# PathSafe

A dive into the viability of detection models aiding in the identification of problematic roads

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#### The Problem

#### Vehicle Damage

Potholes can cause significant damage to vehicles, including bent rims, damaged suspension, and more.

#### Safety Hazards

Potholes present serious safety hazards to drivers, cyclists, and pedestrians.

#### Infrastructure

Potholes are a symptom of underlying issues in road maintenance and can indicate broader infrastructure problems

## Our Approach

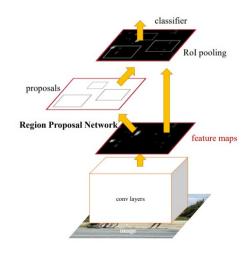
#### Obtain a Dataset

Pothole dataset obtained from

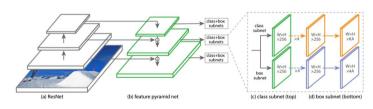


# Choose Models & Implement Using Detectron2

Faster R-CNN:



RetinaNet:



Detectron2:



## Dataset







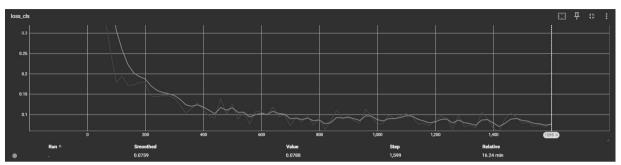


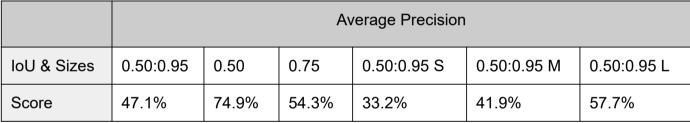




- 665 images of roads with potholes
  - 70/20/10 train, test, and validation split
- All data was already labeled
- No preprocessing was required as the dataset was already in the Detectron2 format

# Results



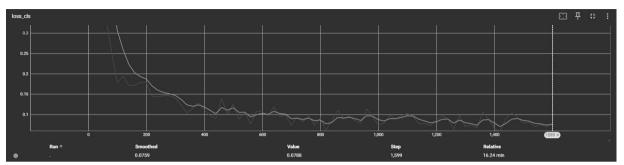


	Average Recall					
Sizes & Max Detections	All (1)	All (10)	All (100)	Small (100)	Medium (100)	Large (100)
Score	27.2%	58.9%	61.1%	48.4%	56.7%	69.7%









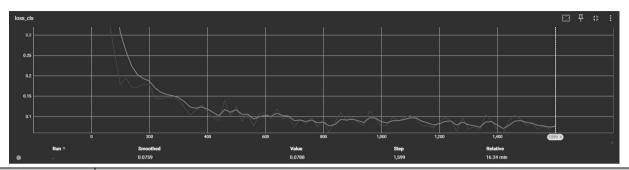


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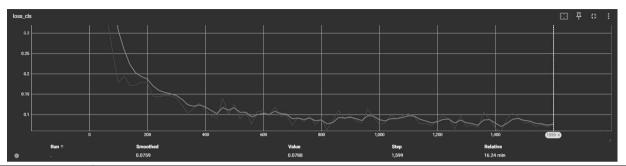


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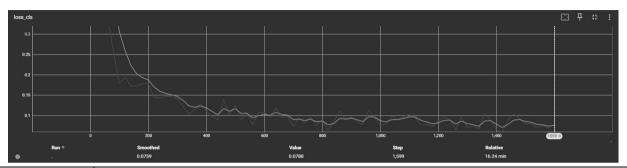


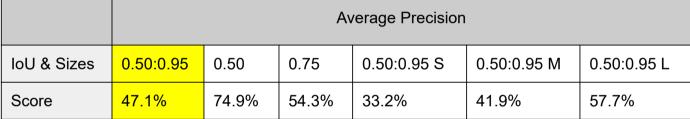
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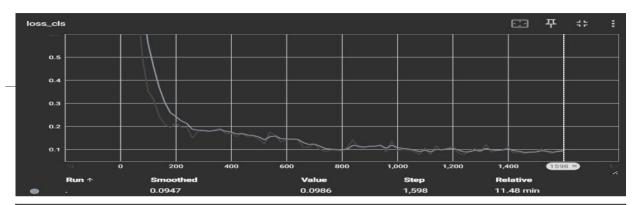


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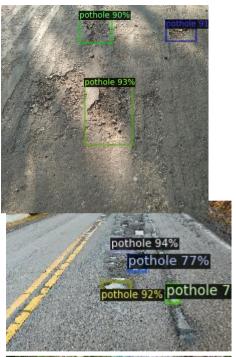






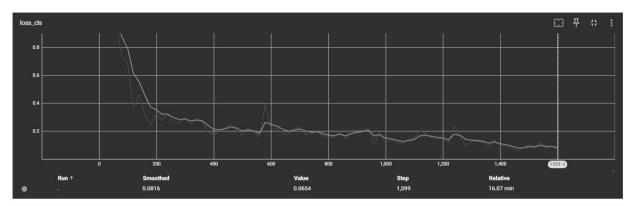
Average Precision						
0.50:0.95	0.50	0.75	0.50:0.95 S	0.50:0.95 M	0.50:0.95 L	
38%	58%	43%	22%	31%	50%	

Average Recall						
All (1)	All (10)	All (100)	Small (100)	Medium (100)	Large (100)	
26%	46%	46%	26%	43%	56%	





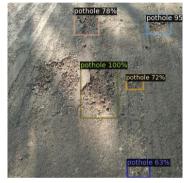
## Results - RetinaNet



Average Precision						
0.50:0.95	0.50	0.75	0.50:0.95 S	0.50:0.95 M	0.50:0.95 L	
48.1%	72.5%	58.3%	34.1%	37.3%	62.0%	

Average Recall						
All (1)	All (10)	All (100)	Small (100)	Medium (100)	Large (100)	
30.90%	60.1%	65.5%	53.6%	62.6%	72.4%	







## Overall Results - Avg. Precision & Avg.

Recall Considering just AP over IoU values in the range of 0.50-0.95 and considering all object sizes, testing the three models on the test set

resul	t <sub>Model</sub> the following	Paster R-CNN 50	Faster R-CNN 101	RetinaNet	
	AP Score	38.0%	47.1%	48.1%	

And, considering AR on all object sizes and allowing a maximum of 100 detections, resulted in the following:

Model	Faster R-CNN 50	Faster R-CNN 101	RetinaNet
AR Score	46.0%	61.1%	65.5%

#### Conclusion

RetinaNet stands out as our most effective model for pothole detection from our comparison, excels in both precision and recall metrics. For real-world implementations this model would offer the best balance between accuracy and reliability.

#### Further considerations:

- Larger Diverse Dataset
- Inference Speeds
- Efficiency

