n+1}, 0)$ is on

$$f(x_n) + f'(x_n)(x_{n+1} - x_n) =$$

- Newton's update: solve for x_n .

If we keep repeating this process, we obtain a sequence of approximations $x_1, x_2, x_3, x_4, \dots$ as shown in Figure 3. In general, if the n th approximation is x_n and $f'(x_n) \neq 0$, then the next approximation is given by

2

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

If the numbers x_n become closer and closer to r as n becomes large, then we say that the sequence *converges* to r and we write



$$\lim_{n \rightarrow \infty} x_n = r$$

- $\sqrt{}$ example, $f(x) = x^2 - a = 0$

>> NMsqrt

a =

3

$$x_{n+1} = x_n - \left(\frac{x_n^2 - a}{2x_n} \right)$$

| | | |
|---|------------------------|--------------------|
| 0 | 1.0000000000000000e+00 | -0.732050807568877 |
| 1 | 2.0000000000000000e+00 | +0.267949192431123 |
| 2 | 1.7500000000000000e+00 | +0.017949192431123 |
| 3 | 1.732142857142857e+00 | +0.000092049573980 |
| 4 | 1.732050810014728e+00 | +0.000000002445850 |
| 5 | 1.732050807568877e+00 | +0.000000000000000 |

zeros after .
" " " "

• two observations from this demo

• need a

• when x_n is

, NM is

this is
tricky

$$\text{error}_{k+1} = O(\quad)$$

CONVERGENT

"

of # of

in error"

• NM is NOT a

|

ALGORITHM

$$| = |f(x_n)| < \quad \text{STEP}$$

parameter

• introductory comments & questions

• NM is NOT a - routine (need

• buggy NM code can still

• NM can completely

• can give

• might converge

• can converge

} choose better

(-order zero)

KEY IDEA is solving of

MORE THAN ONE VARIABLE

$$\vec{F}(\vec{x}) = \begin{pmatrix} f_1(x_1, x_2, \dots, x_N) \\ \vdots \\ f_N(x_1, x_2, \dots, x_N) \end{pmatrix} = \begin{pmatrix} f_1(\vec{x}) \\ \vdots \\ f_N(\vec{x}) \end{pmatrix}$$

• N -variable linear approximation at \vec{y}_n

$$\text{linear approx of } F(\vec{y}) = \vec{F}(\vec{y}_n) + \underbrace{\begin{bmatrix} J \end{bmatrix}}_{\text{Jacobian matrix}} (\vec{y} - \vec{y}_n)$$

$$\begin{matrix} j=1 \\ \vdots \\ j=N \end{matrix} \begin{matrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_N} \\ \vdots & & \vdots \\ \frac{\partial f_N}{\partial x_1} & \dots & \frac{\partial f_N}{\partial x_N} \end{matrix} \begin{matrix} k=1 \\ \vdots \\ k=N \end{matrix} = \left[\frac{\partial f_j}{\partial x_k} \right]$$

Jacobian matrix

• N -variable vector update: solve for \vec{y}_{n+1} when
LIN APPROX = 0

$$\vec{y}_{n+1} = \vec{y}_n - \begin{bmatrix} J \end{bmatrix} \backslash \vec{F}(\vec{y}_n)$$

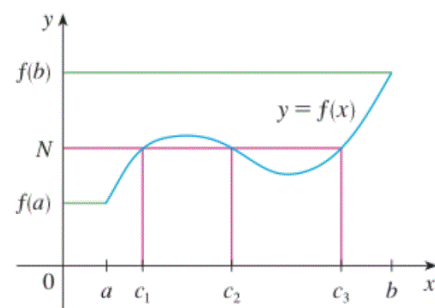
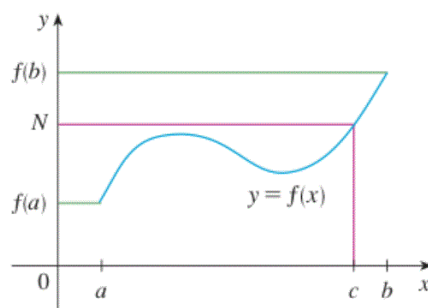
↗ backslash!

FINDING ZEROS

- key question: *for what x does $f(x) = 0$?*
- also: are there any zeros at all?
if more than ONE, how many?
or which one might we want?
- there is NO GENERAL ALGORITHM
 - need some human thought: THINK
PLOT
Know your function
- special case: N -degree polynomials
of zeros = N
(including multiples)

10 The Intermediate Value Theorem Suppose that f is continuous on the closed interval $[a, b]$ and let N be any number between $f(a)$ and $f(b)$, where $f(a) \neq f(b)$. Then there exists a number c in (a, b) such that $f(c) = N$.

The Intermediate Value Theorem states that a continuous function takes on every intermediate value between the function values $f(a)$ and $f(b)$. It is illustrated by Figure 8. Note that the value N can be taken on once [as in part (a)] or more than once [as in part (b)].





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