Demand Forecasting & Rebalancing Planner

Problem & Context

Stations swing between **empty** (no bikes) and **full** (no docks). Today, rebalancing is mostly reactive. We need a **forward-looking planner** that forecasts demand, sets per-station targets, and generates **shift plans and van routes** to keep availability within SLA while minimizing ops cost.

Goals & KPIs

- Forecast accuracy: median MAE ≤ 2 bikes per station-hour (or MAPE ≤ 20% where volume is sufficient).
- Ops efficiency: km driven per resolved stockout ↓ 20%; tasks/van/hour ≥ baseline.
- Guardrails: on-time shift completion ≥ 95%; plan changes (replans) ≤ 2 per van per shift.

Scope & Users

- Users: Rebalancing Leads (plan), Dispatch (assign & monitor), Van Teams (execute), PMs/City Partners (policy).
- Inputs: minute-level availability timeseries, historical pickup/drop patterns, station metadata (capacity, location), calendar (weekday/holiday), major events, and weather.
- Outputs: hourly demand forecasts; station target fill % curves; pickup/drop tasks (quantity, time window); van routes with ETAs and service times; a risk heatmap for the next 2–24 hours.

• Out-of-scope (v1): multi-city simultaneous optimization; dynamic rider incentives (handled in a separate PRD but supported as a fallback).

Target Policy & Event Semantics

- Target fill %: desired bikes/docks per station by hour (e.g., 35–65%).
- Safety stock: extra buffer during rush hours or weather events.
- Deficit/Surplus: forecasted inventory vs target; negative → pickup needed, positive → drop needed.
- **Task:** a pickup or drop action with a time window, a quantity, and a priority derived from risk of stockout/full.

Implementation Guide (v1)

1) Demand Signals

- Aggregate pickups and returns to hourly net flow per station.
- Create features: hour-of-day, day-of-week, holidays, lagged flows (1, 7, 14-day), recent trend, nearby station pressure, precipitation, temperature bands, wind, and known events.
- Maintain **station clusters** (e.g., 300–800m radius or neighborhood) for datapoor stations.

2) Forecasting Service

- **Granularity:** station-hour. **Horizon:** next **2–24 hours** rolling.
- Modeling approach:
 - Baseline: seasonal-naïve + moving-average for transparency.
 - Primary: gradient-boosted or generalized additive model for non-linear effects.
 - Fallback: cluster-level forecast scaled by station capacity for sparse stations.
- Retraining cadence: nightly with weekly hyperparameter refresh; nowcast correction every 15 min using latest telemetry.

 Monitoring: per station MAE/MAPE dashboards; drift alarms when error doubles vs trailing median.

3) Target Policy Engine

- Start with policy tables: fill bands by **capacity tier** (e.g., small <20, medium 20–35, large >35) and **hour segment** (night, AM peak, mid-day, PM peak).
- Adjust dynamically for weather/events: increase safety stock during heavy rain or city events; relax at night.
- Output hourly target curves for each station for the next 24h.

4) Task Generation

- Convert forecasted inventory vs targets into pickup/drop quantities per hour.
- Merge tasks within overlapping windows to reduce touch count.
- Add priority: risk score from (probability × impact) of stockout/full, proximity to critical corridors, and station criticality (ridership, capacity).
- Enforce **operational constraints:** van capacity, bike handling rate (e.g., 2–3 bikes/min), station service time, and depot start/end rules.

5) Route Planning (Planner)

- Heuristic v1: greedy sweep or nearest-neighbor with look-ahead for time windows; respect van capacity; avoid criss-crossing; consolidate clusters.
- Replanning triggers:
 - Forecast error beyond threshold at a critical station.
 - Van running >15 min behind schedule.
 - New high-severity event from monitoring.
- Outputs per van: ordered stop list (station → quantity → ETA → service time), total distance, slack time, and a confidence score.

6) Dispatcher & Driver Experience

• Planner Console: route map, Gantt timeline per van, "what-if" slider (e.g., add 1 van), and risk heatmap (next 2–6–12 hours).

- Driver App: turn-by-turn to next stop, barcode/NFC bike count confirmation, quick "partial complete" action, photo upload for blocked docks, and offline mode.
- **Feedback loop:** drivers confirm actual quantities/time; system updates station inventory immediately and logs plan adherence.

7) Feedback & Learning

- Plan Quality Score: (stockout risk reduction per km) × (on-time stops) × (driver adherence).
- Use feedback to retrain: penalize tasks that routinely under/over-deliver; upweight stations with chronic inaccuracies.
- Weekly calibration of target policy with PM/Ops review.

8) Reliability & Quality

- Data sanity: non-negative inventories; inventory ≤ capacity; sudden jumps flagged.
- **Degradation mode:** if forecasts are stale, fall back to cluster averages and **myopic** routing based on current deficits.
- Retrospective store: keep forecasts, plans, and actuals for audit and simulation.

Expected Behavior (End-to-End)

- 1. **Morning rush forecast:** System predicts high outbound flow from residential stations 07–09; targets increase safety stock at origins and dock availability at downtown destinations; **tasks** created for pre-peak drops at origins and pickups at destinations.
- 2. **Storm approaching:** Rain signal raises safety stock and widens time windows; planner shifts more vans to sheltered depots and focuses on stations with historically sharp demand swings in rain.
- 3. **Event spike:** Near a stadium, demand spike raises risk; planner auto-inserts a pickup-drop loop between two nearby stations; dispatch sees route change with explanation.

- 4. **Driver partial complete:** A dock is unexpectedly full; driver can only drop half the planned bikes; app suggests nearest alternative station and updates plan.
- 5. **Forecast miss:** Error crosses threshold for a critical station; system triggers **mid-shift replanning** for the nearest van and bumps priority.
- 6. **Capacity breach:** Planned pickup would exceed van capacity; planner automatically inserts an intermediate drop to the nearest deficit station.

Experiment & Analysis Plan

- Design: Cluster-level A/B (randomize neighborhoods). Treatment = forecasting + planner; Control = current manual planning. Run 4-6 weeks.
- **Primary metric:** stockout minutes/station/day.
- **Secondary:** forecast MAE/MAPE, rides completed, ops km/ride, tasks/van/hour, driver adherence.
- Stratification: capacity tiers, ridership bands, weather regimes.
- Success criteria: ≥20% reduction in stockout minutes with neutral/favorable ops cost; no increase in alert fatigue.
- Guardrails: task replan rate, driver overtime, missed time windows.

Risks & Mitigations

- **Model drift / special events:** add event calendar hooks; human override for one-off closures; weekly error review.
- Over-optimization (fragile plans): cap replan frequency; keep buffers; prefer robust sequences over perfect distance minima.
- **Data latency:** show forecast freshness; fall back to myopic rebalancing when stale.
- **Driver adoption:** keep steps minimal; support partial completes and quick notes; ride-along training in week 1.
- **Equity/compliance:** ensure underserved areas aren't systematically deprioritized; add fairness constraints to the planner.

Trade-offs

| Choice | Pros | Cons | Use When |
|----------------------------|-------------------|----------------------|----------------------------------|
| Simple hourly models | Fast, explainable | Misses fine patterns | Early rollout, low data volume |
| Advanced ML (GBMs/GAMs) | Higher accuracy | More tuning | Medium-large networks |
| Station-level routing | Tailored | Fragmented plans | Few vans, compact zones |
| Cluster routing | Efficient | Less precise | Many stations, longer drives |
| Static shift plan | Predictable ops | Lower resilience | Stable demand, low incident rate |
| Rolling replan | Resilient | Operational churn | Volatile demand, many incidents |

Rollout Plan

- 1. **Weeks 1–2:** Stand up baseline forecasts; publish risk heatmap and target curves; dry-run plans (no driver dispatch).
- 2. **Week 3:** Pilot with 2–3 vans in mixed neighborhoods; driver app soft-launch.
- 3. **Weeks 4–6:** City-wide treatment clusters; enable controlled replans; start A/B measurement.
- 4. **Week 8:** Tune targets and buffers; expand to full fleet; integrate with Monitoring alerts for proactive inserts.
- Week 10+: Add fairness constraints and cost-aware multi-objective optimization.

Engineering Work Pack

- **Forecasting Service:** feature pipeline, training jobs, rolling inference, accuracy dashboards, drift alarms.
- **Policy Engine:** target fill curves, safety stock rules, fairness constraints, event/weather modifiers.

- **Planner/Solver:** task builder, van constraints, heuristic routing, replan triggers, plan quality scorer.
- **Dispatcher Console:** map + Gantt, what-if tools, explanations, manual overrides, export.
- **Driver App:** stop list, confirmations, partial completes, offline cache, incident reporting.
- **Simulation Harness:** backtests and what-ifs (add vans, change targets), with standardized reports.
- **Integrations:** mapping/ETA, depot/warehouse systems, alerting from Monitoring.

GenAl Assist (workshop-friendly prompts)

- **Forecast coaching:** "Explain which features matter most for predicting net flow at a station and why. Propose a simple, interpretable model and how to validate it."
- Policy drafting: "Given morning commuter patterns and capacity tiers, draft target fill % curves by hour with safety stock for rain and events."
- **Plan explanation:** "Turn this route plan into a driver brief with plain-language rationale for each stop and what success looks like."
- **Daily ops brief:** "Summarize the top 15 at-risk stations for the next 6 hours and the planned actions; flag where van capacity is insufficient and suggest alternatives."

Roadmap impact: With proactive forecasts and executable plans, availability improves **before** outages occur. This planner feeds **Incentives** (when vans can't cover risk) and informs **Network Expansion** (where structural capacity is needed), closing the loop from prediction \rightarrow action \rightarrow learning.