

①

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(a) $x_1(t) = x(5+t) - x(-t+4)$

$$x(t) \xleftrightarrow{FT} X(j\omega) \begin{cases} x(-t) \xleftrightarrow{FT} X(-j\omega) \\ x(t-t_0) \xleftrightarrow{FT} e^{-j\omega t_0} X(j\omega) \end{cases}$$

$$\Rightarrow X_1(j\omega) = e^{-5j\omega} X(j\omega) - e^{-4j\omega} X(-j\omega)$$

(b) $x_2(t) = x(3t+1)$

$$x(t) \xleftrightarrow{FT} X(j\omega) : x(\alpha t) \xleftrightarrow{FT} \frac{1}{|\alpha|} X\left(\frac{j\omega}{\alpha}\right)$$

$$\Rightarrow X_2(j\omega) = \frac{e^{-j\omega}}{3} X\left(\frac{j\omega}{3}\right)$$

(c) $x_3(t) = \frac{d^3}{dt^3} x(t-3) : \frac{d}{dt} x(t) \longleftrightarrow j\omega X(j\omega)$

$$\Rightarrow X_3(j\omega) = e^{-5j\omega} X(j\omega)^3 X(j\omega)$$

(d) $x_4(t) = tx(t-1) : tx(t) \longleftrightarrow j \frac{dX(j\omega)}{d\omega}$

$$\Rightarrow X_4(j\omega) = e^{-j\omega} X(j\omega) \times j \frac{dX(j\omega)}{d\omega}$$

② (a) $x(t) = 2 + \cos(3\pi t + \pi/4)$ =

$$= 2 + \frac{1}{2} \left(e^{j(3\pi t + \pi/4)} + e^{-j(3\pi t + \pi/4)} \right) =$$

$$= \underbrace{2}_{a_0} + \underbrace{\frac{1}{2} e^{j\pi/4}}_{a_1} e^{j(3\pi t)} + \underbrace{\frac{1}{2} e^{-j\pi/4}}_{a_{-1}} e^{-j(3\pi t)}$$

$$\Rightarrow X(j\omega) = 2 \times 2\pi \delta(\omega) + 2\pi \frac{1}{2} e^{j\pi/4} \delta(\omega - 6\pi) + 2\pi \frac{1}{2} e^{-j\pi/4} \delta(\omega + 6\pi)$$

(b) $x(t) = te^{-4t} \cos(2t) u(t) = m(t)n(t)$

$$m(t) = te^{-4t} u(t), n(t) = \cos(2t)$$

$$x(t) = m(t)n(t) \xleftrightarrow{FT} X(j\omega) = \frac{1}{2\pi} (M(j\omega) * N(j\omega))$$

$$m(t) : \frac{t^{n-1}}{(n-1)!} e^{-at} u(t) \xleftrightarrow{FT} \frac{1}{(a+j\omega)^n}$$

$$\Rightarrow m(t) \xleftrightarrow{FT} M(j\omega) = \frac{1}{(2+j\omega)^2} \text{ (I)}$$

$$n(t) : \cos(\omega_0 t) \xleftrightarrow{FT} \pi (\delta(\omega + \omega_0) + \delta(\omega - \omega_0))$$

$$\Rightarrow n(t) \xleftrightarrow{FT} N(j\omega) = \pi (\delta(\omega + 2) + \delta(\omega - 2)) \text{ (II)}$$

$$\text{(I), (II)} \Rightarrow X(j\omega) = \pi (M(j(\omega+2)) + M(j(\omega-2)))$$

(c) $x(t) = t \frac{\sin(3t)}{\pi t}$

$$\frac{\sin(3t)}{\pi t} \xleftrightarrow{FT} X(j\omega) = \text{rect}\left(\frac{\omega}{6}\right)$$

$$tx(t) \xleftrightarrow{FT} j \frac{dX(j\omega)}{d\omega}$$

$$\Rightarrow t \frac{\sin(3t)}{\pi t} \xleftrightarrow{FT} 0$$

(d) $x(t) = \frac{4t}{(1+t^2)^2}$

$$e^{-|t|} \xleftrightarrow{FT} \frac{2}{1+\omega^2} \xrightarrow{\text{duality}} \frac{2}{1+t^2} \longleftrightarrow 2\pi e^{-|\omega|}$$

$$x(t) \xleftrightarrow{FT} \frac{-2}{1+t^2} \longleftrightarrow -4\pi e^{-|\omega|} \xrightarrow{d/dt}$$

$$\frac{4t}{(1+t^2)^2} \longleftrightarrow (j\omega) (-4\pi e^{-|\omega|})$$

$$(e) x(t) = e^{-3|t|} \sin(2t)$$

$$e^{-3|t|} = (e^{-|t|})^3 \xrightarrow{\text{FT}} \left(\frac{1}{1+t^2} * \frac{1}{1+t^2} * \frac{1}{1+t^2} \right) \quad \text{I}$$

$$\sin(2t) \longleftrightarrow j\pi (\delta(\omega+2) - \delta(\omega-2)) \quad \text{II}$$

$$\Rightarrow X(j\omega) = \text{I} * \text{II}$$

$$(3) (a) X(j\omega) = 3\delta(\omega+4)$$

$$2\pi\delta(\omega - (-4)) \longleftrightarrow e^{-4jt} \xrightarrow{\times 3/2\pi}$$

$$\frac{3}{2\pi} e^{-4jt} \longleftrightarrow 3\delta(\omega+4)$$

$$(b) \frac{-j\omega + 5}{-\omega^2 + 10j\omega + 21} = \frac{-j\omega + 5}{(j\omega)^2 + 10j\omega + 21} =$$

$$= \frac{-j\omega + 5}{(j\omega+3)(j\omega+7)} = \frac{A}{j\omega+3} + \frac{B}{j\omega+7} \Rightarrow$$

$$\Rightarrow \begin{cases} A+B = -1 \\ 7A+3B = 5 \end{cases} \Rightarrow A=2, B=-3$$

$$\frac{2}{j\omega+3} \longleftrightarrow 2e^{-3t}u(t), \quad \frac{-3}{j\omega+7} \longleftrightarrow -3e^{-7t}u(t)$$

$$\Rightarrow X(j\omega) = \frac{2}{j\omega+3} + \frac{-3}{j\omega+7} \longleftrightarrow$$

$$2e^{-3t}u(t) - 3e^{-7t}u(t)$$

$$(c) X(j\omega) = \pi e^{-5|\omega|}$$

$$e^{-a|t|} \longleftrightarrow \frac{2a}{a^2+\omega^2} \xrightarrow{\text{duality}} \frac{2a}{a^2+t^2} \longleftrightarrow$$

$$2\pi e^{-a|\omega|} \xrightarrow{a=5} 2\pi e^{-5|\omega|} \xrightarrow{\div 2}$$

$$\pi e^{-5|\omega|} \longleftrightarrow \frac{5}{25+t^2}$$

$$(5) (a) \xrightarrow{\text{FT}} (j\omega)^2 Y(j\omega) + (j\omega) Y(j\omega)$$

$$-12 Y(j\omega) = 7 X(j\omega), \quad H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} =$$

$$= \frac{7}{(j\omega)^2 + (j\omega) - 12} = \frac{7}{(j\omega+4)(j\omega-3)}$$

$$= \frac{A}{j\omega+4} + \frac{B}{j\omega-3} \Rightarrow A=-1, B=1$$

$$\Rightarrow H(j\omega) = \frac{-1}{j\omega+4} + \frac{1}{j\omega-3} \Rightarrow$$

$$\Rightarrow h(t) = -e^{-4t}u(t) + e^{3t}u(t)$$

$$(b) x(t) = te^{-4t}u(t) \Rightarrow X(j\omega) =$$

$$= \frac{1}{(4+j\omega)^2}, \quad H(j\omega) X(j\omega) = Y(j\omega) =$$

$$= \frac{1}{(4+j\omega)^2} \cdot \frac{7}{(j\omega+4)(j\omega-3)} =$$

$$= \frac{7}{(j\omega+4)^3(j\omega-3)} = \frac{A}{(j\omega+4)^3} + \frac{B}{(j\omega+4)^2}$$

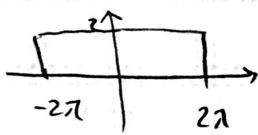
$$+ \frac{C}{(j\omega+4)} + \frac{D}{(j\omega-3)} \Rightarrow$$

(بى 2 لۇغىتى، نۇقتىدا - آفرىنىش 10%)

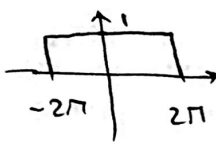
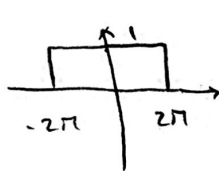
$$\Rightarrow D = \frac{7}{199}, C = \frac{-7}{199}, B = \frac{-49}{199}, A = \frac{-231}{199}$$

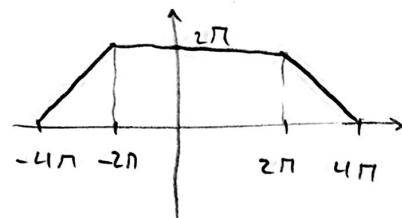
$$\Rightarrow y(t) = \frac{-231}{199} \frac{t^2}{2} e^{-4t}u(t) - \frac{49}{199} t e^{-4t}u(t)$$

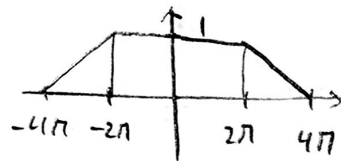
$$- \frac{7}{199} e^{-4t}u(t) + \frac{7}{199} e^{3t}u(t)$$

⑥ $H(j\omega) =$ 

$A(j\omega) = \frac{1}{2\pi} (X(j\omega) * P(j\omega)) =$

$= \frac{1}{2\pi}$  $*$ 

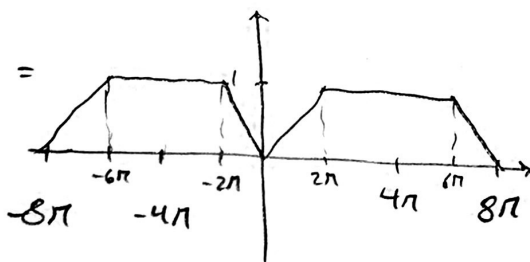
$= \frac{1}{2\pi}$ 

$=$ 

$B(j\omega) = \frac{1}{2\pi} (A(j\omega) * Q(j\omega)) =$

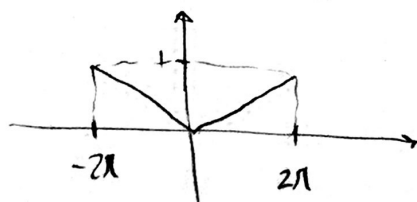
$= \frac{1}{2\pi} (A(j\omega) * \pi(\delta(\omega+4\pi) + \delta(\omega-4\pi))) =$

$= \frac{1}{2} (A(j(\omega+4\pi)) + A(j(\omega-4\pi)))$

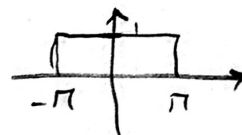
$\Rightarrow B(j\omega) =$ 

$C(j\omega) = B(j\omega) H(j\omega) \Rightarrow$

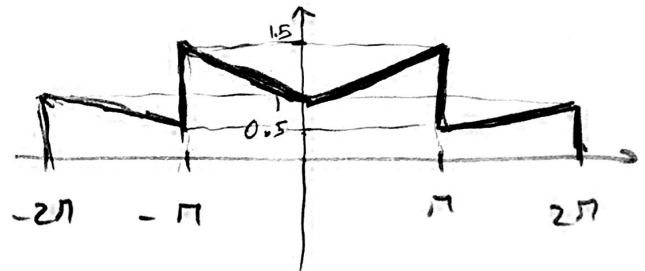
$\Rightarrow C(j\omega) =$



$D(j\omega) = C(j\omega) + R(j\omega)$

$R(j\omega) =$ 

$\Rightarrow D(j\omega) =$



$$\textcircled{7} H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{j\omega + 10}{98 - \omega^2 + 21\omega}$$

$$= \frac{j\omega + 10}{(j\omega)^2 + 21\omega + 98} =$$

$$= \frac{j\omega + 10}{(j\omega + 14)(j\omega + 7)} =$$

$$= \frac{A}{j\omega + 14} + \frac{B}{j\omega + 7} \Rightarrow$$

$$\Rightarrow A = 4/7, B = 3/7$$

$$\Rightarrow h(t) = \left(\frac{4}{7} e^{-14t} u(t) + \frac{3}{7} e^{-7t} u(t) \right)$$

$$\Rightarrow y(t) = x(t) * h(t)$$

$$\Rightarrow y(t) = x(t) * \left(\frac{4}{7} e^{-14t} u(t) + \frac{3}{7} e^{-7t} u(t) \right)$$